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some observations in the high-frequency versions of a standard new-keynesian model

by Reiner Franke and Stephen Sacht
Some Observations in the High-Frequency Versions of a Standard New-Keynesian Model

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Abstract
In a small-scale New-Keynesian model with a hybrid Phillips curve and IS equation, the paper is concerned with an arbitrary frequency of the agents’ synchronized decision making. It investigates the validity of a fundamental methodological precept according to which no substantive prediction or explanation of a well-defined macroeconomic period model should depend on the real time length of the period. While this principle is basically satisfied as the period goes to zero, the impulse-response functions of the high-frequency versions can qualitatively as well as quantitatively be fairly dissimilar from their quarterly counterpart. The result proves to be robust under variations of the degree of price stickiness. The main conclusion is that DSGE modelling may be more sensitive to its choice of the agents’ decision interval.

\textit{JEL classification:} C63; E31; E32; E52.
\textit{Keywords:} Hybrid New-Keynesian model; high-frequency modelling; impulse-response functions; Foley’s methodological precept.

1. Introduction
In macroeconomics, dynamic stochastic general equilibrium (DSGE) models are usually formulated in discrete time. As an approximation to reality, they assume that decisions are not only taken discontinuously but also that all transactions of a certain class occur in the same, synchronized rhythm. There is, however, no argument that would allow one to identify a “natural period” for economic activity in these models. If they, especially

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in numerical studies, invoke a definite period like a quarter, say, this choice is entirely
determined by convention or the frequency of the available data.

Given this ‘degree of freedom’, a sound model will certainly be required to produce
similar outcomes if its underlying period is changed. This is a fundamental methodological
precept that goes back (at least) to May (1970). To quote from a more extensive
discussion of this issue by Duncan Foley (1975, p. 310; his emphasis):

“No substantive prediction or explanation in a well-defined macroeconomic period
model should depend on the real time length of the period.”

For simplicity, and because of the influence the paper had at its time, we may refer to
this maxim as Foley’s precept.

The general idea of the precept can be expressed in several ways, with different degrees
of detail. Most fundamentally, the requirement that the results of a model do not depend
in any important way on the period is translated into the condition that it should be
feasible to make the period arbitrarily short. Consequently, in the limit, one would arrive
at a continuous-time respecification: “The method used to accomplish this is to retain
the length of the period as an explicit variable in the mathematical formulation of a
period model and to make sure that it is possible to find meaningful limiting forms of
the equations as the period goes to zero” (Foley, 1975, p. 311). For short, this criterion
for consistent discrete-time macroeconomic modelling will henceforth be called Foley’s
Criterion CT, which is to be mnemonic for a well-defined continuous-time limit.

A reduction of the period length is tantamount to more frequent decisions and trans-
actions within a given calendar time unit. A model version with a shorter period than
in the original formulation is thus a high-frequency economy. If the period of the bench-
mark model serves as the time unit, which is fixed, and a high-frequency economy is
constituted by a period of length \( h < 1 \), the latter will also conveniently be designated
an \( h \)-economy.

A study of Criterion CT in a standard DSGE model will be one subject of this pa-
er. This, however, is not to say that modelling should be done in continuous time.
Nevertheless, if discrete-time modelling employs some lower frequency in the agents’
decision-making, one has to be aware of the possibility that versions of the same model
with different periods \( h \leq 1 \) may have different dynamic properties. A positive finding in
this respect would cast doubt on the conventional quarterly period and raise the problem
of which frequency to choose in the end.

One approach to address this question is that a calibration or estimation procedure
takes explicit account of different decision intervals on the part of the economic agents
and tries to let the data decide about an appropriate period.\(^2\) As long as this is not
systematically done, one may resort to the concept of a robust period length \( h^* \). Quite

\(^2\) We only know of two examples of such work in the literature, namely, Christiano (1985) and
in line with the abovementioned maxim, we mean by this an upper-bound on $h$ that is low enough to rule out any overly strong dissimilarities in the model’s most fundamental properties across the high-frequency versions with $h \leq h^*$. For example, if in a quarterly model a dynamic property $P$ in its monthly version, $P(\text{month})$, turns out to be too different from $P(\text{quarter})$ but not so much from $P(\text{week})$, the quarter as a suitable decision interval may better be abandoned and replaced with a month or a week, for that matter. The second subject of the paper is an investigation of the question whether, in the given model and if the choice of the period is not to be too arbitrary, there is a need for such a reconsideration.

While the first dynamic property of a DSGE model to check is determinacy, it poses no problem here and can be safely taken for granted. We rather direct the focus on the features of the model’s impulse-response functions (IRFs), where it suffices for our purpose to limit the interest to monetary policy shocks.

The similarity or dissimilarity of the time paths of two IRFs can be assessed along two dimensions. On the one hand, it will be required that they have a similar shape. We refer to this criterion of qualitative similarity as Criterion $\text{QualS}$. It would typically fail to apply if, after the impact effect, one IRF immediately turns around and converges in a monotonic way back to the steady state level, and the other initially moves further away from the equilibrium for a while until it starts to revert.

The second dimension is that of quantitative similarity, which may be referenced as Criterion $\text{QuantS}$. What exactly constitutes a numerical threshold below (above) which Criterion $\text{QuantS}$ is said to be fulfilled (or violated) is a matter of convenience, which is no problem if the threshold is explicitly stated. Here it will become apparent in the course of the discussion of our results.

The present paper investigates the three criteria for the high-frequency versions of a quarterly small-scale standard model of the New-Keynesian variety. Neglecting the wage side of the economy, it generally admits backward-looking elements in the form of a hybrid Phillips curve for price inflation and a hybrid IS equation for the output gap. We thus have four different variants, according to which of the hybrid components are switched on or off. Section 2 specifies the transformation of the quarterly model into a high-frequency version, where for better comparability across different decision intervals the variables continue to be expressed as quarterly magnitudes. Section 3 works out the analytical results that can be obtained for the limiting process $h \to 0$. After setting up a benchmark parameter scenario, Section 4 turns to a numerical investigation of the IRFs in the four model variants that compares the outcome of a quarterly, monthly and daily frequency. It thus addresses the question of whether the quarterly decision interval is a sufficiently

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3 This is different in the high frequency versions of the Benhabib and Farmer (1994) real business cycle model. Hintermaier (2005) discusses a set of numerical parameters such that, for instance, the quarterly economy is determinate but not the weekly version.
robust base period. Section 5 presents a short sensitivity analysis. Concentrating on a comparison of the quarterly with the perhaps still convenient monthly economies, it examines how the gaps between the two IRFs at selected points in time increase or decrease when the model’s price stickiness parameter is varied over an empirically relevant range. Section 6 concludes, and an appendix contains some technical details and additional diagrams.

2. The concept of a high-frequency economy

The New-Keynesian model underlying our investigations combines two well-known specifications of a hybrid IS equation and of a hybrid Phillips curve derived from a Calvo setting. Thus, with respect to a period of given length, let \( y_t \) be the output gap in period \( t \), \( \pi_t \) the rate of price inflation (being zero in the steady state), \( i_t \) the nominal interest rate, and \( v_t \) a serially correlated monetary policy shock. The latter will be the only exogenous force imposed on the system, which is set in motion by a one-time impulse \( \varepsilon^v \) in period \( t = 0 \). The natural real rate of interest is treated as a constant, which coincides with the households’ discount rate \( \rho \). Assuming a Taylor rule with reactions to the contemporaneous values of inflation and economic activity, the model reads as follows:

\[
\begin{align*}
\pi_t &= \gamma_f E_t[\pi_{t+1}] + \gamma_b \pi_{t-1} + \lambda y_t \\
y_t &= \frac{1}{1+\chi} E_t[y_{t+1}] + \frac{\chi}{1+\chi} y_{t-1} - \frac{1-\chi}{(1+\chi)\sigma} (i_t - E_t[\pi_{t+1}] - \rho) \\
i_t &= \rho + \phi_\pi \pi_t + \phi_y y_t + v_t \\
v_{t+1} &= \alpha v_t, \quad \text{where } v_0 = \varepsilon^v
\end{align*}
\]

It goes without saying that \( E_t \) denotes the mathematical expectation operator conditional on information up to period \( t \), and that all coefficients are constant and positive or nonnegative, as the case may be. The autocorrelation \( \alpha \) is contained between zero and one, \( \sigma \) is the households’ intertemporal elasticity of substitution in consumption, \( \phi_\pi \) and \( \phi_y \) are the central bank’s policy parameters, and \( \chi \) is the parameter that measures the degree of the households’ external habit formation (\( 0 \leq \chi < 1 \)), where we adopt the specification in Smets and Wouters (2003, p. 1134). The coefficients in the Phillips curve are composed of \( \sigma \) and three further structural parameters:

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\( ^4 \) See also Abel (1990, p. 38), who first introduced this concept of habit formation into the macroeconomic literature. \( \chi = 1 \) would disconnect output and inflation from the real interest rate, while \( \chi > 1 \) is inadmissible because it would imply a falling steady state utility in consumption (Fuhrer, 2000, p. 370).
\[ \gamma_f = \frac{\beta \theta}{\theta + \omega [(1 - \theta(1 - \beta))]}, \quad \beta = 1/(1 + \rho) \]

\[ \gamma_b = \frac{\omega}{\theta + \omega [(1 - \theta(1 - \beta))]}, \quad \lambda = \frac{(1 - \omega) (\sigma + \eta) (1 - \theta)(1 - \beta \theta)}{\theta + \omega [(1 - \theta(1 - \beta))]}. \tag{2} \]

Here, \( \beta \) is the discount factor; \( \eta \) the substitution elasticity of labour in the households’ utility function; \( \theta \) the degree of price stickiness, i.e., \( (1 - \theta) \) is the fraction of all firms that happen to reset their price in a given period \( (0 < \theta < 1) \); and \( \omega \) is the fraction of the rule-of-thumb price setters \( (0 \leq \omega < 1) \), i.e. when resetting the price, these firms are ‘backward-looking’ and simply extrapolate the recent history of aggregate prices, whereas a fraction \( (1 - \omega) \) of the firms reset their price optimally, given the constraint on the timing adjustments and using all information to forecast future marginal costs. Hence the deviations \( mc_t \) of the latter from their steady state value feature as the driving force in the determination of inflation. On the supposition that \( mc_t \) is linked to the output gap by the factor \( (\sigma + \eta) \), the hybrid Phillips curve in (1) is seen to be identical to the one put forward by Galí and Gertler (1999, pp. 209–211).  

Certainly, system (1) includes the equations of the New-Keynesian baseline model as special cases (but not the polar case of a purely backward-looking model). For easier reference below, the following four model variants may thus be distinguished:

- NKB: the New-Keynesian baseline case, \( \omega = 0, \chi = 0 \)
- HPC: the hybrid Phillips curve, \( \omega > 0, \chi = 0 \)
- HIS: the hybrid IS equation, \( \omega = 0, \chi > 0 \)
- HMP: the hybrid model proper, \( \omega > 0, \chi > 0 \)

So far, no particular presumption concerning the length of the period has been invoked; it could be a quarter, as usual, as well as a month, a week or a day. In order to compare two economies with different frequencies of the synchronized actions, we now fix the time unit as a quarter, say, and generally allow the agents to make their decisions and carry out the corresponding transactions every \( h \) quarters \( (0 < h \leq 1) \). Let us call such a high-frequency economy an \( h \)-economy.

For a direct comparison of two \( h \)-economies, the flow variables are uniformly expressed as ‘quarterized’ magnitudes. Accordingly, a nominal interest rate \( i_t \) of, for example, 1.50% per quarter means that, in an \( h \)-economy, hundred dollars earn \( h \cdot 1.50 \) dollars over the period \( [t, t+h) \). The discount rate \( \rho \) is to be interpreted analogously. Denoting the log price prevailing over the same time interval by \( p_t \), the quarterized inflation rate is given by

\[ \frac{p_{t+h} - p_t}{h}. \]

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5 See also Galí et al. (2001, pp.1246ff) and Henzel and Wollmershäuser (2008, p. 819).
\[ \pi_t = (p_t - p_{t-h}) / h \]  

(3)

It is not necessary to spell out the details that lead from the microfoundations to the structural Phillips curve and IS equation in an \( h \)-economy.\(^6\) All of the agents’ optimization procedures and the subsequent mathematical operations go through unaltered if the following rules are obeyed: (i) the output gap \( y_t \) as a ratio of two flow magnitudes need not be transformed since it has no time dimension; (ii) the inflation, interest and discount rates \( \pi_t, i_t, \rho \) in (1) have to be replaced with \( h\pi_t, hi_t, h\rho \), respectively; (iii) the frequency-dependent parameters in (1) and (2) have to be suitably adjusted.

Regarding the last point, let us first list the parameters that remain unaffected by a change in the length of the period. These are the two elasticities \( \sigma \) and \( \eta \), the rule-of-thumb price setting parameter \( \omega \), and the habit-formation parameter \( \chi \).\(^7\) The IS equation can then immediately be reformulated for an \( h \)-economy as

\[ y_t = \left[ \frac{1}{1+\chi} \right] E_t[y_{t+h}] + \left[ \frac{\chi}{1+\chi} \right] y_{t-h} + \left[ \frac{(1-\chi)(1+\chi)\sigma}{(1+\chi)\sigma} \right] (hi_t - E_t[p_{t+h} - p_t] - h\rho), \]

and with definition (3) the last term can be rewritten as

\[ h \left[ \frac{1-\chi}{1+\chi} \right] (i_t - E_t[\pi_{t+h}] - \rho). \]

The two policy parameters determining the interest rate pose no problems, either. The Taylor rule adjusted to the \( h \)-economy reads

\[ hi_t = h\rho + \phi_u (p_t - p_{t-h}) + h\phi_y y_t + hv_t. \]

Dividing this equation by \( h \) and again using (3), the same formulation for the interest rate reactions as in (1) is obtained.

The values of two of the structural parameters, which enter eq. (2) and the Phillips curve, are dependent on the frequency of decision-making: the discount factor \( \beta \), which in an \( h \)-economy becomes \( \beta = \beta(h) = 1/(1+h\rho) \), and the price stickiness \( \theta \). As in a period of length \( h \) the fraction of firms resetting their price will be \( h(1-\theta) \), we have \( \theta(h) = 1 - h(1-\theta) \) if the pure symbol \( \theta \) is retained for the constituent stickiness parameter from the quarterly setting. With \( \beta(h) \) just defined, \( (1-\beta) \) turns into \( h\rho/(1+h\rho) \), and the expression \( (1-\theta)(1-\beta\theta) \) in the specification of \( \lambda \) in (2) turns into \( [1-\theta(h)][1-\beta(h)\theta(h)] = h^2 (1-\theta)(1+\rho-\theta)/(1+h\rho) \).

Treating the other frequency-dependent terms in (2) in a similar way, the \( h \)-economy counterparts of the composite coefficients in (2) result like:

---

\(^6\) The Calvo setting is helpful in this respect, whereas markup pricing together with Taylor’s staggered wage contracts would be much more difficult to treat; see Christiano (1985).

\(^7\) In the quarterly model, current consumption \( c^k_t \) of household \( k \) and past aggregate consumption \( C_{t-1} \) (scaled to the household’s consumption level) enter the utility function as the difference \( c^k_t - \chi C_{t-1} \). This expression requires \( \chi \) to be dimensionless, and in the \( h \)-economy it becomes \( hc^k_t - \chi hC_{t-1-h} \) if the consumption variables are quarterized, too.
\[ \beta(h) = \frac{1}{1 + h \rho} \]

\[ \gamma_f(h) = \frac{1 - h(1 - \theta)}{(1 + h \rho) \ a(h)} \]

\[ \gamma_b(h) = \frac{\omega}{a(h)} \]

\[ \lambda(h) = h^2 \ b(h) \]

\[ a(h) = \omega + \frac{[1 + h(1 - \omega) \rho] [1 - h(1 - \theta)]}{1 + h \rho} \]

\[ b(h) = \frac{(1 - \omega)(\sigma + \eta)(1 - \theta)(1 + \rho - \theta)}{a(h)} \quad (4) \]

It will be observed that these terms remain well-defined as the period becomes infinitesimally small. In particular, \( a(h) \) tends to \((1 + \omega)\) as \( h \to 0\), so that the limits of \( \gamma_f(h) \) and \( \gamma_b(h) \) are \( 1/(1 + \omega) \) and \( \omega/(1 + \omega) \), respectively. We also remark that for \( h = 1 \), \( b(1) \) coincides with the definition of \( \lambda \) in (2).

The Phillips curve is now easily derived as follows. In an \( h \)-economy, we have \( p_t - p_{t-h} = \gamma_f(h) E_t[p_{t+h} - p_t] + \gamma_b(h)(p_{t-h} - p_{t-2h}) + \lambda(h) \). So we only have to divide this equation by \( h \) to formulate the relationship in terms of the quarterized inflation rates, which poses no problems by virtue of the expression we got for \( \lambda(h) \). Finally, writing the autoregressive process for the monetary policy shocks in (1) as \( v_{t+1} = v_t - (1 - \alpha) v_t \) and taking into account that in an \( h \)-economy the updating occurs \( 1/h \) times per quarter, the equation becomes \( v_{t+h} = v_t - h(1 - \alpha) v_t \). On the whole, therefore, the hybrid New-Keynesian model with a general period of length \( h \) is described by the following set of equations:

\[ \pi_t = \gamma_f(h) E_t[\pi_{t+h}] + \gamma_b(h) \pi_{t-h} + h b(h) y_t \]

\[ y_t = \frac{1}{1 + \chi} E_t[y_{t+h}] + \frac{\chi}{1 + \chi} y_{t-h} - h \frac{1 - \chi}{(1 + \chi) \sigma} (i_t - E_t[\pi_{t+h}] - \rho) \quad (5) \]

\[ i_t = \rho + \phi_\pi \pi_t + \phi_y y_t + v_t \]

\[ v_{t+h} = [1 - h(1 - \alpha)] v_t \, , \quad \text{where } v_0 = \varepsilon^v \]

Obviously, setting \( h = 1 \) recovers the quarterly model set up in eqs (1) and (2). When studied in the framework of these \( h \)-economies, the cases NKB, HPC, etc. listed above may be referred to as NKB(\( h \)), HPC(\( h \)), etc.

3. Analytical results

Our investigation of the \( h \)-economies begins with Foley’s Criterion \( CT \), which checks the limiting behaviour of system (4) and (5) as the length of the period \( h \) becomes infinitesimally small. Before turning to numerical simulations, let us see what kind of
results can be obtained from a general analytical treatment. In fact, this approach is perfectly suited for the New-Keynesian baseline model, where it allows us to derive all of the information we want.

We first show that in this case the limit process $h \to 0$ transforms (5) into two well-defined differential equations for $\pi$ and $y$. In a framework with a one-time exogenous shock to the interest rate, rational expectations amount to perfect foresight, so that $E_t[\pi_{t+h}] = \pi_{t+h}$ and $E_t[y_{t+h}] = y_{t+h}$. The Phillips curve with $\omega = 0$, from which we have $\gamma_f(h) = \beta(h)$ and $\gamma_b(h) = 0$, may then be rearranged as $\pi_{t+h} - \pi_t = [1 - \beta(h)] \pi_t - hb(h) y_t$. Substituting the Taylor rule in the IS equation gives us, with $\chi = 0$, $y_{t+h} - y_t = (h/\sigma) [(\phi_{\pi} - 1) \pi_t - (\pi_{t+h} - \pi_t) + \phi_y y_t + v_t]$. Putting $b^\sigma = b(0) = (\sigma + \eta)(1 - \theta)(1 + \rho - \theta)$, dividing by $h$ and going to the limit, $h \to 0$, leads to the continuous time formulation,

$$
\begin{bmatrix}
\dot{\pi} \\
\dot{y}
\end{bmatrix} = \begin{bmatrix}
\rho & -b^\sigma \\
(\phi_{\pi} - 1)/\sigma & \phi_y/\sigma
\end{bmatrix} \begin{bmatrix}
\pi \\
y
\end{bmatrix} + \begin{bmatrix}
0 \\
1/\sigma
\end{bmatrix} v
$$

(6)

Determinacy in this system requires both eigen-values of the matrix in (6) to have positive real parts. This is the case if, and only if, the matrix has a positive determinant and a positive trace. As the latter is always ensured, it is immediately seen that a necessary and sufficient condition for determinacy of the continuous-time counterpart of NKB is

$$b^\sigma (\phi_{\pi} - 1) + \rho \phi_y > 0
$$

(7)

Intuition says that, for small values of $h > 0$, the conditions for the $h$-economies are close to (7) (see Franke and Flaschel, 2009, for the precise details). Even the condition for the quarterly model is not very different: $b^\sigma (\phi_{\pi} - 1) + \rho \phi_y/(1 + \rho) > 0$ (Bullard and Mitra, 2002, pp. 1115, 1125f).

A well-defined continuous-time formulation is therefore not only a matter of internal consistency, but it may also be helpful for the analytical tractability of determinacy conditions. Although they are no problem here since results for the original model are readily available, it can be relevant for more general models giving rise to higher-order matrices. It may then happen that the original discrete-time formulations are too complicated to check the Blanchard-Kahn conditions analytically, while their continuous-time counterparts still offer some scope for a mathematical analysis.  

Another pleasant property of the baseline model is that it permits explicit closed-form solutions. Certainly, also their limits are found to be well-defined if we write them down for the $h$-economies (the explicit expressions are given in the appendix). Hence, Criterion $CT$ is satisfied in all pertinent aspects. We summarize this as our first observation, where for better distinction the variables in the $h$-economies are denoted by $y_t^{(h)}$, $\pi_t^{(h)}$, $v_t^{(h)}$.

---

8 This is demonstrated in Franke and Flaschel (2009) for the $4 \times 4$ matrices arising from the high-frequency versions of the New-Keynesian model by Erceg et al. (2000) with sticky wages and prices which, however, is purely forward-looking and neglects habit formation.
Observation 1

In the New-Keynesian baseline case NKB, the limiting forms of the \( h \)-economies (4), (5) for \( h \to 0 \) are well-defined for all \( t \geq 0 \) and given by (6). In addition, there exist two continuous and positive functions \( f_\pi = f_\pi(h) \) and \( f_y = f_y(h) \) defined on the closed unit interval \([0,1]\) such that for each \( h > 0 \) the solution paths of (4), (5) are determined by

\[
\pi_t^{(h)} = -f_\pi(h) v_t^{(h)}, \quad y_t^{(h)} = -f_y(h) v_t^{(h)} \quad (t = 0, h, 2h, \ldots).
\]

Thus, the continuous-time limits \( \pi_t^{(0)} \), \( y_t^{(0)} \) exist for all \( t \geq 0 \). Moreover, \( \pi_t^{(h)} \to \pi_t^{(0)} \) and \( y_t^{(h)} \to y_t^{(0)} \) as \( h \) tends to zero.

The last continuity property is an obvious implication of the continuity in \( h \) of the functions \( f_\pi \), \( f_y \) and the shocks \( v_t^{(h)} \) in the solution formulae. We nevertheless include this feature in the summary since it becomes more noteworthy further below.

To address the issue of transforming the hybrid model variants into continuous time, consider a positive point in time \( t > 0 \) and periods of length \( h = t/k \) for natural numbers \( k \in \mathbb{N} \). If, beginning with the Phillips curve, we suitably rearrange the inflation rates, divide through by \( h \), and use the parametric relationship

\[
1 - \gamma f(h) - \gamma y(h) = c(h) := \frac{(1-\omega) \rho [1 - h(1-\theta)]}{(1+h\rho) a(h)}
\]

we obtain

\[
\frac{\pi_{t+h} - \pi_t}{h} - \frac{\pi_t - \pi_{t-h}}{h} = \frac{-[2\gamma f(h) - 1]}{\gamma f(h)} \frac{\pi_t - \pi_{t-h}}{h} + \frac{c(h) \pi_{t-h} - b(h) y_t}{\gamma f(h)}
\]

(9)

Should the solution paths of the \( h \)-economies happen to exhibit sufficient smoothness over time and across frequencies such that the difference quotients on the left-hand side of (9) tend to become equal as \( h \to 0 \), the derivative of \( \pi \) can be obtained by setting the limit of the right-hand side equal to zero and solving it for \( \dot{\pi} \). With \( b^0 = b(0) \) and the simplifications in the other frequency-dependent expressions for \( h = 0 \), this yields

\[
\dot{\pi} = \rho \pi - \frac{1+\omega}{1-\omega} b^0 y \quad \text{(evaluated at } t > 0) \tag{10}
\]

It will be noted that in the perfectly forward-looking case, \( \omega = 0 \), this differential equation coincides with the first equation in (6), the only difference being that the latter is also well-defined at \( t = 0 \) when the shock occurs.

In a similar way, a high-frequency hybrid IS equation can be rearranged as

\[
\frac{y_{t+h} - y_t}{h} - \frac{y_t - y_{t-h}}{h} = \frac{-[2\delta f - 1]}{\delta f} \frac{y_t - y_{t-h}}{h} + \frac{1}{\sigma \delta f} \left[ (\phi \pi - 1) \pi_t - (\pi_{t+h} - \pi_t) + v_t \right]
\]

(11)

where \( \delta f := 1/(1+\chi) \). Applying the same assumption and reasoning as before leads to the following differential equation for the output gap,
\[ \dot{y} = \frac{1 + \chi}{(1 - \chi)\sigma} \left[ (\phi_\pi - 1) \pi + \phi_y y + v \right] \quad (\text{evaluated at } t > 0) \quad (12) \]

With no habit persistence, \( \chi = 0 \), we are again back to what has been derived for NKB in eq. (6).

In the way they were derived, the differential equations (10) and (12) cannot possibly be defined at \( t = 0 \). From (9) and (11) it is clear that \( \dot{\pi} \) and \( \dot{y} \) must be interpreted as backward derivatives. Since \( \pi_{t-h}, y_{t-h} \) are predetermined at their steady state values and the monetary policy impulse causes an immediate jump of the \( h \)-economies out of this state, the difference quotients \( (\pi_t - \pi_{t-h})/h \) and \( (y_t - y_{t-h})/h \) become unbounded as \( h \) tends to zero—at least if it can be presumed that the impact responses do not become negligibly weak for \( h \to 0 \). Moreover, it will later be seen that the forward derivatives do not exist, either. Let us nevertheless accentuate the positive analytical results concerning Foley’s Criterion \( CT \) for the hybrid economies in an extra observation.

**Observation 2**

If around some positive point in time \( t > 0 \) the solution paths of the \( h \)-economies \( HPC(h) \) or \( HMP(h) \) are so smooth that, for \( h = h_k = t/k \to 0 \) (for \( k \in \mathbb{N} \) and \( k \to \infty \)),

\[
\frac{\pi_{t+h}^{(h)} - \pi_t^{(h)}}{h} - \frac{\pi_t^{(h)} - \pi_{t-h}^{(h)}}{h} \to 0
\]

then in the limit the hybrid Phillips curve turns into the differential equation (10).

Likewise, if for \( HIS(h) \) or \( HMP(h) \) the solutions satisfy

\[
\frac{y_{t+h}^{(h)} - y_t^{(h)}}{h} - \frac{y_t^{(h)} - y_{t-h}^{(h)}}{h} \to 0
\]

for \( h \to 0 \), then in the limit the hybrid IS equation turns into the differential equation (12).

We are thus facing the problem if, or when, the smoothness conditions in Observation 2 are satisfied. Logically prior to it is a confirmation of the intuition (or hope) that the response functions \( \pi_t^{(h)}, y_t^{(h)} \) do tend to finite values as the periods become infinitesimally short. These issues, however, can no longer be treated with analytical mathematical methods. In the next section, the investigation is therefore extended to numerical simulations of the different versions of the model.

4. Numerical investigation

The numerical setting in our simulations of the model relies on parameter values well-known from the literature. They are collected in Table 1, where the frequency-dependent coefficients are based on the quarterly time unit. The real natural rate of interest of about...
4% per annum, log utility ($\sigma = 1$), and a unitary Frisch elasticity of labour supply ($\eta = 1$) are standard. The policy coefficients are the classical Taylor values (the coefficient on the output gap adjusted to the quarterly interest rate), while the value for $\alpha$ is associated with moderately persistent monetary policy shocks. A price rigidity of $\theta = 2/3$ implies an average price duration of three quarters. These parameters are borrowed from Galí (2008, p. 52). The values for $\omega$ and $\chi$ are extracted from two estimation studies, the one for $\omega$ from Galí et al. (2001, p. 1257) and the one for $\chi$ from Smets and Wouters (2003, p. 1143). Finally, the initial shock $\varepsilon^v$ corresponds to a sudden 1% increase in the annualized nominal interest rate, which of course is just a matter of scale.

| $\rho$ | Natural real rate of interest (households’ discount rate) | 0.010 |
| $\sigma$ | Intertemporal elasticity of substitution in consumption | 1.000 |
| $\eta$ | Intertemporal elasticity of substitution of labour | 1.000 |
| $\theta$ | Calvo degree of price stickiness | $2/3$ |
| $\omega$ | Rule-of-thumb parameter in price setting | 0.300 |
| $\chi$ | Habit-formation parameter in consumption | 0.600 |
| $\phi_{\pi}$ | Weight on inflation in the Taylor rule | 1.500 |
| $\phi_y$ | Weight on the output gap in the Taylor rule | 0.125 |
| $\alpha$ | Persistence in the shock process | 0.500 |
| $\varepsilon^v$ | Impulse to the interest rate (in per cent) | 0.250 |

**Table 1:** Numerical parameter scenario.

The outcome of a first set of simulations with these parameters is shown in Figure 1 (the output gap in the left column is given in per cent, the rate of inflation in the right column in per cent per quarter). The impulse-response functions (IRFs) in the upper two panels illustrate the analytical results in Observation 1 for the baseline case. At each of the three frequencies dealt with (a quarter, a month and a day), the two variables $y_t^{(h)}$ and $\pi_t^{(h)}$ converge monotonically back to the steady state values at the speed given by the shock process $v_t^{(h)}$. Hence convergence takes longer at the higher frequencies, although this effect is not very strong; see the dotted (blue) lines for the monthly and the thinner solid (red) lines for the daily economy versus the bold (green) lines for the usual quarterly setting. A discussion of the quantitative impact effects $y_0^{(h)}$ (but apparently not $\pi_0^{(h)}$) across different period lengths concerns Criterion QuantS and is postponed until later.

Before going on it may be mentioned that in Figure 1 as well as in Figure 2 below, the time paths from the weekly economies are fairly close to those from the daily economies (which is the reason why they have not been included in the diagrams). In the descriptions to follow, the daily decision intervals could therefore, for all practical reasons and if preferred, be identified with a weekly decision interval.

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Figure 1: Impulse-response functions for NKB\((h)\) and HMP\((h)\).

Note: The bold (upper green) lines represent the quarterly model \((h = 1)\), the dotted (blue) lines a monthly \((h = 1/3)\) and the solid (red) lines a daily economy \((h = 1/90)\). The two dots on the latter mark the first- and second-period values of the IRF in the hybrid case.

The results for the fully hybrid model in the lower two panels of Figure 1 are noteworthy for a number of reasons. What immediately leaps to the eye are the distinct troughs in the two impulse-response functions at the higher frequencies. That is, after the negative impact response to the shock, both the output gap and the inflation rate continue to decline for a short while. In the monthly economy the trough in the output gap is reached in the third month \((t = 2/3)\), and in the daily economy the turnaround takes place after 9 days, where the further decline after the the initial period is by no means negligible \((y = -0.117, -0.187 -0.279\) on impact, at the second day, and in the trough at the 9th day, respectively). The inflation rate starts to return somewhat earlier to the steady state. Here the trough occurs in the second month for \(h = 1/3\) and at the 5th day for \(h = 1/90\) (with, in the latter case, \(\pi = -0.478\) and \(-0.519\) at the second and 5th day, respectively, which is less dramatic than for the output gap).

The fact that the daily economy produces deeper (or even considerably deeper) troughs than the monthly economy raises the question for the behaviour of these turning points when \(h\) is decreased further. Checking the limiting behaviour (and its monotonicity) up
to an hourly frequency, \( h = 1/(24 \cdot 90) = 1/2160 \), we have every reason to believe that the troughs in \( \text{HMP}(h) \) are bounded from below (of course, for \( \text{NKB}(h) \) this is already known from Observation 1). Actually, the trough values of the daily economy are already fairly close to that of the hourly economy (\( y = -0.287 \) for the former \textit{versus} \( y = -0.293 \) after 15 hours, and \( \pi = -0.519 \) \textit{versus} \( \pi = -0.528 \) after 7 hours). Very similar results are found for the ‘partial’ model variants \( \text{HPC}(h) \) and \( \text{HIS}(h) \) as \( h \) is lowered to \( 1/2160 \).

Hence at least for practical purposes, boundedness of the IRFs can be considered an established fact, which we take down in the next observation. In its formulation we adopt the convention that, for points in time \( t \) that are not an integer multiple of a given \( h \), \( y_{t}^{(h)} \) and \( \pi_{t}^{(h)} \) are to be interpreted as the linearly interpolated values between the two values of the corresponding consecutive periods of the \( h \)-economy (between time \( kh \) and \( (k+1)h \) if \( kh < t < (k+1)h \) for some suitable \( k \in \mathbb{N} \)).

**Observation 3**

In all four model variants \( \text{NKB}(h) \), \( \text{HPC}(h) \), \( \text{HIS}(h) \), \( \text{HMP}(h) \) and for every \( t \geq 0 \) it appears that the impulse-response functions \( \pi_{t}^{(h)} \), \( y_{t}^{(h)} \) converge towards finite values \( \pi_{t}^{(0)} \), \( y_{t}^{(0)} \) as the period length \( h \) becomes small. This has been numerically confirmed for \( h \to 1/(24 \cdot 90) \).

Taking the boundedness of the IRFs for granted, the main message of the lower two panels in Figure 1 is the contrast between the pronounced troughs of \( y_{t}^{(h)} \) and \( \pi_{t}^{(h)} \) in \( \text{HMP}(h) \) for all periods of length \( h \) equal to or shorter than a month, and the monotonic behaviour of the output gap or the only weakly nonmonotonic behaviour of inflation in the quarterly economy. To distinguish which of the two backward-looking features is responsible for which effect, Figure 2 plots the IRFs for, respectively, the model with the hybrid Phillips curve only (in the upper part) and with the hybrid IS equation only (in the lower part). In both variants the quarterly IRFs are monotonic, whereas \( \text{HPC}(h) \) causes the inflation rate \( \pi_{t}^{(h)} \) and \( \text{HIS}(h) \) causes the output gap \( y_{t}^{(h)} \) to be nonmonotonic as soon as \( h \leq 1/3 \).\(^9\) Hence we have a number of cases where the precept of qualitative similarity of models with different period lengths is substantially violated.

These findings are stated as Observation 4, where we also add the obvious quantitative gaps between the quarterly and daily—and therefore weekly—economies (recall the remark above that the weekly and daily IRFs are quite close). This leads us to the conclusion of the quarterly model’s lack of robustness with respect to its decision interval, in the sense in which this concept was discussed in the Introduction.

\(^9\) The timing of the troughs is the same as before.
Observation 4

For $\pi_t^{(h)}$ in HPC($h$), and for $y_t^{(h)}$ in HIS($h$) and HMP($h$), Criterion QualS is not satisfied in that, after the impact effect, the impulse-response functions of the quarterly economy return monotonically to zero, whereas for the $h$-economies with $h \leq 1/3$ they exhibit a markedly nonmonotonic behaviour.

Furthermore, the model’s quarterly decision interval is not a robust period. That is, at least for weekly decision intervals and at least for the response of the output gap, Criterion QuantS is clearly violated.

At the end of this section we may once more return to the properties of the hybrid model when the period shrinks to zero. The implications from the results so far together with some formal arguments, which are given in the appendix, can be summarized by another observation.

Observation 5

The forward derivatives of $\pi$ at $t=0$ in HPC and HMP, and of $y$ in HIS and HMP, do
not exist. That is, the difference quotients \((\pi_h^{(h)} - \pi_0^{(h)})/h\) and \((y_h^{(h)} - y_0^{(h)})/h\) diverge as the period length \(h\) shrinks to zero. In addition, the corresponding second-period effects in the \(h\)-economies, \(\pi_h^{(h)}\) and \(y_h^{(h)}\), converge to finite values \(\tilde{\pi}\) and \(\tilde{y}\), respectively, where \(\tilde{\pi} < \pi_0^{(0)}\) and \(\tilde{y} < y_0^{(0)}\) with respect to the limits from Observation 3.

The nonexistence of the (backward and forward) time derivatives at \(t=0\) and the discontinuity that the sequences of the second-period values converge to different values from the limits of the impact effects means that Criterion \(CT\) for a transition to a continuous-time formulation is not perfectly satisfied. However, responsible for this is not necessarily the model as such but the sudden jump of the shock variable at \(t=0\). A smoother shock scenario in the \(h\)-economies, where, for example, the impulse is distributed over the entire first quarter, may well be able to avoid this kind of deficiency.\(^{10}\)

In particular, there might then also be good prospects for the assumption on the limits of the difference quotients in Observation 2 to be fulfilled, which would give rise to the differential equations (10) and (12). As a matter of fact, even in the present shock scenario the consecutive difference quotients become quite close after a short while if \(h\) is small enough. In the hourly economy, for example, the order of magnitude of \((\pi_{t+h}^{(h)} - \pi_t^{(h)})/h\) is 0.26 for some time after \(t = 0.015\) quarters, while the absolute differences between two consecutive quotients are already as small as 0.000086 and lower; similarly so for the output gap, where \((y_{t+h}^{(h)} - y_t^{(h)})/h \approx 0.14\) at that time and the differences are less than 0.000065.

We can conclude from these remarks and the previous observations that Criterion \(CT\) may not be seriously incriminated. What nevertheless remains is Observation 4, that is, the failure of the model to meet the qualitative and partly also the quantitative consistency criterion, if the original quarterly decision interval is taken as the base period. The conclusion from this observation is that, at least for the present parameter scenario, the model and its generic dynamic properties should rather be discussed on the basis of a daily or weekly decision interval. Alternatively, as alluded to in the Introduction, the length of the decision interval should be an integral part of attempts to calibrate or estimate the model.

5. A comparison of quarterly and monthly economies

It was apparent from the diagrams in Section 4 that at least for the variables with a corresponding hybrid model component, the deviations of the daily (weekly) from the quarterly economies are by no means negligible. Both Criterion \(QualS\) and Criterion \(QuantS\) are clearly violated. We summarized that therefore, for the present parameter

\(^{10}\)In general, on the other hand, it depends on the specific kind of shock(s) considered whether such a supposition would make economic sense.
scenario, the quarter is not a robust period and tentatively indicated that a day or a week would be much more appropriate in this respect.

The present section initiates a more extensive examination of Criterion QuantS, which would be necessary for more definite statements. Its perspective will, however, be more conservative in that we confine our interest to the quantitative differences between the impulse-response functions from the quarterly and monthly economies. If they are found to be displeasingly large across a certain range of relevant parameters, we have a firm basis to conclude that a quarterly decision interval of the agents yields misleading results in some of the IRFs.

More specifically, a month would at least be shown to be a better candidate for a robust period than a quarter. It could then, in a next step, be decided whether a base period of a month, which is still in the range of (a subset of) available data, would also be preferred to a weekly decision interval—which possibly would better serve as a robust period but might be regarded as “implausibly” low. In this situation, a monthly decision interval could represent some sort of compromise.\footnote{Nevertheless, Aadland (2001) shows the superiority of a weekly over a monthly decision interval in his calibration of a standard real business cycle model. Hence a week may not be dismissed altogether.}

For a better evaluation of the results across different model versions or across different parameters, the deviations of the monthly from the quarterly economy are measured in percentage terms. Accordingly, we compute the expressions

\[ d_t := 100 \cdot \frac{|x_t^{(h)} - x_t^{(1)}|}{x_t^{(1)}}, \quad h = 1/3, \quad x = \pi, y \]  

For the non-hybrid cases, the deviations \( d_t \) on impact, at \( t=0 \), and at the quarter \( t=1 \) are studied. For the variables associated with a hybrid Phillips curve or IS equation, which imply a nonmonotonic IRF, we have an additional look at the deviations in the second month, at \( t=1/3 \). At least for the output gap this is a conservative statistic since, as seen from Figures 1 and 2, it takes another month until \( y_t^{(1/3)} \) reaches its trough (while the quarterly IRF is already on the rise). Concerning the quarterly series at \( t=1/3 \), the corresponding convex combination is used to enter (13), which is given by \( x_t^{(1)} := (1-t)x_0^{(1)} + tx_1^{(1)} \).

To begin with the benchmark parameter scenario, Table 2 reports the deviations (13) that result from the IRFs in Figures 1 and 2, i.e., they quantify the gap between the bold and dotted lines. The table points out that not all of these gaps are negligible. There are in fact several instances where they are wider than, say, 25%. The deviations of more than 50% are in bold type because we think they could no longer be disregarded as being “not too serious”. These notable cases are obtained for the output gap, while the gaps in the inflation rate are less dramatic (except perhaps for the intermediate period in the fully hybrid model). It is also remarkable that the serious deviations of the output gap

\footnote{Nevertheless, Aadland (2001) shows the superiority of a weekly over a monthly decision interval in his calibration of a standard real business cycle model. Hence a week may not be dismissed altogether.}
Table 2: Absolute percentage deviations $d_t$ of monthly from quarterly IRFs in the benchmark parameter scenario.

<table>
<thead>
<tr>
<th></th>
<th>NKB</th>
<th>HMP</th>
<th>HPC</th>
<th>HIS</th>
</tr>
</thead>
<tbody>
<tr>
<td>$t = 0$</td>
<td>34</td>
<td>4</td>
<td>15</td>
<td>15</td>
</tr>
<tr>
<td>$t = 1/3$</td>
<td>4</td>
<td>46</td>
<td>26</td>
<td>65</td>
</tr>
<tr>
<td>$t = 1$</td>
<td>55</td>
<td>63</td>
<td>76</td>
<td>75</td>
</tr>
</tbody>
</table>

occur in all four model variants; whether the Phillips curve or the IS equation is hybrid or not plays no major role for this.

Figure 3: Absolute percentage deviations $d_t$ of monthly from quarterly IRFs under variations of the price stickiness parameter $\theta$; in NKB and HMP.

The quantitative effects of different frequencies summarized in Table 2 are based on a given numerical parameter scenario. This raises the question of the robustness of these results. Here we content ourselves with concentrating on the Calvo price stickiness as one
central parameter. While $\theta \approx \frac{2}{3}$ is a generally accepted benchmark that is supported by several empirical studies (Gali et al., 2001, p. 1255; Christiano et al., 2005, p. 18; or Álvarez et al., 2006, p. 578), one can also find lower and higher degrees of stickiness in the literature. Fabiani et al. (2007, p. 41) analyze data from surveys of 11000 firms which were conducted by the national banks of 9 European countries. The median number of price changes per year in these different countries is equal to one, which implies $\theta \approx \frac{3}{4}$. By estimating a DSGE model with sticky prices and wages for the euro area with Bayesian techniques, Smets and Wouters (2003, p. 1144) obtain a much longer average duration of price contracts of two and a half years, or $\theta \approx \frac{9}{10}$. In contrast, from the data of the U.S. Bureau of Labor Statistics, Bils and Klenow (2004, p. 953) derive evidence for firms changing their price every two quarters or even less, according to which $\theta$ can become as low as $\frac{1}{2}$ and less.

![Figure 4](image)

**Figure 4:** Absolute percentage deviations $d_t$ of monthly from quarterly IRFs under variations of the price stickiness parameter $\theta$; in HPC and HIS.

This material gives us an idea of the range of price stickiness that a robustness check should cover, that is, $0.50 \leq \theta \leq 0.90$. Increasing the parameter in steps of 0.01 from the lower to the upper end of the interval, we compute for each of these values, and for $t = 0, 1/3, 1$, the same deviation statistics $d_t$ as in Table 2. Doing this for all of the
four model variants and plotting $d_t$ against $\theta$, the graphs presented in Figure 3 and 4 are obtained. The dotted vertical lines indicate the benchmark $\theta = 2/3$, which has been investigated above.\footnote{Additional results covering $d_t$ for $0 \leq t \leq 5$ are given in the appendix.}

The first result to observe is the monotonic relationship between $\theta$ and $d_t$. Except for $t=0$ for the inflation rate in NKB, the deviations diminish as the prices become stickier. For the IRFs of the output gap at $t=1$, on the other hand, the deviations increase well above 50% or even 100% when the prices become more and more flexible. The effects on the inflation rate are similar in kind but more limited in size.

A second remarkable outcome is that, if we focus on the bold (red) lines for the deviations at $t=1$, they are not very different across the variants NKB, HMP, HPC and HIS for either the output gap and the inflation rate. A side result is that the deviations in the impact effects are rather small (except for the lower price stickiness in the purely forward-looking case). The intermediate effects at $t=1/3$ can be stronger than $d_t$ for $t=1$, which is the case for the inflation rate, or they can be slightly weaker, which is seen in the output gap diagrams.

The minimum conclusion that can be drawn from the numerical sensitivity analysis is that, between the output gap IRFs at $t=1$ of the quarterly and monthly economies with a hybrid IS equation (and with or without a hybrid Phillips curve), there are substantial differences of more than 50%. This holds over the entire range of price stickiness considered, and the effects are severely aggravated as the prices become more flexible. If in addition the different shapes of these IRFs are taken into account, the results of the quarterly economies concerning the output gap must be evaluated as nonrepresentative.

6. Conclusion

Referring to a standard New-Keynesian model the Phillips curve and IS equation of which allow for a purely forward-looking and a hybrid version, this paper asked for the possible implications if one varies the length of the period, i.e., the agents’ decision interval. The question can be seen as reviving Foley’s (1975) long neglected methodological precept that the basic properties of a discrete-time model without a “natural period” should not depend on the length of the period.

Our interest concentrated on the impulse-response functions (IRFs) of a monetary policy shock. On the one hand, it was found that, if we abstract from the discontinuities arising from the impulse in the hybrid versions, the limit of the high-frequency economies as their period shrinks to zero is well-defined, thus satisfying Foley’s most fundamental requirement. At the lower frequencies, on the other hand, we provided evidence of marked qualitative differences. In the hybrid variants of the model with a monthly or shorter decision interval, the IRFs reinforce the impact reaction for a short while and only then
return to the steady state values. This produces a sharp spike in the solution path, which is not present in the quarterly model. Furthermore, even when limiting the investigation to a comparison of the quarterly and monthly economies, the quantitative gaps in the initial phase of the two IRFs are not negligible. In particular, as confirmed by a sensitivity analysis of *ceteris paribus* variations of the Calvo price stickiness parameter, stronger reactions of the monthly output gap by 50 per cent and more after the first quarter are by no means exceptional.

These results resuscitate the question, “which interval best represents agents’ decision-making process?” (Aadland, 2001, p. 291). One answer is more practically oriented: use calibration or estimation methods to find out if variations of the period length can improve the matching of certain empirical moments or the value of an objective function in general. However, research in this direction seems to be rare.\(^{13}\)

A theoretical answer returns to Foley’s principle and requires robustness of the period on which one decides to settle down. Accordingly, a period may be called robust if it is an upper-bound on the length of the decision intervals with, in our case, essentially similar IRFs. From this point of view, the main conclusion of the paper is that, in the present modelling framework, the conventional quarter cannot be claimed to be a robust period length. The more general message is that DSGE modelling may be more sensitive to the possible “pitfalls of timing misspecification” (to use the words of Christiano, 1985, p. 397).

**Appendix**

**Solution of NKB(\(h\))**

For easier reference, we first restate the subcase NKB(\(h\)) of system (4), (5) where the contemporaneous Taylor rule and, regarding the compatibility with (1), the observation \(\beta(1) = \lambda\) for \(h=1\) are understood:

\[
\pi_t = \beta(h) E_t[\pi_{t+h}] + h b(h) y_t
\]

\[
y_t = E_t[y_{t+h}] - (h/\sigma) (i_t - E_t[\pi_{t+h}] - \rho)
\]

\[
v_{t+h} = \alpha(h) v_t := [1 - h(1-\alpha)] v_t
\]

The solution formula can directly be taken over from Galí (2008, p. 51). Adjusting the notation correspondingly and recalling \(\alpha = \alpha(1), \beta = \beta(1)\), the solution for the quarterly economy reads here,

\[
\pi_t = -\beta(1) \Lambda v_t
\]

\(^{13}\) Christiano (1985) and Aadland (2001) may be recalled as the only two references that we know. Future estimations might also consider a differentiation of the decision intervals of households and firms.
Showing this for the case where \( z = 1 \) and 2, the two matrices appear to converge towards finite and nonzero matrices \( \Omega \), dividing the result by the output gap. Leading it by one period, subtracting one equation from the other and quantities might be an interesting result in itself.

Using \( 1 - \beta(h)\alpha(h) = h(1 + \rho - \alpha)/(1 + h\rho) \), the counterparts for \( C \) and \( \Lambda \) in the high-frequency economies become

\[
C = (\sigma/h) [1 - \alpha(h)] [1 - \beta(h)\alpha(h)] - \alpha(h) h b(h) \\
= h \{ \sigma (1 - \alpha) (1 + \rho - \alpha) / (1 + h\rho) - [1 - h(1 - \alpha)] b(h) \} \\
=: \ h \ c(h) \\
1/\Lambda(h) = h \{ c(h) + b(h) \phi_x + (1 + \rho - \alpha) \phi_y / (1 + h\rho) \} \\
=: \ h \ d(h)
\]

The solution of \( \text{NKB}(h) \) can thus be written as

\[
\pi_t^{(h)} = -h b(h) \Lambda(h) \upsilon_t^{(h)} = -[b(h) / d(h)] \upsilon_t^{(h)} \\
y_t^{(h)} = -[1 - \beta(h)\alpha(h)] \Lambda(h) \upsilon_t^{(h)} = -\{ (1 + \rho - \alpha) / [(1 + h\rho) d(h)] \} \upsilon_t^{(h)}
\]

Clearly, the expressions \( b(h) \) and \( c(h) \) tend to finite values as \( h \to 0 \). Limiting our interest to \( \phi_x \geq 1 \), it is also immediately seen that the sum \( c(h) + b(h) \phi_x \) in \( 1/\Lambda(h) \) exceeds \(-[1 - (1 - \alpha)] b(h) + b(h), which in turn is not less than zero for \( h \geq 0 \). This ensures that \( d(h) \) is positively bounded away from zero as \( h \) becomes infinitesimally small.\(^{14}\) Hence the functions \( f_x = f_x(h), f_y = f_y(h) \) have the properties stated in Observation 1.

Arguments underlying Observation 5

The reduced-form solutions of the \( h \)-economies are given by

\[
z_t^{(h)} = \Omega^{(h)} z_{t-h}^{(h)} + \Gamma^{(h)} \upsilon_t^{(h)}
\]

(14)

where \( z^{(h)} = (\pi_t^{(h)}, y_t^{(h)})', \Omega^{(h)} \in \mathbb{R}^{2 \times 2}, \Gamma^{(h)} \in \mathbb{R}^{2 \times 1} \). As can also be inferred from Figures 1 and 2, the two matrices appear to converge towards finite and nonzero matrices \( \Omega^o \), \( \Gamma^o \) as \( h \to 0 \) (with the exception of \( \Omega^{(h)} \equiv 0 \) in the baseline model). Incidentally, for \( h = 1/(24 \cdot 90) \) the transition matrix \( \Omega^{(h)} \) is close to a diagonal matrix (with entries of approximately 0.30 and 0.60 on the main diagonal). This decoupling of prices and quantities might be an interesting result in itself.

Equation (14) can be used to compute the forward difference quotients of inflation and the output gap. Leading it by one period, subtracting one equation from the other and dividing the result by \( h \) yields

\[
\frac{z_{t+h}^{(h)} - z_t^{(h)}}{h} = \Omega^{(h)} z_{t-h}^{(h)} + \Gamma^{(h)} \frac{\upsilon_{t+h}^{(h)} - \upsilon_t^{(h)}}{h}
\]

(15)

\(^{14}\) Showing this for the case \( \phi_x < 1 \), given that (7) is still satisfied, requires a little bit more effort.
Owing to $z^{(h)} = 0$, $v^{(h)}_0 = 0$ and $z^{(h)}_0 = \Gamma^{(h)} \varepsilon^v \rightarrow \Gamma^0 \varepsilon^v \neq 0$, the first difference quotient on the right-hand side of (15), when evaluated at $t = 0$, diverges as $h$ becomes small. Since $(v_{t+h}^{(h)} - v_t^{(h)})/h = -(1-\alpha) v_t^{(h)}$ is bounded, the limit of the left-hand side of this equation is not well-defined, either. By the same token, the second-period effects $z^{(h)}_h$ remain bounded away from the impact effects $z^{(h)}_0$. These features, then, allow us to formulate Observation 5.

**Deviations $d_t$ from eq. (13) across quarters $t$ and price stickiness $\theta$**

The surface of $d_t$ above the plane $0 \leq t \leq 5$ and $0.50 \leq \theta \leq 0.90$ is truncated at $d = 100\%$. A plateau at $d = 50\%$ indicates an upper-bound on deviations that might still be regarded as acceptable.
References


