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MEMORANDUM

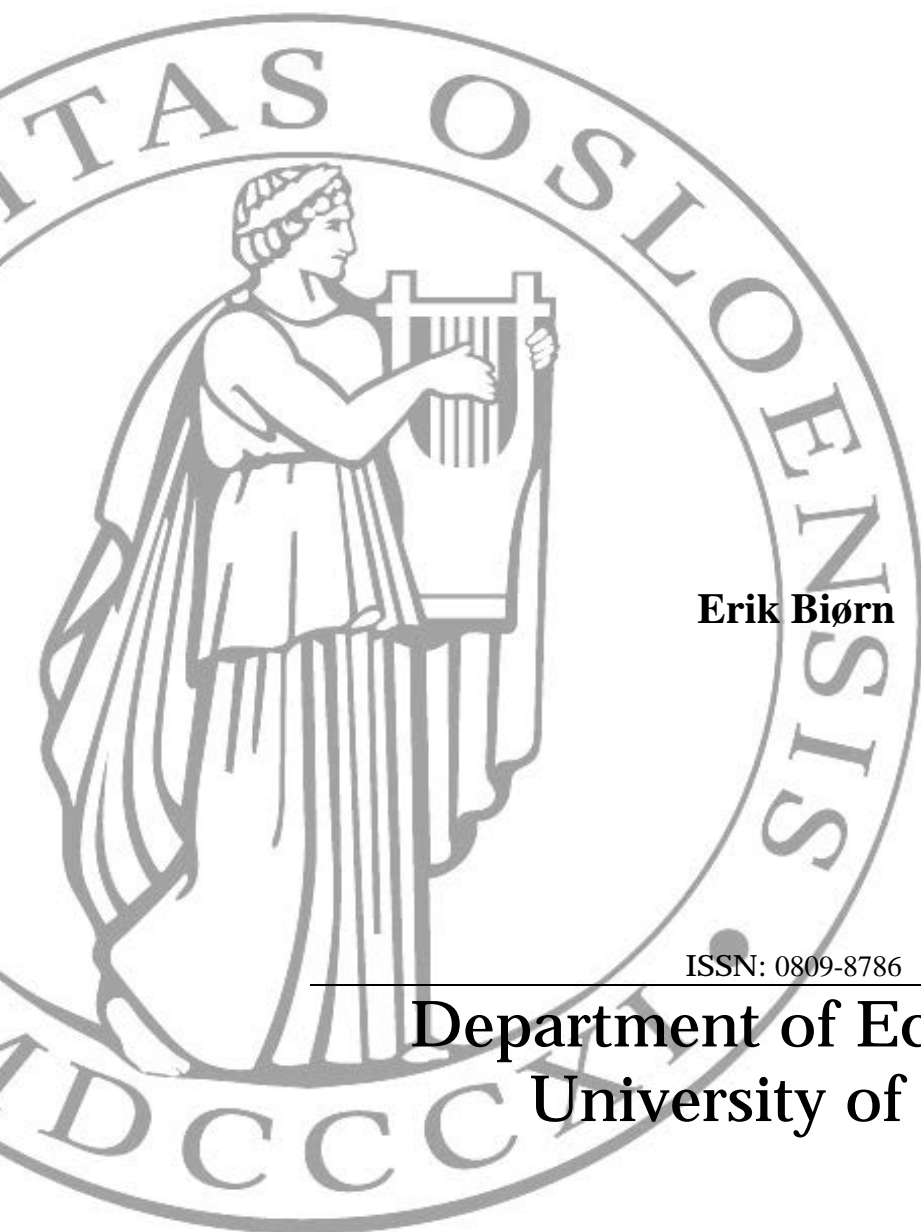
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ESTIMATING SUR SYSTEMS WITH RANDOM COEFFICIENTS:
THE UNBALANCED PANEL DATA CASE

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ABSTRACT: A system of regression equations (SURE) for analyzing panel data with random heterogeneity in intercepts and coefficients, and unbalanced panel data is considered. A Maximum Likelihood (ML) procedure for joint estimation of all parameters is described. Since its implementation for numerical computation is complicated, simplified procedures are presented. The simplifications essentially concern the estimation of the covariance matrices of the random coefficients. The application and ‘anatomy’ of the proposed algorithm for modified ML estimation is illustrated by using panel data for output, inputs and costs for 111 manufacturing firms observed up to 22 years.

KEYWORDS: Panel Data. Unbalanced data. Random Coefficients. Heterogeneity. Regression Systems. Iterated Maximum Likelihood

JEL CLASSIFICATION: C33, C51, C63, D24

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1 INTRODUCTION

An issue in the analysis of economic relationships by means of panel data is how to treat heterogeneity regarding the form of the relationships across the units or groups in the panel. Often a common coefficient structure is assumed, only allowing for unit specific (or time specific) differences in the intercepts ('fixed' or 'random' effects). If the heterogeneity has a more complex form, this approach may lead to inefficient (and sometimes inconsistent) estimation of the slope coefficients.

A more appealing modelling approach is to jointly allow for heterogeneity in the intercepts and the slopes. We may, for instance, want to investigate heterogeneity in returns to scale coefficients and elasticities of substitution across firms in factor demand, in Engel and Cournot elasticities across households in commodity demand, or in accelerator coefficients in investment equations. The challenges then become how to construct and estimate a model which is sufficiently flexible while being parsimonious. The fixed coefficients approach, with each unit having a distinct coefficient vector, is very flexible, but may easily suffer from overparametrization; the number of degrees of freedom being too small to permit reliable inference. The *random coefficients* approach, in which specific assumptions are made about the distribution from which the unit specific coefficients are 'drawn', is far more parsimonious in general. The common expectation vector represents the coefficients of an average unit, *e.g.*, the average scale elasticity, its covariance matrix gives readily interpretable measures of the degree of heterogeneity. The random coefficients approach may also be viewed a parsimonious way of representing certain kinds of disturbance heteroskedasticity in panel data analysis.

A growing number of methodological papers deal with this random coefficient problem for balanced panel data; see Longford (1995) and Hsiao (2008) for surveys. Early contributions to the econometric literature on random coefficients for linear, static single regression equations with *balanced* panel data are Swamy (1970), Hsiao (1975), and Swamy and Mehta (1977). Estimation problems for the covariance matrices of such models are discussed in Wansbeek and Kapteyn (1982). Avery (1977) and Baltagi (1980) consider systems of regression equations with random intercept heterogeneity for balanced panels. Biørn (1981), Baltagi (1985), and Wansbeek and Kapteyn (1989) consider a single regression equation with random intercept heterogeneity for *unbalanced* panels. Systems of regression equations for unbalanced panel data with random *intercept* heterogeneity are considered in Biørn (2004) and Platoni, and Sckokai and Moro (2012).

The model class to be considered in the present paper extends those mentioned above, except that only unit-specific heterogeneity is allowed for. For micro data and several data sets for aggregate units, *e.g.*, regions, unbalanced data are the exception rather than the rule. We may waste a lot of observations if we curtail an originally unbalanced data set to make it balanced. Our setup is characterized by a static system of linear regressions equations, random unit specific heterogeneity in intercepts and coefficients and unbalanced panel data. The sample selection rules are

assumed to be *ignorable*, *i.e.*, the way the units or groups enter or exit is not related to the model's endogenous variables. See Verbeek and Nijman (1996, section 18.2) for an elaboration of this topic.

The paper proceeds as follows: The model is presented in Section 2, with specific attention to the treatment of equality constraints on coefficients in different equations. Section 3 describes the main stages in Maximum Likelihood (ML) estimation. A basic difficulty in computer implementation stems from the unbalance of the panel in combination with the complexity in the way the covariance matrices of the coefficients enter the likelihood function. In Section 4, we consider a simpler, stepwise procedure for estimation of these covariance matrices before we in Section 5 present a simplified algorithm for modified ML estimation. An illustration of this algorithm based on cost and input data for Norwegian manufacturing, with firm data having a time series length up to 22 years, is presented in Section 6.

2 MODEL AND NOTATION

Our regression model has G equations, indexed by $g = 1, \dots, G$, equation g having K_g regressors. The data are from a panel with units observed in at least 1 and at most P periods. In describing unbalanced panel data sets, the observations from a specific unit i is often indexed as $t = 1, \dots, T_i$, where T_i is the number of observations from unit i ; see, *e.g.*, Baltagi (2008, section 9.3). Our notation is different, based on the assumption that the units are arranged in groups, or blocks, according to the number of times they are observed. Let N_p be the number of units observed in p periods (not necessarily the same and not necessarily contiguous), let (ip) index unit i in block p ($i = 1, \dots, N_p$; $p = 1, \dots, P$), and let t index the running observation ($t = 1, \dots, p$). In unbalanced panels, t differs from the calendar period (year, quarter etc.).¹ The total number of units and the total number of observations are then $N = \sum_{p=1}^P N_p$ and $n = \sum_{p=1}^P N_p p$, respectively. Formally, the data set in block p ($p = 2, \dots, P$) is a balanced panel data set with p observations of each of the N_p units, while the data set in block 1 is a cross-section.

Two ways of formulating the model will be described: [A] assuming the G equations to contain disjoint sets of coefficients, and [B] assuming some equations to have coefficients in common. We first consider [A], next the modifications needed in [B], and then describe a general formulation which includes both.

[A]. When *each equation has a distinct coefficient vector*, the total number of coefficients is $K = \sum_{g=1}^G K_g$. Let the $(p \times 1)$ vector of observations of the regressand in Equation g from unit (ip) be $\mathbf{y}_{g(ip)}$, let its $(p \times K_g)$ regressor matrix be $\mathbf{X}_{g(ip)}$ (including a vector of ones associated with the intercept), and let $\mathbf{u}_{g(ip)}$ be the $(p \times 1)$ disturbance vector in Equation g from unit (ip) . We represent heterogeneity, for Equation g , unit (ip) , by the *random coefficient vector* $\boldsymbol{\beta}_{g(ip)}$ (including the

¹Subscripts denoting the *calendar* period may be attached. This may be convenient for data documentation and in formulating dynamic models, but will not be necessary for the static model considered here. For example, in a data set with $P=20$, from the years 1981–2000, some units in the $p=18$ group may be observed in the years 1981–1998, some in 1982–1999, some in 1981–1990 and 1992–1999, etc.

intercept) as

$$(2.1) \quad \beta_{g(ip)} = \beta_g + \delta_{g(ip)}, \quad g = 1, \dots, G, \quad i = 1, \dots, N_p, \quad p = 1, \dots, P,$$

where β_g is its fixed expectation and $\delta_{g(ip)}$ is a random shift vector. We assume that $\mathbf{u}_{g(ip)}$ and $\delta_{g(ip)}$ are independently distributed and that

$$(2.2) \quad \begin{aligned} \mathbb{E}[\delta_{g(ip)}] &= \mathbf{0}_{K_g,1}, & \mathbb{E}[\delta_{g(ip)} \delta'_{h(ip)}] &= \Sigma_{gh}^\delta, \\ \mathbb{E}[\mathbf{u}_{g(ip)}] &= \mathbf{0}_{p,1}, & \mathbb{E}[\mathbf{u}_{g(ip)} \mathbf{u}'_{h(ip)}] &= \sigma_{gh}^u \mathbf{I}_p, \\ \mathbf{X}_{g(ip)} &\perp \mathbf{u}_{g(ip)} \perp \delta_{g(ip)}, & & g, h = 1, \dots, G, \end{aligned}$$

where $\mathbf{0}_{m,n}$ is the $(m \times n)$ zero matrix and \mathbf{I}_p is the p -dimensional identity matrix. Equation g for unit (ip) is

$$(2.3) \quad \mathbf{y}_{g(ip)} = \mathbf{X}_{g(ip)} \beta_{g(ip)} + \mathbf{u}_{g(ip)} = \mathbf{X}_{g(ip)} \beta_g + \boldsymbol{\eta}_{g(ip)},$$

where we interpret

$$(2.4) \quad \boldsymbol{\eta}_{g(ip)} = \mathbf{X}_{g(ip)} \delta_{g(ip)} + \mathbf{u}_{g(ip)},$$

as a *gross disturbance vector*, representing both the genuine disturbances and the random coefficient variation. These vectors are independent across units, with²

$$(2.5) \quad \mathbb{E}[\boldsymbol{\eta}_{g(ip)}] = \mathbf{0}_{p,1}, \quad \mathbb{E}[\boldsymbol{\eta}_{g(ip)} \boldsymbol{\eta}'_{h(ip)}] = \mathbf{X}_{g(ip)} \Sigma_{gh}^\delta \mathbf{X}'_{h(ip)} + \sigma_{gh}^u \mathbf{I}_p.$$

[B]. When *some coefficients occur in more than one equation* – reflecting for instance cross-equational (symmetry) constraints resulting from micro units' optimizing behaviour – the total number of free coefficients is less than $\sum_{g=1}^G K_g$. Such coefficient restrictions are assumed to affect both components of (2.1). We stack, for unit (ip) , the \mathbf{y} 's, the \mathbf{u} 's, and the $\boldsymbol{\eta}$'s by equations and define

$$\begin{aligned} \mathbf{y}_{(ip)} &= [\mathbf{y}'_{1(ip)}, \dots, \mathbf{y}'_{G(ip)}]', \quad \mathbf{u}_{(ip)} = [\mathbf{u}'_{1(ip)}, \dots, \mathbf{u}'_{G(ip)}]', \quad \boldsymbol{\eta}_{(ip)} = [\boldsymbol{\eta}'_{1(ip)}, \dots, \boldsymbol{\eta}'_{G(ip)}]' \\ \Sigma^u &= \begin{bmatrix} \sigma_{11}^u & \cdots & \sigma_{1G}^u \\ \vdots & & \vdots \\ \sigma_{G1}^u & \cdots & \sigma_{GG}^u \end{bmatrix}. \end{aligned}$$

We can now rewrite (2.1) as

$$(2.6) \quad \beta_{(ip)} = \beta + \delta_{(ip)}, \quad p = 1, \dots, P,$$

where $\beta_{(ip)}$ is the random $(K \times 1)$ vector containing *all* coefficients, β is its expectation and $\delta_{(ip)}$ is its random shift vector when redefining $\mathbf{X}_{g(ip)}$ as the $(p \times K)$ matrix of regressors in the g th equation whose k th column contains the observations on *the variable which corresponds to the k th coefficient in $\beta_{(ip)}$* ($k = 1, \dots, K$). If the g th equation does not contain the latter coefficient, the k th column of $\mathbf{X}_{g(ip)}$ is set to zero. Accordingly, (2.2)–(2.4) are modified to

²For notational simplicity, the conditioning on $(\mathbf{X}_{g(ip)}, \mathbf{X}_{h(ip)})$ is suppressed.

$$(2.7) \quad \begin{aligned} \mathbb{E}[\boldsymbol{\delta}_{(ip)}] &= \mathbf{0}_{K,1}, & \mathbb{E}[\boldsymbol{\delta}_{(ip)}\boldsymbol{\delta}_{(ip)}'] &= \boldsymbol{\Sigma}^\delta, \\ \mathbb{E}[\mathbf{u}_{(ip)}] &= \mathbf{0}_{Gp,1}, & \mathbb{E}[\mathbf{u}_{(ip)}\mathbf{u}_{(ip)}'] &= \mathbf{I}_p \otimes \boldsymbol{\Sigma}^u, \end{aligned}$$

$$(2.8) \quad \begin{aligned} \mathbf{X}_{(ip)} &\perp \mathbf{u}_{(ip)} \perp \boldsymbol{\delta}_{(ip)}, \\ \mathbf{y}_{(ip)} &= \mathbf{X}_{(ip)}\boldsymbol{\beta} + \mathbf{u}_{(ip)} = \mathbf{X}_{(ip)}\boldsymbol{\beta} + \boldsymbol{\eta}_{(ip)}, \end{aligned}$$

$$(2.9) \quad \boldsymbol{\eta}_{(ip)} = \mathbf{X}_{(ip)}\boldsymbol{\delta}_{(ip)} + \mathbf{u}_{(ip)},$$

where $\mathbf{X}_{(ip)} = [\mathbf{X}'_{1(ip)}, \dots, \mathbf{X}'_{G(ip)}]'$, so that (2.5) is generalized to

$$(2.10) \quad \mathbb{E}[\boldsymbol{\eta}_{(ip)}] = \mathbf{0}_{Gp,1}, \quad \mathbb{E}[\boldsymbol{\eta}_{(ip)}\boldsymbol{\eta}_{(ip)}'] = \mathbf{X}_{(ip)}\boldsymbol{\Sigma}^\delta\mathbf{X}_{(ip)}' + \mathbf{I}_p \otimes \boldsymbol{\Sigma}^u = \boldsymbol{\Omega}_{(ip)},$$

where \otimes is the Kronecker product operator and $\boldsymbol{\Omega}_{(ip)}$ is defined by the last equality. While in [B], $\mathbf{X}_{(ip)}$ is not block-diagonal, in [A], we have

$$\mathbf{X}_{(ip)} = \begin{bmatrix} \mathbf{X}_{1(ip)} & \cdots & \mathbf{0} \\ \vdots & \ddots & \vdots \\ \mathbf{0} & \cdots & \mathbf{X}_{G(ip)} \end{bmatrix}, \quad \boldsymbol{\beta} = \begin{bmatrix} \beta_1 \\ \vdots \\ \beta_G \end{bmatrix}, \quad \boldsymbol{\eta}_{(ip)} = \begin{bmatrix} \boldsymbol{\eta}_{1(ip)} \\ \vdots \\ \boldsymbol{\eta}_{G(ip)} \end{bmatrix}, \quad \boldsymbol{\Sigma}^\delta = \begin{bmatrix} \boldsymbol{\Sigma}_{11}^\delta & \cdots & \boldsymbol{\Sigma}_{1G}^\delta \\ \vdots & \ddots & \vdots \\ \boldsymbol{\Sigma}_{G1}^\delta & \cdots & \boldsymbol{\Sigma}_{GG}^\delta \end{bmatrix}.$$

3 THE MAXIMUM LIKELIHOOD PROBLEM

We now describe the Maximum Likelihood (ML) problem for joint estimation of $(\boldsymbol{\beta}, \boldsymbol{\Sigma}^u, \boldsymbol{\Sigma}^\delta)$, additionally assuming the random coefficients and the disturbances to be *normally* distributed:

$$\boldsymbol{\delta}_{(ip)} \sim \text{IN}(\mathbf{0}_{K,1}, \boldsymbol{\Sigma}^\delta), \quad \mathbf{u}_{(ip)} \sim \text{IN}(\mathbf{0}_{Gp,1}, \mathbf{I}_p \otimes \boldsymbol{\Sigma}^u).$$

Then the $(\boldsymbol{\eta}_{(ip)}|\mathbf{X}_{(ip)})$'s are independent across (ip) and distributed as $\text{N}(\mathbf{0}_{Gp,1}, \boldsymbol{\Omega}_{(ip)})$, giving a log-density function of $(\mathbf{y}_{(ip)}|\mathbf{X}_{(ip)})$ equal to

$$\mathcal{L}_{(ip)} = -\frac{Gp}{2} \ln(2\pi) - \frac{1}{2} \ln |\boldsymbol{\Omega}_{(ip)}| - \frac{1}{2} Q_{(ip)},$$

where

$$(3.1) \quad Q_{(ip)} = [\mathbf{y}_{(ip)} - \mathbf{X}_{(ip)}\boldsymbol{\beta}]' \boldsymbol{\Omega}_{(ip)}^{-1} [\mathbf{y}_{(ip)} - \mathbf{X}_{(ip)}\boldsymbol{\beta}] = \boldsymbol{\eta}_{(ip)}' \boldsymbol{\Omega}_{(ip)}^{-1} \boldsymbol{\eta}_{(ip)}.$$

The log-likelihood function of all \mathbf{y} 's, conditional on all \mathbf{X} 's, for block p and for the complete sample can be written as, respectively,

$$(3.2) \quad \mathcal{L}_{(p)} = \sum_{i=1}^{N_p} \mathcal{L}_{(ip)} = -\frac{GN_p p}{2} \ln(2\pi) - \frac{1}{2} \sum_{i=1}^{N_p} \ln |\boldsymbol{\Omega}_{(ip)}| - \frac{1}{2} \sum_{i=1}^{N_p} Q_{(ip)},$$

$$(3.3) \quad \mathcal{L} = \sum_{p=1}^P \mathcal{L}_{(p)} = -\frac{Gn}{2} \ln(2\pi) - \frac{1}{2} \sum_{p=1}^P \sum_{i=1}^{N_p} \ln |\boldsymbol{\Omega}_{(ip)}| - \frac{1}{2} \sum_{p=1}^P \sum_{i=1}^{N_p} Q_{(ip)}.$$

Two ML problems then emerge: ML estimation of $(\boldsymbol{\beta}, \boldsymbol{\Sigma}^u, \boldsymbol{\Sigma}^\delta)$ with data from block p : maximization of $\mathcal{L}_{(p)}$; ML estimation based on the complete data: maximization of $\mathcal{L} = \sum_{p=1}^P \mathcal{L}_{(p)}$.

The block specific problem is the simplest of the two, although more complicated than the ML problem for regression systems with balanced panel data, constant coefficients and random intercepts, see Avery (1977) and Baltagi (1980), as different units have different $\boldsymbol{\Omega}_{(ip)}$ matrices, as shown by (2.10). The complexity of the full ML problem is larger because the unbalance implies that the \mathbf{y} , \mathbf{X} , and $\boldsymbol{\Omega}$ matrices have different number of rows, reflecting the different number of observations of the units: while $\boldsymbol{\Sigma}^u$ and $\boldsymbol{\Sigma}^\delta$ have the same dimensions throughout, the dimensions of

$\mathbf{X}_{(ip)}$ and \mathbf{I}_p , and hence of $\mathbf{\Omega}_{(ip)}$, differ. Below the structure of these two problems is outlined.

ML estimation for block p . Setting the derivatives of $\mathcal{L}_{(p)}$ with respect to $\boldsymbol{\beta}$, $\boldsymbol{\Sigma}^u$, $\boldsymbol{\Sigma}^\delta$ equal to zero we obtain

$$(3.4) \quad \sum_{i=1}^{N_p} \left(\frac{\partial Q_{(ip)}}{\partial \boldsymbol{\beta}} \right) = \mathbf{0}_{K,1},$$

$$(3.5) \quad \sum_{i=1}^{N_p} \left[\frac{\partial \ln |\mathbf{\Omega}_{(ip)}|}{\partial \boldsymbol{\Sigma}^u} + \frac{\partial Q_{(ip)}}{\partial \boldsymbol{\Sigma}^u} \right] = \mathbf{0}_{G,G},$$

$$\sum_{i=1}^{N_p} \left[\frac{\partial \ln |\mathbf{\Omega}_{(ip)}|}{\partial \boldsymbol{\Sigma}^\delta} + \frac{\partial Q_{(ip)}}{\partial \boldsymbol{\Sigma}^\delta} \right] = \mathbf{0}_{K,K}.$$

These first-order conditions define the solution to the ML problem for block p , each p giving a distinct estimator set. Conditions (3.4) coincide with those that solve the GLS problem for $\boldsymbol{\beta}$ for block p , conditional on $\boldsymbol{\Sigma}^u$ and $\boldsymbol{\Sigma}^\delta$, and its solution is

$$(3.6) \quad \hat{\boldsymbol{\beta}}_{(p)}^{GLS} = [\sum_{i=1}^{N_p} \mathbf{X}'_{(ip)} \mathbf{\Omega}_{(ip)}^{-1} \mathbf{X}_{(ip)}]^{-1} [\sum_{i=1}^{N_p} \mathbf{X}'_{(ip)} \mathbf{\Omega}_{(ip)}^{-1} \mathbf{y}_{(ip)}].$$

Inserting $\boldsymbol{\beta} = \hat{\boldsymbol{\beta}}_{(p)}^{GLS}$ in (3.1) and (3.2) gives the concentrated log-likelihood function for block p , which when maximized with respect to $\boldsymbol{\Sigma}^u$, $\boldsymbol{\Sigma}^\delta$ gives block specific ML estimators.

ML estimation for all blocks jointly. Setting the derivatives of \mathcal{L} with respect to $\boldsymbol{\beta}$, $\boldsymbol{\Sigma}^u$, $\boldsymbol{\Sigma}^\delta$ equal to zero we obtain

$$(3.7) \quad \sum_{p=1}^P \sum_{i=1}^{N_p} \left[\frac{\partial Q_{(ip)}}{\partial \boldsymbol{\beta}} \right] = \mathbf{0}_{K,1},$$

$$(3.8) \quad \sum_{p=1}^P \sum_{i=1}^{N_p} \left[\frac{\partial \ln |\mathbf{\Omega}_{(ip)}|}{\partial \boldsymbol{\Sigma}^u} + \frac{\partial Q_{(ip)}}{\partial \boldsymbol{\Sigma}^u} \right] = \mathbf{0}_{G,G},$$

$$\sum_{p=1}^P \sum_{i=1}^{N_p} \left[\frac{\partial \ln |\mathbf{\Omega}_{(ip)}|}{\partial \boldsymbol{\Sigma}^\delta} + \frac{\partial Q_{(ip)}}{\partial \boldsymbol{\Sigma}^\delta} \right] = \mathbf{0}_{K,K}.$$

Conditions (3.7) coincide with those that solve the full GLS problem for $\boldsymbol{\beta}$, conditional on $\boldsymbol{\Sigma}^u$ and $\boldsymbol{\Sigma}^\delta$, and we find

$$(3.9) \quad \hat{\boldsymbol{\beta}}^{GLS} = [\sum_{p=1}^P \sum_{i=1}^{N_p} \mathbf{X}'_{(ip)} \mathbf{\Omega}_{(ip)}^{-1} \mathbf{X}_{(ip)}]^{-1} [\sum_{p=1}^P \sum_{i=1}^{N_p} \mathbf{X}'_{(ip)} \mathbf{\Omega}_{(ip)}^{-1} \mathbf{y}_{(ip)}].$$

Inserting $\boldsymbol{\beta} = \hat{\boldsymbol{\beta}}^{GLS}$ in (3.1) and (3.3) gives the concentrated log-likelihood function, which when maximized with respect to $\boldsymbol{\Sigma}^u$ and $\boldsymbol{\Sigma}^\delta$ to gives their ML estimators.

4 SIMPLIFIED ESTIMATION PROCEDURES

To implement ML as outlined above, in terms of analytical matrix derivatives, is complicated. In particular the procedures for estimating $\boldsymbol{\Sigma}^u$ and $\boldsymbol{\Sigma}^\delta$ are simpler than those following from differentiation of the concentrated log-likelihood functions. Below we present simplified, stepwise procedures. We describe the full procedure as an algorithm with four elements:

- A. Initial OLS estimation of $\beta_{(ip)}$ and β .
- B. Initial estimation of Σ^u, Σ^δ from disturbances and coefficient-slacks.
- C. Revised GLS estimation of $\beta_{(ip)}$ and β .
- D. Revised estimation of Σ^u, Σ^δ from updated disturbances and coefficient-slacks.

A. First-round OLS estimation of β . Consider first the estimation of the expected coefficient vector β . We start by computing *unit specific* OLS estimators separately for all units for which a sufficient number of observations permitting such estimation exist. This means that in each equation, the number of observations p must exceed the number of coefficients, including the intercept.³ Let q denote the lowest value of p that permits OLS estimation of all G equations. The estimator of the coefficient vector for unit (ip) , formally conditioning inference on $\beta_{(ip)}$, is

$$(4.1) \quad \hat{\beta}_{(ip)} = \begin{bmatrix} \hat{\beta}_{1(ip)} \\ \vdots \\ \hat{\beta}_{G(ip)} \end{bmatrix} = [\mathbf{X}'_{(ip)} \mathbf{X}_{(ip)}]^{-1} [\mathbf{X}'_{(ip)} \mathbf{y}_{(ip)}] = \begin{bmatrix} [\mathbf{X}'_{1(ip)} \mathbf{X}_{1(ip)}]^{-1} [\mathbf{X}'_{1(ip)} \mathbf{y}_{1(ip)}] \\ \vdots \\ [\mathbf{X}'_{G(ip)} \mathbf{X}_{G(ip)}]^{-1} [\mathbf{X}'_{G(ip)} \mathbf{y}_{G(ip)}] \end{bmatrix}.$$

Inserting from (2.8) we find that $\hat{\beta}_{(ip)}$ is unbiased for β , with covariance matrix

$$(4.2) \quad \mathbf{V}(\hat{\beta}_{(ip)}) = [\mathbf{X}'_{(ip)} \mathbf{X}_{(ip)}]^{-1} [\mathbf{X}'_{(ip)} \boldsymbol{\Omega}_{(ip)} \mathbf{X}_{(ip)}] [\mathbf{X}'_{(ip)} \mathbf{X}_{(ip)}]^{-1},$$

while conditional on $\beta_{(ip)}$ it is unbiased with covariance matrix⁴

$$\mathbf{V}(\hat{\beta}_{(ip)} | \beta_{(ip)}) = [\mathbf{X}'_{(ip)} \mathbf{X}_{(ip)}]^{-1} [\mathbf{X}'_{(ip)} (\mathbf{I}_p \otimes \Sigma^u) \mathbf{X}_{(ip)}] [\mathbf{X}'_{(ip)} \mathbf{X}_{(ip)}]^{-1},$$

A first-round estimator of β based on the observations from the units observed p times is the sample mean of the unit specific OLS estimators as

$$(4.3) \quad \hat{\beta}_{(p)} = \frac{1}{N_p} \sum_{i=1}^{N_p} \hat{\beta}_{(ip)} = \frac{1}{N_p} \sum_{i=1}^{N_p} [\mathbf{X}'_{(ip)} \mathbf{X}_{(ip)}]^{-1} [\mathbf{X}'_{(ip)} \mathbf{y}_{(ip)}], \quad p = q, \dots, P.$$

A corresponding estimator, based on all observations from units observed *at least* q times, can be obtained as the mean of the $\sum_{p=q}^P N_p$ unit specific estimators:

$$(4.4) \quad \hat{\beta} = [\sum_{p=q}^P N_p]^{-1} \sum_{p=q}^P \sum_{i=1}^{N_p} \hat{\beta}_{(ip)} = [\sum_{p=q}^P N_p]^{-1} \sum_{p=q}^P \sum_{i=1}^{N_p} [\mathbf{X}'_{(ip)} \mathbf{X}_{(ip)}]^{-1} [\mathbf{X}'_{(ip)} \mathbf{y}_{(ip)}].$$

B. First-round estimation of Σ^u and Σ^δ . Construct from (4.1) the $(Gp \times 1)$ OLS residual vector corresponding to $\mathbf{u}_{(ip)}$ and rearrange it into a $(G \times p)$ matrix $\hat{\mathbf{U}}_{(ip)}$:

$$\hat{\mathbf{u}}_{(ip)} = \begin{bmatrix} \hat{\mathbf{u}}_{1(ip)} \\ \vdots \\ \hat{\mathbf{u}}_{G(ip)} \end{bmatrix} = \mathbf{y}_{(ip)} - \mathbf{X}_{(ip)} \hat{\beta}_{(ip)}, \quad \hat{\mathbf{U}}_{(ip)} = \begin{bmatrix} \hat{\mathbf{u}}'_{1(ip)} \\ \vdots \\ \hat{\mathbf{u}}'_{G(ip)} \end{bmatrix}.$$

Element (g, t) of $\hat{\mathbf{U}}_{(ip)}$ is residual t of unit (ip) in equation g . From observations on the units observed p times we obtain a *block* p -specific estimate of Σ^u by analogous moments in residuals,

³We here neglect possible cross-equational coefficient restrictions.

⁴If Σ^u is diagonal it can be simplified to $\mathbf{V}(\hat{\beta}_{(ip)} | \beta_{(ip)}) = \begin{bmatrix} \sigma_{11}^u (\mathbf{X}'_{1(ip)} \mathbf{X}_{1(ip)})^{-1} \\ \vdots \\ \sigma_{GG}^u (\mathbf{X}'_{G(ip)} \mathbf{X}_{G(ip)})^{-1} \end{bmatrix}$.

$$(4.5) \quad \widehat{\Sigma}_{(p)}^u = \frac{1}{N_p p} \sum_{i=1}^{N_p} \widehat{U}_{(ip)} \widehat{U}_{(ip)}', \quad p = q, \dots, P,$$

and, using (4.1) and (4.3), obtain from the resulting coefficient-slack vectors $\widehat{\beta}_{(ip)} - \widehat{\beta}_{(p)}$ a *block* p -specific estimate of the covariance matrix of the coefficient vector, Σ^δ , by using its empirical counterpart, *i.e.*,⁵

$$(4.6) \quad \widehat{\Sigma}_{(p)}^\delta = \frac{1}{N_p} \sum_{i=1}^{N_p} (\widehat{\beta}_{(ip)} - \widehat{\beta}_{(p)}) (\widehat{\beta}_{(ip)} - \widehat{\beta}_{(p)})', \quad p = q, \dots, P.$$

Inserting $\widehat{\Sigma}_{(p)}^u$ and $\widehat{\Sigma}_{(p)}^\delta$ into the expression for $\Omega_{(ip)}$ given by (2.10), we get the following estimator *based solely on the observations from block* p :

$$(4.7) \quad \widehat{\Omega}_{(ip)p} = \mathbf{X}_{(ip)} \widehat{\Sigma}_{(p)}^\delta \mathbf{X}_{(ip)}' + \mathbf{I}_p \otimes \widehat{\Sigma}_{(p)}^u, \quad i = 1, \dots, N_p; \quad p = q, \dots, P.$$

It can be inserted into (4.2) to give an estimator of $V(\widehat{\beta}_{(ip)})$.

An estimator of Σ^u based on observations from all units observed at least q times can now be obtained as

$$(4.8) \quad \widehat{\Sigma}^u = [\sum_{p=q}^P N_p p]^{-1} \sum_{p=q}^P \sum_{i=1}^{N_p} \widehat{U}_{(ip)} \widehat{U}_{(ip)}' = [\sum_{p=q}^P N_p p]^{-1} \sum_{p=q}^P N_p p \widehat{\Sigma}_{(p)}^u.$$

The corresponding estimator of Σ^δ is

$$(4.9) \quad \widehat{\Sigma}^\delta = [\sum_{p=q}^P N_p]^{-1} \sum_{p=q}^P \sum_{i=1}^{N_p} (\widehat{\beta}_{(ip)} - \widehat{\beta}) (\widehat{\beta}_{(ip)} - \widehat{\beta})',$$

which exploits the overall slacks in the $\widehat{\beta}_{(ip)}$'s. Inserting $\widehat{\Sigma}^u$ and $\widehat{\Sigma}^\delta$ in (2.10), we get the following estimator based on all observations:⁶

$$(4.10) \quad \widehat{\Omega}_{(ip)} = \mathbf{X}_{(ip)} \widehat{\Sigma}^\delta \mathbf{X}_{(ip)}' + \mathbf{I}_p \otimes \widehat{\Sigma}^u, \quad i = 1, \dots, N_p; \quad p = 1, \dots, P.$$

Since (4.1) and (4.4) imply

$$\begin{aligned} & [\sum_{p=q}^P N_p]^{-1} \sum_{p=q}^P \sum_{i=1}^{N_p} (\widehat{\beta}_{(ip)} - \widehat{\beta}) (\widehat{\beta}_{(ip)} - \widehat{\beta})' \\ &= [\sum_{p=q}^P N_p]^{-1} \sum_{p=q}^P \sum_{i=1}^{N_p} (\widehat{\beta}_{(ip)} - \widehat{\beta}_{(p)}) (\widehat{\beta}_{(ip)} - \widehat{\beta}_{(p)})' \\ & \quad + [\sum_{p=q}^P N_p]^{-1} \sum_{p=q}^P N_p (\widehat{\beta}_{(p)} - \widehat{\beta}) (\widehat{\beta}_{(p)} - \widehat{\beta})', \end{aligned}$$

$\widehat{\Sigma}^\delta$ can be rewritten as the following counterpart to (4.8)

$$(4.11) \quad \widehat{\Sigma}^\delta = [\sum_{p=q}^P N_p]^{-1} \sum_{p=q}^P N_p \widehat{\Sigma}_{(p)}^\delta + [\sum_{p=q}^P N_p]^{-1} \sum_{p=q}^P N_p (\widehat{\beta}_{(p)} - \widehat{\beta}) (\widehat{\beta}_{(p)} - \widehat{\beta})'.$$

It shows that $\widehat{\Sigma}^\delta$ can be separated into components representing within- and between-block variation in the $\widehat{\beta}$'s, the former a weighted mean of the block specific estimators given by (4.6), the latter a positive definite quadratic form.

C. Second-round GLS estimation of β . Once we have estimated the $\Omega_{(ip)}$'s from (4.10), (asymptotically) more efficient estimators of β can be constructed. The two former steps took the unit specific *OLS* estimators of the coefficient vector, (4.1), as

⁵This estimator is positive definite and consistent if both p and N_p go to infinity. It is not, however, unbiased in finite samples. Modified estimators for similar balanced situations are considered in Hsiao (2003, pp. 146–147).

⁶Note that while $\widehat{\Omega}_{(ip)}$ is constructed from observations from all units, $\widehat{\Sigma}^u$ and $\widehat{\Sigma}^\delta$ are constructed from observations from units observed *at least* q times.

starting point. In this step we start from the more efficient unit- and block specific GLS estimators. We then replace $\widehat{\beta}_{(ip)}$ by

$$(4.12) \quad \widetilde{\beta}_{(ip)} = [\mathbf{X}'_{(ip)} \boldsymbol{\Omega}_{(ip)}^{-1} \mathbf{X}_{(ip)}]^{-1} [\mathbf{X}'_{(ip)} \boldsymbol{\Omega}_{(ip)}^{-1} \mathbf{y}_{(ip)}], \quad i = 1, \dots, N_p; \quad p = q, \dots, P.$$

We here proceed as if the $\boldsymbol{\Omega}_{(ip)}$'s are known. In practice, we may use either the estimators $\widehat{\boldsymbol{\Omega}}_{(ip)}$ from step **B** or estimate the $\boldsymbol{\Omega}_{(ip)}$'s from recomputed GLS residuals and coefficient-slacks, as will be described below. From (3.1) and (4.1) it can be shown that $\widetilde{\beta}_{(ip)}$ is unbiased, with

$$(4.13) \quad \mathbf{V}(\widetilde{\beta}_{(ip)}) = [\mathbf{X}'_{(ip)} \boldsymbol{\Omega}_{(ip)}^{-1} \mathbf{X}_{(ip)}]^{-1},$$

and that $\mathbf{V}(\widehat{\beta}_{(ip)}) - \mathbf{V}(\widetilde{\beta}_{(ip)})$ is positive definite.

A revised estimator of β based on the observations from block p can then be defined as the matrix weighted mean of the unit specific GLS estimators, the matrix weight being their respective inverse covariance matrices:

$$(4.14) \quad \beta_{(p)}^* = [\sum_{i=1}^{N_p} \mathbf{V}(\widetilde{\beta}_{(ip)})^{-1}]^{-1} [\sum_{i=1}^{N_p} \mathbf{V}(\widetilde{\beta}_{(ip)})^{-1} \widetilde{\beta}_{(ip)}] \quad p = q, \dots, P.$$

From (4.12) and (4.13) it follows that $\beta_{(p)}^*$ equals the strict GLS estimator for block p , $\widehat{\beta}_{(p)}^{GLS}$, given in (3.6) as the solution to the ML problem for block p conditional on $\boldsymbol{\Sigma}^u, \boldsymbol{\Sigma}^\delta$. From (4.13) it follows, since all $\widetilde{\beta}_{(ip)}$'s are uncorrelated, that

$$(4.15) \quad \mathbf{V}(\beta_{(p)}^*) = [\sum_{i=1}^{N_p} \mathbf{X}'_{(ip)} \boldsymbol{\Omega}_{(ip)}^{-1} \mathbf{X}_{(ip)}]^{-1}.$$

The corresponding estimator of β using observations from all blocks with $p \geq q$ is

$$(4.16) \quad \begin{aligned} \beta^* &= [\sum_{p=q}^P \sum_{i=1}^{N_p} \mathbf{V}(\widetilde{\beta}_{(ip)})^{-1}]^{-1} [\sum_{p=q}^P \sum_{i=1}^{N_p} \mathbf{V}(\widetilde{\beta}_{(ip)})^{-1} \widetilde{\beta}_{(ip)}] \\ &= [\sum_{p=q}^P \sum_{i=1}^{N_p} \mathbf{X}'_{(ip)} \boldsymbol{\Omega}_{(ip)}^{-1} \mathbf{X}_{(ip)}]^{-1} [\sum_{p=q}^P \sum_{i=1}^{N_p} \mathbf{X}'_{(ip)} \boldsymbol{\Omega}_{(ip)}^{-1} \mathbf{y}_{(ip)}]. \end{aligned}$$

It equals $\widehat{\beta}^{GLS}$, given in (3.9), as the solution to the ML problem conditional on $\boldsymbol{\Sigma}^u$ and $\boldsymbol{\Sigma}^\delta$, except that observations from blocks 1, 2, \dots , $q-1$ are omitted. From (4.13) it follows, because all $\widetilde{\beta}_{(ip)}$'s are uncorrelated, that

$$(4.17) \quad \mathbf{V}(\beta^*) = [\sum_{p=q}^P \sum_{i=1}^{N_p} \mathbf{X}'_{(ip)} \boldsymbol{\Omega}_{(ip)}^{-1} \mathbf{X}_{(ip)}]^{-1}.$$

D. Second-round estimation of $\boldsymbol{\Sigma}^u$ and $\boldsymbol{\Sigma}^\delta$. Using the second-round estimators of β obtained **C**, we can update the estimators $\boldsymbol{\Sigma}^u$ and $\boldsymbol{\Sigma}^\delta$ obtained in the first round. We construct from the unit-specific GLS estimators $\widetilde{\beta}_{(ip)}$ the $(Gp \times 1)$ residual vector corresponding to $\mathbf{u}_{(ip)}$ and rearrange it into the $(G \times p)$ matrix $\widetilde{\mathbf{U}}_{(ip)}$ as follows:

$$\widetilde{\mathbf{u}}_{(ip)} = \begin{bmatrix} \widetilde{\mathbf{u}}_{1(ip)} \\ \vdots \\ \widetilde{\mathbf{u}}_{G(ip)} \end{bmatrix} = \mathbf{y}_{(ip)} - \mathbf{X}_{(ip)} \widetilde{\beta}_{(ip)}, \quad \widetilde{\mathbf{U}}_{(ip)} = \begin{bmatrix} \widetilde{\mathbf{u}}'_{1(ip)} \\ \vdots \\ \widetilde{\mathbf{u}}'_{G(ip)} \end{bmatrix}.$$

The second-round estimator of $\boldsymbol{\Sigma}^u$ and $\boldsymbol{\Sigma}^\delta$ for block p , updating $\widehat{\boldsymbol{\Sigma}}_{(p)}^u$ and $\widehat{\boldsymbol{\Sigma}}_{(p)}^\delta$, given by (4.5) and (4.6). now using the coefficient-slack vectors $\widetilde{\beta}_{(ip)} - \beta_{(p)}^*$, are, respectively

$$(4.18) \quad \tilde{\Sigma}_{(p)}^u = \frac{1}{N_p p} \sum_{i=1}^{N_p} \tilde{U}_{(ip)} \tilde{U}_{(ip)}',$$

$$(4.19) \quad \tilde{\Sigma}_{(p)}^\delta = \frac{1}{N_p} \sum_{i=1}^{N_p} (\tilde{\beta}_{(ip)} - \beta_{(p)}^*)(\tilde{\beta}_{(ip)} - \beta_{(p)}^*)', \quad p = q, \dots, P.$$

We can then update $\hat{\Omega}_{(ip)p}$, given by (4.7), by

$$(4.20) \quad \tilde{\Omega}_{(ip)p} = \mathbf{X}_{(ip)} \tilde{\Sigma}_{(p)}^\delta \mathbf{X}_{(ip)}' + \mathbf{I}_p \otimes \tilde{\Sigma}_{(p)}^u, \quad i = 1, \dots, N_p; \quad p = q, \dots, P.$$

The second-round estimator of Σ^u and Σ^δ , updating $\hat{\Sigma}^u$ and $\hat{\Sigma}^\delta$, given by (4.8) and (4.9), respectively, are

$$(4.21) \quad \tilde{\Sigma}^u = [\sum_{p=q}^P N_p p]^{-1} \sum_{p=q}^P \sum_{i=1}^{N_p} \tilde{U}_{(ip)} \tilde{U}_{(ip)}',$$

$$(4.22) \quad \tilde{\Sigma}^\delta = [\sum_{p=q}^P N_p]^{-1} \sum_{p=q}^P \sum_{i=1}^{N_p} (\tilde{\beta}_{(ip)} - \beta^*)(\tilde{\beta}_{(ip)} - \beta^*)'.$$

We finally update the estimators of $\Omega_{(ip)}$, obtained from (4.10) by using

$$(4.23) \quad \tilde{\Omega}_{(ip)} = \mathbf{X}_{(ip)} \tilde{\Sigma}^\delta \mathbf{X}_{(ip)}' + \mathbf{I}_p \otimes \tilde{\Sigma}^u, \quad i = 1, \dots, N_p; \quad p = 1, \dots, P.$$

5 STEPWISE, MODIFIED ML ALGORITHMS

Stepwise modified estimation algorithms for $(\beta, \Sigma^u, \Sigma^\delta)$ can be constructed by compiling the procedures described in Section 4. Below, we summarize such an algorithm. It can be considered a modified ML algorithm, provided it, when iterated according to a prescribed criterion, converges towards a unique solution. We specify it for both block specific estimation and for estimation using the full data set. Block-specific estimates can be obtained for any block $p \in [q, P]$, where q still denotes the lowest value of p for which OLS estimation is possible for all G equations.

ALGORITHM FOR ONE BLOCK p :

- 1: Estimate by (4.1) for one $p (\geq q)$, $i = 1, \dots, N_p$, unit-specific estimators of β . Extract the corresponding OLS residuals.
- 2: Compute from (4.3) an estimator of β for block p .
- 3: Compute from (4.5)–(4.6) block specific estimators of Σ^u and Σ^δ .
- 4: Compute from (4.7) $\hat{\Omega}_{(ip)p}$ for $i = 1, \dots, N_p$.
- 5: Insert $\Omega_{(ip)} = \hat{\Omega}_{(ip)p}$ into (4.12) and (4.14) to compute the unit- and block-specific estimators $\tilde{\beta}_{(ip)}$ and $\beta_{(p)}^*$.
- 6: Extract revised residuals and coefficient-slacks and recompute from (4.18)–(4.19) block-specific estimators of Σ^u and Σ^δ .
- 7: Compute $\tilde{\Omega}_{(ip)p}$ from (4.20) for $i = 1, \dots, N_p$.
- 8: Insert $\Omega_{(ip)} = \tilde{\Omega}_{(ip)p}$ into (4.12) and (4.14) and recompute $\tilde{\beta}_{(ip)}$ and $\beta_{(p)}^*$.

ALGORITHM FOR THE FULL DATA SET

- 1: Estimate by (4.1) unit-specific estimators of β for $i = 1, \dots, N_p$; $p \in [q, P]$. Extract the corresponding OLS residuals.
- 2: Compute from (4.4) an estimator of β from the data for blocks $p \in [q, P]$.
- 3: Compute from (4.8)–(4.9) overall estimators of Σ^u and Σ^δ .
- 4: Compute from (4.10) $\hat{\Omega}_{(ip)}$ for $i = 1, \dots, N_p$; $p \in [1, P]$.

- 5: Insert $\Omega_{(ip)} = \hat{\Omega}_{(ip)}$ into (4.12) and (4.16) to compute $\tilde{\beta}_{(ip)}$ and β^* .
- 6: Extract revised residuals and coefficient-slacks and recompute from (4.21)–(4.22) overall estimators of Σ^u and Σ^δ .
- 7: Compute $\tilde{\Omega}_{(ip)}$ from (4.23) for $i = 1, \dots, N_p$; $p \in [1, P]$.
- 8: Insert $\Omega_{(ip)} = \tilde{\Omega}_{(ip)}$ into (4.16) and recompute β^* .

Steps 6–8 can be iterated till convergence, according to some criterion.

If, after iteration of steps 6–8, the latter eight-step algorithm converges towards a unique solution, it gives our modified ML estimator.

6 AN APPLICATION

Parts of the approach described above are applied to data for the Pulp and Paper industry in Norway for the years 1972–1993. With $T=22$ this is a rather long panel of micro manufacturing data. A substantial part of the sample relates to firms observed in the full 22 years, but sample attrition and accretion as well as gaps in the series have resulted in a data set with also firms responding $p = 1, 2, \dots, 21$ years included. The data set comes from virtually the same source as that used in Biørn, Lindquist, and Skjerpen (2002). For the present application not all available observations are exploited. Only a selection of about two thirds, $N = 111$ firms, those observed $p = 22, 21, 20, 10, 7, 5$ times – *i.e.*, 6 blocks among the original 22 are included. One reason why we have ‘curtailed’ the data set in this way is that N_p for several p is quite low, giving potentially ‘volatile’ estimates in the block-specific regressions. The number of observations from the firms selected is $n = 1891$, giving an average of $n/N = 17$ observations per firm. The design of this data set is described in Table 1.

Our model example has $G = 3$ equations, all containing the same $K = 2$ regressors. Given the rather small data set, with some units observed only 5 times, it is essential to keep the dimension of the regressor vector small.⁷ Within this setting, the model is intended to explain, in a simplistic way, total factor cost per unit of output as well as cost shares for two inputs. The first equation expresses the log of the variable cost per unit of output as functions of the log of output and the log of the material price/labour cost. In this way the potential presence of non-constant returns to scale (non-unitary scale elasticity) can be examined. Equations two and three express, respectively, the cost share of materials and the cost share of labour as functions of the same exogenous variables. Technical change is, for simplicity, disregarded.⁸ The specific variable definitions are:

$$y_1, y_2, y_3 = \log cx, \text{ csm}, \text{ csl} \text{ (endogenous)}, \quad x_1, x_2 = \log x, \log pml \text{ (exogenous)},$$

where

⁷For an elaboration of this issue for a, somewhat related, random coefficient analysis based on a small-sized *balanced* panel data set, see Biørn *et al.* (2010, Section 4.2).

⁸The underlying total cost also includes energy cost, which is not modelled in the example. Neither are capital cost and capital input represented in the model. Hence, we have no ‘full’ cost function represented.

$\log cx = \log(\text{cost/output}),$
 $csm = \text{cost of materials as share of total cost},$
 $csl = \text{cost of labour as share of total cost},$
 $\log x = \log(\text{output}),$
 $\log pml = \log(\text{material price/labour cost}).$

Tables 2 through 6 collect results from this application, the *con* columns in Tables 2 and 5 relating to the intercept of the equations. Supplementary, block-specific results are given in the Appendix. All computations are done by routines programmed in the Gauss software code.

First, Table 2 contains, as benchmarks, OLS estimates based on all $n = 1891$ observations and standard errors *for the u disturbances* ($\hat{\sigma}_u$) and coefficient standard errors calculated in the ‘customary’ way neglecting coefficient heterogeneity. The empirical means of the n coefficient estimates, as obtained from (4.1) and (4.4), and the empirical standard deviations computed from the former are reported in Table 3. Not surprisingly, the two sets overall ‘means’ differ substantially, reflecting, *inter alia*, their different weighting of the firm-specific estimates in the aggregates. These means agree with respect to sign, but differ substantially in magnitude. The empirical standard deviations in Table 3 signalize considerable coefficient heterogeneity.

The block-specific estimates underlying the overall estimates in Table 3 are given in the Appendix; see columns 1–4 of the A panels of Table A.1. The block-specific OLS standard errors of regression (SER), computed in the ‘customary’ way, are given in column 5. In columns 1–4 of the B panels of Table A.1, the block-specific coefficient distributions are described by their estimated skewness and kurtosis. By and large, the kurtosis estimates do not depart substantially from their value under normality, which is 3. The majority of the skewness estimates are in the $(-1, +1)$ range, indicating both left-skewed and right-skewed coefficient distributions. Columns 5–6 of the B panels contain the empirical means of the standard error estimates of the firm-specific estimates, while column 7 gives the means of estimated standard errors of the u disturbances, $\hat{\sigma}_u$, corresponding to the overall estimate in Table 2, column 4. Their orders of magnitude are similar.

The covariance matrix of the ‘coefficient-slack’ vector, $\hat{\Sigma}^\delta$, as estimated from (4.1), (4.4) and (4.9), is given in Table 6. The covariance matrix of the ‘genuine disturbance vector’ $\mathbf{u}_{(ip)}$, *i.e.*, $\hat{\Sigma}^u$, as estimated from (4.8), the residual vectors being $\hat{\mathbf{u}}_{(ip)} = \mathbf{y}_{(ip)} - \mathbf{X}_{(ip)}\hat{\boldsymbol{\beta}}_{(ip)}$, is given in Table 4.

Finally, Table 5 gives the overall Feasible Generalized Least Squares (FGLS) estimates, as obtained from (4.16), with their standard errors obtained from the diagonal elements of (4.17). The standard errors exceed those in Table 2 by a large margin. This is as expected, since the former refer to a model which disregards any coefficient heterogeneity, while the latter fully capture this heterogeneity, ‘weighting together’ the effects of the firm-to-firm ‘coefficient slack’ and genuine ‘disturbance noise’. We find clear evidence of increasing returns to scale, as $\log x$ comes out with a significantly negative estimate of the *expected* coefficient in the $\log cx$ equation,

implying an elasticity of cost with respect to output in the (0,1) interval. Increasing the production scale affects the materials cost share negatively and the labour cost share positively, and the effect is significant at ‘standard’ p -values. Also the logged factor price ratio comes out with significant responses, again in the expected coefficient value sense.

Overall, with respect to sign, these results based on FGLS and the random coefficient setup, in Table 5 can be said to ‘robustify’ the results based on simple OLS estimation in Table 2, but the coefficient estimates deviate substantially. Block specific FGLS estimates underlying those in Table 5, computed from (4.14) and (4.15), are given in the Appendix, Table A.2. Most of the estimated expected coefficients come out as *insignificant*, except for the $p = 22$ block, for which both the number of firms and the number of observations are by far the largest. One notable exception is that $\log x$ comes out with an estimate close to zero in the $\log c x$ equation, suggesting constant returns to scale.

Table 1: Panel design

p	N_p	$N_p p$
22	61	1342
21	8	168
20	6	120
10	11	110
7	13	91
5	12	60
Σ	111	1891

Table 2: Overall OLS Estimates, for all blocks ($p=22, 21, 20, 10, 7, 5$)

Standard errors, from OLS formula *neglecting coefficient heterogeneity*, in square bracket

Eq. with LHS VAR	con	$\log x$	$\log pml$	OLS SER: $\hat{\sigma}_u$
$\log c x$	0.6609 [0.2843]	-0.3008 [0.0094]	0.6786 [0.0661]	0.2802
csm	0.5630 [0.0399]	-0.0439 [0.0013]	0.0244 [0.0093]	0.0340
csl	0.5950 [0.0455]	0.0283 [0.0015]	-0.0400 [0.0106]	0.0395

Table 3: Means ($\hat{\beta}$) and Standard deviations of OLS estimates. All firms

Means based on (4.1) and (4.4). Standard deviations based on (4.1).

Eq. with LHS var	$\hat{\beta} = \text{Mean of } \hat{\beta}_{(ip)}$		Emp.st.dev. of $\hat{\beta}_{(ip)}$	
	$\log x$	$\log pml$	$\log x$	$\log pml$
$\log c x$	-0.2461	0.8074	0.8424	0.9871
csm	-0.0377	0.0823	0.0722	0.1360
csl	0.0369	-0.1138	0.0785	0.1413

Table 4: Disturbance covariance matrix $\hat{\Sigma}^u$, estimated from (4.8)

LHS var:	LHS var:		
	<i>logcx</i>	<i>csm</i>	<i>csl</i>
<i>logcx</i>	0.0785		
<i>csm</i>	-0.0026	0.0012	
<i>csl</i>	0.0008	-0.0011	0.0016

Table 5: Overall FGLS Coefficient Estimates, β^* , based on (4.16)–(4.17)

Standard errors, from estimated $\text{diag}[V(\beta^*)]^{1/2}$, in parenthesis.

Eq. with LHS var:	RHS var:		
	<i>con</i>	<i>logx</i>	<i>logpml</i>
<i>logcx</i>	-1.9173 (0.9393)	-0.2158 (0.0852)	0.9230 (0.1073)
<i>csm</i>	0.2684 (0.0935)	-0.0367 (0.0076)	0.0742 (0.0144)
<i>csl</i>	0.8984 (0.1007)	0.0327 (0.0083)	-0.1112 (0.0152)

Table 6: Coefficient covariance matrix, $\hat{\Sigma}^\delta$, estimated from (4.9)

	Eq. with LHS var: <i>logcx</i>			Eq. with LHS var: <i>csm</i>			Eq. with LHS var: <i>csl</i>		
	<i>con</i>	<i>logx</i>	<i>logpml</i>	<i>con</i>	<i>logx</i>	<i>logpml</i>	<i>con</i>	<i>logx</i>	<i>logpml</i>
<i>con</i>	82.6957								
<i>logx</i>	-6.7030	0.7096							
<i>logpml</i>	-4.0870	0.0010	0.9744						
<i>con</i>	-2.3112	0.1591	0.1955	0.7651					
<i>logx</i>	0.1653	-0.0144	-0.0075	-0.0429	0.0052				
<i>logpml</i>	0.2056	-0.0082	-0.0316	-0.0813	-0.0004	0.0185			
<i>con</i>	0.2429	0.0143	-0.1378	-0.6685	0.0376	0.0713	0.8655		
<i>logx</i>	0.0079	-0.0018	0.0074	0.0358	-0.0047	0.0009	-0.0512	0.0062	
<i>logpml</i>	-0.1156	0.0056	0.0155	0.0757	0.0005	-0.0174	-0.0840	-0.0008	0.0200

Square root of elements of $\text{diag}[\hat{\Sigma}^\delta]$

Eq. with LHS var:	RHS var:		
	<i>con</i>	<i>logx</i>	<i>logpml</i>
<i>logcx</i>	9.0937	0.8424	0.9871
<i>csm</i>	0.8747	0.0722	0.1360
<i>csl</i>	0.9303	0.0785	0.1413

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Table A.1: *Block-specific OLS results and summary statistics*

A. Means and Standard deviations of firm specific coefficient estimates (4.1)

	LHS Var.	$\hat{\beta}_{(p)} = \text{Mean of } \hat{\beta}_{(ip)}$ $\log x$ $\log pml$		Emp.st.dev. of $\hat{\beta}_{(ip)}$ $\log x$ $\log pml$		Block OLS SER
$p = 22$ block	$\log cx$	0.0319	1.0723	0.8952	0.8423	1.3806
	csm	-0.0447	0.0601	0.0601	0.0915	0.1542
	csl	0.0337	-0.1010	0.0659	0.1165	0.1818
$p = 21$ block	$\log cx$	-0.4422	1.0260	0.5993	0.3999	1.2822
	csm	-0.0089	0.0153	0.0635	0.1212	0.2198
	csl	-0.0045	-0.0818	0.0734	0.1637	0.2491
$p = 20$ block	$\log cx$	-0.6212	1.0240	0.3854	0.6940	1.3738
	csm	-0.0369	-0.0082	0.0403	0.1196	0.1650
	csl	0.0466	-0.0372	0.0480	0.1065	0.1936
$p = 10$ block	$\log cx$	-0.5530	0.5915	0.7356	1.0568	0.5448
	csm	-0.0581	0.0873	0.1128	0.1727	0.0992
	csl	0.0840	-0.1110	0.1188	0.1527	0.1048
$p = 7$ block	$\log cx$	-0.4860	0.5150	0.7932	1.2818	0.4772
	csm	-0.0113	0.1620	0.1001	0.1742	0.0707
	csl	0.0304	-0.1556	0.1048	0.1757	0.0757
$p = 5$ block	$\log cx$	-0.7996	-0.2786	0.4086	0.9098	0.3544
	csm	-0.0320	0.1939	0.0639	0.1728	0.0366
	csl	0.0398	-0.1954	0.0669	0.1774	0.0380

B. Across-firm Skewness and Kurtosis of coef. estimates. Means of Std.Err. estimates

	LHS Var.	Skewness of $\hat{\beta}_{(ip)}$ $\log x$ $\log pml$		Kurtosis of $\hat{\beta}_{(ip)}$ $\log x$ $\log pml$		Mean of $\hat{\sigma}_{\hat{\beta}_{(ip)}}$ $\log x$ $\log pml$		Mean of $\hat{\sigma}_u$
$p = 22$ block	$\log cx$	0.2072	-0.3719	1.8810	3.0642	0.2995	0.4323	0.3009
	csm	0.5425	0.4122	4.1847	4.8145	0.0298	0.0439	0.0312
	csl	0.0206	-0.1114	2.9044	3.1033	0.0381	0.0544	0.0379
$p = 21$ block	$\log cx$	0.3884	0.4161	1.8163	1.5646	0.3300	0.4736	0.2920
	csm	-0.2462	-0.6004	1.6532	3.2693	0.0519	0.0816	0.0471
	csl	0.1807	0.7127	1.9881	2.9226	0.0641	0.0964	0.0545
$p = 20$ block	$\log cx$	1.4469	-0.2405	3.6188	2.0464	0.2352	0.4954	0.3227
	csm	0.5037	-0.1589	2.1310	1.8273	0.0272	0.0523	0.0371
	csl	0.1325	1.0647	2.9129	2.9540	0.0340	0.0652	0.0442
$p = 10$ block	$\log cx$	-1.2123	0.0727	4.3715	2.8245	0.3023	0.4993	0.1909
	csm	-0.0205	0.2585	2.3166	2.3321	0.0477	0.0848	0.0318
	csl	0.1884	-0.4170	2.0474	2.2100	0.0479	0.0889	0.0339
$p = 07$ block	$\log cx$	-0.3412	-0.4855	2.8204	2.1651	0.3612	0.7595	0.2092
	csm	-0.1380	-0.4044	1.5448	2.5538	0.0458	0.1176	0.0310
	csl	0.1039	0.3700	1.5484	3.1027	0.0519	0.1300	0.0346
$p = 05$ block	$\log cx$	-0.7242	-0.9904	3.1037	3.0776	0.3047	0.9746	0.2190
	csm	-1.6330	0.3938	4.4491	2.3055	0.0342	0.1159	0.0235
	csl	1.2148	-0.5350	3.4305	2.7534	0.0344	0.1144	0.0241

Table A.2: *Block-specific FGLS results based on (4.14)–(4.15)*Coefficient Estimates, $\beta_{(p)}^*$. Standard errors, from estimate of $\text{diag}[\mathbf{V}(\beta_{(p)}^*)]^{1/2}$, in parenthesis

Eq. with LHS VAR	$p = 22$ block		$p = 21$ block		$p = 20$ block	
	$\log x$	$\log pml$	$\log x$	$\log pml$	$\log x$	$\log pml$
$\log cx$	-0.0004 (0.1145)	1.1254 (0.1366)	-0.4659 (0.3196)	1.0674 (0.3845)	-0.5887 (0.3549)	1.0756 (0.4376)
csm	-0.0407 (0.0102)	0.0578 (0.0185)	-0.0101 (0.0287)	0.0227 (0.0519)	-0.0345 (0.0312)	-0.0074 (0.0592)
csl	0.0291 (0.0112)	-0.0967 (0.0195)	0.0014 (0.0316)	-0.0894 (0.0547)	0.0386 (0.0341)	-0.0409 (0.0624)
Eq. with LHS VAR	$p = 10$ block		$p = 7$ block		$p = 5$ block	
	$\log x$	$\log pml$	$\log x$	$\log pml$	$\log x$	$\log pml$
$\log cx$	-0.4244 (0.2822)	0.6200 (0.3566)	-0.4835 (0.2551)	0.2797 (0.3702)	-0.6110 (0.2588)	-0.1336 (0.4164)
csm	-0.0651 (0.0256)	0.0887 (0.0474)	-0.0134 (0.0231)	0.1787 (0.0483)	-0.0263 (0.0234)	0.1787 (0.0536)
csl	0.0815 (0.0280)	-0.1244 (0.0505)	0.0228 (0.0252)	-0.1917 (0.0520)	0.0275 (0.0256)	-0.1836 (0.0578)