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Monetary Policy and Multiple Equilibria*

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Abstract

In this paper, we characterize conditions under which interest rate feedback rules that set the nominal interest rate as an increasing function of the inflation rate induce aggregate instability by generating multiple equilibria. We show that these conditions depend not only on the monetary-fiscal regime (as emphasized in the fiscal theory of the price level) but also on the way in which money is assumed to enter preferences and technology. We provide a number of examples in which, contrary to what is commonly believed, active monetary policy in combination with a fiscal policy that preserves government solvency under all circumstances gives rise to multiple equilibria, and passive monetary policy renders the equilibrium unique. Our general conclusion holds in flexible- and sticky-price environments as well as under backward- or forward-looking interest rate feedback rules.

JEL Classification Numbers: E52, E31, E63.

Keywords: Interest rate feedback rules, multiple equilibria, sticky prices.

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1 Introduction

Recent developments in monetary economics have emphasized the link between the degree to which monetary and fiscal policies respond to endogenous variables such as the inflation rate or the stock of public debt and macroeconomic stability.\(^1\) Perhaps the best-known result in this literature is that if fiscal solvency is preserved under all circumstances, then an active monetary policy, that is, a policy that aggressively fights inflation by raising the nominal interest rate by more than the increase in inflation, stabilizes the real side of the economy by ensuring the uniqueness of equilibrium. At the same time, a passive monetary policy, that is, a policy that underreacts to inflation by raising the nominal interest rate by less than the observed increase in inflation, destabilizes the economy by giving rise to expectations-driven fluctuations.

In this paper, we argue that whether a particular monetary-fiscal regime is conducive to macroeconomic stability in the sense given above depends crucially on the way in which money is assumed to enter preferences and technology. One important point of departure of our theoretical framework from the one used in the recent related literature is our emphasis on the role that the demand for money by firms plays in the monetary transmission mechanism. Specifically, we follow Calvo (1979) in assuming that money affects not only preferences but also production possibilities. Introducing a demand for money by firms is motivated by the fact that in industrialized countries firms hold a substantial fraction of the money supply. For example, in the United States, nonfinancial firms held at least 50 percent more demand deposits than households over the period 1970-1990 (see Mulligan, 1997, and the references cited therein). Given this empirical regularity, it is surprising that recent theoretical evaluations of monetary policy rules have restricted attention to the case in which variations in the nominal interest rate affect real variables solely through their effect on aggregate demand.

Our main finding is that regardless of the stance of fiscal policy, an active monetary policy does not necessarily bring about the determinacy of equilibrium. In the context of a flexible-price, money-in-the-utility-function model, we show that the standard result, i.e., equilibrium is unique under active monetary policy, holds in an endowment economy in which consumption and real balances are Edgeworth-complements in preferences in the sense that the marginal utility of consumption is increasing in real balances. However, the opposite result, i.e., uniqueness of the equilibrium occurs under passive monetary policy and multiplicity of equilibria occurs under active monetary policy, obtains if consumption and real balances are Edgeworth-substitutes. More importantly, the opposite result also obtains in an economy in which money enters in the production function even if real balances and consumption are Edgeworth-complements in preferences. This result is of particular interest for it highlights the fact that the usual implicit assumption that firms’ costs of production are unaffected by variations in the nominal interest rate is not inconsequential for the stabilizing properties of alternative interest-rate feedback rules.

In the literature that stresses the desirability of active interest-rate feedback rules, the need for monetary stabilization policy typically arises because of short-run nominal price rigidities. Therefore, we also analyze economies with sluggish price adjustment. Specifically, we study the role of interest-rate feedback rules for aggregate stability in the Rotemberg (1982) model with convex cost of price adjustment and in the Calvo (1983) and Yun (1996) model of staggered price setting. We show that, as in the flexible-price case, when money enters in the production function, active monetary policy may render the equilibrium indeterminate regardless of the stance of fiscal policy. A further novel result that emerges from the analysis of sticky-price models in which productivity is affected by the cost of funds is that restricting the evaluation of interest rate rules to their con-

sequences for local stability might be misleading. In particular, we find that an active monetary policy stance may appear to be stabilizing because it ensures the uniqueness of equilibrium locally, when in fact it is destabilizing because it gives rise to equilibria in which the economy converges to a cycle.

In our baseline analysis, we assume that the policymaker sets the nominal interest rate as a function of an instantaneous rate of inflation. This is clearly not a practical proposal since instantaneous measures of inflation do not exist. Consequently, any practical inflation measure to which the central bank responds must involve some average of past inflation rates or forecasts of expected future rates of inflation, or both. For example, Taylor’s (1993) characterization of recent U.S. monetary policy assumes that the Federal Reserve’s operating target for the federal funds rate is a function of average inflation over the previous four quarters. Other authors have argued that actual Federal Reserve policy is best described by a forward-looking interest-rate feedback rule (Clark, Galí, and Gertler, 1997). The use of medium-term forecasts of inflation, rather than past inflation, has also been suggested as the ideal intermediate variable for an inflation targeting regime on theoretical grounds (Svensson, 1997; 1998). For these reasons, we extend the baseline analysis to allow for feedback rules in which the interest rate depends on past or expected future rates of inflation. We find that our main argument is robust to this extension: even in the presence of backward- or forward-looking components in monetary policy, the deep structural parameters defining preferences and technologies play a crucial role in determining whether a particular monetary-fiscal regime is stabilizing or not.

The remainder of the paper is organized in four sections. Section 2 studies the macroeconomic effects of interest-rate feedback rules in a flexible-price economy. Section 3 extends the analysis to an economy with slow adjustment of product prices. Section 4 investigates the robustness of the results to the introduction of backward- and forward-looking elements in the intermediate target, and section 5 concludes.

2 A flexible-price model

In this section, we study the determinacy of equilibrium under alternative monetary and fiscal policies in a flexible-price model. Our modeling approach differs from the one used in the more recent related literature in that we assume that money facilitates firms’ production as in Calvo (1979). We depart from Calvo’s analysis by considering different monetary-fiscal regimes. Calvo focuses on monetary policies whereby the central bank pegs either the money growth rate or the inflation rate in combination with a fiscal policy that specifies zero public debt at all times implying full monetization of primary deficits. By contrast, as will be explained in detail shortly, we analyze interest rate feedback rules in combination with fiscal policies in which the real primary surplus is either constant or proportional to the stock of real government liabilities.²

2.1 The economic environment

2.1.1 Households

The household’s lifetime utility function is given by

$$U = \int_0^{\infty} e^{-rt} u(c, m^{np}) dt$$

²Taylor (1977) is another example of a study of price level determination in a model with money in the production function. The two main differences between our analysis and Taylor’s is that his model does not allow for optimizing behavior on the part of households and firms and that, like Calvo, he considers different monetary policy regimes.
where $r > 0$ denotes the rate of time preference, $c$ consumption, $m^{np} \equiv M^{np}/P$ real balances held for non-production purposes, $M^{np}$ nominal money balances held for non-production purposes, and $P$ the nominal price level. The instant utility function $u(\cdot, \cdot)$ satisfies Assumption 1, which implies that $c$ and $m^{np}$ are normal goods.

**Assumption 1** $u(\cdot, \cdot)$ is strictly increasing and strictly concave, and satisfies $u_{cc} - u_{cm} u_c / u_m < 0$ and $u_{mm} - u_{cm} u_m / u_c < 0$.

We consider two alternative production technologies: (1) output is produced with real balances held by the household for production purposes, $m^p \equiv M^p / P$, where $M^p$ denotes nominal money balances held for production purposes, and (2) output is equal to a positive constant. Formally, the production technology, $y(m^p)$, satisfies either Assumption 2 or Assumption 2'.

**Assumption 2** $y(m^p)$ is positive, strictly increasing, strictly concave, and satisfies

$$\lim_{m^p \to 0} y'(m^p) = \infty, \quad \text{and} \quad \lim_{m^p \to \infty} y'(m^p) = 0.$$

**Assumption 2'** $y(m^p)$ is a positive constant.

In addition to money, the household can hold nominal bonds, $B$, which pay the nominal interest rate $R > 0$. Letting $a(\equiv (M^{np} + M^p + B)/P$ denote the household’s real financial wealth, $\tau$ real lump-sum taxes, and $\pi \equiv \dot{P}/P$ the inflation rate, the household’s instant budget constraint can be written as

$$\dot{a} = (R - \pi)a - R(m^{np} + m^p) + y(m^p) - c - \tau. \quad (2)$$

The household chooses sequences for $c$, $m^{np}$, $m^p \geq 0$ and $a$ so as to maximize (1) subject to (2) and the following no-Ponzi-game condition

$$\lim_{t \to \infty} e^{-\int_0^t R(s) - \pi(s) ds} a(t) \geq 0, \quad (3)$$

taking as given $a(0)$ and the time paths of $\tau$, $R$, and $\pi$. The optimality conditions associated with the household’s problem are

$$u_c(c, m^{np}) = \lambda \quad (4)$$

$$m^p [y'(m^p) - R] = 0 \quad (5)$$

$$\frac{u_m(c, m^{np})}{u_c(c, m^{np})} = R \quad (6)$$

$$\lambda (r + \pi - R) = \dot{\lambda} \quad (7)$$

$$\lim_{t \to \infty} e^{-\int_0^t R(s) - \pi(s) ds} a(t) = 0 \quad (8)$$

where $\lambda$ is the Lagrange multiplier associated with the household’s instant budget constraint. Assumption 2 together with equation (5) and $R > 0$ implies that $m^p$ is a strictly decreasing function of $R$:

$$m^p = m^p(R), \quad (9)$$

with $m^{p'} \equiv dm^p/dR < 0$. Alternatively, Assumption 2', equation (5), and the fact that $R > 0$ imply that $m^p = m^{p'} = 0$. Using equation (6) and Assumption 1, $m^{np}$ can be expressed as a function of consumption and the nominal interest rate that is increasing in $c$ and decreasing in $R$:

$$m^{np} = m^{np}(c, R). \quad (10)$$
2.1.2 The government

We assume that monetary policy takes the form of an interest rate feedback rule whereby the nominal interest rate is set as an increasing function of the inflation rate. Specifically, we assume that

\[ R = \rho(\pi), \]  

(11)

where \( \rho(\cdot) \) is continuous, non-decreasing, and strictly positive and there exists at least one \( \pi^* > -r \) such that \( \rho(\pi^*) = r + \pi^* \). Following Leeper (1991), we refer to monetary policy as active if \( \rho' > 1 \) and as passive if \( \rho' < 1 \).

Government purchases are assumed to be zero at all times. Then, the sequential budget constraint of the government is given by

\[ \dot{B} = R B - \dot{M}^p - \dot{M}^p - P \tau, \]

which can be written as

\[ \dot{a} = (R - \pi)a - R(m^{np} + m^p) - \tau. \]  

(12)

Because the nominal value of initial government liabilities, \( A(0) \), is predetermined, the initial condition \( a(0) \) must satisfy

\[ a(0) = \frac{A(0)}{P(0)}. \]  

(13)

We classify fiscal policies into two categories: Ricardian fiscal policies and non-Ricardian ones. Ricardian fiscal policies are those that ensure that the present discounted value of total government liabilities converges to zero—that is, equation (8) is satisfied—under all possible, equilibrium or off-equilibrium, paths of endogenous variables such as the price level, the money supply, inflation, or the nominal interest rate. Our definition of Ricardian fiscal policy is different from the one given in Woodford (1995). In the first place, Woodford uses the term Ricardian to refer to monetary-fiscal regimes rather than to fiscal regimes alone. Second, according to Woodford, Ricardian regimes are combinations of monetary and fiscal policies that ensure that the present discounted value of public debt, not total government liabilities, converges to zero. Thus, for example, a balanced-budget rule in combination with a positive interest rate peg is Ricardian according to our definition but not according to Woodford’s (see Schmitt-Grohé and Uribe, 1999). Also, Ricardian fiscal policies that are Ricardian according to our definition are not necessarily passive in the sense of Leeper (1991) because they do not guarantee that the real value of public debt remains bounded.

Throughout the paper, we restrict attention to one particular Ricardian fiscal policy that takes the form

\[ \tau + R(m^{np} + m^p) = \alpha a \]

(14)

where the sequence \( \alpha \) is chosen arbitrarily by the government subject to the constraint that it is positive and bounded below by \( \underline{\alpha} > 0 \). This policy states that consolidated government revenues, that is, tax revenues plus interest savings from the issuance of money, are always higher than a certain fraction \( \underline{\alpha} \) of total government liabilities. A special case of this type of policy is a balanced-budget rule whereby tax revenues are equal to interest payments on the debt, which results when \( \alpha = R \) (provided \( R \) is bounded away from zero). To see that the fiscal policy given by (14) is Ricardian, let \( d \equiv \exp[- \int_0^t (R - \pi) ds] \) and \( x \equiv da \). The definition of a Ricardian fiscal policy requires that \( x \to 0 \) as \( t \to \infty \). Note that \( \dot{x} = d [\dot{a} - (R - \pi)a] \). Using equations (12) and (14), this expression can be written as \( \dot{x} = -\alpha x \), which implies that \( x \) converges monotonically to zero.

We will also analyze a particular non-Ricardian fiscal policy consisting of an exogenous path for lump-sum taxes

\[ \tau = \bar{\tau} > 0. \]  

(15)
2.1.3 Equilibrium

In equilibrium the goods market must clear

\[ c = y(m^P). \]  

(16)

Using equations (9)–(11) and (16) to replace \( m^P, m^{np}, R, \) and \( c \) in equation (4), \( \lambda \) can be expressed as a function of \( \pi \),

\[ \lambda = \lambda(\pi) \]  

(17)

with

\[ \lambda'(\pi) = \rho' [u_{cc} y' y' + u_{cm}(m^{np} y' y' + m^{np})] \]  

(18)

where \( m^{np}_c \) and \( m^{np}_R \) denote the partial derivatives of \( m^{np} \) with respect to \( c \) and \( R \), respectively. Using this expression, (9)–(11), and (16), equations (7), (8), (12), and (14) can be rewritten as

\[ \lambda'(\pi) \hat{\pi} = \lambda(\pi) [r + \pi - \rho(\pi)] \]  

(19)

\[ \dot{\hat{a}} = [\rho(\pi) - \pi]a - \rho(\pi) [m^{np} (y(m^P(\rho(\pi))), \rho(\pi)) + m^P(\rho(\pi))] - \tau \]  

(20)

\[ \lim_{t \to \infty} e^{-\int_0^t (\rho(\sigma) - \pi(\sigma))d\sigma} a(t) = 0 \]  

(21)

\[ \tau + \rho(\pi)[m^{np}(y(m^P(\rho(\pi))), \rho(\pi)) + m^P(\rho(\pi))] = \alpha a \]  

(22)

**Definition 1** (Perfect-foresight equilibrium in the flexible-price economy) In the flexible-price economy, a perfect-foresight equilibrium is a set of sequences \( \{\pi, a, \tau\} \) and an initial price level \( P(0) > 0 \) satisfying (13), (19)–(21) and either (15) if fiscal policy is non-Ricardian or (22) if fiscal policy is Ricardian, given \( A(0) > 0 \).

Given an equilibrium sequence for \( \pi \), equations (9)–(11), (16), and (17) uniquely determine the equilibrium sequences \( \{c, m^{np}, m^P, \lambda, R\} \).

2.2 Determinacy of equilibrium under alternative monetary-fiscal regimes

In the remainder of this section, we restrict the analysis to equilibria in which the inflation rate converges asymptotically to a steady-state value, \( \pi^* \), which is defined as a constant value of \( \pi \) that solves (19), that is, a solution to \( r + \pi = \rho(\pi) \). By assumption, \( \pi^* \) exists and is greater than \( -r \).

It is clear from equations (9)–(11) and (16) that if the equilibrium time path of inflation is unique, then so is the equilibrium real allocation \( \{c, m^{np}, m^P\} \) independently of whether the equilibrium price level is unique. Thus, it is useful to introduce the following terminology:

**Definition 2** (Real and Nominal Indeterminacy) The equilibrium displays real indeterminacy if there exists an infinite number of equilibrium sequences \( \{\pi\} \). The equilibrium exhibits nominal indeterminacy if for any equilibrium sequence \( \{\pi\} \), there exists an infinite number of initial price levels \( P(0) > 0 \) consistent with a perfect-foresight equilibrium.
Under a Ricardian fiscal policy, the set of equilibrium conditions includes equation (22). Given a sequence \( \{ \pi \} \) satisfying (19) and an arbitrary initial price level \( P(0) > 0 \), equations (13), (20) and (22) can be used to construct a pair of sequences \( \{ a, \tau \} \). Because the fiscal policy is Ricardian, the transversality condition (21) is always satisfied. Therefore, under a Ricardian fiscal policy the price level is always indeterminate. If instead the fiscal authority follows the non-Ricardian fiscal policy given in (15), combining (13), (20), and (21) yields

\[
\frac{A(0)}{P(0)} = \int_{0}^{\infty} e^{-\int_{0}^{s} \rho(\pi) - \pi ds} \left\{ \rho(\pi) [m^{np}(y(m^{p}(\rho(\pi))), \rho(\pi)) + m^{p}(\rho(\pi))] + \tau \right\} ds
\]

which given \( A(0) > 0 \) and a sequence for \( \pi \) converging to \( \pi^* \) uniquely determines the initial price level \( P(0) \).

The above analysis demonstrates that for the class of monetary-fiscal regimes studied in this paper nominal determinacy depends only on fiscal policy and not on monetary policy—a result that has been emphasized in the recent literature on the fiscal determination of the price level and that we summarize in the following proposition:

**Proposition 2.1** If fiscal policy is Ricardian, the equilibrium exhibits nominal indeterminacy. Under the non-Ricardian fiscal policy given by (15), the equilibrium displays nominal determinacy.

By contrast, the determinacy of the real allocation is independent of fiscal policy but depends on the stance of monetary policy and on the particular way in which inflation affects production and consumption. To see this, consider solutions to equation (19). If \( \lambda'(\pi^*) \) and \( 1 - \rho'(\pi^*) \) are of opposite sign, any initial inflation rate near the steady state \( \pi^* \) will give rise to an inflation trajectory that converges to \( \pi^* \). If, on the other hand, \( \lambda'(\pi^*) \) and \( 1 - \rho'(\pi^*) \) are of the same sign, the only sequence of inflation rates that converges asymptotically to \( \pi^* \) is one in which the inflation rate is constant and equal to \( \pi^* \). If \( \rho'(\pi) = 0 \) for all \( \pi \), then equations (18) and (19) imply that \( \lambda \) and \( \pi \) are constant. Thus, under a pure interest rate peg the economy exhibits real determinacy.

To understand the conditions under which the model displays real indeterminacy, it is instructive to consider the following two polar cases. Consider first the case in which preferences are separable in consumption and money (\( u_{cm} = 0 \)) and money is productive (Assumption 2 holds). In this case, equation (18) implies that \( \lambda' = \rho' u_{cc} y^{m^{pl}} > 0 \), so that the model displays real indeterminacy if \( 1 - \rho'(\pi^*) < 0 \), that is, if monetary policy is active, and is unique if \( 1 - \rho'(\pi^*) > 0 \), that is, if monetary policy is passive. The intuition behind this result is as follows. Suppose firms initially hold more real balances for production purposes than in the steady state. This will happen only if the nominal interest rate is below its steady-state level. By the interest rate feedback rule, the inflation rate has to be below its steady-state value as well. If monetary policy is active, the decline in the inflation rate is accompanied by a decline in the real interest rate, \( R - \pi \), which in turn induces negative consumption growth. Since in equilibrium consumption equals output, and output is an increasing function of real balances, real balances for production purposes will be expected to decline. Therefore, the initial increase in real balances is reversed and the resulting trajectory is consistent with equilibrium. If, on the other hand, monetary policy is passive, the decline in the inflation rate is associated with a rise in the real interest rate, and thus consumption will be expected to grow, moving output and real balances even further away from the steady state. Such a trajectory for real balances would not be remain bounded in a neighborhood around the steady state and thus would not be consistent with an equilibrium in which inflation converges to \( \pi^* \). This result is summarized in the following proposition:

**Proposition 2.2** Suppose preferences are separable in consumption and money (\( u_{cm} = 0 \)) and money is productive (Assumption 2 holds), then if monetary policy is active (\( \rho'(\pi^*) > 1 \), the
equilibrium displays real indeterminacy, whereas if monetary policy is passive \( (\rho'(\pi^*) < 1) \), then the only perfect-foresight equilibrium in which the real allocation converges to the steady state is the steady state itself.

Consider now the case in which money is not productive, that is, Assumption 2 holds. In this case, equation (18) implies that \( \lambda' = \rho' u_{cm} m_{np}^R \) which is positive if \( u_{cm} < 0 \), that is, if consumption and money are Edgeworth-substitutes, and is negative if \( u_{cm} > 0 \), that is, if consumption and money are complements. Thus the economy displays real indeterminacy if monetary policy is active and consumption and money are substitutes or if monetary policy is passive and consumption and money are complements.\(^3\) The intuition behind this indeterminacy result is as follows. Consider the case that monetary policy is passive and \( u_{cm} > 0 \). Suppose that real balances for non-productive purposes are increased above their steady-state level. Because the money demand function of the household is decreasing in the nominal interest rate and consumption is constant, it follows that the nominal interest rate has to be below its steady-state level. At the same time, passive monetary policy implies that the decline in the nominal interest rate is associated with an increase in the real interest rate. In response to the increase in the real interest rate agents will lower the growth rate of the marginal utility of consumption. With consumption constant and \( u_{cm} > 0 \), this requires that the growth rate of real balances be negative. Thus real balances will return to their steady level and this trajectory is consistent with equilibrium. The next two propositions summarize these results.

**Proposition 2.3** Suppose that money is not productive (Assumption 2 holds) and consumption and money are Edgeworth-substitutes \( (u_{cm} < 0) \). Then, if monetary policy is active \( (\rho'(\pi^*) > 1) \), the real allocation is indeterminate, and if monetary policy is passive \( (\rho'(\pi^*) < 1) \), then the only perfect-foresight equilibrium in which the real allocation converges to the steady state is the steady state itself.

**Proposition 2.4** Suppose that money is not productive (Assumption 2 holds) and consumption and money are Edgeworth-complements \( (u_{cm} > 0) \). Then, if monetary policy is passive \( (\rho'(\pi^*) < 1) \), the real allocation is indeterminate, and if monetary policy is active \( (\rho'(\pi^*) > 1) \), then the only perfect-foresight equilibrium in which the real allocation converges to the steady state is the steady state itself.

<table>
<thead>
<tr>
<th>Monetary Policy</th>
<th>Non-productive money ( (y' = 0) )</th>
<th>Productive money ( (y' &gt; 0) )</th>
</tr>
</thead>
<tbody>
<tr>
<td>( u_{cm} &gt; 0 )</td>
<td>( u_{cm} &lt; 0 ) ( u_{cm} = 0 )</td>
<td>( u_{cm} &gt; 0 ) ( u_{cm} &lt; 0 ) ( u_{cm} = 0 )</td>
</tr>
<tr>
<td>Passive ( (\rho'(\pi^*) &lt; 1) )</td>
<td>I</td>
<td>D</td>
</tr>
<tr>
<td>Active ( (\rho'(\pi^*) &gt; 1) )</td>
<td>D</td>
<td>I</td>
</tr>
</tbody>
</table>

Note: The notation is: D, determinate; I, indeterminate; A, ambiguous. (Under A the real allocation may be determinate or indeterminate depending on specific parameter values.)

\(^3\)As is well-known, there exists an exact correspondence between the equilibrium conditions of the economy with \( y' = 0 \) and \( u_{cm} > 0 \) and those of the cash-in-advance economy with cash and credit goods developed by Lucas and Stokey (1987). Therefore, in the (continuous-time version of the) Lucas–Stokey model, the real allocation is indeterminate under passive monetary policy.
Table 1 summarizes the combinations of preference, technology, and monetary policy specifications under which real indeterminacy arises in the flexible-price model. The second row of the table highlights the main result of this section, namely, that, contrary to what is often asserted, real indeterminacy may arise under active monetary policy. Most existing studies restrict attention to the case in which money is not productive ($y' = 0$) and money and consumption either are complements in preferences or enter the utility function in a separable fashion ($u_{cm} \geq 0$). As a result, these studies have arrived at the potentially misleading conclusion that an active monetary policy stabilizes the economy by bringing about real determinacy.

An assumption of our analysis is that in setting the nominal interest rate the central bank responds to an instantaneous measure of inflation. This assumption is clearly unrealistic for such a measure of inflation does not exist in practice. In section 4, we try to capture the notion that a realistic measure of the inflation rate to which the central bank responds involves some degree of time-averaging by assuming that the policy instrument is a function of a geometric average of all past inflation rates.

Before closing this subsection, we wish to point out that there are additional reasons to those spelled out here, why the results on local uniqueness under active monetary policy should be interpreted with caution. For if there exists a steady state $\pi^*$ with $\rho'(\pi^*) > 1$, then since $\rho(\cdot)$ is assumed to be non-decreasing and strictly positive, there must also exist a steady state with $\rho'(\cdot) < 1$, which is indeterminate precisely under the assumptions that assure local determinacy at the steady state $\pi^*$. Benhabib, Schmitt-Grohé, and Uribe (1999) demonstrate the existence of equilibrium paths connecting these two steady states.

2.3 Comparison with discrete-time models

Preference and technology specifications also play an important role in determining whether active interest rate feedback rules are stabilizing in discrete-time models. In making a sensible comparison between discrete- and continuous-time models two key aspects should be taken into account. First, in discrete-time models the current rate of inflation, $\pi_t$, is given by the change in the price level between periods $t-1$ and $t$, whereas in continuous-time specifications, $\pi_t$ is the instantaneous rate of inflation given by the right-hand side derivative of the price level. Therefore, the discrete-time counterpart of the instantaneous rate of inflation is better approximated by the change in the price level between periods $t$ and $t+1$ than by the change in the price level between periods $t-1$ and $t$. Second, the reduced form of the equilibrium conditions of a given model may differ depending on whether the model is laid out in discrete or continuous time.

Consider, for example, the case of non-productive money (Assumption 2') in combination with preferences that are separable in consumption and real balances ($u_{cm} = 0$). This specification of preferences and technology is the one analyzed in Leeper (1991). In the continuous-time model analyzed here, such a specification implies by equation (18) that $\lambda$ is constant. It then follows that $\pi_t$, $R_t$, and $m^{np}$ are also constant, and the only equilibrium real allocation is the steady state. This result differs from that obtained by Leeper who finds that under passive monetary policy the inflation rate is indeterminate. The difference stems from the fact that in Leeper’s discrete-time model the nominal interest rate in period $t$ is assumed to be a function of the change in the price level between periods $t-1$ and $t$, which as pointed out above is not the correct approximation of the instantaneous rate of inflation in a continuous-time setting. In fact, if in Leeper’s discrete-time model the feedback rule is assumed to be forward looking—that is, $R_t = \rho(P_{t+1}/P_t)$—the equilibrium displays real determinacy. To see this, consider the log-linearized version of the equilibrium conditions of a
discrete-time endowment economy with money in the utility function

\[ \rho_{cm}(\tilde{m}_t - \tilde{m}_{t+1}) = \tilde{R}_t - \tilde{\pi}_{t+1} \]
\[ \tilde{m}_t = -\epsilon_m R_{t} \tilde{R}_t \]
\[ \tilde{R}_t = \epsilon_R \tilde{\pi}_{t+1} \]

where \( \tilde{m}_t \) is the log-deviation of real balances from steady state and \( \tilde{R}_t \) and \( \tilde{\pi}_t \) are the deviations of the nominal interest rate and inflation from steady-state. The first equation represents an Euler equation, where we used the fact that consumption is constant over time and let \( \rho_{cm} \) denote the elasticity of the marginal utility of consumption with respect to real balances. The second equation is the liquidity preference function with \( \epsilon_m > 0 \) denoting the interest elasticity of money demand. The third equation is the interest rate feedback rule, where \( \epsilon_R \) denotes the elasticity of the feedback rule with respect to the intermediate target, \( \pi_{t+1} \). When preferences are separable in consumption and real balances—the preference specification considered in Leeper (1991)—then \( \rho_{cm} = 0 \) and the above three expressions collapse to \( 0 = (\epsilon_R - 1)\tilde{\pi}_{t+1} \), which implies that \( \pi_t = \pi^* \) for all \( t > 0 \), provided that \( \epsilon_R \) is not exactly unity. It follows that the nominal interest rate as well as real balances are uniquely determined (and in fact constant). However, because \( \pi_0 \) is not pinned down, the model displays nominal indeterminacy unless fiscal policy is non-Ricardian. These results are identical to those obtained in the previous subsection under continuous time.

When preferences are non-separable in consumption and real balances (\( \rho_{cm} \neq 0 \)), the above three equations can be reduced to the following first-order difference equation in inflation

\[ \tilde{\pi}_{t+2} = \left[ 1 + \frac{\epsilon_R - 1}{\epsilon_R \rho_{cm} \epsilon_m R} \right] \tilde{\pi}_{t+1}. \]

If consumption and real balances are Edgeworth complements (\( \rho_{cm} > 0 \)), the equilibrium is determinate when monetary policy is active (\( \epsilon_R > 1 \)) and is indeterminate when monetary policy is passive but not too irresponsive to inflation (\( 1 > \epsilon_R > 1/(1 + 2 \rho_{cm} \epsilon_m R) \)). If consumption and real balances are Edgeworth substitutes (\( \rho_{cm} < 0 \)), the equilibrium is determinate when monetary policy is passive and is indeterminate when monetary policy is active. If \( 0 < -\rho_{cm} \epsilon_m R < 1/2 \), a condition that arises at low degrees of substitututability between consumption and real balances and/or at a low interest elasticity of money demand, the equilibrium becomes determinate for relatively highly active feedback rules. Specifically, this change in the stability properties of the equilibrium system takes place when the elasticity of the feedback rule with respect to inflation exceeds the critical value \( \overline{\epsilon}_R \equiv 1/(1 + 2 \rho_{cm} \epsilon_m R) > 1 \). Although in this case the real allocation is locally unique, real instability may still be present due to the emergence of attracting 2-period cycles.\(^4\) This example illustrates that in the discrete-time model, as in the continuous-time model, small perturbations of the specification of preferences around \( u_{cm} = 0 \)—the case typically studied in the related literature—can reverse the stability properties of a given interest rate feedback rule.

Finally, we wish to show that in discrete-time models, as in continuous-time specifications, small perturbations in the elasticity of output with respect to the nominal interest rate around zero can fundamentally alter the stabilizing properties of a particular interest rate feedback rule. Specifically, consider a discrete-time environment in which money is productive (Assumption 2 holds) and preferences are separable in consumption and real balances (\( u_{cm} = 0 \)). In this case, the

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\(^4\)The possibility of 2-period cycles arises because at \( \epsilon_R = \overline{\epsilon}_R \), the system displays a flip bifurcation. For certain parameter specifications the cycles appear for \( \epsilon_R > \overline{\epsilon}_R \) and are therefore attracting (see Guckenheimer and Holmes, 1983, chapter 3).
log-linearized equilibrium conditions consist of the following two equations:

\[
\rho_{cc}(\hat{y}_{t+1} - \hat{y}_t) = \epsilon_{R} \hat{\pi}_{t+1} - \hat{\pi}_{t+1}
\]

\[
\hat{y}_t = -\epsilon_{yR} \epsilon_{\rho} \hat{\pi}_{t+1}
\]

where \(\rho_{cc} > 0\) is the elasticity of the marginal utility of consumption, \(\epsilon_{yR} \geq 0\) is the elasticity of output with respect to the nominal interest rate and where \(\hat{y}_t\) denotes the log-deviation of output from steady state. The first expression is a standard Euler equation and the second represents the reduced form production function describing a negative relationship between output and expected inflation. Combining the two log-linearized equilibrium conditions we obtain the following first-order difference equation

\[
\hat{\pi}_{t+2} = \left[1 + \frac{1 - \epsilon_{\rho}}{\rho_{cc} \epsilon_{yR} \epsilon_{\rho}}\right] \hat{\pi}_{t+1}.
\]

If money is productive \((\epsilon_{yR} > 0)\), then a monetary policy stance that is neither passive nor active \((\epsilon_{\rho} = 1)\) represents a bifurcation point of the system. For \(\epsilon_{\rho} < 1\), that is, when monetary policy is passive, the coefficient on \(\hat{\pi}_{t+1}\) is greater than one, and therefore, the difference equation is unstable. This implies that the only perfect-foresight equilibrium that converges asymptotically to the steady state \(\pi^*\) is \(\pi_t = \pi^*\) for all \(t > 0\). For \(\epsilon_{\rho} > 1\), that is, when monetary policy is active, the coefficient on \(\hat{\pi}_{t+1}\) is less than one in absolute value, implying indeterminacy of the perfect foresight real allocation. Consequently, as in the continuous-time case, the real allocation is uniquely determined when monetary policy is passive and is indeterminate when monetary policy is active. However, a difference with the continuous-time model arises when productivity effects of money are small relative to the interest-sensitivity of aggregate demand. In particular, if \(\rho_{cc} \epsilon_{yR} < 1/2\), then a second bifurcation point emerges at \(\epsilon_{\rho} = \frac{1}{\rho_{cc} \epsilon_{yR}} \approx 1/(1 - 2 \rho_{cc} \epsilon_{yR}) > 1\). For mildly active monetary policy \((1 < \epsilon_{\rho} < \tau_{\rho})\) equilibrium is still indeterminate but for a more aggressive stance \((\epsilon_{\rho} > \tau_{\rho})\), the real allocation becomes locally determinate. For certain parameterizations real instability is present even if \(\epsilon_{\rho} > \tau_{\rho}\) due to the emergence of 2-period cycles (see footnote 4). Note that the second bifurcation point does not exist if \(\rho_{cc} \epsilon_{yR} > 1/2\).

Finally, we note that if the interest rate feedback rule is assumed to depend not on \(\pi_{t+1}\) but on \(\pi_t\), which as we have argued above is not the appropriate discrete-time counterpart to our continuous-time feedback rule, then it can be shown that for productivity effects of money that are small relative to the interest-sensitivity of aggregate demand \((\rho_{cc} \epsilon_{yR} < 1/2)\), the real allocation is always determinate under active monetary policy, as is the case when money does not affect production possibilities. This continuity result in the conditions for determinacy as the productivity effects of money become negligible is similar to the one obtained by Woodford (1998) in the context of a monetary economy converging to a cashless limit. On the other hand, the real allocation is always indeterminate under active monetary policy when productivity effects of money are sufficiently large \((\rho_{cc} \epsilon_{yR} \geq 1)\).\(^5\)

3 A sticky-price model

The flexible-price economy analyzed in the previous section conveys the main message of the paper in a direct and transparent way. However, most of the literature devoted to evaluating the stabilizing properties of interest rate feedback rules includes as a central theoretical element the presence of nominal rigidities. Consequently, in this section we consider a model with sluggish price adjustment.

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\(^5\)We thank Michael Woodford for drawing our attention to this result.
Following Rotemberg (1982), we introduce price stickiness by assuming that the household–firm unit operates in imperfectly competitive product markets and dislikes changing the price it charges for the goods it produces. The implications of the Rotemberg model for the relation between the stance of monetary policy and aggregate stability are likely to carry over to economic environments with alternative sources of nominal price rigidities. For example, in appendix A we show that the equilibrium conditions associated with the model developed here are locally identical to those of a model with Calvo-Yun price staggering. Models with price stickiness are a step closer to the data than flexible-price frameworks in that they allow for a source of non-neutrality of monetary policy shocks. However, this type of new Keynesian feature per se is not enough to overcome a number of well-known empirical shortcomings of standard optimizing macroeconomic models. One limitation that has attracted some attention recently is the lack of inflation persistence. Later in the paper, we seek to introduce a low frequency component in the nominal interest rate and inflation by introducing lags in the interest rate feedback rule.

3.1 The economic environment

3.1.1 The household/firm unit

Assume an economy populated by a continuum of household–firm units indexed by $j$, each of which produces a differentiated good $Y^j$ and faces a demand function $Y^d d(P^j, \bar{P})$, where $Y^d$ denotes the level of aggregate demand, $P^j$ the price firm $j$ charges for its output, and $\bar{P}$ the aggregate price level. Such a demand function can be derived by assuming that households have preferences over a composite good that is produced from differentiated intermediate goods via a Dixit-Stiglitz production function. The function $d(\cdot)$ is assumed to satisfy $d(1) = 1$ and $d'(1) < -1$. The restriction imposed on $d'(1)$ is necessary for the firm’s problem to be well defined in a symmetric equilibrium. The production of good $j$ is assumed to take real money balances, $m^p_j$, as the only input

$$Y^j = y(m^p_j)$$

where $y(\cdot)$ satisfies Assumption 2.

The household’s lifetime utility function is assumed to be of the form

$$U_j = \int_0^\infty e^{-\gamma t} \left[ u(c^j, m^{np}_j) - \frac{\gamma}{2} \left( \frac{\dot{P}_j}{P_j} - \pi^* \right)^2 \right] dt \quad (24)$$

where $c^j$ denotes consumption of the composite good by household $j$, $m^{np}_j \equiv M^{np}_j / \bar{P}$ denotes real money balances held by household $j$ for non-productive purposes, $M^{np}_j$ denotes nominal money balances, and $\pi^* > -\tau$ denotes the steady-state inflation rate. The utility function $u(\cdot, \cdot)$ satisfies Assumption 1, and the parameter $\gamma$, measuring the degree to which household–firm units dislike to deviate in their price-setting behavior from the long-run level of aggregate price inflation, is positive. The household’s instant budget constraint and no-Ponzi-game restriction are

$$\dot{a}^j = (R - \pi)a^j - R(m^{np}_j + m^p_j) + \frac{P_j}{\bar{P}} y(m^p_j) - c^j - \tau \quad (25)$$

and

$$\lim_{t \to \infty} e^{-\int_0^t [R(s) - \pi(s)] ds} a^j(t) \geq 0. \quad (26)$$
In addition, firms are subject to the constraint that given the price they charge, their sales are demand-determined

\[ y(m_{pj}) = Y^d d\left(\frac{P_j}{P}\right). \]  

(27)

The household chooses sequences for \( c^j, m_{npj}, m_{pj}, a^j, \) so as to maximize (24) subject to (25)–(27) taking as given \( a^j(0), P^j(0), \) and the time paths of \( \tau, R, Y^d, \) and \( P. \) The Hamiltonian of the household’s optimization problem takes the form

\[
e^{-rt} \left\{ u(c^j, m_{npj}) - \frac{\gamma}{2} \left( \frac{P_j}{P_j} - \pi^* \right)^2 + \lambda^j \left[ (R - \pi)a^j - R(m_{npj} + m_{pj}) \right] \\
+ \frac{P_j}{P} y(m_{pj}) - c^j - \dot{a}^j \right\} + \mu^j \left[ Y^d d\left(\frac{P_j}{P}\right) - y(m_{pj}) \right].
\]

The first-order conditions associated with \( c^j, m_{npj}, m_{pj}, a^j, \) and \( P^j \) and the transversality condition are, respectively,

\[
u_c(c^j, m_{npj}) = \lambda^j
\]

(28)

\[
u_m(c^j, m_{npj}) = \lambda^j R
\]

(29)

\[
\lambda^j \left[ \frac{P_j}{P} y'(m_{pj}) - R \right] = \mu^j y'(m_{pj})
\]

(30)

\[
\dot{\lambda}^j = \lambda^j (\tau + \pi - R)
\]

(31)

\[
\lambda^j \frac{P_j}{P} y(m_{pj}) + \mu^j \frac{P_j}{P} Y^d d'\left(\frac{P_j}{P}\right) = \gamma r(\pi^j - \pi^*) - \gamma \pi^j
\]

(32)

\[
\lim_{t \to \infty} e^{-f_0[R(s) - \pi(s)]ds} a^j(t) = 0
\]

(33)

where \( \pi^j \equiv \hat{P}^j / P^j. \) Combining equations (28) and (29), the demand for real balances for non-production purposes can be expressed as

\[
m_{npj} = m_{np}(c^j, R)
\]

(34)

which by Assumption 1 is increasing in \( c^j \) and decreasing in \( R. \)

### 3.1.2 Equilibrium

In a symmetric equilibrium all household–firm units choose identical sequences for consumption, asset holdings, and prices. Thus, \( c^j = c, m_{pj} = m_p, m_{npj} = m_{np}, a^j = a, \) \( P^j = P, \lambda^j = \lambda, \mu^j = \mu, \) and \( \pi^j = \pi. \) In addition, the goods markets clear and the no-Ponzi-game restriction holds with
equality, that is, equations (8) and (16) are part of the equilibrium conditions. Using (11), (16), and (34), to eliminate \( m^{np} \), \( c \), and \( R \) in (28) yields

\[
u_c(y(m^p), m^{np}(y(m^p), \rho(\pi))) = \lambda. \tag{35}\]

Equation (35) together with Assumption 1 implies that \( m^p \) can be expressed as a function of \( \pi \) and \( \lambda \) that is decreasing in \( \lambda \) and decreasing (increasing) in \( \pi \) if \( u_{cm} > 0(< 0) \). Formally,\(^6\)

\[
m^p = m^p(\lambda, \pi), \tag{36}\]

where \( m^p_\lambda < 0, m^p_\pi u_{cm} < 0 \) if \( u_{cm} \neq 0 \), and \( m^p_\pi = 0 \) if \( u_{cm} = 0 \). Let \( \eta \equiv d'(1) < -1 \) denote the equilibrium price elasticity of the demand function faced by the individual firm. Using (11), (16), (30), and (36) to eliminate \( m^p, m^{np}, \mu, R \), and \( c \) from equations (8), (12), (14), (31), and (32) yields

\[
\dot{\lambda} = \lambda [r + \pi - \rho(\pi)] \tag{37}
\]

\[
\gamma \pi = \gamma r(\pi - \pi^*) - y(m^p(\lambda, \pi)) \left[ 1 + \eta \left( 1 - \frac{\rho(\pi)}{y'(m^p(\pi, \lambda))} \right) \right] \tag{38}
\]

\[
\dot{a} = \left[ \rho(\pi) - \pi \right] a - \rho(\pi) \left[ m^{np}(y(m^p(\lambda, \pi)), \rho(\pi)) + m^p(\lambda, \pi) \right] - \tau \tag{39}
\]

\[
0 = \lim_{t \to \infty} e^{-\int_{0}^{t}[\rho(\pi) - \pi] ds} a(t) \tag{40}
\]

\[
\tau = -\rho(\pi) \left[ m^{np}(y(m^p(\lambda, \pi)), \rho(\pi)) + m^p(\lambda, \pi) \right] + a a \tag{41}
\]

**Definition 3 (Perfect-foresight equilibrium in the sticky-price economy)** In the sticky-price economy, a perfect-foresight equilibrium is a set of sequences \( \{\lambda, \pi, \tau, a\} \) satisfying (37)--(40) and either (15) if the fiscal regime is non-Ricardian or (41) if the fiscal regime is Ricardian, given \( a(0) \).

Given the equilibrium sequences \( \{\lambda, \pi, \tau, a\} \), the corresponding equilibrium sequences \( \{c, m^{np}, m^p, R\} \) are uniquely determined by (11), (16), (34), and (36).

### 3.2 Determinacy of equilibrium under Ricardian fiscal policy

In this case, the equilibrium conditions include equation (41). Given a pair of sequences \( \{\pi, \lambda\} \), equations (39) and (41) can be used to construct time paths for \( a \) and \( \tau \). Because the fiscal policy is Ricardian, the sequences \( \{\pi, a\} \) satisfy the transversality condition (40). Thus any pair of sequences \( \{\lambda, \pi\} \) satisfying (37) and (38) can be supported as a perfect-foresight equilibrium.

#### 3.2.1 Perfect-foresight equilibria converging to the steady state

Consider first perfect-foresight equilibria in which \( \{\lambda, \pi\} \) converge to a steady-state \( \{\lambda^*, \pi^*\} \). The steady-state values \( \lambda^* \) and \( \pi^* \) are defined as constant values of \( \lambda \) and \( \pi \) that solve (37) and (38). Thus, \( \pi^* \) is a solution to \( r + \pi^* = \rho(\pi^*) \), which by assumption exists though need not be unique. Given a \( \pi^* \), the steady-state value of real balances for production purposes, \( m^{ps} \), is given by the solution to \( y'(m^{ps}) = \eta/(1+\eta)R^* \), where \( R^* = \rho(\pi^*) \) is the steady state value of the nominal interest rate. By Assumption 2, \( m^{ps} \) exists and is positive and unique for a given \( \pi^* \). Finally, \( \lambda^* \) is given by \( \lambda^* = u_c(c^*, m^{np}(c^*, R^*)) > 0 \), where \( c^* = y(m^{ps}) \) denotes the steady-state level of consumption.

\(^6\)Differentiating equation (35), it follows that \( m^p_\pi = \frac{u_{cm} - (u_m/u_c)u_{cm}}{y'(u_{cm}u_{mm} - u_{cm}^2)} \). The concavity of the instant utility function and the normality of consumption imply, respectively, that the denominator of this expression is positive and the numerator negative. Also, \( m^p_{\lambda} = -u^2_{cm} u_{cm} m^{np}_{x^p} \rho' \), which is of the opposite sign of \( u_{cm} \).
In a neighborhood around \((\lambda^*, \pi^*)\), the equilibrium paths of \(\lambda\) and \(\pi\) can be approximated by the solutions to the following linearization of (37) and (38) around \(\{\lambda^*, \pi^*\}\)

\[
\begin{pmatrix}
\dot{\lambda} \\
\dot{\pi}
\end{pmatrix} = A 
\begin{pmatrix}
\lambda - \lambda^* \\
\pi - \pi^*
\end{pmatrix}
\]

(42)

where

\[
A = \begin{bmatrix}
0 & u_c(1 - \rho') \\
A_{21} & A_{22}
\end{bmatrix}
\]

\[
A_{21} = -\frac{u_c \epsilon^* \eta R^* y'' m^p}{\gamma y'^2} > 0
\]

\[
A_{22} = r + \frac{u_c \epsilon^* \eta}{\gamma} \left[ \frac{\rho'}{y'} - \frac{R^*}{y'^2 y'' m^p} \right]
\]

If at the particular steady state considered monetary policy is passive \((\rho'(\pi^*) < 1)\), the determinant of \(A\), given by \(-A_{21} u_c(1 - \rho')\), is negative, implying that \(A\) has one positive real root and one negative real root. Since both \(\lambda\) and \(\pi\) are jump variables, it follows that there exists a neighborhood around the steady state such that for any initial \(\lambda(0)\) there exists a \(\pi(0)\) in that neighborhood such that the trajectories of \(\lambda\) and \(\pi\) implied by (42) will converge asymptotically to the steady state. The following proposition summarizes this result.

**Proposition 3.1** If fiscal policy is Ricardian and monetary policy is passive \((\rho'(\pi^*) < 1)\), then there exists a continuum of perfect-foresight equilibria in which \(\pi\) and \(\lambda\) converge asymptotically to the steady state \((\pi^*, \lambda^*)\).

Under active monetary policy \((\rho'(\pi^*) > 1)\) the determinant of \(A\) is positive and hence the real parts of its eigenvalues have the same sign. If the trace of \(A\), given by \(A_{22}\), is negative, then the real parts of the roots are negative, which implies that near the steady state there exists an infinite number of perfect-foresight equilibria converging to the steady state. If, on the other hand, the trace of \(A\) is positive, both eigenvalues have positive real parts, and therefore the only perfect-foresight equilibrium converging to the steady state is the steady state itself. We formally state these results in the following proposition.

**Proposition 3.2** If fiscal policy is Ricardian and monetary policy is active \((\rho'(\pi^*) > 1)\), then, if \(A_{22} > 0(<0)\), there exists a unique (a continuum of) perfect-foresight equilibria in which \(\pi\) and \(\lambda\) converge to the steady state \((\pi^*, \lambda^*)\).

To illustrate that the equilibrium can be either determinate or indeterminate under active monetary policy consider the simple case that the instant utility function is separable in consumption and money and logarithmic in consumption, so that \(u_c \epsilon^* = 1\). In this case, the trace of \(A\) is given by

\[
\text{trace} (A) = r + \frac{(1 + \eta) \rho'}{\gamma R^*}
\]

(43)

Let \(\bar{\rho}' = \frac{r R^* \gamma}{1 + \eta}\) denote the value of \(\rho'\) at which the trace vanishes. Clearly, \(\bar{\rho}'\) may be greater or less than one. If \(\bar{\rho}' \leq 1\), then the equilibrium is indeterminate for any active monetary policy. We highlight this result in the following corollary.

\footnote{In deriving this expression we used the facts that when \(u_{cm} = 0\), \(m^p = 0\) and that in the steady state \(y' = R^* \eta/(1 + \eta)\).}
Corollary 1 Suppose fiscal policy is Ricardian and preferences are separable in consumption and real balances and logarithmic in consumption. If \( \beta' \equiv -\frac{\gamma R}{1+\eta} \) is less than or equal to one, then there exists a continuum of perfect-foresight equilibria in which \( \pi \) and \( \lambda \) converge to the steady state \((\pi^*, \lambda^*)\) for any active monetary policy. The indeterminacy is of order two.

If \( \beta' > 1 \), then for values of \( \rho' \in (1, \beta') \) the trace of \( A \) is positive, and the only equilibrium paths \( \{\lambda, \pi\} \) converging to the steady state are ones in which \( \lambda \) and \( \pi \) are constant and equal to their steady-state values. For values of \( \rho' > \beta' \) the trace of \( A \) is negative and the perfect-foresight equilibrium is indeterminate.\(^8\)

To facilitate comparison to recent studies on the macroeconomic effects of alternative interest rate feedback rules in environments with sluggish price adjustment continue to assume that the instant utility function is log-linear in consumption, for this is the standard assumption in the existing literature. In this case, equations (37) and (38) are qualitatively equivalent to the IS and New Keynesian aggregate supply equations arising from a Calvo-Yun-type sticky-price model in which money does not enter the production function, such as Woodford (1996), Bernanke and Woodford (1997), or Clarida, Galí, and Gertler (1997), with one important exception: in our model the aggregate supply equation features an ambiguous partial derivative of \( \tilde{\pi} \) with respect to \( \pi \) given by \( r + \frac{(1+\eta)\rho'}{\gamma R} \) whereas in the models just cited this derivative is unambiguously positive and equal to \( r \). The ambiguity in the sign of the partial derivative of \( \tilde{\pi} \) with respect to \( \pi \) is neither due to the way we introduce price stickiness nor is it due to our assumption that time is continuous. In fact, one can show that in a continuous-time version of the Calvo-Yun model without money in the production function the partial derivative of \( \tilde{\pi} \) with respect to \( \pi \) is unambiguously positive and equal to \( r \), just like in its discrete time counterpart. Rather the difference in the sign of the partial derivative arises because of our assumption that money affects productivity.

If the partial derivative of \( \tilde{\pi} \) with respect to \( \pi \) is positive, then \( A_{22} \) is positive and by propositions 3.1 and 3.2 the equilibrium is locally indeterminate under passive monetary policy and is locally determinate under active monetary policy. In this case our findings coincide with those reported in the studies cited above. On the other hand, if the partial derivative of \( \tilde{\pi} \) with respect to \( \pi \) is negative, that is, \( A_{22} < 0 \), then equilibrium is indeterminate not only under passive but also under active monetary policy. This result is important because it calls into question the policy recommendation implicit in the analysis of previous papers that active monetary policy is stabilizing. The existing literature has arrived at this conclusion by assuming that the only supply side effects of nominal shocks are brought about through sluggish adjustment of product prices ignoring direct effects of changes in the opportunity cost of holding money on the productivity of firms.

3.2.2 Periodic perfect-foresight equilibria

So far we have restricted attention to perfect-foresight equilibria in which \( \{\lambda, \pi\} \) converge asymptotically to \( \{\lambda^*, \pi^*\} \). We now investigate the existence of perfect-foresight equilibria in which \( \lambda \) and \( \pi \) converge asymptotically to a deterministic cycle. Consider an economy with preferences given by \( u(c, m^{np}) = (1 - s)^{-1}c^{1-s} + V(m^{np}) \), \( s > 0 \); technology given by \( y(m^p) = (m^p)^{\alpha} \), \( 0 < \alpha < 1 \); and a smooth interest-rate feedback rule, \( \rho(\pi) > 0 \), which in for \( \pi \) in the neighborhood of \( \pi^* \) takes

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\(^8\)In the context of a discrete-time, flexible-price, cash-in-advance economy with cash and credit goods, Schmitt-Grohé and Uribe (1999) obtain a similar result, namely, the perfect-foresight equilibrium is indeterminate for passive and very active monetary policy and is determinate for moderately active policies. Clarida, Galí and Gertler (1997) also find an indeterminacy region for highly active interest rate feedback rules in a discrete-time model with Calvo-Yun price staggering, with money not affecting production possibilities, and forward-looking monetary policy. It is noteworthy that in a continuous-time version of the their model, active monetary policy always ensures local determinacy.
the form $\rho(\pi) = R^* + a(\pi + r - R^*)$, $a > 0$, $R^* > 0$. Consider the steady state inflation rate $\pi^* = R^* - r$. In this case the trace of $A$ is given by

$$\text{trace}(A) = r + \frac{\eta a}{\alpha \gamma} \left( - \frac{R^*}{1 + \eta \alpha} \right)^{\frac{1 - \alpha s}{\alpha - 1}}.$$ 

Let $\bar{a} \equiv \frac{-\alpha s}{\eta} \left( \frac{\mu + R^*}{1 + \eta \alpha} \right)^{\frac{1 - \alpha s}{\alpha - 1}}$ denote the value of $a$ at which the trace of $A$ is equal to zero. Consider parameter configurations for which $\bar{a} > 1$. As $a$ crosses $\bar{a}$ from below, the real parts of the two complex roots of $A$ change sign from positive to negative. This is the standard case of a Hopf bifurcation, which implies that generically (i.e., if the system is non-linear), there will exist a family of cycles for $a$ either in a left or in a right neighborhood of $\bar{a}$. Furthermore, if the cycle is to the left of $\bar{a}$ where the steady state is unstable (i.e., the bifurcation point is supercritical), the cycle will be attracting. The implication is that if the bifurcation is supercritical, then there exist values of $a$ less than $\bar{a}$ for which any trajectory $\{\lambda, \pi\}$ that starts out in the neighborhood of $\{\lambda^*, \pi^*\}$ will converge to a cycle, so that the equilibrium is indeterminate. The following proposition provides some conditions under which a supercritical Hopf bifurcation exists.

**Proposition 3.3** Consider an economy with preferences given by $u(c, m^{np}) = (1 - s)^{-1} c^{1-s} + V(m^{np})$, $s > 0$; technology given by $y(m^p) = (m^p)^{\alpha}$, $0 < \alpha < 1$; and monetary policy given by a smooth interest-rate feedback rule, $\rho(\pi) > 0$, which for $\pi$ in the neighborhood of $\pi^*$ takes the form $\rho(\pi) = R^* + a(\pi + r - R^*)$, $a > 0$, $R^* > 0$. Let fiscal policy be Ricardian and let the parameter configuration satisfy $\bar{a} \equiv \frac{-s \alpha}{\eta} \left( \frac{\mu + R^*}{1 + \eta \alpha} \right)^{\frac{1 - \alpha s}{\alpha - 1}} > 1$ and $1 < s < 1/\alpha$. Then there exists an infinite number of active monetary policies satisfying $a < \bar{a}$ for each of which the perfect foresight equilibrium is indeterminate and $\pi$ and $\lambda$ converge asymptotically to a deterministic cycle.

**Proof:** See appendix B.

The determinacy results obtained under Ricardian fiscal policies and active monetary policy are of particular relevance to the current debate on optimal monetary policy. It is often argued (typically in the context of discrete-time models) that under fiscal policies which guarantee the solvency of the government, a moderately active monetary policy, that is, a policy such that $\rho'(\pi^*) > 1$ but below a certain threshold, is stabilizing in the sense that it ensures nominal and real determinacy (Bernanke and Woodford, 1997; Clarida, Galí, and Gertler, 1997; Rotemberg and Woodford, 1997). However, propositions 3.2 and 3.3 show that even moderately active monetary policies may not eliminate the possibility of real indeterminacy in a sticky-price economy, and corollary 1 gives sufficient conditions for indeterminacy under any active monetary policy. The reason why the sources of instability stressed in this section have been overlooked in the related literature is twofold. First, existing studies have focused on the limiting case in which the nominal interest rate does not affect the cost of production. Second, the majority of previous studies has focused on the dynamics arising from small fluctuations around a particular steady state that are expected to converge asymptotically to the steady state. Thus, by their very nature, analysis of this type are unable to detect equilibria involving bounded fluctuations converging asymptotically to a limit cycle.

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9Because a linear rule defined for all possible values of $\pi$ would yield negative nominal interest rates for some $\pi$, we do not require the linear specification to hold globally.

10The Hopf Bifurcation Theorem postulates the existence of a family of cycles, which in the pure linear system pile up at the bifurcation value $\bar{a}$ and create a center: any nonlinearity will spread them out to either a left or a right neighborhood of $\bar{a}$. Generically, the amplitude of the cycle varies continuously with $a - \bar{a}$ and is zero at $a = \bar{a}$.
3.3 Determinacy of equilibrium under non-Ricardian fiscal policy

Suppose now that the government follows the non-Ricardian fiscal policy described in equation (15), that is, a fiscal policy whereby the time path of real lump-sum taxes is exogenous. Using (15) to replace \( \tau \) in equation (39) yields

\[
\dot{a} = [\rho(\pi) - \pi]a - \rho(\pi) \left[ m^{np}(y(m^{np}(\lambda, \pi)), \rho(\pi)) + m^{p}(\lambda, \pi) \right] - \tau. \tag{44}
\]

3.3.1 Perfect-foresight equilibria converging to the steady state

As before, we initially restrict attention to equilibria in which \( \{\lambda, \pi\} \) converge to a steady-state \((\lambda^*, \pi^*)\). It is clear from equation (44) that sequences \( \{\lambda, \pi\} \) that converge to \((\lambda^*, \pi^*)\) will in general be associated with sequences for \( a \) that grow asymptotically at the rate \( \rho(\pi^*) - \pi^* = r \), thus violating the transversality condition (40). As a consequence, equations (40) and (44) impose restrictions on the set of sequences \( \{\lambda, \pi\} \) that are consistent with a perfect-foresight equilibrium of the type we are considering. Specifically, only sequences \( \{\lambda, \pi\} \) converging to the steady state \((\lambda^*, \pi^*)\) that imply (via equation (44)) a sequence for \( a \) that converges to a constant value constitute a perfect-foresight equilibrium. Thus, one can analyze the dynamic properties of the model by restricting attention to a linear approximation of the equilibrium conditions (37), (38), and (44), which can be written as

\[
\begin{pmatrix}
\dot{\lambda} \\
\dot{\pi} \\
\dot{a}
\end{pmatrix} =
\begin{bmatrix}
A_{11} & 0 & 0 \\
\epsilon & r & 0 \\
0 & 0 & 0
\end{bmatrix}
\begin{pmatrix}
\lambda - \lambda^* \\
\pi - \pi^* \\
a - a^*
\end{pmatrix}, \tag{45}
\]

where \( A \) is defined in (42) and \( \epsilon \) is a one by two vector whose elements are the steady-state derivatives of \( R(m^{np} + m^{p}) \) with respect to \( \lambda \) and \( \pi \).

Since the Jacobian in (45) is quasi-diagonal, its three eigenvalues are given by the two eigenvalues of the matrix \( A \) and \( r > 0 \). Because \( a \) is the only non-jump variable of the system, there exist multiple equilibria converging to the steady state if and only if both roots of \( A \) have negative real parts. Since—as pointed out above—\( \rho' > 1 \) is a necessary and sufficient conditions for both eigenvalues of \( A \) to be of the same sign, the possibility of multiple equilibrium paths \( \{\lambda, \pi\} \) converging asymptotically to the steady-state can only arise under active monetary policy. Under passive monetary policy the matrix \( A \) has exactly one negative eigenvalue, therefore, there exists a unique equilibrium converging to the steady state. Finally, if all eigenvalues of \( A \) have positive real parts, which will be the case if monetary policy is active and \( A_{22} \) is positive, there exists no equilibrium converging to the steady state. These results are summarized in the following propositions

**Proposition 3.4** If fiscal policy is non-Ricardian and monetary policy is passive \( (\rho'(\pi^*) < 1) \), then there exists a unique perfect-foresight equilibrium in which \( \{\lambda, \pi\} \) converge asymptotically to the steady state \((\pi^*, \lambda^*)\).

**Proposition 3.5** If fiscal policy is non-Ricardian and monetary policy is active \( (\rho'(\pi^*) > 1) \), then if \( A_{22} > 0(< 0) \), there exists no (a continuum of) perfect-foresight equilibria in which \( \{\lambda, \pi\} \) converge asymptotically to the steady state \((\pi^*, \lambda^*)\).

The result contained in proposition 3.4 is similar to the one obtained in Woodford (1996) in the context of a discrete-time Calvo-Yun-type sticky-price model without money in the production function. What distinguishes our findings from previous studies is the result that the equilibrium may be locally indeterminate under non-Ricardian fiscal policy (proposition 3.5). As pointed out above, in a continuous-time version of Woodford (1996), the trace of \( A \) is positive and equal to \( r \), so
that at least one eigenvalue of \( A \) is always positive. Thus, in such a model indeterminacy can never arise under non-Ricardian fiscal policy. What precludes indeterminacy in that class of models is the assumption that costs of production are unaffected by movements in the nominal interest rate.

### 3.3.2 Periodic perfect-foresight equilibria

In the case that monetary policy is active and both eigenvalues of \( A \) are positive, there may exist bounded equilibria that converge to a stable cycle around the steady state. Note that for the system (37), (38), and (44) the dynamics of \( \{ \lambda, \pi \} \) are independent of \( a \), and thus the analysis of periodic equilibria of the previous section still applies. For example, under the preference and technology specification of the economy described in proposition 3.3, if cycles exist, any initial condition for \( (\lambda, \pi) \) in the neighborhood of the steady state will converge to a cycle. To assure that \( a \) does not explode, however, we must restrict ourselves to a one dimensional manifold in \( \{ \lambda, \pi \} \). This follows because while cycles restricted to the \( \{ \lambda, \pi \} \) plane are attracting, in the three dimensional space the cycle in \( \{ \lambda, \pi, a \} \) will have only a two dimensional stable manifold: initial values of \( \lambda \) and \( \pi \) will have to be chosen to assure that the triple \( \{ \lambda, \pi, a \} \) converges to the cycle and \( a \) remains bounded.

#### Table 2: Real indeterminacy in the Sticky-Price Model

<table>
<thead>
<tr>
<th>Monetary Policy</th>
<th>Fiscal Policy</th>
<th>Ricardian</th>
<th>Non-Ricardian</th>
</tr>
</thead>
<tbody>
<tr>
<td>Passive ( (\rho'(\pi^*) &lt; 1) )</td>
<td>I</td>
<td>D</td>
<td></td>
</tr>
<tr>
<td>Active ( (\rho'(\pi^*) &gt; 1) )</td>
<td>I or D</td>
<td>I or NE</td>
<td></td>
</tr>
</tbody>
</table>

Note: The notation is D, determinate; I, indeterminate; NE, no perfect-foresight equilibrium exists.

Table 2 summarizes the results of this section. It shows the combinations of fiscal and monetary policies for which the real allocation is indeterminate in the sticky-price model. The last two rows of the table illustrate a central point of the paper, namely that active monetary policy need not guarantee real determinacy.

### 4 Backward- and forward-looking feedback rules

In this section, we analyze generalizations of the interest-rate feedback rule given in equation (11) by allowing the nominal interest rate to depend not only on current but also either on past or on future expected rates of inflation. Specifically, we consider the following backward-looking feedback rule

\[
R = \rho (q \pi + (1 - q) \pi^p); \quad \rho' > 0; \quad q \in [0, 1],
\]

(46)

where \( \pi^p \) is a weighted average of past rates of inflation and is defined as

\[
\pi^p = b \int_{-\infty}^{t} \pi(s) e^{b(s-t)} ds; \quad b > 0
\]

(47)
Table 3: Backward- and forward looking interest-rate rules in the flexible-price model

(A) Backward-looking rules

\[ R = \rho(q\pi + (1 - q)\pi^p); \quad 0 < q \leq 1 \]
\[ \pi^p = b \int_{-\infty}^{t} \pi e^{b(s-t)} ds; \quad b > 0 \]

<table>
<thead>
<tr>
<th>Monetary Policy</th>
<th>Non-productive money ((y' = 0))</th>
<th>Productive money ((y' &gt; 0))</th>
</tr>
</thead>
<tbody>
<tr>
<td>Passive ((\rho' &lt; 1))</td>
<td>(u_{cm} &gt; 0)</td>
<td>(u_{cm} &lt; 0)</td>
</tr>
<tr>
<td>Active ((\rho' &gt; 1))</td>
<td>(u_{cm} &gt; 0)</td>
<td>(u_{cm} &lt; 0)</td>
</tr>
<tr>
<td>(b, q \text{ large})</td>
<td>D</td>
<td>I</td>
</tr>
<tr>
<td>(b, q \text{ small})</td>
<td>D</td>
<td>NE</td>
</tr>
</tbody>
</table>

(B) Forward-looking rules

\[ R = \rho(q\pi + (1 - q)\pi^f); \quad 0 < q \leq 1 \]
\[ \pi^f = d \int_{-\infty}^{t} \pi e^{-d(s-t)} ds; \quad d > 0 \]

<table>
<thead>
<tr>
<th>Monetary Policy</th>
<th>Non-productive money ((y' = 0))</th>
<th>Productive money ((y' &gt; 0))</th>
</tr>
</thead>
<tbody>
<tr>
<td>Passive ((\rho' &lt; 1))</td>
<td>(u_{cm} &gt; 0)</td>
<td>(u_{cm} &lt; 0)</td>
</tr>
<tr>
<td>Active ((\rho' &gt; 1))</td>
<td>(u_{cm} &gt; 0)</td>
<td>(u_{cm} &lt; 0)</td>
</tr>
<tr>
<td>(d, q \text{ large})</td>
<td>D</td>
<td>I</td>
</tr>
<tr>
<td>(d, d/q \text{ small})</td>
<td>I</td>
<td>I</td>
</tr>
</tbody>
</table>

Note: The notation is: D, determinate; I, indeterminate; NE, no equilibrium exists locally.

Note that when \(q = 1\), the feedback rule given in (46) collapses to a feedback rule linking the nominal interest rate solely to the current instantaneous rate of inflation, which is the case studied in the previous sections. On the other hand, in the special case in which \(q = 0\), the feedback rule becomes purely backward-looking. The forward-looking feedback rule we study takes the form

\[ R = \rho(q\pi + (1 - q)\pi^f); \quad \rho' > 0; \ q \in [0, 1] \] (48)

where \(\pi^f\) is a weighted average of expected future rates of inflation and is defined as

\[ \pi^f = d \int_{t}^{\infty} \pi e^{-d(s-t)} ds; \quad d > 0 \] (49)

Again, in the extreme case in which \(q = 1\), the feedback rule collapses to the purely contemporaneous rule given in (11), while in the case in which \(q = 0\), the operating target depends only on expectations of future inflation.

The equilibrium conditions of the flexible-price economy with backward-looking monetary policy are the same as those pertaining to the flexible-price model under a contemporaneous interest-rate feedback rule with the only difference that equation (11) is replaced by equations (46) and (47). Appendix C contains a detailed characterization of the perfect-foresight equilibrium. The results of the analysis are summarized in panel (A) of table 3. As in section 2, we consider the two polar cases of money entering only through preferences \((y' = 0)\) and money entering only through production \((y' > 0\text{ and }u_{cm} = m_{np}R = 0)\). If money enters only through preferences and money and consumption are Edgeworth complements \((u_{cm} > 0)\), then the conditions governing the
local determinacy of equilibrium are identical to those obtained under a purely contemporaneous feedback rule. Namely, the real allocation is unique under active monetary policy \((\rho' > 1)\) and is indeterminate under passive monetary policy \((\rho' < 1)\).

When money enters only through production or only through preferences with consumption and money being Edgeworth substitutes \((u_{cm} < 0)\), the real allocation is always locally determinate under passive monetary policy, as was the case under purely contemporaneous feedback rules. However, contrary to the case of purely contemporaneous feedback rules, if monetary policy is active, then equilibria in which the real allocation converges to its steady state may not exist. In general, there exists a threshold for the sensitivity of the feedback rule with respect to the intermediate target, \(\rho' > 1\), below which no equilibrium exists locally and above which the equilibrium is indeterminate. Furthermore, the larger the emphasis the feedback rule places on contemporaneous inflation \((q\) close to one) or the lower the weight it assigns to inflation rates observed in the distant past \((b\) large), the smaller is the threshold value \(\rho'\) beyond which the equilibrium becomes indeterminate. In the limit, as \(q\) approaches unity or \(b\) approaches infinity, the equilibrium becomes indeterminate under every active monetary policy, which is the result obtained under purely contemporaneous feedback rules.\(^{11}\)

We conclude that the more backward-looking the feedback rule is, the less likely it is that active monetary policy renders the equilibrium locally indeterminate. This is not to say, however, that backward-looking behavior in the conduct of monetary policy in combination with an active stance enhances economic stability. On the contrary, when such a policy mix eliminates indeterminacy, it replaces it with a potentially more undesirable outcome, namely, local inexistence of equilibrium. More generally, we interpret our results as supporting the basic argument of this paper. That is, even when the central bank’s intermediate target includes a backward-looking component, it is still the case that whether or not a particular monetary policy stance helps bring about macroeconomic stability depends crucially on the underlying preference and technology parameters.

When the feedback rule is forward-looking, the conditions governing the local determinacy of the real allocation are identical to those obtained under purely contemporaneous feedback rules with one exception. When money enters only through preferences and consumption and real balances are Edgeworth complements (i.e., \(y' = 0\) and \(u_{cm} > 0\)), active monetary policy may induce indeterminacy. This is the case when the monetary authority places a relatively strong emphasis on expectations of future inflation in setting the nominal interest rate \((q\) small) and/or when it assigns a large weight on inflation rates in the distant future in computing the average expected future rate of inflation \((d\) small). Panel (B) of table 3 summarizes the results.\(^{12}\) We conclude that the more forward-looking monetary policy is, the more likely it is that active monetary policy renders the equilibrium locally indeterminate.

It is noteworthy that the dichotomy between nominal and real determinacy that appears when

\(^{11}\)But what if monetary policy is purely backward looking \((q = 0)\)? We show in appendix C that in this case local indeterminacy of the real allocation disappears. However, non existence of equilibrium becomes more prevalent. Specifically, if consumption and real balances are Edgeworth complements \((u_{cm} > 0)\) and money is not productive \((y' = 0)\), then the equilibrium fails to exist locally under active monetary policy \((\rho' > 1)\), but is uniquely determined under passive monetary policy \((\rho' < 1)\). When money is productive \((y' > 0)\) and money does not affect preferences or when money is not productive \((y' = 0)\) and consumption and real balances are Edgeworth substitutes \((u_{cm} < 0)\), then the existence of equilibrium depends not only on the stance of monetary policy, but also on the weight the central bank assigns to past inflation rates in setting the operating target. If the monetary authority does not place too much weight on inflation rates in the distant past \((b\) not too large), then the equilibrium exists for all passive policies as well as for highly active policies, but does not exist for mildly active policies. On the other hand, if the monetary authority is only concerned with the most recent inflationary experience \((b\) relatively large), then the equilibrium exists except for a range of mildly passive feedback rules.

\(^{12}\)In appendix C we also analyze the case of purely forward-looking rules \((q = 0)\).
the feedback rule depends only on current inflation survives under backward- and forward-looking policies. Nominal determinacy depends exclusively on fiscal policy. As under purely contemporaneous monetary feedback rules, the price level is determinate if fiscal policy is non-Ricardian and is indeterminate if fiscal policy is Ricardian.

Finally, we offer a brief summary of the results arising from introducing forward- and backward-looking feedback rules in economies with nominal rigidities, leaving the details of the analysis to appendix C. When nominal prices are sticky, the pattern that arises is that if monetary policy is active, the introduction of a backward-looking component in monetary policy makes determinacy more likely, whereas a forward-looking component makes indeterminacy more likely.

5 Conclusion

Given the usual degree of controversy surrounding macroeconomic policy recommendations, the degree of consensus that has emerged regarding the desirability of active monetary policy (in the spirit of Taylor, 1993) for aggregate stability is remarkable. As testified by a recent conference volume on monetary policy rules edited by John B. Taylor (1999), researchers have arrived at this conclusion following very different modeling approaches, from non-optimizing reduced-form models (Levin, Wieland, and Williams; 1999) to optimizing dynamic general equilibrium models (Rotemberg and Woodford; 1999). One important assumption maintained in the existing literature is that firms’ costs of production are unaffected by variations in the nominal interest rate.

In this paper, we show that the implications of particular interest rate feedback rules for aggregate stability depend crucially on the precise way in which money affects aggregate demand and supply. In particular, we find that if firms’ productivity is affected by changes in the opportunity cost of money, then the result that active monetary policy is stabilizing may not hold. Because empirically the opportunity cost of holding money is a significant determinant of firms’ costs of production, models that ignore this channel of monetary transmission may give rise to misleading policy recommendations. It follows that empirical research aimed at providing a better understanding of the relationship between nominal interest rates and firms’ costs of production would shed much needed light on the current debate on the current monetary policy debate.
Appendix

A A model with Calvo-Yun-type price staggering

In this appendix, we develop a continuous-time, money-in-the-production function version of Yun’s (1996) sticky-price model. Yun’s model is a variation of Calvo’s (1983) model in which firms are assumed to set prices so as to maximize the present value of profits, instead of following a rule of thumb as assumed by Calvo. We show that the Calvo-Yun framework implies equilibrium conditions that are qualitatively identical to those obtained under the Rotemberg model. Thus, all the results on local determinacy obtained in section 3 carry over to environments with Calvo-Yun price staggering.

Households

The representative household’s lifetime utility function is assumed to be of the form

\[ \int_0^{\infty} e^{-rt} u(c, m^{np}) dt, \]  

where \( u(\cdot, \cdot) \) satisfies Assumption 1. The household’s instant budget constraint is

\[ \dot{a} = (R - \pi)a + Rm^{np} + x - c - \tau, \]

where \( x \) denotes the household’s income measured in units of the composite good, which consists of profits from ownership of shares in firms. The household chooses sequences for \( c, m^{np}, \) and \( a \) so as to maximize (50) subject to (51) and the no-Ponzi-game borrowing constraint (26), taking as given \( a(0) \) and the time paths of \( \tau, R, x, \) and \( \pi. \) The first-order conditions associated with the household’s optimization problem are (28), (29), and (31) and (26) holding with equality. Combining (28), (29), and (11) yields

\[ c = c(\lambda, \pi); \quad c_\lambda < 0, \quad c_\pi u_{cm} \leq 0 \]  

Firms

The production technology and market structure are identical to those assumed in section 3. The difference with the Rotemberg model stems from the source of nominal rigidities. Following Calvo (1983), suppose that a firm can change the nominal price of the good it produces only when it receives a price-change signal. If the firm does not receive a signal, then its price is assumed to increase automatically at the steady-state inflation rate. The probability of receiving a price-change signal between periods \( t \) and \( s > t \) is assumed to be given by

\[ 1 - e^{-\delta(s-t)}, \quad \delta > 0. \]

Consider the problem faced by firm \( j \) that receives a price-change signal at time \( t. \) The expected stream of profits associated with a particular price \( P^j(t) \) is given by

\[ \Pi(P^j) = \int_t^{\infty} e^{-\delta(s-t)} e^{-r(s-t)} \lambda(s) \left[ \frac{P^j(t)e^{\pi^*(s-t)}}{P(s)} \right] Y^d(s) d \left( \frac{P^j(t)e^{\pi^*(s-t)}}{P(s)} \right) - R(s)m^{np}(s) ds. \]
the events in which the firm receives a price-change signal after time \( t \) because they are irrelevant to the firm’s current price-setting decision. The present discounted value of the firm’s profits are multiplied by \( e^{-\delta(s-t)} \), the probability that the price set in \( t \) will still be in place at time \( s \). The firm discounts profits accruing at time \( s \) using the pricing kernel \( e^{-r(s-t)} \lambda(s) \) that results from the representative household’s optimization problem. This kernel is deterministic because households are assumed to be able to insure against firm-specific risks by holding a portfolio containing shares from all firms in the economy. The firm chooses \( P^j(t) \) so as to maximize \( \Pi(P^j) \), subject to the constraint that sales are demand determined:

\[
y(m^j) \geq Y^d d \left( \frac{P^j}{P} \right).
\]

The first-order condition associated with this optimization problem is

\[
0 = \int_t^\infty e^{-(\delta+r)s} \lambda(s) Y^d(s) d \left( \frac{P^j(t)e^{\pi^*(s-t)}}{P(s)} \right) \left[ \frac{P^j(t)e^{\pi^*(s-t)}}{P(s)} \frac{1+\eta}{\eta} - \frac{R(s)}{y'(m^P(s)j)} \right] ds,
\]

where, as in section 3, \( \eta < -1 \) denotes the price elasticity of the demand faced by an individual firm and is assumed to be constant. The expression within square brackets is the difference between marginal revenue and marginal cost. Thus, the firm chooses to set today’s price so that on average marginal revenue equals marginal cost.

**Equilibrium**

In a symmetric equilibrium all firms that receive a price-change signal will choose the same price. Let this price be denoted by \( \mathcal{P}(t) \). Let \( p(t) = \mathcal{P}(t)/P(t) \). Then equation (55) can be written as

\[
0 = \int_t^\infty e^{-(\delta+r)s} \lambda(s) Y^d(s) d \left( p(t)e^{-\int_t^s [\pi(r) - \pi^*]dr} \right) \left[ \frac{1+\eta}{\eta} p(t)e^{-\int_t^s [\pi(r) - \pi^*]dr} - \frac{R(s)}{y'(m^P(s)j)} \right] ds.
\]

Linearizing this expression around the steady state yields

\[
0 = \int_t^\infty e^{-(\delta+r)s} \lambda(s) Y^d(s) \left[ \frac{1+\eta}{\eta} \left( [p(t) - p^*] - \int_t^s [\pi(r) - \pi^*]dr \right) - \frac{p'}{y'} [\pi(s) - \pi^*] + \frac{R^* y''}{y'^2} [m^P(s)j - m^P*] \right] ds.
\]

Assume that the consumption good is a composite of the goods produced by each firm. Let the aggregator function be of the Dixit-Stiglitz form with an elasticity of substitution across goods of \( \eta \). Then, the price of the composite good is given by

\[
P(t) = \left[ \int_{-\infty}^t \delta e^{-\delta(t-s)} \mathcal{P}(s)^{1+\eta} \right]^{\frac{1}{1+\eta}} ds,
\]

Differentiate this expression to obtain

\[
\pi(t) - \pi^* = \frac{\delta}{1+\eta} \left[ p(t)^{1+\eta} - 1 \right],
\]

which after linearizing can be written as

\[
[p(t) - p^*] = \frac{1}{\delta} [\pi(t) - \pi^*]
\]
Using this equation to eliminate \( p(t) - p^* \) from equation (56) and differentiating the result with respect to \( t \) yields

\[
\dot{\pi} = r[\pi - \pi^*] + (\delta + r)\delta \frac{\eta}{1 + \eta} \left[ -\frac{\rho'}{y'}[\pi - \pi^*] + \frac{R^*y''}{y'^2}[m^{pj} - m^{p*}] \right]. \tag{58}
\]

Using equations (52) and (57) and the fact that in equilibrium \( y(m^{pj}) = cd(p) \) one can express \( m^{pj} \) as a function of \( \lambda \) and \( \pi \), whose linearized form is

\[
m^{pj} - m^{p*} = \frac{1}{y}[c_\lambda(\lambda - \lambda^*) + (c_\pi + \eta/\delta)(\pi - \pi^*)] \]

Finally, use this expression to eliminate \( (m^{pj} - m^{p*}) \) from (58), to get the following aggregate supply equation, or new Keynesian Phillips curve:

\[
\dot{\pi} = \tilde{A}_{21}(\lambda - \lambda^*) + \tilde{A}_{22}(\pi - \pi^*) \tag{59}
\]

where

\[
\begin{align*}
\tilde{A}_{21} &= (\delta + r)\delta \frac{y''}{y^2} c_\lambda > 0 \\
\tilde{A}_{22} &= r - (\delta + r)\delta \left[ \frac{\rho'}{y'} \frac{\eta}{1 + \eta} - \frac{y''}{y'^2}(c_\pi + \eta/\delta) \right]
\end{align*}
\]

The remaining equilibrium conditions are identical to those of the Rotemberg sticky-price model developed in section 3. Comparing \( \tilde{A}_{21} \) with \( A_{21} \) in the aggregate supply function of the Rotemberg model (equation (42)), it follows that the determinants of the Jacobian matrices of the Rotemberg and Calvo-Yun models have the same sign. This implies that the results on local indeterminacy under passive monetary policy are identical under both models. Furthermore, by an analysis similar to the one carried out in section 3, it is possible to show that, like \( A_{22}, \tilde{A}_{22} \) may take either sign. This is important because it implies that, like the Rotemberg model, the Calvo-Yun model can generate local indeterminacy under active monetary policy (regardless of the stance of fiscal policy). This result is entirely due to the assumption that money affects real variables through production. As mentioned earlier, in the Calvo-Yun model without money in the production function, the trace of the Jacobian is always positive and equal to \( r \).

**B Proof of proposition 3.3**

In the economy under analysis, the equilibrium conditions (37) and (38) take the form

\[
\begin{align*}
\frac{\dot{\lambda}}{\lambda} &= (1 - a)(\pi - \pi^*) \tag{60} \\
\dot{\pi} &= r(\pi - \pi^*) - \gamma^{-1}\lambda^{(s-1)/s} \left[ 1 + \eta \left( 1 - \frac{R^* + a(\pi - \pi^*)}{\alpha\lambda^{(1-\alpha)/as}} \right) \right] \tag{61}
\end{align*}
\]

To prove orbital stability, we use the formula provided by Guckenheimer and Holmes (1983, p. 152), which requires a change of variables and expressing the above system at the Hopf bifurcation as

\[
\begin{bmatrix}
\dot{u} \\
\dot{v}
\end{bmatrix} = \begin{bmatrix}
0 & -\omega \\
\omega & 0
\end{bmatrix} \begin{bmatrix}
u \\
v
\end{bmatrix} + \begin{bmatrix}
f(u, v) \\
g(u, v)
\end{bmatrix}
\]

24
where \( \omega \) is a function of the parameters of the model and \( f(\cdot, \cdot) \) and \( g(\cdot, \cdot) \) satisfy \( f(0, 0) = g(0, 0) = 0 \)
and \( f_i(0, 0) = g_i(0, 0) = 0 \) for \( i = 1, 2 \); that is, \( f(\cdot, \cdot) \) and \( g(\cdot, \cdot) \) have no constant or linear terms.
The Hopf bifurcation is supercritical (and thus stable cycles exist) if
\[
\kappa \equiv (f_{uuu} + f_{uvv} + g_{uuv} + g_{vvv}) + \frac{1}{\omega}[f_{uv}(f_{uu} + f_{vv}) - g_{uv}(g_{uu} + g_{vv}) - f_{uu}g_{aa} + f_{vv}g_{a}] < 0
\]
at \( u = v = 0 \). We obtain this condition by steps.

**STEP 1:** Let \( p = \pi - \pi^* \) and \( z = \ln(\lambda/\lambda^*) \), where \( \lambda^* \) denotes the steady-state value of \( \lambda \). Then equations (60) and (61) can be written as
\[
\begin{bmatrix}
\dot{z} \\
\dot{p}
\end{bmatrix} =
\begin{bmatrix}
0 & 1-a \\
-M(\beta - \sigma) & 0
\end{bmatrix}
\begin{bmatrix}
z \\
p
\end{bmatrix} +
\begin{bmatrix}
0 \\
G(z, p)
\end{bmatrix}
\]
where \( \sigma = \frac{s-1}{s}, \beta = \sigma + \frac{\alpha-1}{\alpha s}, M = \gamma^{-1}(1 + \eta) \lambda^*\sigma < 0, \) and \( N = \gamma^{-1}\eta\alpha^{-1}a\lambda^*\beta < 0. \)

**STEP 2:** Write the system of differential equations as:
\[
\begin{bmatrix}
\dot{z} \\
\dot{p}
\end{bmatrix} =
\begin{bmatrix}
0 & 1-a \\
-M(\beta - \sigma) & 0
\end{bmatrix}
\begin{bmatrix}
z \\
p
\end{bmatrix} +
\begin{bmatrix}
0 \\
G(z, p)
\end{bmatrix}
\]
where
\[
G(z, p) = M[e^{\beta z} - e^{\sigma z} - (\beta - \sigma)z] + p(Ne^{\beta z} + r)
\]
Note that the matrix in the linear part satisfies:
\[
DET = -M(\beta - \sigma)(1-a)
\]
\[
TRACE = 0
\]
Assume that \( a > 1 \) and \( N = -r \). That is, the parameter configuration corresponds to a Hopf bifurcation. Then letting \( \omega = \sqrt{DET} \), \( \mu = \sqrt{\frac{M(\beta - \sigma)}{a-1}} \), \( v = -z \), and \( u = \mu^{-1} p \), the two differential equations become:
\[
\begin{bmatrix}
\dot{u} \\
\dot{v}
\end{bmatrix} =
\begin{bmatrix}
0 & -\omega \\
\omega & 0
\end{bmatrix}
\begin{bmatrix}
u \\
v
\end{bmatrix} +
\begin{bmatrix}
f(u, v)
\end{bmatrix}
\]
where
\[
f(u, v) = \frac{M}{\mu}[e^{-\beta v} - e^{-\sigma v} + (\beta - \sigma)v] + u(Ne^{-\beta v} + r)
\]
Note that \( f(0, 0) = f_u(0, 0) = f_v(0, 0) = 0 \). Also, in our formulation \( g(\cdot, \cdot) = 0 \).

**STEP 3:** The relevant derivatives of \( f \) are
\[
f_{vv} = \frac{M}{\mu}[\beta^2 e^{-\beta v} - \sigma^2 e^{-\sigma v}] + \mu u N \beta^2 e^{-\beta v}
\]
\[
f_{uv} = 0
\]
\[
f_{uu} = 0
\]
\[
f_{uuu} = 0
\]
\[
f_{uvv} = -\beta N e^{-\beta v}
\]
\[
f_{uvw} = \beta^2 N e^{-\beta v}
\]
Setting \( u = v = 0 \), it follows that
\[
\kappa = (\beta N) [\beta - \mu^{-1} \omega^{-1} M (\beta^2 - \sigma^2)]
\]
Noting that \( \mu^{-1} \omega^{-1} M = (\beta - \sigma)^{-1} \) and recalling that \( N = -r \), \( \kappa \) reduces to
\[
\kappa = \beta r \sigma
\]
Thus \( \kappa \) will be less than zero if and only if
\[
1 < s < \frac{1}{\alpha}
\]

C Backward- and forward-looking interest-rate feedback rules

C.1 Flexible-price model

C.1.1 Backward-looking feedback rules

Differentiating (47) with respect to time yields
\[
\dot{\pi}^p = b(\pi - \pi^p)
\] (62)
In equilibrium, the evolution of the nominal interest rate is given by
\[
\lambda'(R) \dot{R} = \lambda(R)[r + \pi - R]
\] (63)
where
\[
\lambda'(R) = [u_{c\epsilon'} y' m_{\rho} + u_{cm} (m_{\epsilon} m_{\rho} y' m_{\rho} + m_{\epsilon} m_{\rho})]
\] (64)
Using equation (46) to eliminate \( \pi \) from (62) and (63) and linearizing around the steady state results in the following system of linear differential equations, valid for \( 0 < q \leq 1 \):
\[
\begin{bmatrix}
\dot{R} \\
\dot{\pi}^p
\end{bmatrix} = \begin{bmatrix}
\frac{\lambda}{\lambda'} \left( \frac{1}{\rho' q} - 1 \right) & -\frac{\lambda}{\lambda'} \left( \frac{1-q}{q} \right) \\
\rho^{-1} & \frac{\lambda}{\lambda'} \left( \frac{1}{\rho' q} - 1 \right)
\end{bmatrix} \begin{bmatrix}
R - R^* \\
\pi^p - \pi^*
\end{bmatrix}; \quad q \in (0, 1].
\]
Let \( J \) denote the Jacobian matrix of this system. Because \( R \) is a jump variable and \( \pi^p \) is predetermined, the real allocation is locally unique if the real parts of the eigenvalues of \( J \) have opposite signs, or, equivalently, if the determinant of \( J \) is negative. On the other hand, the real allocation is locally indeterminate if both eigenvalues have negative real parts, that is, if the determinant of \( J \) is positive and its trace is negative. The determinant and trace of \( J \) are given by
\[
\text{det}(J) = \frac{\lambda}{\lambda'} \frac{b}{\rho' q} (\rho' - 1)
\]
\[
\text{trace}(J) = \frac{\lambda}{\lambda'} \left( \frac{1}{\rho' q} - 1 \right) - \frac{b}{q}
\]
If \( u_{cm} > 0 \) and \( y' = 0 \), then equation (64) implies that \( \lambda' \) is negative. It follows that the equilibrium is unique if \( \rho' > 1 \) and is indeterminate if \( \rho' < 1 \). If \( u_{cm} < 0 \) and \( y' = 0 \) or if \( u_{cm} = 0 \) and \( y' > 0 \), then
\( \lambda' > 0 \). Thus, the equilibrium is always locally determinate when \( \rho' < 1 \). If \( \rho' > 1 \), the determinant of \( J \) is positive, so that the real parts of the roots of \( J \) have the same sign as the trace of \( J \). However, the trace of \( J \) can have either sign. If the trace is positive, then no equilibrium converging to the steady state exists. If it is negative, the equilibrium is indeterminate. For large enough values of \( \rho' \) the trace of \( J \) becomes negative and the equilibrium is indeterminate. Furthermore, the larger \( q \) and/or the larger \( b \), the smaller is the minimum value of \( \rho' \) above which the equilibrium becomes indeterminate. As \( q \to 1 \) and/or \( b \to \infty \), the equilibrium becomes indeterminate for any \( \rho' > 1 \).

If \( q = 0 \), the equilibrium conditions reduce to a single differential equation:

\[
\dot{\pi}^p = A[r + \pi^p - \rho(\pi^p)],
\]

where

\[
A = \frac{b}{b \rho' \lambda' / \lambda - 1}.
\]

Because \( \pi^p \) is a predetermined variable, the equilibrium cannot be locally indeterminate. The equilibrium exists locally if \( A(1 - \rho') < 0 \) and fails to exist locally if \( A(1 - \rho') > 0 \). If \( u_{cm} > 0 \) and \( y' = 0 \), then \( \lambda' < 0 \). It follows that the equilibrium is determinate if \( \rho' < 1 \) and does not exist locally if \( \rho' > 1 \). If \( u_{cm} < 0 \) and \( y' = 0 \) or \( u_{cm} = 0 \) and \( y' > 0 \), then \( \lambda' > 0 \). Thus, for large enough values of \( b \) (\( b > \lambda'/\lambda' \)), the equilibrium exists for \( \rho' > 1 \) as well as for \( \rho' \) close enough to 0. For low enough values of \( b \) (\( b < \lambda'/\lambda' \)), the equilibrium exists for \( \rho' < 1 \) as well as for \( \rho' > 1 \) and large enough, but does not exist for moderately active feedback rules.

### C.1.2 Forward-looking feedback rules

It is straightforward to show that the system describing the equilibrium dynamics is identical to the one obtained under backward-looking feedback rules with \( b \) replaced by \(-d\) and \( \pi^p \) replaced by \( \pi^f \). Thus, in this case, provided \( q > 0 \), the determinant and trace of the Jacobian become

\[
det(J) = -\frac{\lambda}{\lambda'} \frac{d}{\rho' q} (\rho' - 1)
\]

\[
trace(J) = \frac{\lambda}{\lambda'} \left( \frac{1}{\rho' q} - 1 \right) + \frac{d}{q}
\]

Because neither \( R \) nor \( \pi^f \) are predetermined variables, the real allocation is locally unique if both eigenvalues of \( J \) have positive real parts (\( \det(J) > 0 \) and \( \text{trace}(J) > 0 \)) and is locally indeterminate if at least one of the roots of \( J \) has a negative real part (\( \det(J) < 0 \)). If \( u_{cm} < 0 \) and \( y' = 0 \) or \( u_{cm} = 0 \) and \( y' > 0 \), then \( \lambda' > 0 \). If \( \rho' > 1 \), then \( \det(J) < 0 \). If \( \rho' < 1 \), then both \( \det(J) > 0 \) and \( \text{trace}(J) > 0 \). On the other hand, if \( y' = 0 \) and \( u_{cm} > 0 \), then \( \lambda' < 0 \). If \( \rho' < 1 \), then \( \det(J) < 0 \). When \( \rho' > 1 \), we have that \( \det(J) > 0 \) but \( \text{trace}(J) \) can have either sign. For \( q \) or \( d \) large, \( \text{trace}(J) \) is positive. For \( q \) and \( d/q \) small enough, \( \text{trace}(J) \) becomes negative.

If \( q = 0 \), the equilibrium conditions reduce to (65) and (66) with \( \pi^p \) replaced by \( \pi^f \) and \( b \) by \(-d\). Because \( \pi^f \) is non-predetermined, at least one equilibrium always exists locally. The equilibrium is locally indeterminate if \( A(1 - \rho') < 0 \) and is locally determinate if \( A(1 - \rho') > 0 \). If \( u_{cm} < 0 \) and \( y' = 0 \) or \( u_{cm} = 0 \) and \( y' > 0 \), then \( \lambda' > 0 \). It follows that the equilibrium is determinate if \( \rho' > 1 \) and is indeterminate if \( \rho' < 1 \). If \( u_{cm} > 0 \) and \( y' = 0 \), then \( \lambda' < 0 \). Thus, for large enough values of \( d \) (\( d > -\lambda'/\lambda' \)), the equilibrium is determinate for \( \rho' > 1 \) as well as for \( \rho' \) close enough to 0. For low enough values of \( d \) (\( d < -\lambda'/\lambda' \)), the equilibrium is determinate for \( \rho' < 1 \) as well as for \( \rho' > 1 \) and large enough, but is indeterminate for moderately active feedback rules.
### C.2 Sticky-price model

To facilitate the analysis, we reproduce here the equilibrium conditions for the sticky-price model.

\[
\dot{\lambda} = \lambda [r + \pi - R]
\]

\[
\gamma \dot{\pi} = \gamma r (\pi - \pi^*) - y (m^p(\lambda, R)) \lambda \left[ 1 + \eta \left( 1 - \frac{R}{y'(m^p(\lambda, R))} \right) \right]
\]

\[
\dot{a} = [R - \pi] a - R [m^{np}(y(m^p(\lambda, R)), R) + m^p(\lambda, R)] - \tau
\]

\[
\tau = \begin{cases} \tau & \text{non-Ricardian fiscal policy} \\ \alpha a - R [m^{np}(y(m^p(\lambda, R)), R) + m^p(\lambda, R)] & \text{Ricardian fiscal policy} \end{cases}
\]

\[
0 = \lim_{t \to \infty} e^{-\int_0^{t[R-\pi]} ds} a(t)
\]

where \(m^p(\lambda, R)\) results from replacing \(\rho(\pi)\) by \(R\) in equation (35) and is decreasing in \(\lambda\) and increasing (decreasing) in \(R\) if \(u_{cm}\) is negative (positive).

#### C.2.1 Backward-looking feedback rules

Combining (46) and (47) to eliminate \(\pi^p\) and linearizing around the steady state yields

\[
\hat{R} = q \rho' \hat{\pi} + \rho' (\pi - \pi^*) - b (R - R^*)
\]

Using this expression and linearizing equations (67) and (68), the evolution of \(\lambda\), \(\pi\), and \(R\) is described by the following system of differential equations:

\[
\begin{pmatrix}
\frac{d}{dt}\lambda \\
\frac{d}{dt}\pi \\
\frac{d}{dt}R
\end{pmatrix} = A
\begin{pmatrix}
\lambda - \lambda^* \\
\pi - \pi^* \\
R - R^*
\end{pmatrix}
\]

where

\[
A = \begin{bmatrix}
0 & u_c & -u_c \\
A_{21} & r & A_{23} \\
\rho'(b + qr) & -b + \rho' q A_{23}
\end{bmatrix}
\]

and

\[
A_{21} = -\frac{u_c c' \eta R^* y' m^p_{\lambda}}{\gamma y'^2} > 0
\]

\[
A_{23} = \left( \frac{u_c c' \eta}{\gamma y'} \right) \left( 1 - \frac{R^* y' m^p_{\lambda}}{y R} \right)
\]

Because \(\pi^p\) is predetermined and \(R\) is a function of \(\pi\) and \(\pi^p\), it follows that a linear combination of \(\pi - \pi^*\) and \(R - R^*\) is predetermined. In addition, \(\lambda\) is a jump variable. Assume first that fiscal policy is Ricardian. Then the local determinacy of the perfect-foresight equilibrium is governed by the eigenvalues of \(A\). Specifically, the equilibrium is indeterminate if the real part of at least two roots of \(A\) are negative.

Assume that monetary policy is active (\(\rho' > 1\)). We found in section 3 that under a purely contemporaneous feedback rule, the combination of Ricardian fiscal policy and active monetary policy can render the real allocation either locally determinate or indeterminate, depending on parameter values. By contrast, if the feedback rule is sufficiently backward looking (\(q, b \to 0\), the
equilibrium is always unique. To see this, note that when $\rho' > 1$, the determinant of $A$, which is given by

$$\text{Det}(A) = bu_cA_{21}(1 - \rho'),$$

is negative. Thus, the number of roots of $A$ with a negative real part is either one or three. If at the same time the trace of $A$ is positive, then the number of roots of $A$ with a negative real part is exactly equal to one. The trace of $A$ is given by

$$\text{Trace}(A) = r - b + \rho'qa_{23}.$$

Clearly, as $q$ and $b$ approach zero, the trace of $A$ becomes positive.

Assume now that monetary policy is passive ($\rho' < 1$). As shown in section 3, the combination of Ricardian fiscal policy and passive monetary policy always renders the real allocation locally indeterminate under a purely contemporaneous feedback rule. It is straightforward to show that introducing a backward-looking component in the feedback rule cannot bring about local determinacy. To see this, note that if $\rho' < 1$, the determinant of $A$ is positive, so the number of roots of $A$ with a negative real part can never be exactly equal to one. Unlike the case of purely contemporaneous rules, though, a perfect-foresight equilibrium in which the real allocation converges to its steady state may not exist. This will be the case when all eigenvalues of $A$ have positive real parts. However, if the feedback rule is highly contemporaneous either because $q$ approaches unity or because $b$ approaches infinity, then the equilibrium is always locally indeterminate. To see this, we appeal to the following condition:\footnote{This is an application to our special case of a more general theorem due to Routh (see Gantmacher, 1960).} The number of roots of $A$ with positive real parts is equal to the number of variations of sign in the scheme:

$$-1 \quad \text{Trace}(A) \quad -B + \frac{\text{Trace}(A)}{\text{Det}(A)} \quad \text{Det}(A),$$

where

$$B = \text{Sum of the principal minors of } A = -u_cA_{21}(1 - q\rho') - rb - b\rho'a_{23}.$$

This condition implies that in order for all roots of $A$ to have a positive real part, it is necessary that both $B$ and the trace of $A$ be positive. Consider first the case in which $q \to 1$. Then the trace of $A$ is positive if and only if $r + \rho'a_{23} > 0$. But $r + \rho'a_{23} > 0$ implies that $B$ is negative. To see that the equilibrium is also indeterminate when $b \to \infty$, note that in this case the trace of $A$ becomes negative.\footnote{Highly backward-looking policies do not necessarily eliminate the local existence of equilibrium. For example, the equilibrium is indeterminate when the feedback rule places a relatively high weight on inflation rates observed in the distant past ($b \to 0$). This is because in this case $B$ is negative.}

If fiscal policy is non-Ricardian, then the local determinacy of the perfect-foresight equilibrium is governed by the eigenvalues of a four-by-four Jacobian matrix defining the law of motion of $\lambda$, $\pi$, $R$, and $a$. One of the eigenvalues of this matrix is $r > 0$ and the other three are those of the matrix $A$. Because $a$ and a combination of $R$ and $\pi$ are predetermined, the equilibrium is locally unique if and only if the Jacobian has exactly two roots with positive real parts. If monetary policy is active, it follows from our previous analysis that the Jacobian matrix has either one or three roots with negative real parts. Thus, local determinacy is impossible. This is the same result as under purely contemporaneous feedback rules. However, if the feedback rule is strongly backward-looking ($b, q \to 0$), then no equilibrium in which the real allocation converges to its steady state exists. If...
monetary policy is passive, the determinant of the Jacobian is positive, implying that there exist either two or zero roots with negative real parts. Thus, as in the case of purely contemporaneous feedback rules, local indeterminacy is impossible. However, unlike the case of contemporaneous rules, under backward-looking monetary policy an equilibrium may not exist.

C.2.2 Forward-looking feedback rules

Finally, consider the case of a forward-looking feedback rule like the one described by equations (48) and (49). We will limit the analysis to the case of Ricardian fiscal policy, leaving the non-Ricardian case to the reader. The law of motion of the vector \((\lambda \pi R)\) is described by a Jacobian matrix that is identical to \(A\) with \(b\) replaced by \(-d\). In addition, the three variables of the system are non-predetermined. Therefore, as long as the Jacobian has at least one root with a negative real part, the perfect-foresight equilibrium is locally indeterminate. Local determinacy requires that all three roots have positive real parts.

Suppose first that monetary policy is active. Under contemporaneous feedback rules, the equilibrium can be locally determinate or indeterminate. The same result obtains under forward-looking rules. However, if the rule is strongly forward-looking \((d, q \to 0)\), the equilibrium is necessarily locally indeterminate. To see this, note that in this case the trace of the Jacobian tends to \(r > 0\) and that \(B\) tends to \(-u_r A_{21} < 0\), so that the pattern of signs in the scheme (69) is \(- + ++\). If monetary policy is passive, then the determinant is negative, therefore, as in the case of purely contemporaneous rules, the equilibrium is locally indeterminate.
References


