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Nonparametric Estimation of the Costs of Non–Sequential Search

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Abstract

We study a consumer non-sequential search oligopoly model with search cost heterogeneity. We first prove that an equilibrium in mixed strategies always exists. We then examine the nonparametric identification and estimation of the costs of search. We find that the sequence of points on the support of the search cost distribution that can be identified is convergent to zero as the number of firms increases. As a result, when the econometrician has price data from only one market, the search cost distribution cannot be identified accurately at quantiles other than the lowest. To solve this pitfall, we propose to consider a richer framework where the researcher has price data from many markets with the same underlying search cost distribution. We provide conditions under which pooling the data allows for the identification of the search cost distribution at all the points of its support. We estimate the search cost density function directly by a semi-nonparametric density estimator whose parameters are chosen to maximize the joint likelihood corresponding to all the markets. A Monte Carlo study shows the advantages of the new approach and an application using a data set of online prices for memory chips is presented.

Keywords: consumer search, oligopoly, search costs, semi-nonparametric estimation

JEL Classification: C14, D43, D83, L13
1 Introduction

A significant body of work in economics has shown that search costs have far-reaching effects in economic activity. Well-known facts are that search costs alone can lead to price dispersion (Burdett and Judd, 1983; Rob, 1985; Stahl, 1989; Varian, 1980) as well as to wage and technology dispersion (Burdett and Mortensen, 1998; Acemoglu and Shimer, 2000). Search costs can also generate excessive product diversity in differentiated product markets (Anderson and Renault, 2000; Wolinsky, 1984) as well as inefficient quality investments (Wolinsky, 2005). The existence of search costs can also explain asymmetric price-cost adjustments (Lewis, 2003; Tappata, 2007) and the emergence of different price institutions (Bester, 1994).

Given the importance of the costs of search in shaping economic outcomes, part of the recent research in the area is focusing on developing techniques to estimate search costs. This research effort goes along two dimensions. On the one hand, authors are incorporating search cost heterogeneity and market power elements in their models, which makes them empirically more appealing than earlier models. On the other hand, several estimation procedures have been proposed. Hong and Shum (2006) were the first to develop a structural method to retrieve information on search costs using market data. They focused on markets for homogeneous goods and presented various approaches to estimate non-sequential and sequential search models. Moraga-González and Wildenbeest (2007) extend the approach of Hong and Shum (2006) to the case of oligopoly and present a maximum likelihood estimation method. Hortaçu and Syverson (2004) studied a sequential search model where search frictions coexist with vertical product differentiation. In that case, both price and quantity data must be available to the econometrician.

This paper constitutes a twofold contribution to this recent literature. We study a version of the non-sequential search model presented in Burdett and Judd (1983). There are three differences between our model and Burdett and Judd’s original model. First, we consider the oligopoly case; second, we relax the assumption that the first price quotation is obtained at no cost; and third, consumers have heterogeneous search costs. Discarding any of these generalizations leads to biases in the estimates.\footnote{The assumption that the number of firms is finite is useful since it allows the researcher to distinguish between the variation in prices due to changes in the number of competitors from that due to changes in search frictions. The assumption that consumers obtain the first price at no cost has been widely adopted in the search literature and it is not without loss of generality. It implies that all consumers buy in equilibrium so firms may have so weak}
There are several reasons for focusing on non-sequential search models. First, non-sequential search is appealing in a number of relevant market situations, like when looking for a job, a house, a removal company, a mortgage, a subcontractor, or a collaborator. These situations have in common that some time elapses between the moment at which a person searches (e.g. applies for a job) and the moment at which the search outcome is observed (e.g. is hired or not). This feature, as shown in Morgan and Manning (1985), makes searching non-sequentially optimal. The second reason for focusing on the non-sequential search model is that, as shown in Hong and Shum (2006), this model can be estimated using only price data. Since researchers often encounter situations where the available data are limited, it is encouraging to have structural models which can be estimated in the absence of quantities and/or cost information.

Our first contribution pertains to the study of existence, uniqueness, and characterization of equilibrium. We first show that our model can only have mixed strategy equilibria. Despite the fact that the equilibrium price distribution cannot be obtained in closed form, we provide a useful characterization result. We show that, using the inverse of the equilibrium price distribution, one can describe a market (firm and consumer) equilibrium as the solution of a non-linear system of equations. This result is useful for two reasons. On the one hand, it provides a straightforward way to simulate a market equilibrium and therefore it helps infer the effects of various public policies. On the other hand, it helps us tackle the issue of existence of equilibrium by means of a fixed point argument. We show that an equilibrium exists. Moreover, for the special case when there are two firms operating in the market and when the curvature of the search cost distribution is small, we can show the equilibrium is unique.

The second contribution of this paper relates to the study of the nonparametric identification and estimation of the costs of non-sequential search. Given that prices reflect the search behavior of groups of consumers and not the behavior of individual buyers, it turns out that the search cost distribution can only be identified at a series of critical points that are determined by consumers’ incentives to cut each other’s prices that it potentially generates Diamond-like types of equilibrium. The assumption that consumers differ in their opportunity cost of time and therefore in their costs of search makes the model more flexible and consequently empirically more widely applicable.

2In fact, non-sequential search models have been very influential in a well-established literature in labor economics (see e.g. Burdett and Mortensen, 1998; Van den Berg and Ridder, 1998; Burdett and Coles, 2003). For a first attempt to estimate search cost distributions in labor markets see Gautier et al. (2007).

3In Burdett and Judd’s (1983) original model there is a pure-strategy equilibrium where all firms charge the monopoly price. This equilibrium fails to exist in our model because we drop the costless first-search assumption.
optimal search. In fact, if there are \( N \) firms operating in the market then only \( N \) points of the search cost distribution can be identified, each point corresponding to the search cost of the marginal consumer that is indifferent between searching \( k \) and \( k + 1 \) times. Identification of the search cost distribution in its full support, as pointed out by Hong and Shum (2006, p.262), is therefore challenging. One possibility is to consider markets with a very large number of firms. We prove that complete knowledge of the equilibrium price distribution from a market with infinitely many firms does not suffice to identify the search cost distribution completely. The reason is that the (infinite) series of critical search costs that can be retrieved from the data turns out to be convergent to zero. This property, which stems from the fact that the marginal gains from an extra search are declining in the number of searches, implies that the set of search cost values the econometrician can identify, even if the market hosts infinitely many firms, is not dense in the support of the search cost distribution. As a result, non-parametric identification of the search cost distribution at quantiles other than the lowest fails.

The importance of identifying consumer search costs accurately is illustrated by a simulation study. In this study, we first generate data by simulating the equilibrium in a market operated by three firms. Then we calculate the points of the search cost distribution that can be identified if the researcher uses data from only one market and construct an estimate of the search cost distribution by simple interpolation. The study proceeds by comparing the true effects of a merger with the predicted effects that would obtain from simulating the counterfactual using the estimated search cost distribution. The simulations reveal that the true effects of the merger differ from the estimated effects not only quantitatively but also qualitatively. In fact, the econometrician would wrongly be led to believe a merger would increase market average prices while in reality mean price would go down after a merger.

To overcome the identification problem we propose to consider a different framework where the econometrician has price data from several oligopolistic markets. In particular, we consider markets with the common feature that the search cost distribution is the same, while consumer valuations differ across markets. We provide conditions under which the search cost distribution can be identified fully in such a setting; the reason is that every market generates a distinctive set of search cost values for which the econometrician can retrieve the density of search costs, and this forces the search cost distribution to be uniquely determined for a larger set of points.
Given that we need to pool price data from multiple markets to identify and quantify search costs, it is difficult to apply the spline approximation methods employed earlier in the literature (cf. Hong and Shum, 2006; Hortacsu and Syverson, 2004; and Moraga-González and Wildenbeest, 2007). The reason is that spline approximations use procedures in which distinct markets are not linked via the same underlying search cost distribution. To exploit such linkage between markets, we propose to estimate the search cost density function directly by a flexible polynomial-type parametric function, namely, a semi-nonparametric (SNP) density estimator (Gallant and Nychka, 1987). Because the SNP density estimators approximate arbitrarily closely a large class of sufficiently smooth density functions (Gallant and Nychka, 1987), in this way we obtain an essentially nonparametric estimator of the search cost distribution common to all the markets.

To illustrate how our method works with real-world data, we apply the SNP estimation procedure to a data set of online prices for ten notebook memory chips. Our estimate of the search cost distribution shows that consumers have either quite high or quite low search costs. Consumers with high search costs do not compare prices and this gives substantial market power to the firms; as a result, estimated price-cost margins are significantly larger than what one would expect on the basis of the observed large number of firms operating in each market.

The structure of the paper is as follows. In the next section, we present the non-sequential consumer search model studied here. In Section 3 we discuss existence and uniqueness of a price dispersed symmetric equilibrium. Our identification results and our SNP estimation method are presented in Section 4. In this section we also present some simulation results illustrating the scope of the identification problem. In Section 5 we estimate the search cost distribution underlying price data from ten online markets for memory chips. Finally, Section 6 concludes. The proofs of all statements are placed in the Appendix to ease the reading.

2 The model

We examine a model of firm competition in the presence of consumer search. The model is an oligopolistic version of Burdett and Judd (1983) with consumer search cost heterogeneity and

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4A similar finding has already been reported in earlier work (cf. Moraga-González and Wildenbeest, 2007) so it is encouraging to see that it does depend neither on the estimation method nor on the dataset.
where the first price quotation is also costly to obtain.\textsuperscript{5} There are $N$ firms producing a good at constant returns to scale. Their identical unit cost is equal to $r$. There is a unit mass of buyers. Each consumer wishes to purchase a single unit of the good at most. We assume that the maximum price any buyer is willing to pay for the good is $v$. Consumers must engage in costly search to observe prices. Assume they search non-sequentially. Once a consumer has observed the desired number of prices, he/she chooses to buy from the store charging the lowest price. We assume that consumers differ in their search costs. A buyer’s search cost is drawn independently from a common atomless distribution $G(c)$ with support $(0, \infty)$ and positive density $g(c)$ everywhere. A consumer with search cost $c$ sampling $k$ firms incurs a total search cost $kc$.

Firms and buyers play a simultaneous moves game. An individual firm chooses its price taking price choices of the rivals as well as consumers’ search behavior as given. A firm $i$’s strategy is denoted by a distribution of prices $F_i(p)$. Let $F_{-i}(p)$ denote the vector of prices charged by firms other than $i$. The (expected) profit to firm $i$ from charging price $p_i$ given rivals’ strategies is denoted $\Pi(p_i, F_{-i}(p))$. Likewise, an individual buyer takes as given firm pricing and decides on his/her optimal search strategy to maximize his/her expected utility. The strategy of a consumer with search cost $c$ is then a number $k$ of prices to sample. Let the fraction of consumers sampling $k$ firms be denoted by $\mu_k$. We shall concentrate on symmetric Nash equilibria. A symmetric equilibrium is a distribution of prices $F(p)$ and a collection $\{\mu_0, \mu_1, \ldots, \mu_N\}$ such that (a) $\Pi_i(p, F_{-i}(p))$ is equal to a constant $\bar{\Pi}$ for all $p$ in the support of $F(p)$, $\forall i$; (b) $\Pi_i(p, F_{-i}(p)) \leq \bar{\Pi}$ for all $p$, $\forall i$; (c) a consumer sampling $k$ firms obtains no lower utility than by sampling any other number of firms; and (d) $\sum_{k=0}^{N} \mu_k = 1$. Let us denote the equilibrium density of prices by $f(p)$, with maximum price $\bar{p}$ and minimum price $p$.

3 Theoretical analysis

In this section we study the existence and the characterization of Nash equilibrium. Our first result indicates that, for an equilibrium to exist, there must be some consumers who search just once and others who search more than once.

\textsuperscript{5}To put the model in perspective, we note that there are only two other papers studying the estimation of non-sequential search models, namely, Hong and Shum (2006) and Moraga-González and Wildenbeest (2007). By relaxing the assumption that the first price quotation is for free, the model presented here features truly costly search and therefore generalizes previous work.
Proposition 1 If a symmetric equilibrium exists, then $1 > \mu_1 > 0$ and $\mu_k > 0$ for some $k = 2, 3, \ldots, N$.

The intuition behind this result is simple. If all consumers did search at least twice, then all firms would be subject to price comparisons with rival firms so firm pricing would be competitive; however this is contradictory because then consumers would not be willing to search that much. If no consumer compared prices instead, then firms would charge the monopoly price; however, this leads to a contradiction because in that case consumers would not be willing to search at all.\footnote{In the original model of Burdett and Judd (1983) the first price quotation is obtained at no cost and this implies that there always exists an equilibrium where all firms charge the monopoly price.}

Our next observation is that, given consumer behavior, for an equilibrium to exist it must be the case that firm pricing is characterized by mixed strategies.

Proposition 2 If a symmetric equilibrium exists, $F(p)$ must be atomless with upper bound equal to $v$.

The implication of this result is that the proportion of consumers searching for $k$ prices must be strictly positive. We now discuss consumers’ search behavior. Given that firm pricing is characterized by an atomless price distribution, a consumer with search cost $c$ will choose to sample $k$ firms provided that the following three inequalities hold:

\[
\begin{align*}
v - E[\min\{p_1, p_2, \ldots, p_k\}] - kc & > 0; \\
E[\min\{p_1, p_2, \ldots, p_{k-1}\}] - E[\min\{p_1, p_2, \ldots, p_k\}] & > c; \\
E[\min\{p_1, p_2, \ldots, p_{k+1}\}] - E[\min\{p_1, p_2, \ldots, p_k\}] & < c,
\end{align*}
\]

where $E$ denotes the expectation operator. The first condition ensures that a consumer derives positive utility from his/her search strategy. The second and third conditions ensure that a consumer finds it optimal to search for $k$ prices, neither more nor less.

Since the search cost distribution $G(c)$ has support $(0, \infty)$ and positive density everywhere, there exists a consumer indifferent between not searching at all and searching once. Let the search cost of this consumer be denoted $c_0$. Then

\[
c_0 = v - E[p],
\]
since the expected surplus for a consumer who searches one time is \( v - E[p] \). Consumers with a search cost higher than \( c_0 \) obtain negative surplus if they search. As a result, the share of consumers who do not participate in the market altogether is \( \mu_0 = \int_{c_0}^{\infty} dG(c) > 0 \).

Note now that since \( F(p) \) is atomless, the expected value of the order statistic \( E[\min\{p_1, p_2, \ldots, p_k\}] \) is a decreasing and convex function of \( k \). Therefore there exists a consumer indifferent between searching \( k \) times and searching \( k + 1 \) times. Let \( c_k \) be the search cost of this consumer. Then \( c_k \) satisfies \( v - E[\min\{p_1, p_2, \ldots, p_k\}] = kc_k = v - E[\min\{p_1, p_2, \ldots, p_{k+1}\}] - (k + 1)c_k \), i.e.,

\[
  c_k = E[\min\{p_1, p_2, \ldots, p_k\}] - E[\min\{p_1, p_2, \ldots, p_{k+1}\}] \quad \text{for} \quad k = 1, 2, \ldots, N - 1.
\]

Consumers whose search cost lies in between \( c_{k-1} \) and \( c_k \) search \( k \) times. As a result \( \mu_k = \int_{c_{k-1}}^{c_k} dG(c) > 0 \), \( k = 2, 3, \ldots, N \). The following result summarizes:

**Proposition 3** Given any atomless price distribution \( F(p) \), optimal consumer search behavior is characterized as follows: consumers whose search cost \( c < c_{N-1} \) search for \( N \) prices, consumers whose search cost \( c \in (c_{k-1}, c_k) \) search for \( k \) prices, \( k = 1, 2, \ldots, N - 1 \), and consumers whose search cost \( c > c_0 \) stay out of the market, where \( c_k, k = 0, 1, 2, \ldots, N - 1 \), is given by equations (1) and (2).

Proposition 3 shows that for any given atomless price distribution optimal consumer search leads to a unique grouping of consumers.

We now examine firm pricing behavior. Given consumer search strategies the expected profit to firm \( i \) from charging price \( p_i \) when its rivals choose a random pricing strategy according to the cumulative distribution \( F(p) \) is

\[
  \Pi_i(p_i; F(p)) = (p_i - r) \left[ \sum_{k=1}^{N} \lambda_k \mu_k (1 - F(p_i))^{k-1} \right],
\]

where \( \lambda_k \) is the probability that a consumer sampling \( k \) firms is informed of the price of firm \( i \). Firm \( i \) obtains a per consumer profit of \( p_i - r \) and sells to a consumer who compares \( k \) prices whenever the price of the other \( k - 1 \) firms is higher than the price of firm \( i \), which happens with probability \( (1 - F(p_i))^{k-1} \). The probability \( \lambda_k \) is simply the urn-ball probability that a consumer sampling \( k \) firms samples firm \( i \), i.e., \( \lambda_k = k/N \). In equilibrium, a firm must be indifferent between charging any price in the support of \( F(p) \) and charging the upper bound \( p \). Thus, any price in the support
of $F(p)$ must satisfy $\Pi_i(p_i; F(p)) = \Pi_i(p; F(p))$. Since $\Pi_i(p; F(p))$ is monotonically increasing in $p$, it must be the case that $p = v$. As a result, equilibrium requires

$$(p_i - r) \left[ \sum_{k=1}^{N} k \mu_k (1 - F(p_i))^{k-1} \right] = \mu_1 (v - r).$$  \hspace{1cm} (3)

Unfortunately, this equation cannot be solved for $F(p_i)$ analytically. However, the minimum price charged in the market can be found by setting $F(p) = 0$ and solving it for $p$. This yields:

$$p = \frac{\mu_1 (v - r)}{\sum_{k=1}^{N} k \mu_k} + r.$$  \hspace{1cm} (4)

To prove existence of an equilibrium price distribution $F(p_i)$, let us rewrite equation (3) as follows:

$$\sum_{k=1}^{N} k \mu_k (1 - F(p_i))^{k-1} = \frac{\mu_1 (v - r)}{(p_i - r)}.$$  \hspace{1cm} (5)

Note that the RHS of equation (5) is positive and does not depend on $F(p_i)$. By contrast, since $F(p_i)$ must take values on $[0, 1]$, the LHS of equation (5) is a positive-valued function that decreases in $F(p_i)$ monotonically. At $F(p_i) = 0$, the LHS takes on value $\sum_{k=1}^{N} k \mu_k$, while at $p_i = v$ it takes on value $\mu_1$. As a result, for every price $p_i \in (p, v)$, there is a unique solution to equation (5) satisfying $F(p_i) \in [0, 1]$; moreover, the solution $F(p_i)$ is monotonically increasing in $p_i$. The following result summarizes these findings.

**Proposition 4** Given consumer search behavior $\{\mu_k\}_{k=0}^{N}$, there exists a unique symmetric equilibrium price distribution $F(p)$. In equilibrium firms charge prices randomly chosen from the set $\left[ \frac{\mu_1 (v - r)}{\sum_{k=1}^{N} k \mu_k} + r, v \right]$ according to the price distribution defined implicitly by equation (3).

Proposition 4 shows that the equilibrium price distribution is unique for any given grouping of consumers. For the price distribution in Proposition 4 to be an equilibrium of the game, the conjectured grouping of consumers has to be the outcome of optimal consumer search. This requires that the following system of equations holds:

$$\mu_k = \int_{c_{k-1}}^{c_k} dG(c), \text{ for all } k = 1, 2, \ldots, N - 1; \hspace{1cm} (6a)$$

$$\mu_N = \int_{c_{N-1}}^{c_N} dG(c), \hspace{1cm} (6b)$$
with \( \mu_0 = 1 - \sum_{k=1}^{N} \mu_k \) and where \( c_0 \) and \( c_k, k = 1, 2, \ldots, N - 1 \) are the solutions to

\[
\begin{align*}
    c_0 &= v - E[p]; \quad (7a) \\
    c_k &= E[\min\{p_1, p_2, \ldots, p_k\}] - E[\min\{p_1, p_2, \ldots, p_{k+1}\}], \; k = 1, 2, \ldots, N - 1, \quad (7b)
\end{align*}
\]

where the expectation operator is taken over the distribution of prices which solves equation (3).

Using the distributions of the order statistics, and after successively integrating by parts, we can rewrite equations (7a) and (7b) as follows:

\[
\begin{align*}
    c_0 &= \int_{p}^{v} F(p) dp; \quad (8a) \\
    c_k &= \int_{p}^{v} F(p)(1 - F(p))^k dp, \; k = 1, 2, \ldots, N - 1. \quad (8b)
\end{align*}
\]

\( F(p) \) is monotonically increasing in \( p \) so we can use equation (3) to find its inverse:

\[
p(z) = \frac{\mu_1(v - r)}{\sum_{k=1}^{N} k\mu_k(1 - z)^{k-1}} + r. \quad (9)
\]

Using this inverse function, integration by parts and the change of variables \( z = F(p) \) in equations (8a) and (8b) yields:

\[
\begin{align*}
    c_0 &= v - \int_{0}^{1} p(z) dz; \quad (10a) \\
    c_k &= \int_{0}^{1} p(z)[(k + 1)z - 1](1 - z)^{k-1} dz, \; k = 1, 2, \ldots, N - 1. \quad (10b)
\end{align*}
\]

Therefore we can state that:

**Proposition 5** If a symmetric equilibrium of the game exists then consumers search according to Proposition 3, firms set prices according to Proposition 4, and the series of critical cutoff points \( \{c_k\}_{k=0}^{N-1} \) is given by the solution to the system of equations:

\[
\begin{align*}
    c_0 &= (v - r) \left( 1 - \int_{0}^{1} \frac{G(c_0) - G(c_1)}{\sum_{k=1}^{N} k[G(c_{k-1}) - G(c_k)]u^{k-1}} du \right); \quad (11a) \\
    c_k &= (v - r) \int_{0}^{1} \frac{[G(c_0) - G(c_1)] [ku^{k-1} - (k + 1)u^k]}{\sum_{k=1}^{N} k[G(c_{k-1}) - G(c_k)]u^{k-1}} du, \; \forall k. \quad (11b)
\end{align*}
\]
This result is useful for two reasons. First, it provides a straightforward way to simulate the market equilibrium. For fixed $v$, $r$ and $G(c)$, the system of equations (11a)–(11b) can be solved numerically. If a solution exists, then the consumer equilibrium is given by (6a)–(6b) and the price distribution follows readily from equation (9). Secondly, this result enables us to address the existence and uniqueness of equilibrium issues, which are the subject of our next statement.

**Theorem 1** For any consumer valuation $v$ and firm marginal cost $r$ such that $v > r \geq 0$ and for any search cost distribution function $G(c)$ with support $(0, \infty)$ such that either $g(0) > 0$ or $g(0) = 0$ and $g'(0) > 0$, an equilibrium exists in a market with an arbitrary number of firms $N$. Moreover, when $N = 2$ and $g'(\cdot) \approx 0$, there exists a unique equilibrium.

The proof is in the Appendix.7

4 Statistical analysis

4.1 Identification

In order to study the question whether the model can be identified, we ask whether the model provides sufficient information to recover the unknowns of interest given that we have full knowledge of the price distribution. This kind of treatment of the identification problem is in the spirit of Koopmans and Reiersøl (1950). In our model, complete knowledge of the price distribution in a market can be obtained if the econometrician observes the prices of (countably) infinitely many firms. In this situation the model transforms the price distribution in a market into an infinite sequence of points of the search cost distribution. This latter statement is proved in Proposition 6 below, but here we summarize the arguments behind it. The points of the search cost distribution correspond to the sequence $\{c_k\}_{k \geq 0}$, which can be determined from equations (8a) and (8b). The values of the search cost distribution function are determined from the sequence $\{\mu_k\}_{k \geq 1}$ (see equations (6a) and (6b)), where the $\mu_k$’s are determined from equation (3). In this section we maintain the assumption that the sequences $\{c_k\}_{k \geq 0}$ and $\{\mu_k\}_{k \geq 1}$ exist.8

---

7 Simulations of the model for different parameters and search cost distributions suggest the uniqueness result is more general. Proving it turns out to be difficult since we can’t compute the equilibrium explicitly.

8 This assumption is necessary because we have not been able to adapt the proof of existence of equilibrium in Theorem 1 to the case of infinitely many firms. However, since we have proved equilibrium existence for an arbitrary number of firms $N$, the identification results from this section can be viewed as an approximation for the case when the $N$ is finite but sufficiently large to provide reliable information on the price distribution.
Based on the fact that the model transforms the price distribution in a market into an infinite sequence of points of the search cost distribution, identification focuses on the question whether the model can recover the search cost distribution on its full support. We present three results here. Our first result provides conditions for identifying the search cost distribution at the cutoff points $c_k$ when we observe the equilibrium price distribution in a market. More precisely, it says that if we know the price distribution $F(p), r,$ and $\mu_0$ then we can identify the value of the search cost distribution corresponding to the cutoff points $c_k$'s. The second result shows that we cannot identify the search cost distribution on its whole support when we observe prices from only one market. Finally, the third result considers the case when we observe prices from several markets. It provides conditions for identifying the search cost distribution on the interval $[0, \text{sup } c_0]$, where $\text{sup } c_0$ is the supremum of the set of $c_0$-cutoff points from all markets.

**Proposition 6** Suppose that the triples of variables $(F, \{\mu_k\}_{k \geq 1}, \{c_k\}_{k \geq 0})$ and $(F', \{\mu_k'\}_{k \geq 1}, \{c_k'\}_{k \geq 0})$ are generated by the triples of variables $(G, v, r)$ and $(G', v', r')$, respectively, where $G$ and $G'$ are distribution functions with support $(0, \infty)$ and positive density on this support. Suppose also that $F$ is a distribution function with support $(p, p)$ and that $F' = F$. In addition, assume the conditions

6.1 $r' = r$,
6.2 $\mu_0' = \mu_0$.

Then $\mu_k' = \mu_k$, $c_k' = c_k$ and $G'(c_k) = G(c_k)$ for any $k \geq 0$, that is, the points of the search cost distribution corresponding to the $c_k$'s are identified.

Regarding the conditions in this Proposition, we note that Condition 6.1 is adopted to make the problem of identification analytically tractable (see Remark A.1 on p.40 in the Appendix for some intuition). With respect to Condition 6.2, note that it simply reflects the econometrician’s need to observe $\mu_0$.

Even though the search cost distribution can be identified at the cutoff points, our second result shows that identification of the whole search cost distribution using data from only one market is not possible. Intuitively, the reason is that the sequence of critical points $\{c_k\}_{k \geq 0}$ is convergent to zero so the price distribution does not provide the necessary information to identify search costs at quantiles other than the lowest.
**Proposition 7** Suppose that \((F, \{\mu_k\}_{k \geq 1}, \{c_k\}_{k \geq 0})\) and \((F', \{\mu'_k\}_{k \geq 1}, \{c'_k\}_{k \geq 0})\) are generated by \((G, v, r)\) and \((G', v', r')\), respectively, where \(G\) and \(G'\) are distribution functions with support \((0, \infty)\) and positive density on this support. Suppose also that \(F\) and \(F'\) are distribution functions with supports \((\underline{p}, \overline{p})\) and \((\underline{p}', \overline{p}')\), respectively. In addition, assume the conditions

1. \(r' = r\) and \(v' = v\),
2. \(c'_k = c_k\) for any \(k \geq 0\),
3. \(G'(c_k) = G(c_k)\) for any \(k \geq 0\).

Then \(F' = F\).

Proposition 7 implies that the same price distribution can be generated by two search cost distributions \(G\) and \(G'\) that are different for a non-negligible set of points, that is, outside the set \(\{c_0, c_1, \ldots\}\) (cf. Conditions 7.2 and 7.3). Since the sequence of cutoff points \(\{c_k\}_{k \geq 0}\) converges monotonically to zero, it is not dense in any arbitrary interval of the support \((0, \infty)\) of the search cost distribution.

This observation can be seen in Figure 1 where we plot the critical cutoff points \(c_k\) for different number of firms \((N = 10, 15, 50, \text{and } 100)\). In these plots we set \(v = 500\) and \(r = 50\), and assume consumer search costs follow a log-normal distribution with parameters \((\nu, \sigma) = (0.5, 5)\). The graphs illustrate how the sequence of critical search costs \(\{c_k\}_{k \geq 0}\) is convergent to zero so increasing the number of firms does not help much to get information on the magnitude of search costs at high quantiles.

To overcome this identification problem, we propose to consider a richer framework where the econometrician has price data from several markets. In particular, we consider markets where the difference between consumer valuations and firms marginal costs are different but the search cost distribution is the same across markets. Intuitively, this solves the problem of identification because every market generates a distinctive set of cutoff points, and this forces the search cost distribution function to be uniquely determined for a larger set of points.

**Proposition 8** Assume that there are infinitely (countably) many markets, indexed by \(m\), all of them with the same underlying search cost cumulative distribution function \(G\) with support \((0, \infty)\).
Figure 1: Non-identification with data from only one market
Assume also and that the conditions in Proposition 6 are satisfied so that in each market \( m \) the values \( G(c_k^m) \) of the search cost distribution corresponding to the cutoff points \( \{c_k^m\}_{k \geq 0} \) are identified. In addition assume that

8.1 the difference between valuations and marginal costs \( \{v^m - r^m\}_{m \geq 1} \) are random variables drawn independently from a distribution with support \((0, \infty)\),

8.2 \( c_0 \) as a function of \((v - r)\) is continuous on \((0, \infty)\).

Then \( G \) is identified on the interval \([0, \sup c_0]\), where \( \sup c_0 = \sup \{c_0^m : m = 1, 2, \ldots\} \) is the supremum of the set of \( c_0 \)-cutoff points from all markets.

We note that if \( \sup c_0 \to \infty \), then this Proposition establishes identification of the search cost distribution in the entire support. Regarding the conditions of this proposition we note that neither 8.1 nor 8.2 is necessary. They have been adopted here in order to make the proof of identification feasible when we focus only on the cutoff points \( \{c_0^m\} \). Weakening Condition 8.1 to require, for example, that \( v^m - r^m, m \geq 1 \), take values in an interval \((t_1, t_2) \subset (0, \infty)\) would be more realistic, but it would imply that we make explicit use of the relationship among the cutoff points \( c_0^m \geq c_1^m \geq \ldots \geq c_k^m \geq \ldots \) in order to establish identification at low quantiles of the search cost distribution. This appears to be difficult due to the nonlinearity of the system of equations that determines the cutoff points (equations (11a) and (11b) for \( N = \infty \)).

With respect to Condition 8.2 we note that this can be interpreted as a requirement that the global implicit function \( c_0 (v - r) \) is continuous in \( v - r \). We find it difficult to establish this property due to the difficulty of the conditions that need to be verified for existing results on global implicit functions (e.g., Ichiraku, 1985). We also note that uniqueness of the global implicit function (i.e., uniqueness of equilibrium) is not sufficient for its continuity.

Finally, we observe that verification of the conditions of Proposition 8 is not crucial in practice because the validity of the conclusion of the proposition can be checked posterior to estimation. More precisely, we can plot all the estimated cutoff points \( \{c_k^m\}_{k,m} \) and assess visually how well they cover the interval \([0, \hat{\sup} c_0]\), where \( \hat{\sup} c_0 \) denotes the estimate of \( \sup c_0 \) obtained as the maximum of the \( \{c_0^m\} \) cutoff points. In case we find that the cutoff points fail to cover some intervals, the only way we can improve the coverage is by adding data from some new markets. Since the main reason for estimating a search cost distribution is to perform policy analyses, estimating the search
cost distribution on the interval $[0, \sup c_0]$ is sufficient in a large number of practical applications. Beyond $\sup c_0$ the search cost distribution cannot be identified by any estimation method.

The ideas put forward in Proposition 8 are illustrated in Figure 2, where we plot the critical cutoff points $c_k$ obtained from using data from $M = 1, 5, 25, \text{ and } 50$ markets, each of them operated by 10 firms. In these plots we set $r = 50$ and again assume consumer search costs follow a log-normal distribution with parameters $(\nu, \sigma) = (0.5, 5)$. For the case of data from one market only we set $v^m = 500$. For the situation with $M$ markets we take valuations in market $m$ as follows: $v^m = 100 + (500 - 100)(m - 1)/M$, so the lowest consumer valuation is always 100 and if there are for example five markets we get $\{v^m\}_{m=1}^5 = \{100, 200, 300, 400, 500\}$. The graphs illustrate how the set of critical search cost points $c_k$ becomes denser and denser in the full support of the search cost distribution as we increase the number of markets $M$ from 1 to 5, 25, and 50.

Figure 2: Identification with data from $M$ different markets
4.2 Estimation

Previous studies on estimation of search cost distributions employ maximum empirical likelihood or maximum likelihood (cf. Hong and Shum, 2006; Moraga-González and Wildenbeest, 2007) to estimate the parameters of the price distribution \( \{\mu_k\}_{k=1}^{N} \), where \( N \) is the number of firms in the market. Once they obtain estimates of the price distribution the search cost points \( \{c_k\}_{k=0}^{N-1} \) can be computed from the empirical cdf (Hong and Shum, 2006) or from equations (9), (10a), and (10b) (Moraga-González and Wildenbeest, 2007). Using the estimates of \( \{\mu_k\}_{k=1}^{N} \) and \( \{c_k\}_{k=0}^{N-1} \) they construct spline approximation estimates of the search cost distribution. As shown above, those papers can identify the search cost distribution only at the cutoff points.

In our framework identification of the search cost distribution relies on asymptotics regarding both the number of markets and the number of firms in a market. To exploit the feature that the search cost distribution is common to all the markets, we employ semi-nonparametric maximum likelihood estimation (Gallant and Nychka, 1987) and use the prices from all the markets at a time. This method is different from those described above because it takes directly the search cost distribution, which is common across markets, to be the parameter of the likelihood. Since the search cost density is an infinite-dimensional parameter, it is estimated by a finite-dimensional parameter that consists of a distribution having finitely many parameters. This distribution is constructed by employing a flexible polynomial-type approximation of the density function, following the SNP estimation technique developed by Gallant and Nychka (1987).\(^9\)

The likelihood function can be constructed by deriving the density of prices in each market \( m \) as a function of the SNP estimator \( g \) of the search cost density (see equation (14) below for more details on \( g \)). Since the prices observed in a market \( m \) are independent draws from the density \( f^m(p|g) \), the log-likelihood function is \( LL^m(g|p) = \sum_{i=1}^{N_m} \log f^m(p_i|g) \). For this, first we apply the implicit function theorem to equation (3), which yields:

\[
f^m(p|g) = \frac{\sum_{k=1}^{N_m} k\mu_k^m(1 - F^m(p|g))^{k-1}}{(p - r^m) \sum_{k=1}^{N_m} k(k - 1)\mu_k^m(1 - F^m(p|g))^{k-2}}.
\]

The quantities that appear in this expression need to be computed in terms of \( g \). By solving

---

\(^9\)When the researcher has data from \( M \) markets, he/she can apply e.g. the Moraga-González and Wildenbeest’s (2007) method for every market \( m \) separately. This procedure yields a set of points \( \{(c_k, 1 - \sum_{k=0}^{N_m} \mu_k)\}_{m=1}^{M} \) to which the researcher can fit a curve. This two-step procedure is clearly suboptimal.
equation (4) for \( r^m \) we obtain an expression for the marginal cost in market \( m \)

\[
r^m = \frac{p^m \sum_{k=1}^{N^m} k \mu_k^m - \mu_1^m v^m}{\sum_{k=2}^{N^m} k \mu_k^m}.
\]

We can estimate market \( m \)'s lower and upper bounds of the price distribution \( p^m \) and \( v^m \) (super-consistently) by taking the minimum and maximum price observed in the data, respectively. Then, for every market \( m \), we compute \( \{ \mu_k^m \}_{k=1}^{N^m} \) and \( \{ c_k^m \}_{k=0}^{N^m-1} \) from the system of equations in (6a), (6b), (10a) and (10b) in terms of \( g \), and using equation (3) and then equation (12) we express the \( F^m (p_i) \)’s and the \( f^m (p_i) \)’s, respectively, in terms of \( g \). In this way we obtain the joint log-likelihood of all markets as a function of \( g \):

\[
LL(g | p_1, p_2, \ldots, p_M) = \sum_{m=1}^{M} \left( \sum_{i=1}^{N^m} \log f^m (p_i | g) \right).
\]

For the polynomial-type parametric function that estimates the search cost density we employ the so-called semi-nonparametric (SNP) density estimator (Gallant and Nychka, 1987). This SNP estimator is based upon a Hermite polynomial expansion. The idea behind this SNP procedure is that any reasonable density can be mimicked by such a Hermite polynomial series. SNP density estimators are essentially nonparametric, just like the spline approximation method described above, because the set of all Hermite polynomial expansions is dense in the set of density functions that are relevant (Gallant and Nychka, 1987).

To apply the SNP estimation in our problem, we specify the search cost density as

\[
g(c; \gamma, \sigma, \theta) = \left( \frac{\sum_{i=0}^{p_n} \theta_i u_i(c)}{\sum_{i=0}^{p_n} \theta_i^2} \right)^2, \quad \theta \in \Theta_p, \Theta_p = \{ \theta : \theta = (\theta_0, \theta_1, \ldots, \theta_p), \theta_0 = 1 \},
\]

where \( p_n \) is the number of polynomial terms,

\[
\begin{align*}
  u_0(c) &= (c \sigma \sqrt{2\pi})^{-1/2} e^{-((\log c - \gamma)/\sigma)^2/4}, \\
  u_1(c) &= (c \sigma \sqrt{2\pi})^{-1/2} ((\log c - \gamma)/\sigma) e^{-((\log c - \gamma)/\sigma)^2/4}, \\
  u_i(c) &= \left( ((\log c - \gamma)/\sigma) u_{i-1}(c) - \sqrt{i - 1} u_{i-2}(c) \right) / \sqrt{i} \text{ for } i \geq 2.
\end{align*}
\]

This parametric form corresponds to the univariate SNP estimator studied extensively by Fenton and Gallant (1996). Our expressions are obtained by transforming their random variable \( x \) with the density defined in their Section 4.3 to \( c = \exp^{\gamma + \sigma x} \). This transformation is useful in our case since search costs are positive.
The vector of parameters to be estimated by maximum likelihood is \( \{\gamma, \sigma, \theta_0, \theta_1, \ldots, \theta_p\} \). The consistency of the maximum likelihood estimator can be established by verifying the conditions provided by Gallant and Nychka (1987) combined with the conditions from Hoadley (1971), who studies the maximum likelihood estimator for non-identically distributed observations. In addition, appropriate assumptions should be found on the rates at which the number of firms and the number of markets go to infinity. Regarding the search cost distribution we note that the conditions from Gallant and Nychka (1987) require that the search cost density is differentiable and its tail behavior is restricted.

4.3 Simulations

In this section, studying a market operated by three firms, we illustrate how lack of complete identification of the search cost distribution might be problematic for the researcher. In particular, we develop an example which shows that if the econometrician were to assess the effects of a merger on average prices, the lack of good information about search costs would potentially mislead her.

Consider the following parametrization of our search model. Let the number of firms \( N = 3 \), the marginal cost \( r = 100 \), and consumer valuation \( v = 400 \). Moreover, assume search costs are distributed according to the density

\[
g(c) = 0.5 \cdot \text{lognormal}(c, 2, 10) + 0.5 \cdot \text{lognormal}(c, 3, 0.2),
\]
i.e., search costs come from a 50-50 mixture of two log-normal distributions with parameters \((\nu, \sigma) = (2, 10)\) and \((\nu, \sigma) = (3, 0.2)\), respectively. The market equilibrium can be calculated by solving the system of equations (11a) and (11b). The first column of Table 1 gives an overview of the parameters that together lead to this market equilibrium. In addition Table 1 reports expected prices and expected profits. Figure 3 plots the search cost distribution and the implied equilibrium price distribution.

Suppose the researcher had data from many markets. As we explain above, in this case she would be able to identify enough points on the search cost distribution to fully identify it. This is illustrated in the left panel of Figure 4 for a situation where the researcher has data for 100 markets. As can be seen, linear interpolation between all the identified points closely approximates the true search cost distribution. Now suppose the researcher had data from only one market. In
Figure 3: From search costs to equilibrium prices

this case, even if the researcher knew the equilibrium price distribution perfectly, she would be able
to identify at most three points on the search cost distribution. These points are shown in the right
panel of Figure 4, along with the true search cost distribution (dashed curve). Without a priori
knowledge of the search cost distribution, linear interpolation would suggest itself. The estimate
of the search cost distribution would then be the straight solid line plotted in Figure 4(a). This
estimate suggests all search cost levels are equiprobable while the truth is that low and high search
costs are relatively frequent while intermediate search costs are not.

<table>
<thead>
<tr>
<th></th>
<th>$N = 3$ true $g(c)$</th>
<th>$N = 2$ true $g(c)$</th>
<th>$N = 2$ estimated $g(c)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$r$</td>
<td>100.00</td>
<td>100.00</td>
<td>100.00</td>
</tr>
<tr>
<td>$v$</td>
<td>400.00</td>
<td>400.00</td>
<td>400.00</td>
</tr>
<tr>
<td>$p$</td>
<td>132.70</td>
<td>140.33</td>
<td>151.85</td>
</tr>
<tr>
<td>$p_1$</td>
<td>0.22</td>
<td>0.24</td>
<td>0.29</td>
</tr>
<tr>
<td>$p_2$</td>
<td>0.52</td>
<td>0.76</td>
<td>0.71</td>
</tr>
<tr>
<td>$p_3$</td>
<td>0.26</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>$c_1$</td>
<td>33.81</td>
<td>29.36</td>
<td>30.65</td>
</tr>
<tr>
<td>$c_2$</td>
<td>11.23</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>$c_3$</td>
<td>0</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>$E[p]$</td>
<td>195.83</td>
<td>193.50</td>
<td>210.04</td>
</tr>
<tr>
<td>$E[\min{p_1, p_2}]$</td>
<td>162.02</td>
<td>164.14</td>
<td>179.39</td>
</tr>
<tr>
<td>$E[\min{p_1, p_2, p_3}]$</td>
<td>150.79</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>$E\pi$</td>
<td>22.21</td>
<td>35.55</td>
<td>44.21</td>
</tr>
</tbody>
</table>

Table 1: True and estimated effects of a merger

Suppose the researcher were asked to assess the effects of a merger on the price distribution,
average prices and firm profits. In that case, running a merger simulation and comparing the
counterfactual post-merger equilibrium with the pre-merger equilibrium would suggest itself as a
reasonable way to address the issue. To run the counterfactual simulation, since search costs above
$c_0$ are not identified, the researcher needs to make an assumption about the shape of the search cost distribution beyond $c_0$. Let us assume the search cost CDF continues to increase linearly all the way to 1 with the same slope as the one to the right of the highest identified search cost value. Under this assumption, the search cost CDF can be approximated by a uniform distribution with support $[0, 0.43]$.

The true post-merger equilibrium is given in the second column of Table 1. As explained above, one obtains this true equilibrium by using price data from many markets. Note that the merger would lead to a 60% increase in profits and to a 1.2% decrease in the average price.\textsuperscript{10} The third column of Table 1 gives the simulated equilibrium when the researcher uses the estimated uniform search cost density. The simulated effects of the merger are quite different than the true effects: profits would increase by 99% and the average price would go up by 7.25%. As a result, if the competition authority were concerned about market average prices,\textsuperscript{11} it would not approve the merger on the basis of the econometrician’s study while it would approve if it were aware of the true search cost distribution.

Figure 5 gives the true price densities and price CDF’s before and after the merger, as well as the simulated after-merger prices. In Figure 5(a) the pre-merger density of prices is represented by the dashed curve, while the post-merger price PDF using data from many markets is depicted by

\textsuperscript{10} The fact that average prices can decrease as the number of firms in a search market falls is well known (see e.g. Stiglitz, 1987; Stahl, 1989; and Janssen and Moraga-González, 2004).

\textsuperscript{11} In the U.S., current law as well as the Department of Justice and the Federal Trade Commission Horizontal Merger Guidelines focus on merger effects on consumer prices rather than on aggregate welfare considerations (see Baker, 1999).
the solid black curve. The gray curve shows the estimated equilibrium price density using data from only one market. Similarly, Figure 5(b) gives the pre-merger price CDF as well as the post-merger price CDF for both data from one market and many markets.

![Figure 5: Effect on prices of a merger](image)

5 Application

In this section we use the SNP estimation method described above to quantify search costs in real-world markets for memory chips. We focus on computer memory chips for notebooks (so called SO-DIMM, or Small Outline Dual In-line Memory Module). Since we need products from different markets, we select memory chips produced for different brands and types of notebooks. Table 2 gives the details of the 10 products we include in our data set. There are several reasons for choosing these memory chips. First, since all the chips are sold online, we expect search costs to be similar across markets. Second, even though all memory chips are manufactured by Kingston—the largest producer in the sector—each memory chip in our sample is meant to be used in a particular notebook brand only—including Toshiba, Dell, Acer, IBM and HP Compaq. Given that substitutability across products is somewhat limited due to technical reasons, we shall assume that different microchips belong in separate markets so the use of a search model with homogeneous products is reasonable. All the memory chips are somewhat at the top of the product line. In particular they exhibit relatively large storage capacity (1 gigabyte) and fast speed of operation (most of them above 400 MHz). Given the large storage capacity of the memory chips in the data set, most consumers would only consider to buy one memory chip, so the single-unit inelastic
demand assumption of the theoretical model seems also reasonable.

<table>
<thead>
<tr>
<th>Part number</th>
<th>Manufacturer</th>
<th>Compatibility</th>
<th>Size</th>
<th>Speed</th>
<th>Form factor</th>
</tr>
</thead>
<tbody>
<tr>
<td>KTT3311A</td>
<td>Kingston</td>
<td>Toshiba</td>
<td>1GB</td>
<td>333MHz DDR333/PC2700</td>
<td>200-pin SoDIMM</td>
</tr>
<tr>
<td>KTT533D2</td>
<td>Kingston</td>
<td>Toshiba</td>
<td>1GB</td>
<td>533MHz DDR2-533/PC2-4200</td>
<td>200-pin SoDIMM</td>
</tr>
<tr>
<td>KTD-INSPI8200</td>
<td>Kingston</td>
<td>Dell</td>
<td>1GB</td>
<td>266MHz DDR266/PC2100</td>
<td>200-pin SoDIMM</td>
</tr>
<tr>
<td>KTD-INSPI5150</td>
<td>Kingston</td>
<td>Dell</td>
<td>1GB</td>
<td>333MHz DDR333/PC2700</td>
<td>200-pin SoDIMM</td>
</tr>
<tr>
<td>KTD-INSPI6000</td>
<td>Kingston</td>
<td>Dell</td>
<td>1GB</td>
<td>533MHz DDR2-533/PC2-4200</td>
<td>200-pin SoDIMM</td>
</tr>
<tr>
<td>KTD-INSPI6000A</td>
<td>Kingston</td>
<td>Dell</td>
<td>1GB</td>
<td>533MHz DDR2-533/PC2-4200</td>
<td>200-pin SoDIMM</td>
</tr>
<tr>
<td>KAC-MEME</td>
<td>Kingston</td>
<td>Acer</td>
<td>1GB</td>
<td>533MHz DDR2-533/PC2-4200</td>
<td>200-pin SoDIMM</td>
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<td>400MHz DDR400/PC3200</td>
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<td>Kingston</td>
<td>IBM</td>
<td>1GB</td>
<td>533MHz DDR2-533/PC2-4200</td>
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<tr>
<td>KTH-ZD8000A</td>
<td>Kingston</td>
<td>HP Compaq</td>
<td>1GB</td>
<td>533MHz DDR2-533/PC2-4200</td>
<td>200-pin SoDIMM</td>
</tr>
</tbody>
</table>

Table 2: List of products

For all the memory chips in the data set we collected online prices charged in the United States, in February 2006. To obtain a sufficiently representative sample, we gathered product and price information from several sources at the same time. We proceeded as follows. We first visited the price comparison sites shopper.com and pricegrabber.com and collected the names of all the shops that were seen active in markets for memory chips; in total we found 49 stores. If for a particular product we saw a shop quoting its price on shopper.com and/or pricegrabber.com, we took the price directly from the price comparison site; otherwise we visited the web-address of the vendor to check if the product was available and at what price it was offered. Table 3 gives some summary statistics of the data set. The number of firms quoting prices in each market is relatively large, ranging from 24 to 41. In our study we estimate the number of stores operating in each market \( N \) by the number of firms that were observed to be quoting prices in that market.

<table>
<thead>
<tr>
<th>Part number</th>
<th>No. of Stores</th>
<th>Mean Price (Std)</th>
<th>Min. Price</th>
<th>Max. Price</th>
<th>Coeff. of Var. (as %)</th>
</tr>
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<tr>
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<td>181.67 (21.62)</td>
<td>148.62</td>
<td>235.00</td>
<td>13.55</td>
</tr>
<tr>
<td>KTT533D2</td>
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<td>123.33 (15.62)</td>
<td>100.45</td>
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</tr>
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<td>KTD-INSPI8200</td>
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<td>173.59 (21.31)</td>
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<td>249.54</td>
<td>12.28</td>
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<td>222.35</td>
<td>11.08</td>
</tr>
<tr>
<td>KTD-INSPI6000</td>
<td>35</td>
<td>120.29 (13.48)</td>
<td>100.45</td>
<td>151.05</td>
<td>11.21</td>
</tr>
<tr>
<td>KTD-INSPI6000A</td>
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<td>116.33 (13.43)</td>
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<td>11.54</td>
</tr>
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<td>161.64</td>
<td>14.14</td>
</tr>
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<td>KTD-INSPI9100</td>
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<td>175.84 (24.38)</td>
<td>148.62</td>
<td>249.54</td>
<td>13.87</td>
</tr>
<tr>
<td>KTM-TP3840</td>
<td>37</td>
<td>122.83 (14.32)</td>
<td>104.55</td>
<td>161.94</td>
<td>11.65</td>
</tr>
<tr>
<td>KTH-ZD8000A</td>
<td>41</td>
<td>116.77 (12.25)</td>
<td>100.45</td>
<td>154.50</td>
<td>10.49</td>
</tr>
</tbody>
</table>

Notes:
Prices are in US dollars.

Table 3: Summary statistics

Our model assumes consumers search non-sequentially. As shown by Morgan and Manning
(1985), non-sequential search is optimal when there is a time lag between the moment at which
the search effort takes place and the moment at which the search outcome is observed. Given
that there is usually no such time lag when searching for memory chips, one could argue that
sequential search would be more appropriate. Even though this is true, one reason for using the
non-sequential search protocol is that it allows for the identification of search costs using only
price data, while with sequential search marginal cost data would also be needed. Another reason
for using the non-sequential search approach is that a price comparison site like shopper.com and
pricegrabber.com very much resembles a non-sequential search setting, since consumers who use
these web sites receive several price quotes instantaneously, as they would if they were searching
non-sequentially.

Almost all memory chips are priced above 100 US dollars. For all products we observe significant
price dispersion as measured by the price range (difference between the maximum and the minimum
prices) and by the coefficient of variation. The benefits to a consumer from searching are significant;
in particular, the gains from being fully informed relative to buying from a shop at random in these
markets range from 16.32 to 33.05 US dollars. As mentioned above, we estimate the valuation of a
memory chip by the maximum price observed in the market.

The prices used for our estimations include neither shipping costs nor sales taxes. The main
reason for this omission is that shipping costs and sales taxes depend on the state in which the
consumer resides, which makes it difficult to compare total prices. However, for robustness purposes,
we estimated the model neglecting sales taxes but using the shipping costs as if we were living in
New York. The qualitative nature of the results did not change.

Although the memory chips themselves are completely homogeneous, the price differences across
vendors of a given chip may be due to store differentiation. Consumers might prefer one shop
over another on the basis of observable store characteristics like quality ratings, return policies,
stock availability, order fulfillment, payment methods, etc. To see the impact of observable shop
characteristics on prices, we regressed prices on indicators that are readily available from the price
comparison sites. More precisely, we estimated the following model:

\[
PRICE_j = \beta_0 + \beta_1 \cdot RATING_j + \beta_2 \cdot DISCLOSE_j + \beta_3 \cdot STOCK_j + \beta_4 \cdot LOGO_j + \varepsilon_j,
\]

where, for each product, \(PRICE_j\) is the list price of store \(j\), \(RATING_j\) is an average of the
SNP

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<tr>
<td>$p^n$</td>
</tr>
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</table>

Notes:
Estimated standard errors in parenthesis.

Table 4: Parameter estimates SNP function

The ranking of store $j$ on shopper.com and pricegrabber.com, $DISCLOSE_j$ is a dummy for whether shop $j$ disclosed shipping cost on either shopper.com or pricegrabber.com, $STOCK_j$ is a dummy for whether shop $j$ had the item in stock, and $LOGO_j$ is a dummy for whether shop $j$ had its logo on either shopper.com or pricegrabber.com. We estimated this equation by OLS. The resulting $R$-squared values indicate that only between 3% and 21% of the total variation in prices can be attributed to observable differences in store characteristics. This suggests that the rest of the price variation can be due to either unobservable heterogeneity across shops (e.g., cost differences or branding) or to strategic price setting in the presence of consumer search costs. Here we focus on the second explanation.

Because we only observe the stores’ prices at one moment in time, we cannot check whether stores indeed randomize their prices over time, as predicted by our search model. However, using a different data set Moraga-González and Wildenbeest (2007) show that firms indeed seem to randomize in the online market for memory chips; at the same time, other studies find evidence for mixed strategies in other markets (e.g., Lach (2002) for chicken, refrigerators, coffee, and flour in Israel; and Wildenbeest (2007) for grocery products in the Netherlands).

Table 4 presents the SNP estimation results. We follow the procedure explained in Section 4.2 and the recommendation by Fenton and Gallant (1996) and set $p^n = 3$, which equals the closest integer to the fifth root of the total number of observations. Table 4 shows that all parameter

---

12For all memory chips, all the OLS coefficient estimates were not significant except the coefficient for $LOGO_j$, which was positive and significant at a 5% level for the chips KAC-MEME and KTM-TP3840.

13For our estimations we set $\mu_0 = 0$, which amounts to assuming that consumers obtain the first price quotation at no cost. As we will see below, the model performed relatively well thus suggesting our simplifying assumption was not too unreasonable. Alternatively one could (roughly) proxy the value of $\mu_0$ by multiplying the failure rate of a memory chip by the total sales of a particular notebook.

14In cases when there are sufficiently many observations to estimate the $c_k$’s, as is the case in our data set, we can
estimates are significant at a 1% level, except for $\theta_1$ and $\theta_2$, which are significant at a 5% level. The standard errors reported in the table are meaningful in the case when the presented model is the true parametric model. Figures 6(a) and 6(b) plot the estimated search cost CDF and PDF respectively. These graphs also show how well the points that are identified cover the support of the search cost distribution.

![Figure 6: Estimated search cost distribution](image)

Using the estimates of the parameters of the SNP specification for $p^n = 3$ we can compute the mean, the median, and the standard deviation of the unobserved search cost distribution. The median consumer has a search cost equal to 5.05 US dollars. On average a consumer has a search cost value equal to 13.41 US dollars and the standard deviation is 24.49 US dollars. It is also interesting to investigate the distribution of search intensities in these markets. Since each market has specific parameters, even though search costs are assumed to be similar, it is unlikely that consumer behavior will be the same across markets. Table 5 shows that it is indeed the case that search intensities are different across markets. For example, 18% of consumers search once for the KTD-INSP9100 memory chip, while 33% searches once for the KTD-INSP6000 memory chip. Similarly, for the KTD-INSP9100 chip 37% of consumers searches twice, while 49% searches twice for the KTD-INSP5150G memory chip. However, the share of consumers searching at most three times is more or less similar across markets; approximately 85% of the consumers have search cost above $2 and search for at most three prices. Table 5 also illustrates that the group of consumers searching for between 4 and 10 firms is with percentages between 2 and 4 relatively small. About use the empirical distribution of prices in each market. The gain in computing time is huge and the results for our data are very similar.
13% of consumers search with more than 10 times thoroughly, which means they have search costs less than 30 dollar cents. Figures 6(a) and 6(b) show that the consumers can roughly be divided into three groups: buyers who do not search, buyers who compare at most three prices and buyers who compare many prices in the market. In sum, we conclude that consumers have either quite high search costs or quite low search costs.

The gray dots in Figures 6(a) and 6(b) denote identified points on the search cost CDF and PDF respectively. Not surprisingly, given that we have data from only 10 markets, most identified points are found at low search cost values. As explained in Section 4.1, adding extra markets will increase the number of identified points for higher search cost values.

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<td>1.49</td>
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Notes: Estimated standard errors in parenthesis.

Table 5: Parameter estimates products and fit

The fact that a significant proportion of consumers does not compare prices gives substantial market power to the firms. Using the estimates of the SNP specification, we can retrieve the marginal cost $r$ in each market, which is also reported in Table 5. Marginal costs range between 57% and 65% of the value of the product so the average price-cost margins range between 17% and 23% across markets. We calculate standard errors for $r$ using the delta method. All the estimated values for $r$ are highly significant.

To test whether the estimated model explains observed prices well, we calculate the Kolmogorov-Smirnov statistic (KS-test) in each individual market. The KS-test statistic is based on the maximum difference between the empirical price CDF and the estimated price CDF. The null hypothesis for this test is that the distributions are similar, the alternative hypothesis is that the empirical and the estimated price CDF are different. Table 5 gives the KS-test results and since for the majority of products the KS value is below the 95%-critical value of the KS-statistic of 1.36, for
Figure 7: Estimated and empirical price CDF’s
eight out of ten memory chips we cannot reject the null-hypothesis that the prices are drawn from
the estimated price CDF. The goodness-of-fit is also shown in Figure 7, where we have plotted
both the empirical and the estimated price CDF for each market. A solid curve represents the
empirical price CDF, while a dashed curve represents an estimated price CDF; the graphs show
that both curves are quite close to each other for most products.

6 Conclusions

Since the seminal contribution of Stigler (1961), economists have dedicated a significant amount of
effort to understand the nature of competition in markets where price information is not readily
available to consumers. One of the lessons learned is that consumer search models may lead to
predictions different from those obtained from conventional economic theory. Another is that the
particular direction of the effects of public policy measures such as the introduction of taxes or
the dismantling of barriers to entry depends on the shape of the search cost distribution. These
observations motivate the development of methods to identify and estimate search costs.

This paper has contributed to this literature in two ways. First, we have shown that an equi-
librium always exists in a model of non-sequential search with search cost heterogeneity. Second,
we have studied the nonparametric identification and estimation of the costs of search. We have
proven that the search cost distribution can only be identified with precision in a neighborhood
of zero when the econometrician observes prices from only one market. To solve this pitfall, we
have proposed to examine a richer framework where the econometrician has price data from sev-
eral markets with the same search cost distribution. We have shown that pooling price data from
multiple markets enables us to identify the search cost density fully in the relevant support. To
take advantage of the relationship between markets we have proposed to estimate the search cost
density function by a semi-nonparametric density estimator whose parameters maximize the joint
likelihood corresponding to all the markets.

The paper has also provided a Monte Carlo study showing the gains that obtain from pooling
data from several markets. In addition, we have illustrated the potential of our method by applying
it to a data set of online prices for ten notebook memory chips.

\footnote{We have calculated $K'S$ in Table 5 as $\sqrt{M} \cdot \tau_M$, where $M$ is the number of price observations for the specific
memory chip and $\tau_M$ is the maximum absolute difference over all prices between the estimated price cdf and the
empirical price cdf.}
Along the way we have made several simplifying assumptions. One of the assumptions has been that consumers have the same valuation. In future work, we would like to relax this assumption and study a framework where there is consumer valuation and search cost heterogeneity. One of the advantages of developing such a framework is that it would enable the econometrician to estimate the correlation between consumer valuations and search costs. Another important assumption has been that firms are symmetric, i.e., they have the same marginal costs of production. Since marginal cost heterogeneity may be an important factor behind the observed price variation in real-world markets, future work should allow for heterogeneous firms. Such a framework would help the researcher separate price variation caused by search costs from that caused by firm heterogeneity.
Proof of Proposition 1. First, suppose, on the contrary, that $\mu_1 = 0$. Then we have two possibilities: (i) either $\mu_0 = 1$ in which case the market does not open, or (ii) $\mu_k > 0$ for some $k = 2, 3, \ldots, N$ in which case all firms would charge a price equal to the marginal cost $r$. But if this were so, consumers would gain by deviating and searching less. Second, suppose, on the contrary, that $\mu_1 = 1$. Then firms prices would be equal to the monopoly price $v$. But if this were so then consumers would gain by deviating and exiting the market. Finally, suppose, on the contrary, that $1 > \mu_1 > 0$ and that $\mu_k = 0$ for all $k = 2, 3, \ldots, N$. Then $\mu_0 + \mu_1 = 1$ and the argument applied before would hold here too; as a result, there must be some $k \geq 2$ for which $\mu_k > 0$. 

Proof of Proposition 2. Suppose, on the contrary, that firms did charge a price $\hat{p} \in (r, v]$ with strictly positive probability in equilibrium. Consider a firm $i$ charging $\hat{p}$. The probability that $\hat{p}$ is the only price in the market is strictly positive. This occurs when all other firms are charging $\hat{p}$. From Proposition 1 we know that in equilibrium there exists some $\hat{k} \geq 2$ for which $\mu_{\hat{k}} > 0$. Consider the fraction of consumers sampling $\hat{k}$ firms. The probability that these consumers are sampling firm $i$ is strictly positive; as a result, firm $i$ would gain by deviating and charging $\hat{p} - \epsilon$ since in that case the firm would attract all consumers in $\mu_{\hat{k}}$ who happened to sample firm $i$. This deviation would give firm $i$ a discrete increase in its profits and thus rules out all atoms in the set $(r, v]$. It remains to be proven that an atom at the marginal cost $r$ cannot be part of an equilibrium either. Consider a firm charging $r$. From Proposition 1 we know that $1 > \mu_1 > 0$. As a result, this firm would serve a fraction of consumers at least as large as $\mu_1/N$ but obtain zero profits. This implies that the firm would have an incentive to deviate by increasing its price. We now prove that the upper bound of $F(p)$ must be equal to $v$. Suppose not and consider a firm charging an upper bound $\bar{p} < v$. Since this firm would not sell to any consumer who compares prices, its payoff would simply be equal to $(\bar{p} - r)\mu_1/N$, which is strictly increasing in $\bar{p}$; as a result the firm would gain by deviating and charging $v$. 

Proof of Theorem 1. Let $\theta := v - r$ and consider the change of variables $x_k := G(c_k)$. Then
we can rewrite the equations describing the equilibrium (11a)-(11b) as

\[
x_0 = G \left( \theta - \theta \int_0^1 \frac{x_0 - x_1}{\sum_{h=1}^N h (x_{h-1} - x_h) u^{h-1}} du \right);
\]

\[
x_k = G \left( \theta \int_0^1 \frac{x_0 - x_1}{\sum_{h=1}^N h (x_{h-1} - x_h) u^{h-1}} \left[ k u^{k-1} - (k + 1) u^k \right] du \right), \quad k = 1, 2, \ldots, N - 1, \quad (x_N = 0).
\]

Let \( y_k = \frac{x_k}{x_0} \). Then the solution of this system will be

\[
x_0 = G \left( \theta - \theta \int_0^1 \frac{1 - y_1}{1 - y_1 + \sum_{h=2}^N \frac{1 - y_1}{h (y_{h-1} - y_h) u^{h-1}} du} \right),
\]

\[
x_1 = x_0 y_1, \ldots, x_{N-1} = x_0 y_{N-1},
\]

if \( y = (y_1, y_2, \ldots, y_{N-1}) \) is the solution of the following system of equations:

\[
y_k = \frac{G \left( \theta \int_0^1 \frac{1 - y_1}{1 - y_1 + \sum_{h=2}^N \frac{1 - y_1}{h (y_{h-1} - y_h) u^{h-1}} du} \right)}{G \left( \theta - \theta \int_0^1 \frac{1 - y_1}{1 - y_1 + \sum_{h=2}^N \frac{1 - y_1}{h (y_{h-1} - y_h) u^{h-1}} du} \right)}, \quad k = 1, 2, \ldots, N - 1, \quad (y_N = 0). \quad (A15)
\]

We are looking for a solution of this latter system in \([0, 1]^{N-1}\) for which \( y_1 \geq y_2 \geq \ldots \geq y_{N-1} \). For this purpose, we define the set \( Y = \{(y_1, y_2, \ldots, y_{N-1}) \in [0, 1]^{N-1} : y_1 \geq y_2 \geq \ldots \geq y_{N-1}\} \).

Likewise, define the function \( H = (H_1, \ldots, H_{N-1}) : Y \setminus \{0\} \to \mathbb{R}^{N-1} \) with

\[
H_k (y) = \frac{G \left( \theta \int_0^1 \frac{1 - y_1}{1 - y_1 + \sum_{h=2}^N \frac{1 - y_1}{h (y_{h-1} - y_h) u^{h-1}} du} \right)}{G \left( \theta - \theta \int_0^1 \frac{1 - y_1}{1 - y_1 + \sum_{h=2}^N \frac{1 - y_1}{h (y_{h-1} - y_h) u^{h-1}} du} \right)}, \quad k = 1, 2, \ldots, N - 1, \quad (y_N = 0).
\]

Then the solution of the system (A15) is a fixed point of \( H \). In what follows we apply Brouwer’s theorem to show that the function \( H \) has a fixed point.

First we show that the function \( H \) takes values in the set \( Y \). This is intuitively clear based on the properties of the model since by appropriate transformations it is equivalent to the inequalities \( c_0 \geq c_1 \geq \ldots \geq c_{N-1} \). Here we provide a direct proof.

**Lemma A.1** The function \( H(\cdot) \) takes values in \( Y \).

**Proof.** Take an arbitrary \( y \in Y \setminus \{0\} \). We need to prove that \( 0 \leq H_k (y) \leq 1 \) for all \( k = 1, 2, \ldots, N - 1 \) and \( H_k (y) \leq H_{k-1} (y) \) for all \( k = 2, \ldots, N - 1 \). The inequality \( 0 \leq H_k (y) \) follows

\[32\]
straightforwardly from the nonnegativity of $G$. In order to prove $H_k (y) \leq 1$ and $H_k (y) \leq H_{k-1} (y)$ we use integration by parts. First we observe that

$$
\int_0^1 \frac{1 - y_1}{1 - y_1 + \sum_{h=2}^N h (y_{h-1} - y_h) u^{h-1}} du = \int_0^1 \frac{1 - y_1}{1 - y_1 + \sum_{h=2}^N h (y_{h-1} - y_h) (1 - u)^{h-1}} du.
$$

By integration by parts

$$
\int_0^1 \frac{1 - y_1}{1 - y_1 + \sum_{h=2}^N h (y_{h-1} - y_h) u^{h-1}} du = 1 - \int_0^1 \frac{1 - y_1}{1 - y_1 + \sum_{h=2}^N h (y_{h-1} - y_h) (1 - u)^{h-1}} \left[ \sum_{h=2}^N h (h - 1) (y_{h-1} - y_h) (1 - u)^{h-2} \right] du.
$$

So the argument of $G$ in the denominator is proportional to

$$
1 - \int_0^1 \frac{1 - y_1}{1 - y_1 + \sum_{h=2}^N h (y_{h-1} - y_h) u^{h-1}} du = \int_0^1 \frac{1 - y_1}{1 - y_1 + \sum_{h=2}^N h (y_{h-1} - y_h) (1 - u)^{h-1}} \left[ \sum_{h=2}^N h (h - 1) (y_{h-1} - y_h) u^{h-2} \right] du.
$$

The argument of $G$ in the numerator of $H_k (\cdot)$ is proportional to

$$
\int_0^1 \frac{(1 - y_1) \left[ ku^{k-1} - (k + 1) u^k \right]}{1 - y_1 + \sum_{h=2}^N h (y_{h-1} - y_h) u^{h-1}} du = \int_0^1 \frac{1 - y_1}{1 - y_1 + \sum_{h=2}^N h (y_{h-1} - y_h) u^{h-1}} \left[ \sum_{h=2}^N h (h - 1) (y_{h-1} - y_h) u^{h-2} \right] du.
$$

The inequality $H_k (y) \leq 1$ follows from the fact that $u \geq u^k (1 - u)$ while the inequalities $H_k (y) \leq H_{k-1} (y)$, $k = 2, 3, \ldots, N - 1$ follow because all terms in the expressions of the integrals are non-negative and $u^k$ is decreasing in $k$. 

We now apply Brouwer’s fixed point theorem to prove a fixed point of $H$ exists. Since the denominator of $H_k$ is 0 for $y = 0$, we need to modify the function $H$ in the neighborhood of 0. We do this in three steps: (i) We first prove that the limit inferior of $H$ when $y \to 0$ is strictly positive (Proposition A.1). (ii) We then construct a neighborhood $V$ of 0 such that $H$ is continuously extendable from $Y \setminus V$ to $Y$ such that the extended function has no fixed point in $V$ (Lemma A.3, Lemma A.4). (iii) Finally, we apply Brouwer’s fixed point theorem to the extended function to
establish the existence of a solution of the system (A15).

We start by showing that the limit inferior of \( H \) is strictly positive. Since \( H_k(y) \leq H_{k-1}(y), k = 2, 3, \ldots, N - 1 \), is is sufficient to study the limit inferior of \( H_1 \).

**Proposition A.1** \( \liminf_{y \to 0} H_1(y) \geq \begin{cases} \frac{1}{3} & \text{if } g(0) > 0, \\ \frac{1}{5} & \text{if } g(0) = 0 \text{ and } g'(0) > 0. \end{cases} \)

**Proof.** By definition \( \liminf_{y \to 0} H_1(y) = \liminf_{\varepsilon \to 0} \{ H_1(y) : y \in Y \cap B(0, \varepsilon) \setminus \{0\} \} \), where \( B(0, \varepsilon) = \{ x \in \mathbb{R}^{N-1} : ||x|| < \varepsilon \} \). By Lemma A.2 below there exists an \( \varepsilon > 0 \) such that \( H_1(y) \) is increasing in \( y_k \) for \( k = 2, \ldots, N - 1 \) on \( Y \cap B(0, \varepsilon) \setminus \{0\} \). This implies that for any \( y \in Y \cap B(0, \varepsilon) \setminus \{0\} \) such that \( y_1 > 0 \)

\[
H_1(y_1, y_2, \ldots, y_{N-1}) \geq H_1(y_1, y_2, \ldots, y_{N-2}, 0) \geq \cdots \geq H_1(y_1, 0, \ldots, 0)
\]

\[
= \frac{G\left(\int_0^1 \frac{(1-y_1)(1-2u)}{1-y_1+2yu} du\right)}{G\left(\theta - \theta \int_0^1 \frac{1-y_1}{1-y_1+2yu} du\right)}
\]

Therefore,

\[
\liminf_{y \to 0} H_1(y) \geq \liminf_{\varepsilon \to 0} \left\{ \frac{G\left(\theta \int_0^1 \frac{(1-y_1)(1-2u)}{1-y_1+2yu} du\right)}{G\left(\theta - \theta \int_0^1 \frac{1-y_1}{1-y_1+2yu} du\right)} : 0 < y_1 < \varepsilon \right\}
\]

The limit on the right hand side is by definition the limit inferior of \( \liminf_{y_1 \to 0} \frac{G\left(\theta \int_0^1 \frac{(1-y_1)(1-2u)}{1-y_1+2yu} du\right)}{G\left(\theta - \theta \int_0^1 \frac{1-y_1}{1-y_1+2yu} du\right)} \) when \( y_1 \to 0, y_1 > 0 \). We show that this limit inferior is just equal to the limit, due to the fact that the limit exists. Indeed, we can apply the l'Hôpital rule to obtain

\[
\lim_{y_1 \to 0} \frac{G\left(\theta \int_0^1 \frac{(1-y_1)(1-2u)}{1-y_1+2yu} du\right)}{G\left(\theta - \theta \int_0^1 \frac{1-y_1}{1-y_1+2yu} du\right)} = \lim_{y_1 \to 0} \frac{g(\theta \int_0^1 \frac{(1-y_1)(1-2u)}{1-y_1+2yu} du)}{g(\theta - \theta \int_0^1 \frac{1-y_1}{1-y_1+2yu} du)} \int_0^1 \frac{u(1-2u)}{(1-y_1+2yu)^2} du
\]

\[
= \frac{1}{3}.
\]
If \( g(0) = 0 \) and \( g'(0) > 0 \) then the limit (A16) is equal to the limit of
\[
-g'(0) \int_0^1 (1-2u) \, du + g(0) \int_0^1 2u (1-2u) \, du
= \int_0^1 (1-2u) \, du \int_0^1 u (1-2u) \, du = \frac{1}{9}.
\]

Lemma A.2 There exists an \( \varepsilon > 0 \) such that \( H_1(y) \) is increasing in \( y_k \) for \( k = 2, \ldots, N-1 \) on \( Y \cap B(0, \varepsilon) \setminus \{0\} \).

Proof. For simplicity of notation we use
\[
H_1(y) = \frac{U(y)}{D(y)},
\]
where \( U, D : Y \to \mathbb{R} \)
\[
U(y) = G\left( \theta \int_0^1 \frac{(1-y_1)(1-2u)}{1-y_1 + \sum_{h=2}^N h (y_{h-1} - y_h) u^{h-1}} \, du \right),
\]
\[
D(y) = G\left( \theta - \int_0^1 \frac{1-ynk}{1-y_1 + \sum_{h=2}^N h (y_{h-1} - y_h) u^{h-1}} \, du \right).
\]
The partial derivatives of \( U \) and \( D \) with respect to \( y_k \) for some \( k \in \{2, \ldots, N-1\} \) are
\[
\frac{\partial U}{\partial y_k} = g\left( \theta \int_0^1 \frac{(1-y_1)(1-2u)}{1-y_1 + \sum_{h=2}^N h (y_{h-1} - y_h) u^{h-1}} \, du \right) \theta I_U(y),
\]
\[
\frac{\partial D}{\partial y_k} = g\left( \theta - \int_0^1 \frac{1-ynk}{1-y_1 + \sum_{h=2}^N h (y_{h-1} - y_h) u^{h-1}} \, du \right) (-\theta) I_D(y),
\]
where
\[
I_U(y) = \int_0^1 \frac{(1-y_1)(1-2u) \left[ku^{k-1} - (k+1) u^k\right]}{\left(1-y_1 + \sum_{h=2}^N h (y_{h-1} - y_h) u^{h-1}\right)^2} \, du,
\]
\[
I_D(y) = \int_0^1 \frac{(1-y_1) \left[ku^{k-1} - (k+1) u^k\right]}{\left(1-y_1 + \sum_{h=2}^N h (y_{h-1} - y_h) u^{h-1}\right)^2} \, du.
\]

35
By integration by parts
\[ I_D (y) = 2 \int_0^1 (1 - y t) \left( u^k - u^{k+1} \right) \frac{N \sum_{h=2}^N h (h-1) (y_{h-1} - y_h) u^{h-2}}{1 - y t + \sum_{h=2}^N h (y_{h-1} - y_h) u^{h-1}} \, du. \]

Now, \( I_D \geq 0 \) for any \( y \in Y \) because all terms in the integral are nonnegative. Therefore \( \frac{\partial I}{\partial y_k} \leq 0 \) for any \( y \in Y \), which implies that \( D \) is decreasing in \( y_k \) at any point \( y \in Y \).

Regarding the integral \( I_U \) we note that
\[ I_U (0) = \int_0^1 (1 - 2u) \left[ ku^{k-1} - (k+1) u^k \right] \, du = \frac{2}{(k+1)(k+2)} > 0. \]

So for each \( k \) there is an \( \varepsilon_k > 0 \) such that \( I_U (y) \geq 0 \) for any \( y \in Y \cap B(0, \varepsilon_k) \); so for \( \varepsilon = \min \{ \varepsilon_2, \ldots, \varepsilon_{N-1} \} \) it holds that \( I_U (y) \geq 0 \) for any \( y \in Y \cap B(0, \varepsilon) \). Therefore \( \frac{\partial U}{\partial y_k} \geq 0 \) for any \( y \in Y \cap B(0, \varepsilon) \) and \( k = 2, \ldots, N-1 \). This implies that \( U \) is increasing in \( y_k \) for any \( y \in Y \cap B(0, \varepsilon) \).

This establishes that \( H_1 (y) \) is increasing in \( y_k \) for any \( y \in Y \cap B(0, \varepsilon) \setminus \{0\} \).

So we have established that the limit inferior of \( H_1 (y) \) when \( y \to 0 \) is strictly positive. Then the following statement establishes that there is an \( \varepsilon > 0 \) such that the set \( Y \cap [0, \varepsilon]^{N-1} \) can take the role of the neighborhood \( V \) mentioned above.

**Lemma A.3** Let \( H : Y \setminus \{0\} \to \mathbb{R}^{N-1} \) be a continuous function such that \( \lim \inf_{y \to 0} H_1 (y) \geq a > 0 \). Then there exists \( \varepsilon > 0 \) such that \( H_1 (y) > \varepsilon \) for any \( y = (y_1, y_2, \ldots, y_{N-1}) \in Y \setminus \{0\} \) with \( y_1 \leq \varepsilon \).

**Proof.** Condition \( \lim \inf_{y \to 0} H_1 (y) \geq a > 0 \) implies that for any \( \delta > 0 \) there exists \( \varepsilon_\delta > 0 \) such that \( H_1 (y) > a - \delta \) for any \( y = (y_1, y_2, \ldots, y_{N-1}) \in Y \setminus \{0\} \) with \( y_1 \leq \varepsilon_\delta \). Take \( \delta_1 > 0 \) such that \( a - \delta_1 > 0 \). Then there exists \( \varepsilon_1 > 0 \) such that \( H_1 (y) > a - \delta_1 \) for any \( y = (y_1, y_2, \ldots, y_{N-1}) \in Y \setminus \{0\} \) with \( y_1 \leq \varepsilon_1 \). Now, if \( a - \delta_1 > \varepsilon_1 \) then choose \( \varepsilon = \varepsilon_1 \) and the result is proved. If \( a - \delta_1 \leq \varepsilon_1 \) then choose \( \varepsilon > 0 \) such that \( a - \delta_1 > \varepsilon \). For any \( y = (y_1, y_2, \ldots, y_{N-1}) \in Y \setminus \{0\} \) with \( y_1 \leq \varepsilon < \varepsilon_1 \) it holds that \( H_1 (y) > a - \delta_1 > \varepsilon \), so in this case the result is proved as well.

Since we established condition \( \lim \inf_{y \to 0} H_1 (y) \geq a > 0 \) in Proposition A.1 we can now use \( \varepsilon \) from Lemma A.3. Define the function \( J = (J_1, \ldots, J_{N-1}) : Y \to \mathbb{R}^{N-1} \) such that
\[ J (y) = \begin{cases} H (y) & \text{for } y \in Y \setminus Y_\varepsilon, \\ H (\varepsilon, y_2, \ldots, y_{N-1}) & \text{for } y \in Y_\varepsilon, \end{cases} \]
where \( Y_\varepsilon = \{ (y_1, y_2, \ldots, y_{N-1}) \in Y : y_1 \leq \varepsilon \} = Y \cap [0, \varepsilon]^{N-1} \). Notice that \( J \) is also defined in 0.
Lemma A.4 The function $J$ has the properties: (i) $J$ is continuous. (ii) $J$ takes values in $Y$. (iii) $J$ has no fixed point in $Y_{\varepsilon}$.

Proof. (i) Based on the fact that $H$ is continuous, $J$ is also continuous at points $y$ that are not on the boundary between $Y_{\varepsilon}$ and $Y \setminus Y_{\varepsilon}$. The only non-trivial case is when $y$ is on the boundary between $Y_{\varepsilon}$ and $Y \setminus Y_{\varepsilon}$, that is, in \( \{(y_1, y_2, \ldots, y_{N-1}) \in Y : y_1 = \varepsilon\} \). In this case the limit of $J(t^n)$ for a sequence $(t^n)_{n \geq 1} \subset \{(y_1, y_2, \ldots, y_{N-1}) \in Y : y_1 > \varepsilon\}$ with $t^n \to y$ should be $J(y)$. Indeed, $J(t^n) = H(t^n) \to H(y) = H(\varepsilon, y_2, \ldots, y_{N-1}) = J(y)$.

(ii) The fact that $J$ takes values in $Y$ follows from Lemma A.1 trivially for the case $(y_1, y_2, \ldots, y_{N-1}) \in Y \setminus Y_{\varepsilon}$. For the case $(y_1, y_2, \ldots, y_{N-1}) \in Y_{\varepsilon}$ it follows because $(\varepsilon, y_2, \ldots, y_{N-1}) \in Y$ for any $(y_1, y_2, \ldots, y_{N-1}) \in Y_{\varepsilon}$, so $J(\varepsilon, y_2, \ldots, y_{N-1}) = H(\varepsilon, y_2, \ldots, y_{N-1}) \in Y$.

(iii) For an arbitrary $(y_1, y_2, \ldots, y_{N-1}) \in Y_{\varepsilon}$ we have $J_1(y_1, y_2, \ldots, y_{N-1}) = H_1(\varepsilon, y_2, \ldots, y_{N-1})$. Since $y = (\varepsilon, y_2, \ldots, y_{N-1}) \in Y \setminus \{0\}$ with $y_1 \leq \varepsilon$, by Lemma A.3 it holds that $H_1(\varepsilon, y_2, \ldots, y_{N-1}) > \varepsilon$. Thus $J_1(y_1, y_2, \ldots, y_{N-1}) > \varepsilon \geq y_1$, so $(y_1, y_2, \ldots, y_{N-1})$ cannot be a fixed point of $J$. 

Finally we can establish that the system of equations (A15) has a solution. By Lemma A.4 the function $J : Y \to Y$ is continuous. $Y$ is a convex and compact set, so by Brouwer’s fixed point theorem $J$ has a fixed point $y^*$. The fixed point cannot be in $Y_{\varepsilon}$ by Lemma A.4, so $y^* \in Y \setminus Y_{\varepsilon}$. Therefore $y^* = J(y^*) = H(y^*)$, that is, $y^* \in Y \setminus Y_{\varepsilon}$ is a fixed point of $H$. By definition, any fixed point of $H$ is a solution of the system (A15). This completes the proof of existence of equilibrium in Theorem 1.

We now prove the part on uniqueness of equilibrium. Setting $N = 2$ in equations (A15) gives

\[
x_0 = G \left( \theta - \theta \int_0^1 \frac{x_0 - x_1}{x_0 - x_1 + 2x_1u} \, du \right);
\]

\[
x_1 = G \left( \theta \int_0^1 \frac{(x_0 - x_1)(1 - 2u)}{x_0 - x_1 + 2x_1u} \, du \right).
\]

Using the notation introduced before, $y_1 = x_1/x_0 \in (0, 1)$, the solution to this system of equations is given by the solution to $H_1(y_1) - y_1 = 0$, or

\[
\phi(y_1) \equiv y_1 G (\theta - \theta (1 - y_1) I(y_1)) - G (\theta (1 - y_1) J(y_1)) = 0.
\]
The derivations above in the proof of Proposition A.1 can readily be used to show that \( \lim_{y_1 \to 1} \phi(y_1) = G(\theta) > 0 \), \( \lim_{y_1 \to 0} \phi(y_1) = 0 \) and \( \lim_{y_1 \to 0} \phi'(y_1) < 0 \). Therefore, if the function \( \phi(y_1) \) is strictly convex, the equilibrium is unique. Let us now examine the second derivative of the function \( \phi(y_1) \).

First we have

\[
\phi'(y_1) = G(\theta - \theta(1 - y_1)I(y_1)) + y_1 g(\theta - \theta(1 - y_1)I(y_1)) \frac{d(-\theta(1 - y_1)I(y_1))}{dy_1} - g(\theta(1 - y_1)J(y_1)) \frac{d(\theta(1 - y_1)J(y_1))}{dy_1}
\]

and then

\[
\phi''(y_1) = 2g(\theta - \theta(1 - y_1)I(y_1)) \frac{d(-\theta(1 - y_1)I(y_1))}{dy_1} + y_1 g(\theta - \theta(1 - y_1)I(y_1)) \frac{d^2(-\theta(1 - y_1)I(y_1))}{dy_1^2} + y_1 g'(\theta - \theta(1 - y_1)I(y_1)) \left( \frac{d(-\theta(1 - y_1)I(y_1))}{dy_1} \right)^2 - g'(\theta(1 - y_1)J(y_1)) \left( \frac{d((1 - y_1)J(y_1))}{dy_1} \right)^2 - g(\theta(1 - y_1)J(y_1)) \left( \frac{d^2(\theta(1 - y_1)J(y_1))}{dy_1^2} \right)
\]

When \( g'(\cdot) = 0 \), this simplifies to

\[
\phi''(y_1) = g(\theta - \theta(1 - y_1)I(y_1)) \left( 2 \frac{d(-\theta(1 - y_1)I(y_1))}{dy_1} + y_1 \frac{d^2(-\theta(1 - y_1)I(y_1))}{dy_1^2} \right) - g(\theta(1 - y_1)J(y_1)) \left( \frac{d^2(\theta(1 - y_1)J(y_1))}{dy_1^2} \right)
\]

Notice that

\[
\frac{d(-\theta(1 - y_1)I(y_1))}{dy_1} = \log \left[ \frac{1+y_1}{1-y_1} \right] - \frac{2y_1}{(1-y_1)^2}
\]

\[
\frac{d^2(-\theta(1 - y_1)I(y_1))}{dy_1^2} = \frac{1+y_1}{(1-y_1)^3} + \frac{2y_1(y^2-y_1-1)}{(1+y_1)^2(1-y_1)}
\]

So

\[
2 \frac{d(-\theta(1 - y_1)I(y_1))}{dy_1} + y_1 \frac{d^2(-\theta(1 - y_1)I(y_1))}{dy_1^2} = \frac{2\theta}{(1-y_1)(1+y_1)^2} > 0 \text{ for all } y_1
\]
Finally
\[
\frac{d}{dy_1} \left( -\theta(1 - y_1)J(y_1) \right) = \theta \frac{2y_1(2 + y_1) - (2 - y_1) \log \left( \frac{1+y_1}{1-y_1} \right)}{2y_1^4}
\]

So
\[
\frac{d^2}{dy_1^2} \left( -\theta(1 - y_1)J(y_1) \right) = \theta \frac{-2y_1(3 + 2y_1 - 3y_1^2 - y_1^3)}{(1-y_1)(1+y_1)^2} + \frac{(3 - y_1) \log \left( \frac{1+y_1}{1-y_1} \right)}{y_1^4} < 0 \text{ for all } y_1
\]

Therefore we conclude that \( \phi(y_1) \) is strictly convex so the equilibrium is unique. \( \blacksquare \)

**Appendix B: Proofs Section 4.1**

The problem of identification studies whether we can determine the search cost distribution \( G \), the consumer valuation \( v \) and the firms’ marginal cost \( r \), when we know the price distribution. For this, we consider infinitely many firms in a market. Then the model can be described as follows. The exogenous variables are the triplet \( (G, v, r) \) that generate the endogenous variables \( (F, \{\mu_k\}_{k \geq 1}, \{c_k\}_{k \geq 0}) \). In this section we maintain the assumption that these latter variables exist. They satisfy

\[
\sum_{k \geq 1} k \mu_k (1 - F(p))^{k-1} = \mu_1 \frac{\overline{p} - r}{p - r} \text{ for any } p \in [\underline{p}, \overline{p}], \quad (A17a)
\]

\[
\overline{p} = v, \quad (A17b)
\]

\[
\mu_k = G(c_{k-1}) - G(c_k) \quad \text{for any } k \geq 1, \quad (A17c)
\]

\[
c_k = \int_{\underline{p}}^{\overline{p}} F(p) (1 - F(p))^k \, dp \quad \text{for any } k \geq 0. \quad (A17d)
\]

As before in the paper, here we also use the notation \( \mu_0 = 1 - \sum_{k \geq 1} \mu_k \).

**Proof of Proposition 6.** As argued in the text, the upper bound of \( F \) must be equal to the consumer valuation, i.e., \( \overline{p} = v \), so \( v' = v \); by Condition 6.1, \( r' = r \). First we show that \( \mu'_k = \mu_k \) for any \( k \). For this we note first that neither \( \mu_1 \) nor \( \mu'_1 \) can be equal to zero. If \( \mu_1 = 0 \) then by equation \( (A17a) \) \( \sum_{k \geq 2} k \mu_k (1 - F(p))^{k-1} = 0 \) for any \( p \in [\underline{p}, \overline{p}] \), which, due to the fact that \( F \) is continuous, can only happen if \( \mu_k = 0 \) for any \( k \geq 2 \). This further implies by equation \( (A17c) \) that \( G(c_k) = G(c_0) \) for any \( k \geq 1 \). By equation \( (4) \), \( c_n = e_n - e_{n+1} \), where \( e_n = E[\min \{p_1, \ldots, p_n\}] \). Since \( e_n \geq e_{n+1} \) and \( e_n \geq \underline{p} \) for any \( n \), the series \( (e_n)_n \) is convergent. Hence \( e_n \to 0 \) as \( n \to \infty \).
Because $G$ is continuous in 0, $G(c_n) \to G(0) = 0$, so $G(c_0) = 0$. Because the density function corresponding to $G$ is positive on $(0, \infty)$, this can only happen if $c_0 = 0$. But by equation (A17d) $c_0 = \int_0^p F(p) \, dp$, which is positive because $F$ is a continuous CDF with support $(\underline{p}, \overline{p})$, so we arrive at a contradiction. Since exactly the same arguments apply to $\mu_1'$, we have shown that $\mu_1$ and $\mu_1'$ are strictly positive.

From equation (A17a) we obtain

$$\sum_{k \geq 1} k \frac{\mu_k}{\mu_1} (1 - F(p))^{k-1} = \frac{v - r}{p - r} = \sum_{k \geq 1} k \frac{\mu_k'}{\mu_1'} (1 - F(p))^{k-1} \quad \text{for any } p \in (\underline{p}, \overline{p}).$$

This is equivalent to

$$\sum_{k \geq 2} \lambda_k t^{k-1} = 0 \quad \text{for any } t \in (0, \alpha), \quad (A18)$$

where $\lambda_k = k \left( \frac{\mu_k}{\mu_1} - \frac{\mu_k'}{\mu_1'} \right)$ for $k \geq 1$ and $t = 1 - F(p)$. This latter transformation is possible because $F$ is strictly increasing on some interval $(\underline{p}, \overline{p})$, where $1 - F(\underline{p}) = \alpha$. We now refer to Lemma A.5 below. This lemma implies that equation (A18) can only hold if $\lambda_k = 0$ for any $k \geq 2$. Therefore

$$\frac{\mu_k}{\mu_1} = \frac{\mu_k'}{\mu_1'}. \quad \text{On the other hand, by Condition 6.2, } \mu_1 + \sum_{k \geq 2} \mu_k = \mu_1' + \sum_{k \geq 2} \mu_k' = 1 - \mu_0,$$

which implies $1 - \frac{\mu_0}{\mu_1} = 1 - \frac{\mu_0}{\mu_1'}$. Therefore $\mu_k' = \mu_k$ for any $k \geq 1$.

The equalities $c_k' = c_k$ follow from equation (A17d). It remains to show that $G'(c_k) = G(c_k)$ for any $k \geq 0$. We do so by showing that the $G(c_k)$’s for $k \geq 0$ are uniquely determined by the $\mu_k$’s. By equation (A17c) $G(c_{k-1}) - G(c_k) = \mu_k$ for any $k \geq 1$. This implies that $G(c_0) - G(c_n) = \sum_{k=1}^n \mu_k$. The limit of the right hand side, when $n \to \infty$, exists and is $1 - \mu_0$. Therefore $G(c_0) - \lim_{n \to \infty} G(c_n) = 1 - \mu_0$. Because $G$ is continuous in $0$, $G(c_n) \to G(0) = 0$. Therefore $G(c_0) = 1 - \mu_0$ and $G(c_n) = 1 - \sum_{k=0}^n \mu_k$ for any $n \geq 1$. The result then follows from the equality of the $\mu_k$’s established above.

**Remark A.1** Condition 6.1 on p.12 is probably not necessary but we adopt it here for the simplicity of the proof. If this condition does not hold then equation (A17a) implies

$$\frac{p - r}{v - r} \sum_{k \geq 1} k \frac{\mu_k}{\mu_1} (1 - F(p))^{k-1} = \frac{p - r'}{v - r'} \sum_{k \geq 1} k \frac{\mu_k'}{\mu_1'} (1 - F(p))^{k-1} \quad \text{for any } p \in (\underline{p}, \overline{p}),$$

and this cannot be simplified to a power series identity as equation (A18). Still intuition suggests that the equalities $\mu_k' = \mu_k$ and $r' = r$ follow, since we may view this as a system of a continuum of equations with countably many unknowns $r, r', \mu_k, \mu_k'$ for $k \geq 1$. 

40
Proof of Proposition 7. Conditions 7.2 and 7.3 together with equation (A17c) imply that \( \mu'_k = \mu_k \) for any \( k \geq 1 \). From the proof of Proposition 6 we know that \( \mu_1 > 0 \), so by equations (A17a) and (A17b), and the first condition we have

\[
\sum_{k \geq 1} k \mu_k \left(1 - F'(p)\right)^{k-1} = \mu_1 \frac{v-r}{p-r} \quad \text{for any } p \in (p', \overline{p}'],
\]

without the right hand side being identically 0. Therefore \( F'(p) = F(p) \) for any \( p \in (p', \overline{p}'] \). This implies, by using the continuity of \( F \), that \( F(p') = 0 \) and \( F(\overline{p}') = 1 \) so \( p' \leq \overline{p} \) and \( \overline{p} \leq \overline{p}' \). If now we interchange \( F \) and \( F' \) in this argument then we obtain \( \underline{p} \leq p' \) and \( \underline{p} \leq \overline{p}' \), so \( p' = \overline{p} \) and \( \overline{p} = \overline{p}' \). This implies that \( F' = F \). \( \blacksquare \)

Proof of Proposition 8. In the proof we write \( c_0(t) \) to make explicit the dependence of \( c_0 \) on \( t = v - r \). Take an arbitrary interval \( (a, b) \subset \left(0, \sup_{t \in (0, \infty)} c_0(t)\right) \). Then the pre-image set defined as \( c_0^{-1}(a, b) = \{ t : c_0(t) \in (a, b) \} \) is a nonempty set, open in \( (0, \infty) \) because \( \lim_{t \to 0^+} c_0(t) = 0 \) (by equation (A17d)) and \( c_0 \) is a continuous function of \( t = v - r \). Therefore, with probability 1, there exists an \( m \) such that \( t_m = v^m - r^m \in c_0^{-1}(a, b) \), which means that \( c_0(t_m) \in (a, b) \).\(^{16}\) Because the interval \( (a, b) \) has been chosen arbitrarily, we have proved that for any interval, with probability 1 we can find an \( m \) such that the corresponding cutoff point \( c_0(t_m) \) is included in the interval. Since \( G(c_m, 0) = G(c_0(v^m - r^m)) \), \( m \geq 1 \), are identified, this establishes that in an arbitrary interval \( (a, b) \subset \left(0, \sup_{t \in (0, \infty)} c_0(t)\right) \) we can find a point at which the search cost distribution is identified with probability 1. Therefore, since it is continuous, \( G \) is identified on \( \left[0, \sup_{t \in (0, \infty)} c_0(t)\right] \). \( \blacksquare \)

Lemma A.5 (Power Series) Suppose that \( (a_n)_{n \geq 1} \subset \mathbb{R} \) and \( \sum_{n \geq 1} a_n x^n = 0 \) \( \forall x \in (0, \alpha) \) for some \( \alpha > 0 \). Then \( a_n = 0 \) for any \( n \geq 1 \).

Proof. \( \sum_{n \geq 1} a_n x^n = 0 \) implies \( a_1 + x \sum_{n \geq 0} a_n x^n = 0 \) \( \forall x \in (0, \alpha) \). This can also be written as \( \sum_{n \geq 0} a_{n+2} x^n = -\frac{a_1}{x} \) \( \forall x \in (0, \alpha) \), which means that the power series \( \sum_{n \geq 0} a_{n+2} x^n \) converges \( \forall x \in (0, \alpha) \). Then by Lemma A.6 below there exists \( \rho \in (0, \alpha) \) such that \( \sum_{n \geq 0} a_{n+2} x^n \) is uniformly convergent on \( [-\rho, \rho] \). Let \( p_1(x) \) be its limit, where \( p_1 : [-\rho, \rho] \to \mathbb{R} \), that is, \( \sum_{n \geq 0} a_{n+2} x^n =\)

\(^{16}\)The argument for this statement is the following. Suppose that we have iid random variables \( x_1, x_2, \ldots, x_n \) drawn from a distribution with support \( (0, \infty) \) and let \( (c, d) \subset (0, \infty) \). Then the probability that at least one of these random variables is in \( (c, d) \) is \( 1 - P(x, \notin (c, d)) = 1 - [1 - P(x, \in (c, d))]^n \). Since \( P(x, \in (c, d)) > 0 \), the above probability goes to 1 when \( n \to \infty \). So when we have a countably infinite sequence of random variables, the probability that at least one of these random variables is in \( (c, d) \) is 1.
\( p_1(x) \forall x \in [-\rho, \rho] \). Therefore

\[
a_1 = -xp_1(x) \quad \forall x \in [-\rho, \rho]. \tag{A19}
\]

The function \( p_1 \) is continuous because it is the uniform limit of a sequence of continuous functions, so \( \lim_{x \to 0} p_1(x) = p_1(0) = a_2 \). This further implies that \( \lim_{x \to 0} xp_1(x) = 0 \), so based on equation (A19), for any \( \varepsilon > 0 \) there is \( \delta(\varepsilon) > 0 \) such that \( |a_1| = |xp_1(x)| < \varepsilon \) for any \( x \) with \( |x| < \delta(\varepsilon) \). This implies that \( a_1 = 0 \).

So we have obtained that \( \sum_{n \geq 2} a_n x^n = 0 \ \forall x \in (0, \alpha) \), which implies \( \sum_{n \geq 2} a_n x^{n-1} = 0 \ \forall x \in (0, \alpha) \). By renaming the sequence \((a_n)_{n \geq 2}\) as \((b_n)_{n \geq 1}\) with \( b_n = a_{n+1} \) we have \( \sum_{n \geq 1} b_n x^n = 0 \ \forall x \in (0, \alpha) \). The arguments of the previous paragraph imply that \( b_1 = 0 \), that is, \( a_2 = 0 \). Going on this way we can show that \( a_n = 0 \) for any \( n \geq 1 \).  

The following lemma is a version of a result also known as Abel’s Uniform Convergence Test.

**Lemma A.6 (Abel)** Suppose that the series \( \sum_{n \geq 0} a_n x^n \) is convergent. Then \( \forall \rho \) with \( 0 < \rho < |x_0| \) the series \( \sum_{n \geq 0} a_n x^n \) is uniformly convergent \( \forall x \in [-\rho, \rho] \).

**Proof.** Let \( y \) be arbitrary with \( 0 < |y| < |x_0| \). First we note that the convergence of the series \( \sum_{n \geq 0} a_n x^n \) implies that \( \lim_{n \to \infty} a_n x^n = 0 \) and therefore there exists \( M \) with \( |a_n x^n| < M \ \forall n \). The sequence \( b_n = \sum_{k=0}^{n} |a_k| |y|^k \) is convergent because it is increasing and

\[
\sum_{k=0}^{n} |a_k| |y|^k = \sum_{k=0}^{n} |a_k| |x_0|^k \frac{|y|^k}{|x_0|^k} < M \sum_{k=0}^{n} \frac{|y|^k}{|x_0|^k} \leq \frac{M}{1 - \frac{|y|}{|x_0|}}, \quad \forall n,
\]

that is, \((b_n)\) is bounded above. Let \( b = \lim_{n \to \infty} b_n = \sum_{k \geq 0} |a_k| |y|^k \). Then the sequence \( \sum_{k \geq n+1} |a_k| |y|^k = b - b_n \), and hence it converges to 0.

In particular, by taking \( y = \rho \) we have obtained that \( \sum_{k \geq n+1} |a_k| \rho^k \) converges to 0 for arbitrary \( \rho \) with \( 0 < \rho < |x_0| \) and by taking \( y = |x| \) we have obtained that \( \sum_{k \geq 0} |a_k| |x|^k \) is convergent for \( \forall x \in [-\rho, \rho] \). This latter statement means that the series \( \sum_{k \geq 0} a_k x^k \) is absolutely convergent and hence convergent for \( \forall x \in [-\rho, \rho] \). So we can write

\[
\sup_{x \in [-\rho, \rho]} \left| \sum_{k \geq 0} a_k x^k - \sum_{k=0}^{n} a_k x^k \right| = \sup_{x \in [-\rho, \rho]} \left| \sum_{k=0}^{n} a_k x^k \right| \leq \sup_{x \in [-\rho, \rho]} \sum_{k \geq n+1} |a_k| |x|^k \leq \sum_{k \geq n+1} |a_k| \rho^k.
\]

Since the right hand side goes to 0 as \( n \to \infty \), we have obtained that \( \sum_{k \geq 0} a_k x^k \) converges to \( \sum_{k \geq 0} a_k x^k \) uniformly for \( x \in [-\rho, \rho] \).
References


