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Unique Equilibrium in Contests with Incomplete Information

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Unique Equilibrium in Contests with Incomplete Information^{*}

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Abstract. Szidarovszky and Okuguchi (Games and Economic Behavior, 6 1997) have provided useful conditions for the existence of a unique pure-7 strategy Nash equilibrium in rent-seeking games of complete information. In 8 this paper, we generalize their results to contests with incomplete informa-9 tion. Two assumptions are imposed on the information structure. First, the 10 players' valuations of winning are assumed to be multiplicatively separable 11 (which includes the polar cases of private values and pure common value). 12 Second, it is assumed that a player is never certain to be the only one with 13 a positive budget. It is also shown that, unless the budgets of all players are 14 zero in all states, at least two players realize a positive expected net rent. 15

¹⁶ Keywords Contests · Equilibrium existence and uniqueness · Incomplete
 ¹⁷ information · Rent dissipation

¹⁸ JEL Classification $D72 \cdot C72$

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¹⁹ 1 Preliminaries

20 1.1 Introduction

Over the course of the past several decades, contest theory has emerged 21 through the study of substantial economic problems in areas such as po-22 litical campaigning, lobbying, R&D, legal dispute, promotion tournaments, 23 marketing, and sports.¹ Based upon game-theoretic methods, the literature 24 has sought to characterize the extent of rent dissipation in equilibrium, i.e., 25 the share of the contested rent that is spent by the competing parties in an 26 attempt to win the contest. Of much value for any such applied analysis, 27 however, is typically also the assurance that an equilibrium solution exists 28 and is unique.² 29

The literature has considered two main classes of models, the perfectly discriminating contest (or all-pay auction) and the imperfectly discriminating contest. This paper deals with imperfectly discriminating contests, for which Tullock (1980)'s rent-seeking game is an important example. In the case of complete (or public) information, the problem of equilibrium existence and uniqueness has been studied quite thoroughly.³ For rent-seeking games with

¹See Corchón (2007) for an introduction to the theory of contests.

²Indeed, the existence of a unique pure-strategy Nash equilibrium is generally a useful property for modeling frameworks, for reasons such as analytical convenience, predictive power, comparative statics, and global stability.

³Pérez-Castrillo and Verdier (1992) offer a complete characterization of the symmetric pure-strategy Nash equilibrium in the Tullock contest. Szidarovszky and Okuguchi (1997) show that a unique equilibrium exists in rent-seeking games with logit technologies of strictly decreasing returns. Nti (1999) derives a necessary and sufficient condition for the existence of a unique pure-strategy Nash equilibrium in the Tullock contest with asymmetric valuations. Cornes and Hartley (2005) study the pure-strategy equilibrium in asymmetric contests with general technologies. Yamazaki (2008, 2009) reduces further the smoothness assumptions and allows for risk aversion and financial constraints.

incomplete information, however, such comprehensive results have not been 36 available, in any case not regarding the uniqueness of the equilibrium.⁴ This 37 is unfortunate because private information in contests is a realistic assump-38 tion,⁵ and known to impact on the strategic incentives of players in a variety 39 of interesting ways.⁶ Moreover, studying contests with asymmetric informa-40 tion typically presupposes some knowledge of the corresponding equilibrium 41 set. Thus, there is a gap in the literature that concerns general conditions for 42 the uniqueness of the equilibrium in contests with incomplete information. 43 The purpose of the present paper is it to fill this gap.⁷ 44

In this paper, we consider rent-seeking games in which any uncertainty 45 about the primitives of the contest is conveniently captured in a single (po-46 tentially multi-dimensional) state variable. Specifically, the state of the world 47 pins down the effective number of players, the scale economies and any poten-48 tial bias of the contest technology, players' valuations of winning, their cost 49 functions, and any budget constraints. Each contestant then receives a pri-50 vate signal that is not observable to any other contestant. Thus, depending 51 on the nature of the signal, a contestant may be either completely informed, 52 completely uninformed, or possess some arbitrary partial information about 53 the state of the world. 54

⁴The literature on contests with incomplete information is surveyed in Subsection 1.2. ⁵For example, in a patent race, it is often hard to tell for one market participant how advanced her opponents are with their research. Other examples are readily available.

⁶For example, as Hurley and Shogren (1998a) have pointed out, asymmetric information turns the expenditure of a player into an uncertain investment, which may weaken her incentives. This, in turn, induces the other player to either increase or decrease her expenditures, depending on whether she is underdog or favorite in that situation.

⁷In fact, since the literature does not provide existence results sufficiently general to cover our asymmetric setting with a state-dependent success function and budget constraints, we will offer a self-contained discussion of existence as well.

Our results directly generalize the well-known conditions of Szidarovszky 55 and Okuguchi (1997) to contests of incomplete information. Two assump-56 tions are imposed on the information structure of the contest. First, to ensure 57 uniqueness, it is assumed that players' valuations are multiplicatively separa-58 ble, i.e., that they can be written as a product of a private-value component 59 and a public-value component. This assumption covers, in particular, the 60 polar cases of private values and pure common value, as well as mixed set-61 tings. Second, to ensure existence, it is assumed that a player is never certain 62 to be the only one with a positive budget. Under these two assumptions on 63 the information structure, we prove that there exists a unique pure-strategy 64 Nash equilibrium. We also show that, unless all players have zero budgets in 65 all states of the world, at least two players will earn a positive expected net 66 rent. 67

The rest of the paper is structured as follows. The remainder of the present section discussed some related literature. Section 2 describes the set-up. Section 3 presents our main result, the uniqueness theorem. The corresponding existence result is derived in Section 4. Section 5 considers the extent of rent dissipation in contests with incomplete information. Implications for specific settings are outlined in Section 6. Section 7 concludes. Technical lemmas have been relegated to an Appendix.

75 1.2 Related literature

This section briefly reviews some papers on contests with incomplete information, where we focus on the existence and uniqueness of the pure-strategy ⁷⁸ equilibrium. For a more complete account of the individual contributions,⁷⁹ the reader is referred to the original works.

In a seminal paper, Hurley and Shogren (1998a) consider a model with 80 one-sided asymmetric information and private valuations. Assuming that the 81 informed player is never discouraged from competing in the contest, they find 82 a unique equilibrium. Hurley and Shogren (1998b) use the index approach to 83 show that there is at most one interior equilibrium in any two-player lottery 84 contest with private valuations and with two types for one player and three 85 for the other, where types may be correlated. Malueg and Yates (2004) study 86 the unique symmetric equilibrium in a symmetric two-player lottery contest, 87 where each player may possess one of two equally likely valuations. Sui (2009) 88 extends that model by introducing the possibility of resale. Münster (2009) 89 finds a unique equilibrium in a two-player lottery contest with independent ۹N valuations that are either positive or zero. Schoonbeek and Winkel (2006) 91 characterize the unique equilibrium in an *n*-player contest with potential in-92 activity, where one player has private information about her valuation and all 93 other players are identical. More recently, Einy et al. (2013) prove existence 94 for general (state-independent) success functions and unbounded budgets, 95 and also derive a uniqueness result for a two-player common-value Tullock 96 contest with identical linear costs in which players' information partitions 97 are nested. 98

A number of papers allow for continuous type distributions. Fey (2008) studies the problem of the existence of a pure-strategy Nash equilibrium in the symmetric two-player lottery contest with uniformly distributed, privately known marginal costs. Ryvkin (2010) examines existence in symmet-

ric *n*-player contests with likewise independently distributed private mar-103 ginal costs, yet allowing for a wider class of contest success functions and 104 for more general probability densities functions. Wärneryd (2003, 2012) and 105 Rentschler (2009) find a unique equilibrium in common-value contests be-106 tween players that are either privately informed or completely uninformed. 107 Based on a contraction argument, Wasser (2013a) finds a sufficient condition 108 for uniqueness for a modified lottery contest with heterogeneous continu-109 ous distributions of marginal costs. Wasser (2013b) proves the existence of a 110 monotone equilibrium in continuous contests with interdependent valuations, 111 yet does not discuss uniqueness. 112

Models of population uncertainty have been studied by several authors. In these models, each player may enter the contest with some exogenous independent probability. Depending on the set-up, the potential number of contestants is either finite (Münster, 2006; Lim and Matros, 2009; Fu et al., 2011) or unbounded (Myerson and Wärneryd, 2006). Münster (2006) proves uniqueness of the pure-strategy equilibrium in this setting.

Clark (1997) characterizes the pure-strategy equilibrium in a lottery con-119 test in which players are uncertain about the success function. Such uncer-120 tainty may result, for example, when players do not know the exact pref-121 erences of the contest administrator, or if players have private information 122 about their "talent." Epstein and Mealem (2013) study a lottery contest 123 with uncertainty about abilities in which one player has perfect information, 124 while the other player knows only her own ability. They characterize the 125 equilibrium for two types, and also explore the case of more than two types.⁸ 126

⁸Baik and Shogren (1995) have considered a model with uncertainty about players'

As this overview shows, general results regarding the uniqueness of the pure-strategy equilibrium in contests of incomplete information have not been available so far.

130 2 Set-up

We consider a contest between $n \ge 2$ players. All uncertainty about the primitives of the contest is summarized in a state variable ω , which is drawn ex ante from a finite state space Ω .⁹ Player *i*'s (i = 1, ..., n) expenditure $x_i \ge 0$ in the contest causes the production of $f_{i,\omega}(x_i) \ge 0$ "lottery tickets" in state ω . Consequently, player *i*'s probability of winning the contest is given by

$$p_{i,\omega}(x_1, ..., x_n) = \frac{f_{i,\omega}(x_i)}{\sum_{j=1}^n f_{j,\omega}(x_j)},$$
(1)

provided the denominator in (1) does not vanish. Otherwise, i.e., if the denominator vanishes, the probability $p_{i,\omega}$ is set equal to some arbitrary value $p_{i,\omega}(0,...,0) \in [0,1)$ such that $\sum_{i=1}^{n} p_{i,\omega}(0,...,0) \leq 1$ for all ω . This clearly includes the two common cases where either $p_{i,\omega}(0,...,0) = \frac{1}{n}$ for any i and ω , or $p_{i,\omega}(0,...,0) = 0$ for any i and ω .

State-contingent production functions arise in a natural way when players
are uncertain about their abilities, as in Clark (1997) or Epstein and Mealem
(2013). These possibilities are obviously covered by our set-up, but cannot
be represented easily in a set-up in which only costs or valuations are state
relative ability before, yet their set-up may not be a game-theoretic one, according to Bolle (1996).

⁹The case of infinite state spaces leads to some technicalities that we prefer not to address in this paper.

147 dependent.

¹⁴⁸ Assume that for all i and ω ,

(A) the function $f_{i,\omega}$ is twice differentiable, strictly increasing and concave, with $f_{i,\omega}(0) = 0$.

This assumption captures the case of weakly decreasing returns of the technology that transforms expenditures into "lottery tickets."

¹⁵³ Player *i*'s net rent in state ω is given by

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$$\Pi_{i,\omega}(x_1,...,x_n) = p_{i,\omega}(x_1,...,x_n)v_i(\omega) - c_{i,\omega}(x_i), \qquad (2)$$

where $v_i(\omega) > 0$ denotes player *i*'s valuation of winning in state ω , and $c_{i,\omega}(x_i)$ is player *i*'s cost of bidding x_i in state ω . We will alternatively refer to $\Pi_{i,\omega}(x_1,...,x_n)$ as player *i*'s payoff in state ω . Assume that for any *i* and ω ,

(B) the function $c_{i,\omega}$ is twice differentiable, strictly increasing and convex, with $c_{i,\omega}(0) = 0$.

Each player *i* observes a signal θ_i (her "type") that is taken from a corresponding signal space Θ_i . The signal θ_i is the value $\theta_i = t_i(\omega)$ of a mapping $t_i : \Omega \to \Theta_i$. Thus, θ_i may be thought of as the realization of the "random variable" t_i . Signals are private information of the respective contestants, i.e., player *i* does not observe the signal $\theta_j = t_j(\omega)$ of any other player $j \neq i$. Note, however, that some primitives of the contest that are directly relevant for player *i* (specifically, her production function, her valuation of winning, and her cost function) may in general be dependent on, or correlated with, other players' signals that are not directly observable to her. For convenience, we write $\mathcal{P}_i(\theta_i) = \{\omega \in \Omega | t_i(\omega) = \theta_i\}$ for type θ_i 's possibility set, i.e., for the set of states in which player *i* observes the signal θ_i . Thus, $\omega \in \mathcal{P}_i(\theta_i)$ is equivalent to $t_i(\omega) = \theta_i$.

Let $x_i^{\max}(\theta_i) \ge 0$ denote the budget of type θ_i . If $x_i^{\max}(\theta_i) = 0$, then type θ_i is forced to remain inactive. Note that the assumption of a finite budget for all types is without loss of generality because no type θ_i would optimally choose an expenditure causing interim expected costs in excess of her highest possible valuation (which is bounded as a consequence of the finiteness of the state space).¹⁰

By a bid function for player *i*, we mean a mapping $\beta_i : \Theta_i \to \mathbb{R}_+$ such that $\beta_i(\theta_i) \in [0, x_i^{\max}(\theta_i)]$. We denote the set of player *i*'s bid functions by B_i . For a profile of bid functions $\beta_{-i} = \{\beta_j\}_{j \neq i} \in B_{-i} = \prod_{j \neq i} B_j$, denote by $\beta_{-i}(t_{-i}(\omega)) = \{\beta_j(t_j(\omega))\}_{j \neq i}$ the corresponding profile of bids resulting in state ω , where $t_{-i}(\omega) = \{t_j(\omega)\}_{j \neq i}$. Similarly, for any $\beta = \{\beta_i\}_{i=1}^n \in B =$ $\prod_{i=1}^n B_i$, we shall write $\beta(t(\omega)) = \{\beta_i(t_i(\omega))\}_{i=1}^n$ for the corresponding profile of bids resulting in state ω , where $t(\omega) = \{t_i(\omega)\}_{i=1}^n$.

Let $q(\omega)$ denote the ex-ante probability of state ω , where we assume $q(\omega) > 0$ without loss of generality. The unconditional probability that signal θ_i realizes is then given by $q_i(\theta_i) = \sum_{\omega \in \mathcal{P}_i(\theta_i)} q(\omega)$. Based on the private signal θ_i received, player *i* forms a posterior belief on Ω , given by a probability $q_i(\omega|\theta_i)$ for each ω . It is assumed that each possible realization of player *i*'s signal occurs with positive probability, i.e., $q_i(\theta_i) > 0$ for any *i*

¹⁰A similar argument has been used by Yamazaki (2008).

and any θ_i . Hence, according to Bayes' rule, $q_i(\omega|\theta_i) = q(\omega)/q_i(\theta_i)$ for any $\omega \in \mathcal{P}_i(\theta_i)$, and $q_i(\omega|\theta_i) = 0$ otherwise. Note that $q_i(\omega|\theta_i) > 0$ is equivalent to $\omega \in \mathcal{P}_i(\theta_i)$, i.e., the support of type θ_i 's posterior is just $\mathcal{P}_i(\theta_i)$. The interim expected payoff for type $\theta_i \in \Theta_i$ is given by the conditional expectation

¹⁹⁶
$$\overline{\Pi}_i(x_i,\beta_{-i},\theta_i) = \sum_{\omega \in \mathcal{P}_i(\theta_i)} q_i(\omega|\theta_i) \Pi_i(x_i,\beta_{-i}(t_{-i}(\omega)),\omega).$$
(3)

¹⁹⁷ A pure-strategy Nash equilibrium is then a profile $\beta^* \in B$ such that

$$\overline{\Pi}_i(\beta_i^*(\theta_i), \beta_{-i}^*, \theta_i) \ge \overline{\Pi}_i(x_i, \beta_{-i}^*, \theta_i)$$
(4)

199 for any i, θ_i and any $x_i \in [0, x_i^{\max}(\theta_i)]$.

200 **3** Uniqueness

²⁰¹ 3.1 Approach to uniqueness

Our approach to uniqueness rests upon J.B. Rosen's (1965) result for con-202 cave *n*-person games with strategy spaces that are convex subsets of some 203 Euclidean space. Rosen (1965) considers the Jacobian matrix J associated 204 with players' marginal payoff functions, and requires that $J + J^T$, i.e., the 205 sum of J and its transpose, be negative definite at all strategy profiles. To 206 obtain some intuition, consider the pseudogradient associated with the pay-207 off functions in an asymmetric two-player lottery contest. I.e., to each pair 208 of bids $(x_1, x_2) \in \mathbb{R}^2_+ \setminus \{(0, 0)\}$, one attaches a vector whose *i*'s component 209 corresponds to player i's marginal payoff, for i = 1, 2. Figure 1 shows the 210

corresponding directional field, in which the length of the pseudogradient at 211 each point is normalized to one.¹¹ At the unique interior equilibrium β^* , the 212 pseudogradient vanishes. Suppose there was another interior equilibrium β^{**} 213 that differs from β^* . Then the inner product between the pseudogradient 214 and the vector pointing from β^{**} to β^{*} would have to vanish at both β^{*} and 215 β^{**} . But under Rosen's (1965) condition on the Jacobian, this inner product 216 turns out to be strictly declining as one moves along the straight line from 217 β^{**} to β^{*} , which is impossible. The argument works, in fact, equally well for 218 boundary equilibria. Hence, there is at most one equilibrium. 219



Figure 1: Illustration of Rosen's (1965) argument.

¹¹In the example drawn, the common valuation of winning is v = 1, and marginal costs are $c_1 = 0.6$ for player 1, and $c_2 = 0.4$ for player 2.

220 3.2 Multiplicative separability

The following assumption of multiplicative separability will be imposed on players' valuation functions.

(C) There is a function $v : \Omega \to \mathbb{R}_{++}$ and, for each i = 1, ..., n, a function $\kappa_i : \Theta_i \to \mathbb{R}_{++}$ such that $v_i(\omega) = v(\omega) \cdot \kappa_i(t_i(\omega))$ for any ω .

This assumption encompasses many of the information structures that 225 have been used in the literature. In a setting with private valuations, for 226 instance, the common-value component can be normalized to unity, i.e., $v \equiv$ 227 1. In this case, every player knows her valuation at the time of bidding. 228 Note that these private valuations can be either independently distributed 229 or correlated. In another example, a pure common value setting, each player's 230 private-value component is normalized to unity, i.e., $\kappa_i \equiv 1$ for i = 1, ..., n. In 231 this case, the value of winning is the same for all players, yet each individual 232 player may possess only incomplete information about the value at the time 233 of bidding. Further settings are feasible.¹² A setting excluded by Assumption 234 (C) is one with truly interdependent valuations. In this case, $v_i(\omega)$ would 235 depend not only on $\theta_i = t_i(\omega)$ but also on $\theta_j = t_j(\omega)$, for at least one 236 $j \neq i$, and in such a way that a representation as in Assumption (C) becomes 237 impossible. However, we are aware of only one paper that has dealt with this 238 case so far, which is Wasser (2013b).¹³ 239

¹²For example, in an international conflict about an oil field located under the Northern polar cap, $v(\omega)$ might correspond to the size of the oil field, and $\kappa_i(\theta_i)$ to a countryspecific parameter. This setting is, in general, neither one of private values nor one of pure common value.

¹³While it must be conjectured that multiplicity of equilibria is a possibility with interdependent valuations, we have not managed to come up with a suitable example.

240 3.3 The uniqueness theorem

We shall now present the uniqueness argument more formally. We shall deal with the case of a pure common value first. Suppose there are two equilibria β^* and β^{**} with $\beta^* \neq \beta^{**}$. Consider the convex combination

$$\beta^s = s\beta^* + (1-s)\beta^{**} \tag{5}$$

for $s \in [0, 1]$, and fix some type $\theta_i \in \Theta_i$ of some player *i*. If $x_i^{\max}(\theta_i) > 0$, then by Lemma A.1 in the Appendix, type θ_i 's expected payoff $\overline{\Pi}_i(x_i, \beta_{-i}^s, \theta_i)$ is differentiable at $x_i = \beta_i^s(\theta_i)$ with

$$\frac{\partial \overline{\Pi}_i(\beta_i^s(\theta_i), \beta_{-i}^s, \theta_i)}{\partial x_i} = \sum_{\omega \in \mathcal{P}_i(\theta_i)} q_i(\omega | \theta_i) \frac{\partial \Pi_i(\beta_i^s(\theta_i), \beta_{-i}^s(t_{-i}(\omega)), \omega)}{\partial x_i}.$$
 (6)

²⁴⁹ Therefore, the "marginal payoff"

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$$\pi_{i}(s,\theta_{i}) = \begin{cases} \frac{\partial \overline{\Pi}_{i}(\beta_{i}^{s}(\theta_{i}),\beta_{-i}^{s},\theta_{i})}{\partial x_{i}} & \text{if } x_{i}^{\max}(\theta_{i}) > 0\\ 0 & \text{if } x_{i}^{\max}(\theta_{i}) = 0 \end{cases}$$
(7)

is well-defined for any i, any θ_i , and any $s \in [0, 1]$. Following Rosen (1965), consider now the "inner product"

$$\gamma_s = \sum_{i=1}^n \sum_{\theta_i \in \Theta_i} q_i(\theta_i) \{\beta_i^*(\theta_i) - \beta_i^{**}(\theta_i)\} \overline{\pi}_i(s, \theta_i).$$
(8)

Recall that $\beta^0 = \beta^{**}$ and $\beta^1 = \beta^*$ are equilibria. Hence, for s = 0 or s = 1, from the necessary Kuhn-Tucker conditions, $\beta_i^s(\theta_i) = 0$ if $\overline{\pi}_i(s, \theta_i) < 0$ and $\beta_i^s(\theta_i) = x_i^{\max}(\theta_i)$ if $\overline{\pi}_i(s, \theta_i) > 0$, for any i and any θ_i . It follows that $\gamma_0 \leq 0$ and $\gamma_1 \ge 0$. To provoke a contradiction, we shall now show that $\gamma_1 - \gamma_0 < 0$. Let $s \in [0, 1]$ be general again. Combining equations (6) and (7) delivers

$$\overline{\pi}_i(s,\theta_i) = \sum_{\omega \in \mathcal{P}_i(\theta_i)} q_i(\omega|\theta_i) \pi_{i,\omega}(s), \tag{9}$$

 $_{260}$ with

$$\pi_{i,\omega}(s) = \begin{cases} \frac{\partial \Pi_i(\beta^s(t(\omega)),\omega)}{\partial x_i} & \text{if } x_i^{\max}(t_i(\omega)) > 0\\ 0 & \text{if } x_i^{\max}(t_i(\omega)) = 0. \end{cases}$$
(10)

Plugging equation (9) into (8), and subsequently exploiting $q_i(\theta_i)q_i(\omega|\theta_i) = q(\omega)$ for any $\omega \in \mathcal{P}_i(\theta_i)$ yields

$$\gamma_s = \sum_{i=1}^n \sum_{\theta_i \in \Theta_i} \sum_{\omega \in \mathcal{P}_i(\theta_i)} q(\omega) \{\beta_i^*(\theta_i) - \beta_i^{**}(\theta_i)\} \pi_{i,\omega}(s).$$
(11)

Since player *i*'s possibility sets $\mathcal{P}_i(\theta_i)$, for signals $\theta_i \in \Theta_i$, form a partition of the state space Ω , we may write this more compactly as

$$\gamma_s = \sum_{i=1}^n \sum_{\omega \in \Omega} q(\omega) z_i(\omega) \pi_{i,\omega}(s), \qquad (12)$$

where $z_i(\omega) = \beta_i^*(t_i(\omega)) - \beta_i^{**}(t_i(\omega))$. For any ω satisfying $\beta^s(t(\omega)) = 0$ for some $s \in [0, 1]$, necessarily $\beta^*(t(\omega)) = 0$ or $\beta^{**}(t(\omega)) = 0$, so that by part (ii) of Lemma A.4 (and its obvious counterpart for β^{**}), $x_i^{\max}(t_i(\omega)) = 0$ for any i, and hence, $\pi_{i,\omega}(s) = 0$ for any i. Therefore,

$$\gamma_s = \sum_{i=1}^n \sum_{\omega \in \Omega_0} q(\omega) z_i(\omega) \pi_{i,\omega}(s), \qquad (13)$$

where Ω_0 is the set of ω such that $\beta^s(t(\omega)) \neq 0$ for all $s \in [0, 1]$. Consider next the difference

$$\gamma_{1} - \gamma_{0} = \sum_{i=1}^{n} \sum_{\omega \in \Omega_{0}} q(\omega) z_{i}(\omega) (\pi_{i,\omega}(1) - \pi_{i,\omega}(0))$$
(14)

$$= \sum_{i=1}^{n} \sum_{\omega \in \Omega_0} q(\omega) \int_0^1 \frac{\partial \pi_{i,\omega}(s)}{\partial s} z_i(\omega) ds.$$
(15)

Fix for the moment some *i* and $\omega \in \Omega_0$. If $x_i^{\max}(t_i(\omega)) > 0$, then

$$\pi_{i,\omega}(s) = v_i(\omega) \frac{\partial p_{i,\omega}(\beta_1^s(t_1(\omega)), \dots, \beta_n^s(t_n(\omega)))}{\partial x_i} - \frac{\partial c_{i,\omega}(\beta_i^s(t_i(\omega)))}{\partial x_i}, \quad (16)$$

and a straightforward application of the chain rule for differentiation, using $\beta_j^s(t_j(\omega)) = \beta_j^{**}(t_j(\omega)) + s \cdot z_j(\omega)$ for j = 1, ..., n, leads to

$$\frac{\partial \pi_{i,\omega}(s)}{\partial s} = v_i(\omega) \sum_{j=1}^n \frac{\partial^2 p_{i,\omega}(\beta_1^s(t_1(\omega)), \dots, \beta_n^s(t_n(\omega)))}{\partial x_j \partial x_i} z_j(\omega)$$

$$-\frac{\partial^2 c_{i,\omega}(\beta_i^s(t_i(\omega)))}{\partial x_j \partial x_i} z_i(\omega)$$
(17)

$$-\frac{\partial^2 c_{i,\omega}(\beta_i^s(t_i(\omega)))}{\partial x_i^2} z_i(\omega).$$
(17)

Multiplying this through with $z_i(\omega)$, and subsequently exploiting Assumption (B), one obtains the inequality

$$\frac{\partial \pi_{i,\omega}(s)}{\partial s} z_i(\omega) \le v_i(\omega) \sum_{j=1}^n \frac{\partial^2 p_{i,\omega}(\beta^s(t(\omega)))}{\partial x_j \partial x_i} z_j(\omega) z_i(\omega).$$
(18)

If, on the other hand, $x_i^{\max}(\theta_i) = 0$, then $z_i(\omega) = \beta_i^{**}(t_i(\omega)) - \beta_i^*(t_i(\omega)) = 0$, and (18) holds likewise. Thus, (18) holds for any *i* and any $\omega \in \Omega_0$. Plugging this into (15), and exploiting that $v_i(\omega) = v(\omega)$ for i = 1, ..., n, one arrives at

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$$\leq \sum_{i=1}^{n} \sum_{\omega \in \Omega_0} q(\omega) v_i(\omega) \int_0^1 \sum_{j=1}^n \frac{\partial^2 p_{i,\omega}(\beta^s(t(\omega)))}{\partial x_j \partial x_i} z_j(\omega) z_i(\omega) ds \qquad (19)$$

$$= \sum_{\omega \in \Omega_0} q(\omega)v(\omega) \int_0^1 z(\omega)^T J_{p,\omega}(\beta^s(t(\omega)))z(\omega)ds, \qquad (20)$$

where $z(\omega) = (z_1(\omega), ..., z_n(\omega))^T$, and $J_{p,\omega}(x)$ is the $n \times n$ -matrix whose elements are $\partial^2 p_{i,\omega}(x) / \partial x_i \partial x_j$. It suffices to show now that the right-hand side of (20) is negative. By part (iii) of Lemma A.2, $J_{p,\omega}(\beta^s(t(\omega))) + J_{p,\omega}(\beta^s(t(\omega)))^T$ is negative semi-definite for any $\omega \in \Omega_0$. Hence, by Lemma A.5,

$$z(\omega)^T J_{p,\omega}(\beta^s(t(\omega))) z(\omega) \le 0,$$
(21)

for any $s \in [0, 1]$ and for any $\omega \in \Omega_0$. Moreover, by Lemma A.3, there is a state ω_0 such that $z(\omega_0) \neq 0$ and such that $\beta^s(t(\omega_0))$ has two or more nonzero components. Hence, using the respective strict versions of part (iii) of Lemma A.2 and of Lemma A.5, we obtain even

$$z(\omega_0)^T J_{p,\omega_0}(\beta^s(t(\omega_0))) z(\omega_0) < 0,$$
(22)

for any $s \in [0, 1]$. Since $\omega_0 \in \Omega_0$, $q(\omega_0) > 0$, and $v(\omega_0) > 0$, this implies that the right-hand side of (20) is indeed negative. Thus, $\gamma_1 - \gamma_0 < 0$, as claimed, which is inconsistent with $\gamma_0 \leq 0$ and $\gamma_1 \geq 0$. The contradiction shows that there cannot be two distinct equilibria.

306 We arrive at the following result:

Theorem 1 Under Assumptions (A), (B) and (C), there exists at most one pure-strategy Nash equilibrium in the contest with incomplete information.

³¹⁰ **Proof.** The case of pure common value has been proved in the text ³¹¹ above. The general case can be reduced to the case of pure common value ³¹² as follows. Maximizing type θ_i 's expected payoff

$$\overline{\Pi}_i(x_i,\beta_{-i},\theta_i) \tag{23}$$

$$= \sum_{\omega \in \mathcal{P}_i(\theta_i)} q_i(\omega|\theta_i) \left(\frac{f_{i,\omega}(x_i)}{f_{i,\omega}(x_i) + \sum_{j \neq i} f_{j,\omega}(\beta_j(t_j(\omega)))} v_i(\omega) - c_{i,\omega}(x_i) \right)$$

is, by the virtue of Assumption (C), equivalent to maximizing type θ_i 's expected payoff in units of her private-valuation component $\kappa_i(\theta_i) > 0$,

³¹⁷
$$\frac{\overline{\Pi}_i(x_i,\beta_{-i},\theta_i)}{\kappa_i(\theta_i)}$$
(24)

$$= \sum_{\omega \in \mathcal{P}_i(\theta_i)} q_i(\omega|\theta_i) \left(\frac{f_{i,\omega}(x_i)}{f_{i,\omega}(x_i) + \sum_{j \neq i} f_{j,\omega}(\beta_j(t_j(\omega)))} v(\omega) - \frac{c_{i,\omega}(x_i)}{\kappa_i(\theta_i)} \right).$$

The normalized contest \widehat{C} with valuations $\widehat{v}_i(\omega) = v(\omega)$ and cost functions $\widehat{c}_{i,\omega}(x_i) = c_{i,\omega}(x_i)/\kappa_i(t_i(\omega))$, all else equal, is one of pure common value. Therefore, as shown above, there is at most one pure-strategy equilibrium in the contest \widehat{C} . Hence, there is at most one pure-strategy equilibrium in the original contest. \Box

Theorem 1 subsumes and extends a variety of conditions that have been proposed for the existence of at most one pure-strategy Nash equilibrium. In particular, this is true for conditions used by Szidarovszky and Okuguchi (1997), Clark (1997), Schoonbeek and Winkel (2006), Münster (2006), and
Einy et al. (2013).

329 4 Existence

4.1 Approach to existence

To prove existence, we will deal more explicitly with the discontinuity of the contest success function (1). Indeed, since there is no optimal choice for a player if all of her opponents remain inactive, the best-response correspondence does not possess a closed graph, which conflicts with the usual way of constructing an equilibrium.¹⁴ To circumvent the problem, a number of papers, including Fey (2008), Ryvkin (2010), and Einy et al. (2013), introduce a minimum bid $\varepsilon > 0$, and let ε go to zero. Our approach is similar.

4.2 An assumption

We will say that player *i* is the only player with a positive budget in state ω if $x_i^{\max}(t_i(\omega)) > 0$ and $x_j^{\max}(t_j(\omega)) = 0$ for any $j \neq i$. Clearly, to obtain an equilibrium, we need to require that a player cannot be certain to be the only one with a positive budget. We therefore assume that

⁽D) there is no state ω in which a player is certain to be the only player with a positive budget.

¹⁴Note that changing the value of the contest success function at the origin would not solve the problem. Also, restricting attention to symmetric contests with independent types does not help. While any equilibrium is then necessarily interior, a proof of existence is still needed.

³⁴⁵ Certainty is defined here in the usual way. I.e., a type θ_i is certain of ³⁴⁶ an arbitrary event $E \subseteq \Omega$ when she assigns probability one to E, i.e., if ³⁴⁷ $\sum_{\omega \in E} q_i(\omega | \theta_i) = 1.$

4.3 The existence theorem

Consider a modified contest C^m in which each type θ_i of any player *i* with a positive budget is obligated to bid at least $\varepsilon_m > 0$, for some positive integer m, where $\lim_{m\to\infty}\varepsilon_m = 0$. We assume that *m* is sufficiently large so that the minimum bid is not in conflict with the budget constraint, i.e., such that $\varepsilon_m < x_i^{\max}(\theta_i)$ for all *i* and all θ_i with $x_i^{\max}(\theta_i) > 0$. Then, clearly, there exists a pure-strategy Nash equilibrium β^m in C^m .¹⁵

To construct an equilibrium in the original rent-seeking game, we let m355 go to infinity. Since strategy spaces are closed and bounded, we may assume 356 without loss of generality that $\{\beta^m\}_{m=1}^{\infty}$ is convergent to some profile β^* (if 357 $\{\beta^m\}_{m=1}^{\infty}$ is not convergent, then one may select a converging subsequence). 358 We first claim that, in each state ω_0 in which at least one player has 359 a positive budget, there is at least one player active in the profile β^* . To 360 see this, fix ω_0 and let $\delta > 0$ be sufficiently small, in all what follows. To 361 provoke a contradiction, suppose that for any sufficiently large m, all bids 362 in the profile $\beta^m(t(\omega_0))$ are smaller than or equal to δ . Consider now some 363 player i_0 that has a positive budget in state ω_0 . By Assumption (D), player 364

¹⁵Here is a sketch of the proof. Consider the agent-normal form of the game C^m , i.e., the game in strategic form in which each type realization $\theta_i \in \Theta_i$ of each player i = 1, ..., nis considered a separate player. In that game, type θ_i 's expected payoff $\overline{\Pi}_i$ is continuous in the profile β . Moreover, by part (i) of Lemma A.1 in the Appendix, $\overline{\Pi}_i$ is concave in x_i . Therefore, invoking standard existence theorems (see, e.g., Fudenberg and Tirole, 1991, Theorem 2.1), there is indeed a pure-strategy Nash equilibrium β^m in C^m .

 i_0 must not be certain in state ω_0 to be the only one with a positive budget. Therefore, there is another player $i_1 \neq i_0$ and a state ω_1 consistent with player i_0 's information in state ω_0 such that player i_1 's budget is positive in state ω_1 . Note that player i_0 has a positive budget at state ω_1 as well, because she cannot distinguish ω_0 and ω_1 . Thus, there are at least two players with a positive budget in state ω_1 .

Write now $b_j^m = \beta_j^m(t_j(\omega_1))$ for j = 1, ..., n, and consider, among the players that have a positive budget in state ω_1 , the player *i* with the smallest number of "lottery tickets" $f_{i,\omega_1}(b_i^m)$ (if there are several such players, any one of those can be chosen). The expected marginal payoff of type $\theta_i = t_i(\omega)$ can now be bounded from below as follows:

$$\sum_{\omega \in \mathcal{P}_i(\theta_i)} q_i(\omega|\theta_i) \left(\frac{\partial p_{i,\omega}(\beta^m(t(\omega)))}{\partial x_i} v_i(\omega) - \frac{\partial c_{i,\omega}(\beta^m_i(\theta_i))}{\partial x_i}\right)$$
(25)

$$= q_i(\omega_1|\theta_i) \frac{\partial p_{i,\omega_1}(\beta^m(t(\omega_1)))}{\partial x_i} v_i(\omega_1) - \sum_{\omega \in \mathcal{P}_i(\theta_i)} q_i(\omega|\theta_i) \frac{\partial c_{i,\omega}(\delta)}{\partial x_i}$$

Thus, we dropped all marginal revenue terms corresponding to states $\omega \in \mathcal{P}_i(\theta_i)$ different from ω_1 (these terms are weakly positive by Assumption (A)), and made use of the fact that $\beta_i^m(\theta_i) \leq \delta$, in combination with Assumption (B). By Assumption (A),

$$\frac{\partial p_{i,\omega_1}(\beta^m(t(\omega_1)))}{\partial x_i} = \frac{\partial f_{i,\omega_1}(b_i^m)}{\sum_{j=1}^n f_{j,\omega_1}(b_j^m)} \cdot \frac{\sum_{j\neq i} f_{j,\omega_1}(b_j^m)}{\sum_{j=1}^n f_{j,\omega_1}(b_j^m)}$$
(26)

$$\geq \frac{\partial f_{i,\omega_1}(x_i^{\max}(\theta_i))/\partial x_i}{\sum_{j=1}^n f_{j,\omega_1}(\delta)} \cdot \frac{1}{2}, \qquad (27)$$

because $f_{i,\omega_1}(b_i^m) > 0$, and because there are at least two players with a

positive budget in state ω_1 . Now, if δ is sufficiently small then, by continuity, 385 the denominator in (27) can be made arbitrarily small, while the numerator 386 is bounded away from zero by Assumption (A). Since $q_i(\omega_1|\theta_i) > 0$ and 387 $v_i(\omega_1) > 0$, the right-hand side of inequality (25) will become positive for m 388 sufficiently large, in contradiction to the Kuhn-Tucker condition associated 389 with type θ_i 's optimal bid, which requires the left-hand side of inequality 390 (25) to be weakly negative for δ sufficiently small, because then $\beta_i^m(\theta_i) \leq$ 391 $\delta < x_i^{\max}(\theta_i).$ 392

The contradiction shows that there are infinitely many m such that some bid in $\beta^m(t(\omega_0))$ exceeds δ . Since the number of players is finite, there must be some player that expends more than δ in state ω_0 for infinitely many m. But $\{\beta^m\}_{m=1}^{\infty}$ is known to converge. Hence, indeed, $\beta^*(t(\omega_0)) \neq 0$ in any state ω_0 in which not all players are forced to be remain inactive.

We finally show that β^* is an equilibrium in the original contest. Since β^m is an equilibrium in C^m ,

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$$\sum_{\substack{\omega \in \mathcal{P}_{i}(\theta_{i}) \\ \omega \in \mathcal{P}_{i}(\theta_{i})}} q_{i}(\omega | \theta_{i}) \Pi_{i}(\beta_{i}^{m}(\theta_{i}), \beta_{-i}^{m}(t_{-i}(\omega)), \omega)$$

$$\geq \sum_{\substack{\omega \in \mathcal{P}_{i}(\theta_{i}) \\ \omega \in \mathcal{P}_{i}(\theta_{i})}} q_{i}(\omega | \theta_{i}) \Pi_{i}(x_{i}, \beta_{-i}^{m}(t_{-i}(\omega)), \omega)$$
(28)

holds for any i, θ_i and $x_i \in [\varepsilon_m, x_i^{\max}(\theta_i)]$. Consider first some positive bid $x_i \in (0, x_i^{\max}(\theta_i)]$. Then, $x_i \in [\varepsilon_m, x_i^{\max}(\theta_i)]$ for m sufficiently large. By the continuity of the mapping $x \mapsto \Pi_i(x, \omega)$ over $\mathbb{R}^n_+ \setminus \{0\}$, taking the limit in $_{405}$ inequality (28) yields

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$$\sum_{\omega \in \mathcal{P}_{i}(\theta_{i})} q_{i}(\omega | \theta_{i}) \Pi_{i}(\beta_{i}^{*}(\theta_{i}), \beta_{-i}^{*}(t_{-i}(\omega)), \omega)$$

$$\geq \sum_{\omega \in \mathcal{P}_{i}(\theta_{i})} q_{i}(\omega | \theta_{i}) \Pi_{i}(x_{i}, \beta_{-i}^{*}(t_{-i}(\omega)), \omega)$$
(29)

for any i, θ_i and any $x_i \in (0, x_i^{\max}(\theta_i)]$. Consider now a deviation to $x_i = 0$. 408 Suppose that $\beta_{-i}^*(t_{-i}(\omega)) = 0$ for some $\omega \in \mathcal{P}_i(\theta_i)$. Then the deviation to 409 zero yields a lower expected payoff than a sufficiently small positive bid, 410 and we can argue as before. On the other hand, if $\beta_{-i}^*(t_{-i}(\omega)) \neq 0$ for any 411 $\omega \in \mathcal{P}_i(\theta_i)$, then the right-hand side of inequality (29) vanishes. Moreover, 412 because a bidder could always choose the minimum bid in C_m , which would 413 ensure an expected payoff of at least $-\varepsilon_m$, the left-hand side of inequality 414 (29) weakly exceeds $\lim_{m\to\infty}(-\varepsilon_m) = 0$. Hence, β^* is indeed a pure-strategy 415 Nash equilibrium in the original rent-seeking game. 416

Theorem 2 Under Assumptions (A), (B) and (D), there exists a purestrategy Nash equilibrium in the contest with incomplete information. If Assumption (C) is added, the equilibrium is also unique.

421 4.4 Mixed equilibria

⁴²² One might wonder whether there could be additional equilibria in mixed ⁴²³ strategies. A mixed extension of the contest could be defined, for instance, ⁴²⁴ by assuming that each type θ_i chooses, rather than a bid $x_i \in [0, x_i(\theta_i)]$, a

probability distribution on the Borel subsets of $[0, x_i(\theta_i)]$.¹⁶ We claim that 425 all equilibrium strategies in the mixed extension would be degenerate, i.e., 426 give probability one to a specific bid $x_i \in [0, x_i(\theta_i)]$. To see this, consider 427 some state ω and fix a type of some player *i*. Indeed, under Assumptions 428 (A) and (B), provided the opponents profile of bids is not zero, i.e., $x_{-i} \neq 0$, 429 we have $\partial^2 \Pi_i(x_i, x_{-i}, \omega) / \partial x_i^2 < 0$ for any $x_i \in [0, x_i^{\max}(\theta_i)]$. On the other 430 hand, when $x_{-i} = 0$, then $\partial^2 \Pi_i(x_i, x_{-i}, \omega) / \partial x_i^2 \leq 0$ for any $x_i \in (0, x_i^{\max}(\theta_i)]$. 431 Moreover, $\Pi_i(x_i, 0, \omega)$ jumps up at $x_i = 0$. Since, in a mixed equilibrium, 432 $x_{-i} = 0$ cannot occur with probability one (there would be no best response), 433 the interim expected payoff of each type θ_i against any mixed equilibrium 434 strategy profile of her opponents has a negative second derivative over the 435 interval $(0, x_i^{\max}(\theta_i)]$, and jumps up at $x_i = 0$. Thus, any equilibrium strategy 436 is necessarily a degenerate distribution, and therefore, any equilibrium must 437 be in pure strategies. 438

439 5 Rent dissipation

In prior work, Szidarovszky and Okuguchi (1997) had documented the fact that the expected net rent in rent-seeking games of complete information is always weakly positive for all players. This result and its proof obviously extend to the class of contests with incomplete information considered here, since it is always possible for a player to remain passive, which incurs zero costs to her as a consequence of Assumption (B).

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We examine this point further. From the proof of the existence theorem,

¹⁶See Dasgupta and Maskin (1986) for further details.

we know that in any state ω_0 admitting a positive budget for some player *i*, there is some player *j* (not necessarily identical to *i*) that bids a positive amount at ω_0 .¹⁷ To make this positive bid a best response for type $\theta_j =$ $t_j(\omega_0)$, there must be a state ω_1 consistent with θ_j 's information, and a player *k*, different from *j*, that bids a positive amount in state ω_1 . Thus, unless budgets are zero for all players in all states, there are at least two players that are active with positive probability.

There is more that can be deduced here. As explained above, any active 454 type expects in equilibrium that at least one other player is active with 455 positive probability. Therefore, the expected payoff function for this type, 456 when playing against the opponents' equilibrium profile, is a weighted average 457 of concave payoff functions, with positive weight on functions that have a 458 negative second derivative. As a consequence, the expected payoff for any 459 active type is strictly concave. Since inactivity generates a certain payoff of 460 zero, activity must (as a consequence of the first-order condition and strict 461 concavity of interim expected payoffs) yield a positive payoff. In particular, 462 any player that is active with positive probability (and there are at least two) 463 will realize a positive expected net rent from an ex-ante perspective. 464

465 We summarize the discussion as follows.

Theorem 3 Impose Assumptions (A), (B) and (D). Assume also that there exists a state in which not all budgets are zero. Then the following statements hold true: (i) In each state of the world in which not all budgets are zero, at least one player is active. (ii) There are two players that

¹⁷Alternatively, this can be seen from part (ii) of Lemma A.4.

are active with positive probability. (iii) Any active type earns a positive
expected net rent. In particular, there are at least two players that earn a
positive expected net rent. (iv) If the contest is symmetric and, in addition,
Assumption (C) holds, then all players earn a positive expected net rent.

474 **Proof.** See the text before the statement of the theorem. \Box

475 6 Some implications

This section derives some implications of our main results in a number of specific settings that have been considered in the literature.

478 6.1 Two-sided asymmetric information

Hurley and Shogren (1998b) study the comparative statics of the unique interior equilibrium. Since their setting is one of private valuations, it follows from our results that there is at most one equilibrium. In particular, whenever there is an interior equilibrium for certain parameter values, additional equilibria at the boundary can be definitely excluded.

484 6.2 Symmetric contests

Malueg and Yates (2004) study a class of symmetric Tullock contests, where $f_i(x_i) = x_i^r$ for some parameter r > 0. In their set-up, a player's private value is either v_L or v_H , where $v_H \ge v_L > 0$. Moreover, $\operatorname{pr}\{v_1 = v_2 = v_L\} = \operatorname{pr}\{v_1 = v_2 = v_H\} = \frac{\sigma}{2}$ and $\operatorname{pr}\{v_1 = v_L \text{ and } v_2 = v_H\} = \operatorname{pr}\{v_1 = v_H \text{ and } v_2 = v_L\} = \frac{1-\sigma}{2}$, where $\sigma \in [0, 1]$ is a parameter that measures the correlation between the contestants' value distributions. As Malueg and Yates (2004) note, the corresponding Bayesian game need not in general possess a symmetric Nash equilibrium in pure strategies. Rather,

$$r \le 2\left(\frac{\sigma + (2-\sigma)\rho^r}{1+\rho^r}\right)\left(\frac{2+\rho^{-r}+\rho^r}{2(2-\sigma)+\sigma(\rho^{-r}+\rho^r)}\right)$$
(30)

is a necessary and sufficient condition for existence of a symmetric equilibrium 494 in terms of the parameters r, $\rho = v_L/v_H$ and σ . However, condition (30) 495 holds for any $r \leq 1$.¹⁸ Thus, there exists a unique symmetric equilibrium in 496 Malueg and Yates' (2004) framework when $r \leq 1$. We may now use Theorem 497 1 to conclude that, in fact, the game considered by Malueg and Yates (2004) 498 does not allow any asymmetric equilibria for $r \leq 1.^{19}$ Thus, the symmetric 499 equilibrium studied in this context is indeed the only Nash equilibrium of 500 this game. 501

$$1 \le 2\left(\frac{\sigma + (2-\sigma)\rho^r}{1+\rho^r}\right) \left(\frac{2+\rho^{-r}+\rho^r}{2(2-\sigma)+\sigma(\rho^{-r}+\rho^r)}\right).$$

Re-arranging the ratios individually yields

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$$1 \le 2\left(\frac{2(1-\sigma)}{1+\rho^{-r}} + \sigma\right) \left(\frac{2+\rho^{-r}+\rho^{r}}{4(1-\sigma)+\sigma(2+\rho^{-r}+\rho^{r})}\right).$$

Multiplying through with the reciprocal of the second ratio, one arrives at

$$\frac{4(1-\sigma)}{2+\rho^{-r}+\rho^r} \le \frac{4(1-\sigma)}{1+\rho^{-r}} + \sigma,$$

which is obviously satisfied for any $\sigma \in [0, 1]$ and any $\rho \in (0, 1)$.

¹⁹While for r < 1, the function $f_i(x_i) = x_i^r$ is not differentiable at $x_i = 0$, a simple change of variables turns the Tullock contest into a lottery contest with r = 1 and cost functions $c_i(x_i) = x_i^{1/r}$, which then satisfies Assumptions (A) and (B).

¹⁸This fact is suggested by the intuitive discussion of Malueg and Yates (2004, pp. 168-169). For a proof, note that it suffices to show that the right-hand side of inequality (30) weakly exceeds unity, i.e., it suffices to show that

502 6.3 Contests with resale

Sui (2009) extends the framework of Malueg and Yates (2004) by allowing for 503 the possibility of resale. In substance this means that, should a player with 504 a low valuation v_L win the contest, she may offer the prize to the loser at 505 price (marginally below) v_H , who will accept the offer if and only if she has 506 valuation v_H . Thus, each player's value of winning is v_L if both players have 507 a low valuation of the prize, and v_H otherwise. In other words, the possibility 508 of resale turns the game into one of a pure common value. As a consequence, 509 Theorem 1 applies and we find that there is a unique equilibrium. Thus, 510 again, the restriction to symmetric equilibria is not necessary. 511

512 6.4 Asymmetric information about ability

Epstein and Mealem (2013) derive conditions under which, in an interior equilibrium, an extreme type that is privately informed about her ability would prefer the uninformed player to become informed. Without uniqueness, however, the ranking result for more than two types might be overturned by the presence of additional equilibria at the boundary. Precisely this possibility is, again, excluded by Theorem 1.

519 7 Conclusion

It has been shown that uniqueness of the Nash equilibrium is a pervasive property of contests with weakly decreasing returns and incomplete information. Our conditions subsume and extend various prior conditions for the

existence of a unique equilibrium. As we illustrated in specific settings, our 523 results allow to exclude the possibility of additional equilibria (e.g., at the 524 boundary), or the possibility of asymmetric equilibria in symmetric games. 525 This type of result is useful for both comparative statics and policy analysis. 526 Further, our results should encourage further numerical calculations of equi-527 libria and experiments. In fact, experimental contests with incomplete infor-528 mation such as those reported in Brookins and Ryvkin (2013) and Grosskopf 529 et al. (2010) seem to be a particularly interesting object of research, and 530 should be studied much more thoroughly in our view. 531

532 8 Appendix

This Appendix contains several lemmas that are used in the proof of Theorem 1. We will assume throughout that β^* and β^{**} denote two distinct equilibria, and write $\beta^s = s\beta^* + (1-s)\beta^{**}$ and $z(\omega) = \beta^{**}(t(\omega)) - \beta^*(t(\omega))$, as before. The first lemma deals with the differentiability of interim expected payoffs.

Lemma A.1. If $x_i^{\max}(\theta_i) > 0$, then the function $x_i \mapsto \overline{\Pi}_i(x_i, \beta_{-i}^s, \theta_i)$ is differentiable at $x_i = \beta_i^s(\theta_i)$, with

$${}_{540} \qquad \frac{\partial \overline{\Pi}_i(\beta_i^s(\theta_i), \beta_{-i}^s, \theta_i)}{\partial x_i} = \sum_{\omega \in \mathcal{P}_i(\theta_i)} q_i(\omega|\theta_i) \frac{\partial \Pi_i(\beta_i^s(\theta_i), \beta_{-i}^s(t_{-i}(\omega)), \omega)}{\partial x_i}.$$
(31)

Proof. The claim follows directly from equation (3) if $\beta_i^s(\theta_i) > 0$. Suppose, therefore, that $\beta_i^s(\theta_i) = 0$. Assume first that s = 1, so that $\beta^s = \beta^s$. Since $x_i^{\max}(\theta_i) > 0$, part (ii) of Lemma A.4 below implies that $\beta_{-i}^*(t_{-i}(\omega)) \neq 0$

for any $\omega \in \mathcal{P}_i(\theta_i)$, so that the claim follows in this case. Assume now that 544 $s \in [0,1)$. Then $\beta_i^s(\theta_i) = 0$ implies $\beta_i^{**}(\theta_i) = 0$. Applying part (ii) of Lemma 545 A.4 again (with β^* replaced by β^{**}), it follows that $\beta_{-i}^{**}(t_{-i}(\omega)) \neq 0$ for any 546 $\omega \in \mathcal{P}_i(\theta_i)$. Hence, $\beta_{-i}^s(t_{-i}(\omega)) \neq 0$ for any $\omega \in \mathcal{P}_i(\theta_i)$, which proves the 547 lemma. \Box 548

The next lemma applies an argument due to Goodman (1980) to contests. 549 Recall that $J_{p,\omega}(x)$ is the $n \times n$ -matrix whose elements are $\partial^2 p_{i,\omega}(x) / \partial x_i \partial x_j$. 550

Lemma A.2. Impose Assumption (A), and let $\omega \in \Omega$. Then the following 551 statements hold true: (i) For any i, the function $p_{i,\omega}$ is twice continuously dif-552 ferentiable on $\mathbb{R}^n_+ \setminus \{0\}$ with $\partial^2 p_{i,\omega} / \partial x_i^2 \leq 0$. Moreover, $\partial^2 p_{i,\omega}(x_i, x_{-i}) / \partial x_i^2 < 0$ 553 0 for any $x_i \ge 0$ and any $x_{-i} \in \mathbb{R}^n_+ \setminus \{0\}$. (ii) For any *i* and any $x_i > 0$, 554 the function $x_{-i} \mapsto p_{i,\omega}(x_i, x_{-i})$ is convex over \mathbb{R}^{n-1}_+ . (iii) $J_{p,\omega}(x) + J_{p,\omega}(x)^T$ 555 is negative semi-definite for any $x \in \mathbb{R}^n_+ \setminus \{0\}$, and negative definite for any 556 $x \in \mathbb{R}^n_+$ possessing two or more nonzero components. 557

Proof. (i) For any $x \in \mathbb{R}^n_+ \setminus \{0\}$, by Assumption (A), 558

$$\frac{\partial^2 p_{i,\omega}(x)}{\partial x_i^2} = \frac{\partial^2}{\partial x_i^2} \frac{f_{i,\omega}(x_i)}{f_{i,\omega}(x_i) + \sum_{j \neq i} f_{j,\omega}(x_j)}$$

$$= \frac{\partial}{\partial x_i} \frac{(\partial f_{i,\omega}(x_i)/\partial x_i) \sum_{j \neq i} f_{j,\omega}(x_j)}{\left(f_{i,\omega}(x_i) + \sum_{j \neq i} f_{j,\omega}(x_j)\right)^2}$$

$$(32)$$

$$= -\frac{2(\partial f_{i,\omega}(x_i)/\partial x_i)^2 \sum_{j\neq i} f_{j,\omega}(x_j)}{\left(f_{i,\omega}(x_i) + \sum_{j\neq i} f_{j,\omega}(x_j)\right)^3}$$
(33)

$$+ \frac{(\partial^2 f_{i,\omega}(x_i)/\partial x_i^2) \sum_{j \neq i} f_{j,\omega}(x_j)}{\left(f_{i,\omega}(x_i) + \sum_{j \neq i} f_{j,\omega}(x_j)\right)^2} \le 0.$$
(34)

0. \leq

Moreover, if $x_{-i} \in \mathbb{R}^n_+ \setminus \{0\}$, then $\sum_{j \neq i} f_{j,\omega}(x_j) > 0$, and hence, $\partial^2 p_{i,\omega}(x) / \partial x_i^2 < 0$, as claimed.

(ii) The mapping $x_{-i} \mapsto \sum_{j \neq i} f_{j,\omega}(x_j)$ is concave over \mathbb{R}^{n-1}_+ , as can be seen by noting that the corresponding Hessian is a diagonal matrix with weakly negative entries. Further, for any fixed $x_i > 0$, the mapping $y \mapsto \frac{x_i}{x_i+y}$ is convex and decreasing on \mathbb{R}_{++} . The claim follows now from standard results on the concatenation of convex mappings (e.g., Th. 5.1 in Rockafellar, 1970). (iii) Take some $x \in \mathbb{R}^n_+ \setminus \{0\}$. We wish to show that

$$J_{p,\omega}(x) + J_{p,\omega}(x)^T \tag{35}$$

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$$574 = \begin{pmatrix} 2\frac{\partial^2 p_{1,\omega}(x)}{\partial x_1^2} & \frac{\partial^2 p_{2,\omega}(x)}{\partial x_2 \partial x_1} + \frac{\partial^2 p_{1,\omega}(x)}{\partial x_2 \partial x_1} & \cdots & \frac{\partial^2 p_{n,\omega}(x)}{\partial x_n \partial x_1} + \frac{\partial^2 p_{1,\omega}(x)}{\partial x_n \partial x_1} \\ \frac{\partial^2 p_{1,\omega}(x)}{\partial x_1 \partial x_2} + \frac{\partial^2 p_{2,\omega}(x)}{\partial x_1 \partial x_2} & 2\frac{\partial^2 p_{2,\omega}(x)}{\partial x_2^2} & \cdots & \frac{\partial^2 p_{n,\omega}(x)}{\partial x_n \partial x_2} + \frac{\partial^2 p_{2,\omega}(x)}{\partial x_n \partial x_2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 p_{1,\omega}(x)}{\partial x_1 \partial x_n} + \frac{\partial^2 p_{n,\omega}(x)}{\partial x_1 \partial x_n} & \frac{\partial^2 p_{2,\omega}(x)}{\partial x_2 \partial x_n} + \frac{\partial^2 p_{n,\omega}(x)}{\partial x_2 \partial x_n} & \cdots & 2\frac{\partial^2 p_{n,\omega}(x)}{\partial x_n^2} \end{pmatrix}$$

is negative semi-definite. By part (i) of this lemma, $\partial^2 p_{i,\omega} / \partial x_i^2 \leq 0$ over $\mathbb{R}^n_+ \setminus \{0\}$, for all *i*. Therefore, the diagonal matrix

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$$M_{\omega}(x) = \begin{pmatrix} \frac{\partial^2 p_{1,\omega}(x)}{\partial x_1^2} & 0 & \cdots & 0\\ 0 & \frac{\partial^2 p_{2,\omega}(x)}{\partial x_2^2} & \vdots\\ \vdots & & \ddots & 0\\ 0 & \cdots & 0 & \frac{\partial^2 p_{n,\omega}(x)}{\partial x_n^2} \end{pmatrix}$$
(36)

is negative semi-definite. Fix some k = 1, ..., n. From part (ii) of this lemma, for $x_k > 0$, the mapping $x_{-k} \mapsto p_{k,\omega}(x_k, x_{-k})$ is convex over \mathbb{R}^{n-1}_+ . Likewise, for $x_k = 0$, the mapping $x_{-k} \mapsto p_{k,\omega}(0, x_{-k}) \equiv 0$ is convex over $\mathbb{R}^{n-1}_+ \setminus \{0\}$. Therefore, the corresponding Hessian matrix, i.e.,

$$H_{k,\omega}(x) \tag{37}$$

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$$584 = \begin{pmatrix} \frac{\partial^2 p_{k,\omega}(x)}{\partial x_1^2} & \cdots & \frac{\partial^2 p_{k,\omega}(x)}{\partial x_{k-1} \partial x_1} & \frac{\partial^2 p_{k,\omega}(x)}{\partial x_{k+1} \partial x_1} & \cdots & \frac{\partial^2 p_{k,\omega}(x)}{\partial x_n \partial x_1} \\ \vdots & \ddots & \vdots & \vdots & \vdots & \vdots \\ \frac{\partial^2 p_{k,\omega}(x)}{\partial x_1 \partial x_{k-1}} & \cdots & \frac{\partial^2 p_{k,\omega}(x)}{\partial x_{k-1}^2} & \frac{\partial^2 p_{k,\omega}(x)}{\partial x_{k+1} \partial x_{k-1}} & \cdots & \frac{\partial^2 p_{k,\omega}(x)}{\partial x_n \partial x_{k-1}} \\ \frac{\partial^2 p_{k,\omega}(x)}{\partial x_1 \partial x_{k+1}} & \cdots & \frac{\partial^2 p_{k,\omega}(x)}{\partial x_{k-1} \partial x_{k+1}} & \frac{\partial^2 p_{k,\omega}(x)}{\partial x_{k+1}^2} & \cdots & \frac{\partial^2 p_{k,\omega}(x)}{\partial x_n \partial x_{k+1}} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 p_{k,\omega}(x)}{\partial x_1 \partial x_n} & \cdots & \frac{\partial^2 p_{k,\omega}(x)}{\partial x_{k-1} \partial x_n} & \frac{\partial^2 p_{k,\omega}(x)}{\partial x_{k+1} \partial x_n} & \cdots & \frac{\partial^2 p_{k,\omega}(x)}{\partial x_n^2} \end{pmatrix},$$

is positive semi-definite. Thus, $z_{-k}^T H_{k,\omega}(x) z_{-k} \ge 0$ for any

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$$z_{-k} = (z_1, ..., z_{k-1}, z_{k+1}, ..., z_n)^T \in \mathbb{R}^{n-1}.$$
 (38)

587 Consider now the matrix

$$H_{k,\omega}^{0}(x)$$

$$H_{k,\omega}^{0$$

It is straightforward to check that $z^T H^0_{k,\omega}(x) z = z^T_{-k} H_{k,\omega}(x) z_{-k} \ge 0$ for any $z = (z_1, ..., z_n)^T \in \mathbb{R}^n$. Thus, the matrix $H^0_{k,\omega}(x)$ is likewise positive semidefinite. Summing now over k = 1, ..., n, we obtain that

$$\sum_{k=1,\dots,n} H^{0}_{k,\omega}(x)$$

$$\sum_{k=1,\dots,n} H^{0}_{k,\omega}(x)$$

$$\sum_{k=1,\dots,n} H^{0}_{k,\omega}(x)$$

$$\sum_{k=1,\dots,n} \frac{\partial^{2} p_{k,\omega}(x)}{\partial x_{1}^{2}} \sum_{\substack{k=1,\dots,n \\ k \neq 2,1}} \frac{\partial^{2} p_{k,\omega}(x)}{\partial x_{2} \partial x_{1}} \cdots \sum_{\substack{k=1,\dots,n \\ k \neq n,1}} \frac{\partial^{2} p_{k,\omega}(x)}{\partial x_{n} \partial x_{1}}$$

$$\sum_{\substack{k=1,\dots,n \\ k \neq 1,2}} \frac{\partial^{2} p_{k,\omega}(x)}{\partial x_{1} \partial x_{2}} \sum_{\substack{k=1,\dots,n \\ k \neq 2}} \frac{\partial^{2} p_{k,\omega}(x)}{\partial x_{2}^{2}} \cdots \sum_{\substack{k=1,\dots,n \\ k \neq n}} \frac{\partial^{2} p_{k,\omega}(x)}{\partial x_{n}^{2}}$$

$$\sum_{\substack{k=1,\dots,n \\ k \neq 1,n}} \frac{\partial^{2} p_{k,\omega}(x)}{\partial x_{1} \partial x_{n}} \cdots \sum_{\substack{k=1,\dots,n \\ k \neq n}} \frac{\partial^{2} p_{k,\omega}(x)}{\partial x_{n}^{2}} \right).$$
(40)

Since $x \neq 0$, we have $\sum_{k=1}^{n} p_{k,\omega}(x) = 1$ and, consequently, $\sum_{k=1}^{n} \frac{\partial^2 p_{k,\omega}(x)}{\partial x_i \partial x_j} = 0$

⁵⁹⁸ for arbitrary i and j. Hence,

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$$-\sum_{k=1,\dots,n} H^{0}_{k,\omega}(x) \tag{41}$$

$$\int \partial^{2} p_{1,\omega}(x) \qquad \partial^{2} p_{1,\omega}(x) \qquad \partial^{2} p_{2,\omega}(x) \qquad \partial^{2} p_{1,\omega}(x) \qquad \partial^{2} p_{1,$$

$$601 = \begin{pmatrix} \frac{\partial^2 p_{1,\omega}(x)}{\partial x_1^2} & \frac{\partial^2 p_{1,\omega}(x)}{\partial x_2 \partial x_1} + \frac{\partial^2 p_{2,\omega}(x)}{\partial x_2 \partial x_1} & \cdots & \frac{\partial^2 p_{1,\omega}(x)}{\partial x_n \partial x_1} + \frac{\partial^2 p_{n,\omega}(x)}{\partial x_n \partial x_1} \\ \frac{\partial^2 p_{1,\omega}(x)}{\partial x_1 \partial x_2} + \frac{\partial^2 p_{2,\omega}(x)}{\partial x_1 \partial x_2} & \frac{\partial^2 p_{2,\omega}(x)}{\partial x_2^2} & \vdots \\ \vdots & & \ddots & \vdots \\ \frac{\partial^2 p_{1,\omega}(x)}{\partial x_1 \partial x_n} + \frac{\partial^2 p_{n,\omega}(x)}{\partial x_1 \partial x_n} & \cdots & \cdots & \frac{\partial^2 p_{n,\omega}(x)}{\partial x_n^2} \end{pmatrix}.$$

Thus, $J_{p,\omega}(x) + J_{p,\omega}(x)^T = M_{\omega}(x) - \sum_{k=1}^n H_{k,\omega}^0(x)$ is indeed negative semidefinite for any $x \in \mathbb{R}^n_+ \setminus \{0\}$. Let now $x \in \mathbb{R}^n_+$ possess two or more nonzero components. Then, $x_{-i} \in \mathbb{R}^{n-1}_+ \setminus \{0\}$ for all i = 1, ..., n. In this case, therefore, $M_{\omega}(x)$ is negative definite, and so is $J_{p,\omega}(x) + J_{p,\omega}(x)^T$. \Box

The following lemma says that any two distinct equilibria must assign, in some state of the world, different bids for at least two players.

Lemma A.3 There is a state $\omega \in \Omega$ such that $z(\omega) \neq 0$ and such that $\beta^{s}(t(\omega))$ has two or more nonzero components, for any $s \in (0, 1)$.

Proof. Since $\beta^* \neq \beta^{**}$, there is some i and θ_i such that $\beta_i^*(\theta_i) \neq \beta_i^{**}(\theta_i)$. Take an arbitrary $\omega \in \mathcal{P}_i(\theta_i)$. Then $z_i(\omega) = \beta_i^*(t_i(\omega)) - \beta_i^{**}(t_i(\omega)) \neq 0$ and, hence, $z(\omega) \neq 0$. Moreover, $\beta_i^s(t_i(\omega)) > 0$ for any $s \in (0, 1)$, so that the profile $\beta^s(t(\omega))$ has at least one non-zero component. We are done if $\beta^s(t(\omega))$ has two or more nonzero components, for any $s \in (0, 1)$. We may assume therefore that there is some $s \in (0, 1)$ such that $\beta_j^s(t_j(\omega)) = 0$ for all $j \neq i$. Then, clearly, also $\beta_j^*(t_j(\omega)) = 0$ for all $j \neq i$. In other words, $\beta_{-i}^*(t_{-i}(\omega)) =$

0. To provoke a contradiction, suppose that, in fact, $\beta_{-i}^*(t_{-i}(\widetilde{\omega})) = 0$ for any 617 state $\widetilde{\omega} \in \mathcal{P}_i(\theta_i)$. Then necessarily $x_i^{\max}(\theta_i) = 0$ by part (i) of Lemma A.4, 618 and consequently $\beta_i^*(\theta_i) = 0$. Thus, $\beta^*(t(\omega)) = 0$. Analogously, one proves 619 that $\beta^{**}(t(\omega)) = 0$, so that $z(\omega) = \beta^{*}(t(\omega)) - \beta^{**}(t(\omega)) = 0$. It follows from 620 the contradiction that there is a state $\widetilde{\omega} \in \mathcal{P}_i(\theta_i)$ such that $\beta^*_{-i}(t_{-i}(\widetilde{\omega})) \neq 0$. 621 Hence, there is a $j \neq i$ such that $\beta_j^*(t_j(\widetilde{\omega})) > 0$ and, therefore, $\beta_j^s(t_j(\widetilde{\omega})) > 0$ 622 for any $s \in (0,1)$. Since also $\beta_i^s(t_i(\widetilde{\omega})) = \beta_i^s(t_i(\omega)) > 0$ for any $s \in (0,1)$, 623 the profile $\beta^s(t(\widetilde{\omega}))$ has two or more nonzero components for any $s \in (0, 1)$. 624 Moreover, $z_i(\widetilde{\omega}) = \beta_i^*(t_i(\widetilde{\omega})) - \beta_i^{**}(t_i(\widetilde{\omega})) = \beta_i^*(t_i(\omega)) - \beta_i^{**}(t_i(\omega)) = z_i(\omega) \neq 0.$ 625 Therefore, the assertion holds with ω replaced by $\widetilde{\omega}$. 626

The next lemma collects a number of useful facts related to the logit form
 of the contest success function.

Lemma A.4 For any $i \in \{1, ..., n\}$, the following statements hold true: (i) For any $\theta_i \in \Theta_i$ with $x_i^{\max}(\theta_i) > 0$, there is a state $\omega \in \mathcal{P}_i(\theta_i)$ such that $\beta_{-i}^*(t_{-i}(\omega)) \neq 0$. (ii) For any $\theta_i \in \Theta_i$ with $x_i^{\max}(\theta_i) > 0$ and $\beta_i^*(\theta_i) = 0$, we have $\beta_{-i}^*(t_{-i}(\omega)) \neq 0$ for any $\omega \in \mathcal{P}_i(\theta_i)$. (iii) For any $\omega \in \Omega$ with $z(\omega) \neq 0$, we have $\beta^s(t(\omega)) \neq 0$ for any $s \in [0, 1]$.

Proof. (i) Suppose that $\beta_{-i}^{*}(t_{-i}(\omega)) = 0$ for any $\omega \in \mathcal{P}_{i}(\theta_{i})$. Then, $x_{i} = 0$ is not an optimal response to β_{-i}^{*} for type θ_{i} because increasing x_{i} marginally above zero (which is feasible because of $x_{i}^{\max}(\theta_{i}) > 0$) would raise, in each state $\omega \in \mathcal{P}_{i}(\theta_{i})$, the probability of winning the rent $v_{i}(\omega) > 0$ discontinuously from $p_{i}(0,...,0) < 1$ to unity. But there is also no $x_{i} \in$ $(0, x_{i}^{\max}(\theta_{i})]$ that could be a best response because, when type θ_{i} is certain to face zero bids from her opponents, type θ_{i} 's expected payoff $\overline{\Pi}_{i}(x_{i}, \beta_{-i}^{*}, \theta_{i}) =$ ⁶⁴¹ $\sum_{\omega \in P_i(\theta_i)} q_i(\omega|\theta_i)(v_i(\omega) - c_{i,\omega}(x_i))$ is strictly declining over $(0, x_i^{\max}(\theta_i)]$ by ⁶⁴² Assumption (B). Thus, $\beta_i^*(\theta_i)$ is not a best response to β_{-i}^* for type θ_i , which ⁶⁴³ is a contradiction.

(ii) Suppose that $\beta_{-i}^*(t_{-i}(\omega)) = 0$ at some state $\omega \in \mathcal{P}_i(\theta_i)$. Then, 644 for any such state ω , player i's payoff $\Pi_i(x_i, 0, \omega)$ jumps up discontinuously 645 when the bid x_i is increased marginally from zero, because $v_i(\omega) > 0$. More-646 over, for any state $\omega \in \mathcal{P}_i(\theta_i)$ with $\beta^*_{-i}(t_{-i}(\omega)) \neq 0$, if any, player *i*'s pay-647 off $\Pi_i(x_i, \beta^*_{-i}(t_{-i}(\omega)), \omega)$ is continuous at $x_i = 0$. Since $q_i(\omega|\theta_i) > 0$ for all 648 states $\omega \in \mathcal{P}_i(\theta_i)$, type θ_i 's expected payoff $\overline{\Pi}_i(x_i, \beta^*_{-i}, \theta_i)$ jumps up discontin-649 uously when the bid x_i is increased marginally from zero. Hence, $\beta_i^*(\theta_i) > 0$. 650 (iii) Take some ω , and suppose that $\beta^s(t(\omega)) = 0$ for some $s \in [0, 1]$. 651 Then necessarily $\beta^*(t(\omega)) = 0$ or $\beta^{**}(t(\omega)) = 0$. Assume first that $\beta^*(t(\omega)) =$ 652 0. Writing $\theta_i = t_i(\omega)$ for i = 1, ..., n, we obtain $\omega \in \mathcal{P}_i(\theta_i), \ \beta_i^*(\theta_i) = 0$, and 653 $\beta_{-i}^*(t_{-i}(\omega)) = 0$. By part (ii) of this lemma, $x_i^{\max}(\theta_i) = 0$ for any *i*. But then 654 also $\beta_i^{**}(\theta_i) = 0$, so that $z_i(\omega) = \beta_i^*(t_i(\omega)) - \beta_i^{**}(t_i(\omega)) = \beta_i^*(\theta_i) - \beta_i^{**}(\theta_i) = 0$ 655 for any i, which contradicts the assumption that $z(\omega) \neq 0$. The proof is 656 analogous if $\beta^{**}(t(\omega)) = 0.$ 657

⁶⁵⁸ The final lemma states two simple matrix-theoretic facts.

Lemma A.5. Let J be an $n \times n$ -matrix such that $J + J^T$ is negative semi-definite. Then $z^T J z \leq 0$ for any $z \in \mathbb{R}^n$. If $J + J^T$ is even negative definite, then $z^T J z < 0$ for any $z \in \mathbb{R}^n \setminus \{0\}$.

Proof. Since $z^T J z$ is a real number, $z^T J z = ((z^T J)z)^T = z^T (z^T J)^T =$ $z^T J^T (z^T)^T = z^T J^T z$. Therefore, $2z^T J z = z^T J z + z^T J^T z = z^T (J z + J^T z) =$ $z^T (J + J^T) z$. The two assertions are now immediate. \Box

665 References

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