Goovaerts, Marc J.; Kaas, Rob; Laeven, Roger J.A.; Tang, Qihe

Working Paper
A Comonotonic Image of Independence for Additive Risk Measures

Tinbergen Institute Discussion Paper, No. 04-030/4

Provided in Cooperation with:
Tinbergen Institute, Amsterdam and Rotterdam

Suggested Citation: Goovaerts, Marc J.; Kaas, Rob; Laeven, Roger J.A.; Tang, Qihe (2004): A Comonotonic Image of Independence for Additive Risk Measures, Tinbergen Institute Discussion Paper, No. 04-030/4

This Version is available at:
http://hdl.handle.net/10419/86311

Terms of use:
Documents in EconStor may be saved and copied for your personal and scholarly purposes.

You are not to copy documents for public or commercial purposes, to exhibit the documents publicly, to make them publicly available on the internet, or to distribute or otherwise use the documents in public.

If the documents have been made available under an Open Content Licence (especially Creative Commons Licences), you may exercise further usage rights as specified in the indicated licence.
A Comonotonic Image of Independence for Additive Risk Measures

Marc J. Goovaerts\textsuperscript{1,2,3}
Rob Kaas\textsuperscript{1}
Roger J.A. Laeven\textsuperscript{1,3}
Qihe Tang\textsuperscript{1}

\textsuperscript{1} Faculty of Economics and Econometrics, Universiteit van Amsterdam,
\textsuperscript{2} Cath. University of Leuven, Center for Risk and Insurance Studies,
\textsuperscript{3} Tinbergen Institute.
Tinbergen Institute
The Tinbergen Institute is the institute for economic research of the Erasmus Universiteit Rotterdam, Universiteit van Amsterdam, and Vrije Universiteit Amsterdam.

Tinbergen Institute Amsterdam
Roetersstraat 31
1018 WB Amsterdam
The Netherlands
Tel.: +31(0)20 551 3500
Fax: +31(0)20 551 3555

Tinbergen Institute Rotterdam
Burg. Oudlaan 50
3062 PA Rotterdam
The Netherlands
Tel.: +31(0)10 408 8900
Fax: +31(0)10 408 9031

Please send questions and/or remarks of non-scientific nature to driessen@tinbergen.nl. Most TI discussion papers can be downloaded at http://www.tinbergen.nl.
A Comonotonic Image of Independence for Additive Risk Measures

Marc J. Goovaerts†‡, Rob Kaas†, Roger J.A. Laeven†∗, Qihe Tang†

†University of Amsterdam, Dept. of Quantitative Economics, Roetersstraat 11,
1018 WB Amsterdam, The Netherlands
‡Catholic University of Leuven, Center for Risk and Insurance Studies,
Naamsestraat 69, B-3000 Leuven, Belgium

March 9, 2004

Abstract

This paper presents a new axiomatic characterization of risk measures that are additive for independent random variables. In contrast to previous work, we include an axiom that guarantees monotonicity of the risk measure. Furthermore, the axiom of additivity for independent random variables is related to an axiom of additivity for comonotonic random variables. The risk measure characterized can be regarded as a mixed exponential premium.

Keywords: Risk measures, Additivity, Exponential order, Laplace transform order, Esscher transform, Comonotonicity

JEL-Classification: D81, G22

∗Corresponding author. E-mail: R.J.A.Laeven@uva.nl, Phone: +31 20 525 7317, Fax: +31 20 525 4349.
1 Introduction

Several representations of risk measures that are additive for independent random variables are available in the literature. The most general representation has been characterized axiomatically by Gerber & Goovaerts (1981) and is known as the mixed Esscher principle. More restrictive characterizations can be found in Gerber (1974) and Goovaerts & De Vijlder (1980).

The mixed Esscher premium in general and the non-mixed Esscher premium in particular has several appealing features; the interested reader is referred to Bühlmann (1980), Gerber (1980) and Goovaerts, De Vijlder & Haezendonck (1984). However, a serious concern of both the mixed and the non-mixed Esscher premium is that it is not monotonic in general, i.e. it does not in general preserve stochastic dominance; see Gerber (1981) and Van Heerwaarden, Kaas & Goovaerts (1989).

In the present contribution we provide a new axiomatic characterization of risk measures that are additive for independent random variables. The characterization includes an axiom that guarantees monotonicity of the representing risk measure. Moreover, the current characterization relates the axiom of additivity of the risk measure for independent random variables to an axiom of additivity for comonotonic random variables. The risk measure obtained can be regarded as an ordinary mixture of exponential premiums. Equivalently, the obtained risk measure can be regarded as a restricted version of the mixed Esscher principle. In particular, the mixture function of the mixed Esscher principle is now required to be concave on $(0, +\infty)$ and convex on $(-\infty, 0)$, in addition to being non-decreasing.

2 A New Axiomatic Representation of Additive Risk Measures

In this section we present a new axiomatic characterization of risk measures that are additive for independent r.v.’s. Throughout the paper we restrict to bounded r.v.’s, unless stated otherwise. For a given r.v. $X$, we define the real-valued function $\varphi_X(\cdot)$ as follows:

$$
\varphi_X(t) = \begin{cases} 
\frac{1}{t} \log \mathbb{E}[e^{tX}], & t \neq 0; \\
\mathbb{E}[X] & t = 0.
\end{cases}
$$

In the actuarial literature, $\varphi_X(t)$ for $t \geq 0$ is known as the exponential premium with parameter $t$, see Gerber (1974) and Goovaerts, De Vijlder & Haezendonck (1984). For $t < 0$, one may also regard the number $\varphi_X(t)$ as an exponential premium, but then it can
be shown to have a negative safety loading. Notice that the correspondence between the cumulative distribution function (cdf) of $X$ and the function $\varphi_X(\cdot)$ is unique, since $\varphi_X(\cdot)$ corresponds uniquely to the moment generating function of $X$.

Next, for the cdf $F_X(\cdot)$ with differential $dF_X(\cdot)$, corresponding to a given r.v. $X$, we define by

$$dF_X^{(t)}(x) = \frac{e^{tx}dF_X(x)}{\mathbb{E}[e^{tx}]}, \quad t \in \mathbb{R} \quad (2)$$

its Esscher transform with parameter $t$. Furthermore, we define the real-valued function $\psi_X(\cdot)$ as follows:

$$\psi_X(t) = \int_{(-\infty, +\infty)} x dF_X^{(t)}(x) = \frac{\mathbb{E}[Xe^{tx}]}{\mathbb{E}[e^{tx}]}. \quad (3)$$

The number $\psi_X(t)$ is known as the Esscher premium with parameter $t$, see Bühlmann (1980) and Goovaerts, De Vijlder & Haezendonck (1984). Since by (1),

$$\frac{d}{dt}(t\varphi_X(t)) = \psi_X(t)$$

when $t \neq 0$, it follows that

$$\varphi_X(t) = \frac{1}{t} \int_0^t \psi_X(s)ds, \quad t \neq 0. \quad (4)$$

As is well-known, both the Esscher premiums and the exponential premiums and the exponential premiums increase with their parameter. We remark for further reference that

$$\lim_{t \to -\infty} \varphi_X(t) = \min[X] = \lim_{t \to -\infty} \psi_X(t) \quad (5)$$

and that

$$\lim_{t \to +\infty} \varphi_X(t) = \max[X] = \lim_{t \to +\infty} \psi_X(t). \quad (6)$$

For notational convenience, we write in the sequel $\varphi_X(t)$ and $\psi_X(t)$ also for the limits when $t \to -\infty$ and $t \to +\infty$. We introduce the notions of exponential order and Laplace transform order. We say that a r.v. $X$ is smaller than a r.v. $Y$ in exponential order if

$$\mathbb{E}[e^{tx}] \leq \mathbb{E}[e^{ty}], \quad t \geq 0. \quad (7)$$

Furthermore, we say that a r.v. $X$ is smaller than a r.v. $Y$ in Laplace transform order if

$$\mathbb{E}[e^{tx}] \geq \mathbb{E}[e^{ty}], \quad t \leq 0. \quad (8)$$

We write $X \leq_e Y$ and $X \leq_{Lt} Y$ respectively. Note that $X \leq_e Y$ is equivalent to $-Y \leq_{Lt} -X$. In the sequel, we look at pairs of r.v.’s $X$ and $Y$ such that both $X \leq_e Y$ and $X \leq_{Lt} Y$.
(or equivalently $X \leq_e Y$ and $-Y \leq_e -X$). Clearly, the twofold condition $X \leq_e Y$ and $X \leq_{lt} Y$ is also equivalent to the condition $\varphi_X(t) \leq \varphi_Y(t)$ for all $t$. The interested reader is referred to Denuit (2001) for a further treatment of the two notions of stochastic order.

We denote by the functional $\pi[\cdot]$ a risk measure that assigns a real number to a given r.v. Then we introduce the set $S_1$ of axioms that $\pi[\cdot]$ must satisfy:

A1. If $\varphi_X(t) \leq \varphi_Y(t)$ for all $t$ then $\pi[X] \leq \pi[Y]$;

A2. $\pi[c] = c$, for all real $c$;

A3. $\pi[X + Y] = \pi[X] + \pi[Y]$ when $X$ and $Y$ are independent;

A4. If $X_n$ converges weakly to $X$, with $\min[X_n] \to \min[X]$ and $\max[X_n] \to \max[X]$, then $\lim_{n \to +\infty} \pi[X_n] = \pi[X]$.

Clearly, $X$ and $Y$ have uniformly ordered exponential premiums (also for risk-loving exponential decision makers), or what is the same, moment generating functions (mgf’s) crossing at 0, if $X$ is stochastically dominated by $Y$, written as $X \leq_{st} Y$. Therefore, axiom A1 guarantees monotonicity of the risk measure $\pi[\cdot]$. Though stochastic order cannot hold for different distributions that have the same expectation, pairs with ordered exponential premiums and yet the same expectation do exist. Consider for instance the r.v.’s $X$ and $Y$ with $\mathbb{P}[X = 1] = \frac{2}{3} = 1 - \mathbb{P}[X = -2]$ and $Y = -X$. It follows from Taylor expansions for their mgf’s that if $X$ and $Y$ have ordered exponential premiums and equal expectations, they must have the same variance as well. Moreover, if $X$ and $Y$ have the first three moments in common, the fourth moment (“peakedness”) must also be equal if $X$ and $Y$ have ordered exponential premiums. Notice that $X$ and $Y$ having ordered exponential premiums implies that $X \leq_{ex} Y$ cannot hold; here as usual we write $X \leq_{ex} Y$ if for any convex function $f(\cdot)$ it holds that $\mathbb{E}[f(X)] \leq \mathbb{E}[f(Y)]$.

Note that $c$ plays two roles in axiom A2: a r.v. degenerated at $c$ on the left-hand side and a real number on the right-hand side. In the economic literature, axiom A2 is known as the certainty equivalence condition. One can regard axiom A3, which imposes additivity for independent random variables, as the most “characteristic” axiom. Additivity of the risk measure for independent r.v.’s is particularly desirable in the context of premium calculation and allocation from top down for a portfolio consisting of independent policies; see Bühlmann (1985) or Kaas et al. (2001), section 5.2. Axiom A4 can be regarded as a continuity condition on the risk measure $\pi[\cdot]$.

To characterize the mixed Esscher principle, Gerber & Goovaerts (1981) impose the same axioms A2 and A3, and a weaker version of axiom A1. Axiom A4 is imposed tacitly.
Their weaker version of axiom A1 says that if \( \psi_X(t) \leq \psi_Y(t) \) for all \( t \), then \( \pi[X] \leq \pi[Y] \). From (4) it follows that if \( \psi_X(t) \leq \psi_Y(t) \) for all \( t \), then also \( \varphi_X(t) \leq \varphi_Y(t) \) for all \( t \). Note that the converse is not true. Note furthermore that while \( X \leq_{st} Y \) implies ordered exponential premiums, it does not necessarily imply ordered Esscher premiums. Therefore, the mixed Esscher principle is not monotonic in general.

Below we will restate the four axioms using the one-to-one correspondence between the cdf of \( X \) and the function \( \varphi_X(\cdot) \). For that purpose, we first introduce several concepts. In the following, we arbitrarily fix a defective, continuous r.v. \( T_0 \) with a strictly increasing cdf \( F_{T_0}(\cdot) \), supported on \([-\infty, +\infty]\) and having positive jumps at both \(-\infty\) and \(+\infty\). We consider \( \varphi_X(T_0) \), where the function \( \varphi_X(\cdot) \) is as defined in (1). Clearly, because \( \varphi_X(\cdot) \) depends on the cdf of \( X \) rather than on the particular r.v. \( X \), we can assume throughout without loss of generality that \( T_0 \) is independent of all indices used. Hence, \( \varphi_X(T_0) \) can be expressed as

\[
\varphi_X(T_0) = \frac{1}{T_0} \log \mathbb{E}_X[e^{T_0X}].
\]  

(9)

The r.v. \( \varphi_X(T_0) \) can be regarded as an exponential premium with random parameter \( T_0 \). We remark that there exists a one-to-one correspondence between \( X \) and \( \varphi_X(T_0) \) in the sense that two r.v.'s \( X \) and \( Y \) are equal in distribution if and only if \( \varphi_X(T_0) = \varphi_Y(T_0) \), almost surely (a.s.).

Next, we introduce comonotonicity of a random vector.

**Definition 2.1** A random vector \((X_1, \ldots, X_n)\) is comonotonic if there exists an arbitrary r.v. \( T \) and non-decreasing functions \( f_i, i = 1, \ldots, n \), such that

\[
(X_1, \ldots, X_n) = (f_1(T), \ldots, f_n(T)), \quad \text{in distribution.}
\]  

(10)

We refer to Dhaene et al. (2002a, 2002b) for an extensive treatment of comonotonicity and its applications in actuarial science.

We introduce the class \( \Phi_{T_0} \) defined by

\[
\Phi_{T_0} = \{ \varphi_X(T_0) | X \text{ a bounded r.v.} \}.
\]  

(11)

The class \( \Phi_{T_0} \) contains all r.v.'s \( \varphi_X(T_0) \) generated by a bounded r.v. \( X \). Then, we define for the risk measure \( \pi[\cdot] \) satisfying the set \( S_1 \) of axioms, the functional \( \rho_{T_0} : \Phi_{T_0} \rightarrow \mathbb{R} \) that assigns the real number \( \pi[X] \) to the r.v. \( \varphi_X(T_0) \), i.e.

\[
\rho_{T_0}[\varphi_X(T_0)] = \pi[X].
\]  

(12)

If (and only if) \( \pi[\cdot] \) satisfies the set \( S_1 \) of axioms, the risk measure \( \rho_{T_0}[\cdot] \) satisfies the following set \( S'_1 \) of axioms:
A1′. If \( \varphi_X(T_0) \leq \varphi_Y(T_0) \) a.s., then \( \rho_{T_0}[\varphi_X(T_0)] \leq \rho_{T_0}[\varphi_Y(T_0)] \);

A2′. \( \rho_{T_0}[\varphi_c(T_0)] = c \), for all real \( c \);

A3′. \( \rho_{T_0}[\varphi_X(T_0) + \varphi_Y(T_0)] = \rho_{T_0}[\varphi_X(T_0)] + \rho_{T_0}[\varphi_Y(T_0)] \);

A4′. If \( \varphi_{X_n}(T_0) \) converges a.s. to \( \varphi_X(T_0) \), then \( \lim_{n \to +\infty} \rho_{T_0}[\varphi_{X_n}(T_0)] = \rho_{T_0}[\varphi_X(T_0)] \).

To verify that A4′ is equivalent to A4 we state the following lemma:

**Lemma 2.1** For a given sequence \( \{X_n\} \) of bounded r.v.’s and a bounded (limit) r.v. \( X \), it holds that \( X_n \) converges weakly to \( X \), with \( \min[X_n] \to \min[X] \) and \( \max[X_n] \to \max[X] \), if and only if \( \varphi_{X_n}(T_0) \) converges a.s. to \( \varphi_X(T_0) \).

**Proof of “only if” part:** Since \( X_n \) converges weakly to \( X \), with \( \min[X_n] \to \min[X] \) and \( \max[X_n] \to \max[X] \), it is not difficult to see that there exists some constant \( c > 0 \) such that \( |X_n| \leq c \) and \( |X| \leq c \) hold a.s. Hence, by the dominated convergence theorem, the relation

\[
\lim_{n \to \infty} \varphi_{X_n}(t) = \varphi_X(t)
\]

holds for all \( t \in [-\infty, +\infty] \). This proves that \( \varphi_{X_n}(T_0) \) converges a.s. to \( \varphi_X(T_0) \).

**Proof of “if” part:** Since \( \varphi_{X_n}(T_0) \) converges a.s. to \( \varphi_X(T_0) \) and the events \( \{T_0 = -\infty\} \) and \( \{T_0 = +\infty\} \) have positive probabilities, the convergences \( \min[X_n] \to \min[X] \) and \( \max[X_n] \to \max[X] \) follow immediately from (5) and (6). To prove that \( X_n \) converges weakly to \( X \), applying the well-known continuity theorem (see, for example, Theorem 2, Chapter XIII, p. 431 of Feller (1971)), it suffices to prove that relation (13) holds for all real \( t \). For this purpose we recall the assumptions on the random variable \( T_0 \) and the monotonicity of the function \( \varphi_{X_n}(\cdot) \). By the a.s. convergence of \( \varphi_{X_n}(T_0) \) to \( \varphi_X(T_0) \), it holds for any \( \varepsilon > 0 \) that

\[
\lim_{n \to \infty} \mathbb{E}[\varphi_{X_n}(T_0) 1_{\{t < T_0 \leq t + \varepsilon\}}] = \mathbb{E}[\varphi_X(T_0) 1_{\{t < T_0 \leq t + \varepsilon\}}],
\]

where as usual, we denote by \( 1_A \) the indicator function of event \( A \). Hence,

\[
\varphi_{X_n}(t) \leq \frac{1}{\mathbb{P}[t < T_0 \leq t + \varepsilon]} \int_t^{t+\varepsilon} \varphi_{X_n}(u) dF_{T_0}(u) \]

\[
\to \frac{1}{\mathbb{P}[t < T_0 \leq t + \varepsilon]} \int_t^{t+\varepsilon} \varphi_X(u) dF_{T_0}(u) \]

\[
\leq \varphi_X(t + \varepsilon).
\]
Then, by the arbitrariness of \( \varepsilon > 0 \) and the continuity of the function \( \varphi_X(\cdot) \), it follows that

\[
\limsup_{n \to \infty} \varphi_{X_n}(t) \leq \varphi_X(t).
\]

Similarly, we can prove that

\[
\liminf_{n \to \infty} \varphi_{X_n}(t) \geq \varphi_X(t).
\]

This proves that (13) holds for all real \( t \), which ends the proof of Lemma 2.1.

Note that axiom A3’ is the \textit{comonotonic image} of axiom A3, recalling that \( \varphi_X(\cdot) \) is a non-decreasing function. Indeed, the additivity of the risk measure \( \pi[\cdot] \) for independent r.v.’s \( X \) and \( Y \) in axiom A3 corresponds to the additivity of the risk measure \( \rho_{T_0}[\cdot] \) for the comonotonic r.v.’s \( \varphi_X(T_0) \) and \( \varphi_Y(T_0) \) in axiom A3’.

Let us consider the risk measure \( \rho_{T_0}[\cdot] \) in further detail. We define \( p_1 = F_{T_0}(-\infty) \) and \( 1 - p_2 = F_{T_0}(+\infty) \). Let \( A_1 \) be the event \( \{ T_0 = -\infty \} \), \( A_2 \) be the event \( \{ -\infty < T_0 < +\infty \} \) and \( A_3 \) be the event \( \{ T_0 = +\infty \} \). We define the r.v. \( U(T_0) \) as follows:

\[
U(T_0) = 1_{A_1}U_1 + 1_{A_2}F_{T_0}(T_0) + 1_{A_3}U_3,
\]

where \( U_1 \) is uniformly distributed on \( (0,p_1) \) and independent of \( 1_{A_1} \), and \( U_3 \) is uniformly distributed on \( (1 - p_2, 1) \) and independent of \( 1_{A_3} \). Then \( U(T_0) \) is uniformly distributed on \( (0,1) \). Notice that \( U(s) < U(t) \) a.s. whenever \( s < t \) and \( s \) or \( t \) are \( -\infty \) or \( +\infty \), while \( U(s) < U(t) \) for \( s < t \) when both \( s \) and \( t \) are finite. It is well-known that for a given r.v. \( V \) it holds that

\[
V = F_V^{-1}(U(T_0)), \quad \text{in distribution},
\]

where as usual we denote by \( F_V^{-1}(\cdot) \) the \textit{generalized inverse} cdf of \( V \), defined by

\[
F_V^{-1}(p) = \inf\{x \in \mathbb{R} | F_V(x) \geq p\}.
\]

We remark for further reference that a r.v. \( V \) is stochastically dominated by a r.v. \( W \) if and only if \( F_V^{-1}(U(T_0)) \leq F_W^{-1}(U(T_0)) \), a.s. Note that for any given bounded r.v. \( X \) there exists a r.v. \( V \) with the same support as \( X \) such that

\[
\varphi_X(T_0) = F_V^{-1}(U(T_0)), \quad \text{a.s.}
\]

(15)

Note that, conversely, for a particular bounded r.v. \( V \) there may not exist a bounded r.v. \( X \) such that

\[
F_V^{-1}(U(T_0)) = \varphi_X(T_0), \quad \text{a.s.}
\]

(16)

One may verify the latter statement by considering for \( V \) a Bernoulli r.v. Consequently, the functional \( \rho_{T_0}[\cdot] \) defined in (12) is not defined for arbitrary r.v.’s \( F_V^{-1}(U(T_0)) \) with \( V \)
a bounded r.v. To extend the functional $\rho_{T_0}[:]$ to arbitrary bounded r.v.’s $F_v^{-1}(U(T_0))$, we introduce the class $\Theta_{T_0} = \{F_v^{-1}(U(T_0)) | V \text{ a bounded r.v.}\}$ of which $\Phi_{T_0}$ is a subclass and we impose that $\rho_{T_0}[:]; \Theta_{T_0} \rightarrow \mathbb{R}$ satisfies the set of axioms $S_1''$, which is the analog of $S_1'$, given by

A1”. (Monotonicity) If $F_v^{-1}(U(T_0)) \leq F_w^{-1}(U(T_0))$ a.s., then $\rho_{T_0}[F_v^{-1}(U(T_0))] \leq \rho_{T_0}[F_w^{-1}(U(T_0))]$;

A2”. (Certainty Equivalence) $\rho_{T_0}[c] = c$, for all real $c$;

A3”. (Comonotonic Additivity) $\rho_{T_0}[F_v^{-1}(U(T_0)) + F_w^{-1}(U(T_0))] = \rho_{T_0}[F_v^{-1}(U(T_0))] + \rho_{T_0}[F_w^{-1}(U(T_0))]$;

A4”. (Continuity) If $F_v^{-1}(U(T_0))$ converges a.s. to $F_v^{-1}(U(T_0))$, then

$$\lim_{n \rightarrow +\infty} \rho_{T_0}[F_v^{-1}(U(T_0))] = \rho_{T_0}[F_v^{-1}(U(T_0))]$$

Notice that A1” can be restated as: if $V \leq_{st} W$, then $\rho_{T_0}[F_v^{-1}(U(T_0))] \leq \rho_{T_0}[F_w^{-1}(U(T_0))]$. Notice furthermore, that A4” is equivalent to the condition that if $V_n$ converges weakly to $V$, then $\lim_{n \rightarrow +\infty} \rho_{T_0}[F_v^{-1}(U(T_0))] = \rho_{T_0}[F_v^{-1}(U(T_0))]$. However, we prefer to present axioms A1” and A4” in the way we have done above, to demonstrate explicitly that $S_1''$ is the analog of $S_1'$. A representation theorem for the functional $\rho_{T_0}[:]$ is given by Wu & Wang (2003); see for the original work Greco (1982) (or translated into English: Denneberg (1994)) and Yaari (1987). Although Wu & Wang (2003) consider only non-negative r.v.’s, their result also applies to our case where all r.v.’s are bounded. To verify this statement note that because of the comonotonic additivity of the risk measure $\rho_{T_0}[:$, it holds that

$$\rho_{T_0}[F_v^{-1}(U(T_0))] = \rho_{T_0}[F_v^{-1}(U(T_0)) - \min[V] + \min[V]]$$

$$= \rho_{T_0}[F_v^{-1}(U(T_0)) - \min[V]] + \min[V].$$

Then, applying Theorem 3.2 from Wu & Wang (2003), we derive that under the set $S_1''$ of axioms, the risk measure $\rho_{T_0}[:$ is represented by

$$\rho_{T_0}[F_v^{-1}(U(T_0))] = \int_{(-\infty, +\infty)} vd \left( 1 - w(1 - F_v^{-1}(U(T_0))(v)) \right),$$

in which the function $w(.) : [0, 1] \rightarrow [0, 1]$ is non-decreasing, right continuous and satisfies $w(0) = 0$ and $w(1) = 1$. Then we state the main theorem:

**Theorem 2.1** A risk measure $\pi[:$ satisfies the set $S_1$ of axioms if and only if there exists some non-decreasing function $G : [-\infty, +\infty] \rightarrow [0, 1]$ such that

$$\pi[X] = G(-\infty) \min[X] + \int_{(-\infty, +\infty)} \varphi_X(t)dG(t) + (1 - G(+\infty)) \max[X].$$

18
Proof of “only if” part: Consider representation (17). Since $F_V^{-1}(U(t))$ is non-decreasing in $t$ and the generalized inverse cdf $F_V^{-1}(\cdot)$ is appropriately defined, substituting $v = F_V^{-1}(U(t))$ gives
\[
\rho_{T_0}[F_V^{-1}(U(T_0))] = \int_{(-\infty, +\infty)} vd \left( 1 - w(1 - F_V^{-1}(U(T_0))(v)) \right)
\]
\[
= \int_{[-\infty, +\infty]} F_V^{-1}(U(t))d \left( 1 - w(1 - F_{T_0}(t)) \right).
\]
(19)

Then, we define the function $G(\cdot) : [-\infty, +\infty] \to [0, 1]$ as follows:
\[
G(t) = 1 - w(1 - F_T(t)).
\]
(20)

Since $w(\cdot)$ is non-decreasing, we find that $G(\cdot)$ is non-decreasing as well. Hence, on the subclass $\Phi_{T_0}$, the functional $\rho_{T_0}[\cdot]$ can be represented by
\[
\rho_{T_0}[\varphi_X(T_0)] = \int_{[-\infty, +\infty]} \varphi_X(t)dG(t).
\]
(21)

Now representation (18) follows from (21) and equality (12). This ends the proof of the “only if” part.

Proof of “if” part: The proof of A1, A2 and A3 is trivial. Since $X_n$ and $X$ are uniformly bounded by the same constant, the proof of A4 follows by application of the dominated convergence theorem. This ends the proof of the theorem.

One may regard the mixture function $G(\cdot)$ as a cdf, possibly defective with “mass” at both endpoints of its domain. Consequently, the risk measure characterized in Theorem 2.1 can be regarded as the expectation of an exponential premium with random parameter. Here the expectation is not calculated with respect to the real probability distribution of the random parameter but with respect to a transformed probability distribution, see (20). Note the similarity to derivative pricing in arbitrage free financial markets, where derivative prices can be expressed as expectations calculated with respect to an equivalent martingale measure rather than with respect to the real probability measure. We state the following corollary:

Corollary 2.1 A risk measure $\pi[\cdot]$ satisfies the set $\mathcal{S}_1$ of axioms if and only if there exists some non-decreasing function $H : [-\infty, +\infty] \to [0, 1]$, concave on $(0, +\infty)$ and convex on
\((-\infty, 0)\) such that
\[
\pi[X] = H(-\infty)\psi_X(-\infty) + \int_{(-\infty, +\infty)} \psi_X(t) dH(t) + (1 - H(+\infty))\psi_X(+\infty)
\]
\[
= H(-\infty) \min[X] + \int_{(-\infty, +\infty)} \frac{\mathbb{E}[xe^{tx}]}{\mathbb{E}[e^{tx}]} dH(t) + (1 - H(+\infty)) \max[X].
\] (22)

**Proof:** We will show that representation (22) is equivalent to representation (18). Consider representation (18). We define a function \(M(\cdot)\) as follows:
\[
dM(t) = \frac{1}{t} dG(t), \quad t \neq 0, \quad M(-\infty) = M(+\infty) = 0.
\] (23)

Notice that \(M(\cdot)\) is non-decreasing on \((0, +\infty)\) and non-increasing on \((-\infty, 0)\), while \(M(0)\) is irrelevant. By substitution of (23) in (18) we obtain
\[
\pi[X] = G(-\infty) \min[X] + \int_{(-\infty, 0) \cup (0, +\infty)} \log \mathbb{E}[e^{tx}] dM(t) + (1 - G(+\infty)) \max[X]
\]
\[+ \mathbb{E}[X](G(0+) - G(0-)).
\] (24)

Integration by parts of the above representation yields
\[
\pi[X] = G(-\infty) \min[X] - \int_{(-\infty, 0) \cup (0, +\infty)} \frac{\mathbb{E}[xe^{tx}]}{\mathbb{E}[e^{tx}]} M(t) dt + (1 - G(+\infty)) \max[X]
\]
\[+ \mathbb{E}[X](G(0+) - G(0-)),
\] (25)

where it is not difficult to verify that the boundary terms obtained by performing the integration by parts of the integral in (24) vanish. Then we define a function \(H(\cdot)\) as follows:
\[
dH(t) = -M(t) dt, \quad t \neq 0, \quad H(-\infty) = G(-\infty); \quad H(+\infty) = G(+\infty).
\] (26)

Notice that because \(-M(\cdot)\) is non-increasing on \((0, +\infty)\) and non-decreasing on \((-\infty, 0)\), \(H(\cdot)\) is concave on \((0, +\infty)\) and convex on \((-\infty, 0)\). Then, by substitution of (26) in (25) we obtain
\[
\pi[X] = H(-\infty) \min[X] + \int_{(-\infty, 0) \cup (0, +\infty)} \frac{\mathbb{E}[xe^{tx}]}{\mathbb{E}[e^{tx}]} dH(t) + (1 - H(+\infty)) \max[X]
\]
\[+ \mathbb{E}[X](G(0+) - G(0-)).
\]

Now it suffices to verify that \(G(0+) - G(0-)\) is equal to \(H(0+) - H(0-)\). It is not difficult to see by substitution of (23) in (26) that
\[
H(0+) = \lim_{x \downarrow 0} \left( -\int_{(x, +\infty)} \int_{(t, +\infty)} \frac{1}{s} dG(s) dt \right) + G(+\infty).
\]
Observing that the double integral is continuous in $x$ and changing the integration order yields

$$H(0+) = -\int_{(0,+\infty)} \int_{(0,s)} \frac{1}{s} dtdG(s) + G(+\infty) = G(0+).$$

Similarly one can verify that $H(0-) = G(0-)$. This proves the stated result. \hfill \Box

The mixture function $H(\cdot)$ can be regarded as a cdf, unimodal at $\theta$ and possibly defective.

**Remark 2.1** A direct proof of Corollary 2.1, without borrowing the result of Theorem 2.1, can be obtained by considering the following decomposition:

$$\varphi_X(T_0) = \int_{(0,+\infty)} \frac{(T_0 - t)_{+}}{T_0} 1_{(T_0>0)} d\psi_X(t) + \int_{(-\infty,0)} \frac{(t - T_0)_{+}}{T_0} 1_{(T_0<0)} d\psi_X(t) + \psi_X(0),$$

and hence

$$\rho_{T_0}[\varphi_X(T_0)] = \rho_{T_0} \left[ \int_{(0,+\infty)} \frac{(T_0 - t)_{+}}{T_0} 1_{(T_0>0)} d\psi_X(t) 
+ \int_{(-\infty,0)} \frac{(t - T_0)_{+}}{T_0} 1_{(T_0<0)} d\psi_X(t) 
+ \psi_X(0) \right].$$

(27)

**Proof:** We introduce a sequence of partitions $P_n$ given by

$$P_n = \{t_{-n,n}, t_{-n+1,n}, \ldots, t_{-1,n}, t_{0,n}, t_{1,n}, \ldots, t_{n-1,n}, t_{n,n} \}, \quad n = 1, 2, \ldots, \quad (28)$$

in which $t_{m,n}, m = -n, \ldots, n$ are real numbers satisfying $t_{-n,n} < t_{-n+1,n} < \ldots < t_{-1,n} < t_{0,n} = 0 < t_{1,n} < \ldots < t_{n-1,n} < t_{n,n}$, with $\lim_{n \to \infty} \max_{-n+1 \leq m \leq n} |t_{m,n} - t_{m-1,n}| = 0$ and furthermore $t_{-n,n} \to -\infty$ and $t_{n,n} \to +\infty$ if $n \to +\infty$. We let the partitions $P_n$ be increasing in the sense that $P_1 \subset P_2 \subset \ldots$. Then, (27) can be expressed as follows:

$$\rho_{T_0}[\varphi_X(T_0)] = \rho_{T_0} \left[ \lim_{n \to +\infty} \sum_{j=1}^{n} (\psi_X(t_{j,n}) - \psi_X(t_{j-1,n})) \frac{(T_0 - t_{j,n})_{+}}{T_0} 1_{(T_0>0)} 
+ \lim_{n \to +\infty} \sum_{j=-n+1}^{-1} (\psi_X(t_{j,n}) - \psi_X(t_{j-1,n})) \frac{(t_{j-1,n} - T_0)_{+}}{T_0} 1_{(T_0<0)} 
+ \psi_X(0) \right].$$

11
From this representation, it follows by application of A3", A4" and A2" respectively that

$$
\rho_{T_0} [\varphi_X(T_0)] = \int_{(0, +\infty)} \rho_{T_0} \left[ \frac{(T_0 - t)_+}{T_0} 1_{\{T_0 > 0\}} \right] d\psi_X(t)
+ \int_{(-\infty, 0)} \rho_{T_0} \left[ \frac{(t - T_0)_+}{T_0} 1_{\{T_0 < 0\}} \right] d\psi_X(t)
+ \psi_X(0).
$$

Then the mixture function $H(\cdot)$ can be expressed as follows:

$$
H(t) = \begin{cases} 
1 - \rho_{T_0} \left[ \frac{(T_0 - t)_+}{T_0} 1_{\{T_0 > 0\}} \right], & t > 0; \\
-\rho_{T_0} \left[ \frac{(t - T_0)_+}{T_0} 1_{\{T_0 < 0\}} \right], & t < 0; \\
H(0+), & t = 0.
\end{cases}
$$

By substituting (30) into (29), we obtain representation (22) after integration by parts. It is not difficult to verify from (30) that $H(\cdot)$ is non-decreasing. It remains to prove that $H(\cdot)$ is concave on $(0, +\infty)$ and convex on $(-\infty, 0)$. Let $a > 0$ and $b < 0$. Clearly it holds that

$$(T_0 + T_0 - 2t - 2a)_+ \leq (T_0 - t)_+ + (T_0 - t - 2a)_+, \quad \text{a.s.}$$

and that

$$(2t + 2b - T_0 - T_0)_+ \leq (t - T_0)_+ + (t + 2b - T_0)_+, \quad \text{a.s.}$$

and hence that for all $t > 0$

$$
\frac{2(T_0 - t) + 1_{\{T_0 > 0\}}}{T_0} \leq \frac{(T_0 - t)_+ + (T_0 - t - 2a)_+}{T_0} 1_{\{T_0 > 0\}}, \quad \text{a.s.}
$$

and that for all $t < 0$

$$
\frac{2(t + b - T_0) + 1_{\{T_0 < 0\}}}{T_0} \geq \frac{(t - T_0)_+ + (t + 2b - T_0)_+}{T_0} 1_{\{T_0 < 0\}}, \quad \text{a.s.}
$$

Then, we obtain by application of A1” that

$$
\rho_{T_0} \left[ \frac{2(T_0 - t - a)_+}{T_0} 1_{\{T_0 > 0\}} \right] \leq \rho_{T_0} \left[ \frac{(T_0 - t)_+ + (T_0 - t - 2a)_+}{T_0} 1_{\{T_0 > 0\}} \right], \quad t > 0,
$$

and that

$$
\rho_{T_0} \left[ \frac{2(t + b - T_0)_+}{T_0} 1_{\{T_0 < 0\}} \right] \geq \rho_{T_0} \left[ \frac{(t - T_0)_+ + (t + 2b - T_0)_+}{T_0} 1_{\{T_0 < 0\}} \right], \quad t < 0.
$$

Now recall (30) to verify that

$$
2H(t + a) \geq H(t) + H(t + 2a), \quad t > 0
$$

12
and that
\[ 2H(t + b) \leq H(T) + H(t + 2b), \quad t < 0, \]
which proves that \(H(\cdot)\) is concave on \((0, +\infty)\) and convex on \((-\infty, 0)\).

Although the proof along this line is perhaps less straightforward, it has the nice feature that the mixture function \(H(\cdot)\) can be expressed explicitly in terms of the risk measure \(\pi[\cdot]\) applied to a special Bernoulli r.v. To see this, we denote by \(B_{p,z}, p, z > 0\) a Bernoulli r.v. defined by
\[
B_{p,z} = \begin{cases} 
  z, & \text{with } \mathbb{P}[B_{p,z} = z] = p; \\
  0, & \text{with } \mathbb{P}[B_{p,z} = 0] = 1 - p.
\end{cases}
\]
In the following we consider the r.v. \(B_{p(t,z),z}\) for the specific choice of
\[
p(t, z) = \frac{q e^{-tz}}{1 - q + q e^{-tz}}
\]
for some \(q \in (0, 1)\) and some \(z > 0\). Since
\[
\lim_{z \to +\infty} \frac{1}{z} \varphi_{B_{p(t,z),z}}(T_0) = \begin{cases} 
  (\frac{T_0 - t}{T_0})_+ 1\{T_0 > 0\}, & \text{a.s. if } t > 0; \\
  1 + \frac{(t - T_0)_+}{T_0} 1\{T_0 < 0\}, & \text{a.s. if } t < 0.
\end{cases}
\]
the function \(H(\cdot)\) can be expressed as
\[
H(t) = \begin{cases} 
  1 - \rho_{T_0} \left[ \lim_{z \to +\infty} \frac{1}{z} \varphi_{B_{p(t,z),z}}(T_0) \right], & t \neq 0; \\
  H(0+), & t = 0.
\end{cases}
\]
Because of (12) and axiom A4 the function \(H(\cdot)\) can also be expressed as
\[
H(t) = \begin{cases} 
  1 - \lim_{z \to +\infty} \frac{1}{z} \pi \left[ B_{p(t,z),z}(T_0) \right], & t \neq 0; \\
  H(0+), & t = 0.
\end{cases}
\]
Hence, we find that the function \(H(\cdot)\) can be regarded as the risk perception with respect to a special Bernoulli r.v. \(\square\)

**Remark 2.2** Let (22) be rewritten as
\[
\pi[X] = \int_{[-\infty, +\infty]} \frac{E[X e^{tX}]}{E[e^{tX}]} dH(t).
\]
This representation allows us to express \(\pi[\cdot]\) as \(\pi[X] = E^*[X]\), where the expectation is calculated using the differential
\[
dF_X^{(H(\cdot))}(x) = \int_{t \in [-\infty, +\infty]} \frac{e^{tx} dH(t)}{E[e^{tx}]} dF_X(x).
\]
We state the following two corollaries without proof:

**Corollary 2.2** Suppose that $A1$ is strengthened to “if $X \leq_e Y$, then $\pi[X] \leq \pi[Y]$,” and $A2$, $A3$ and $A4$ remain unchanged. Then $\pi[\cdot]$ satisfies the modified set $S_1$ of axioms if and only if there exists some non-decreasing function $H : [0, +\infty] \rightarrow [0, 1]$, concave on $(0, +\infty)$ such that

$$
\pi[X] = H(0)\psi_X(0) + \int_{(0, +\infty)} \psi_X(t) dH(t) + (1 - H(+\infty)) \psi_X(+\infty)
$$

$$
= H(0)E[X] + \int_{(0, +\infty)} \frac{E[Xe^{tX}]}{E[e^{tX}]} dH(t) + (1 - H(+\infty)) \max[X]. \quad (36)
$$

**Corollary 2.3** Suppose that $A1$ is strengthened to “if $X \leq_{Lt} Y$, then $\pi[X] \leq \pi[Y]$,” and $A2$, $A3$ and $A4$ remain unchanged. Then $\pi[\cdot]$ satisfies the modified set $S_1$ of axioms if and only if there exists some non-decreasing function $H : (-\infty, 0) \rightarrow [0, 1]$, convex on $(-\infty, 0)$ such that

$$
\pi[X] = H(-\infty)\psi_X(-\infty) + \int_{(-\infty, 0)} \psi_X(t) dH(t) + (1 - H(0)) \psi_X(0)
$$

$$
= H(-\infty) \min[X] + \int_{(-\infty, 0)} \frac{E[Xe^{tX}]}{E[e^{tX}]} dH(t) + (1 - H(0)) E[X]. \quad (37)
$$

The proofs of Corollary 2.2 and Corollary 2.3 are completely similar to the proof of Remark 2.1, the difference being that $F_T(\cdot)$ is now supported on $[0, +\infty]$ and $[-\infty, 0]$ respectively, rather than on $[-\infty, +\infty]$, in addition to being defective, continuous and strictly increasing.

The condition that $X \leq_e Y$ implies $\pi[X] \leq \pi[Y]$, as imposed in Corollary 2.2, has a natural interpretation in the classical ruin model. It is easy to prove that if $X \leq_e Y$, where $X$ and $Y$ represent the i.i.d. claim amounts of two homogeneous Poisson processes with equal Poisson parameter, then the upper bound for the probability of ruin is smaller in case of individual claims $X$ than in case of individual claims $Y$, regardless of the initial capital.

For the particular case in which $H(\cdot)$ is non-decreasing, concave on $(0, +\infty)$ and $H(t) = 0$ for $t < 0$, i.e. the case of Corollary 2.2, the obtained risk measure is a mixture of premiums with a non-negative safety loading; see in this context Goovaerts et al. (2003). In the remainder of this paper, we consider some properties of the risk measure characterized in Corollary 2.2, thus restricting to the case in which $H(t) = 0$ for $t < 0$, which is reasonable from the viewpoint of premium calculation.
We introduce the notion of *stop-loss* order. We say that a r.v. $X$ is smaller than a r.v. $Y$ in *stop-loss* order if $X$ has smaller stop-loss premiums than $Y$, or equivalently, if for any non-decreasing and convex function $f(\cdot)$ it holds that

$$
\mathbb{E}[f(X)] \leq \mathbb{E}[f(Y)].
$$

(38)

We write $X \leq_{sl} Y$. It is a well-known result (see e.g. Kaas et al. (2001), section 10.6) that for any given random vector $(X_1, \ldots, X_n)$ and an independent r.v. $U$ uniformly distributed on $(0, 1)$ it holds that

$$
X_1 + \ldots + X_n \leq_{sl} F_{X_1}^{-1}(U) + \ldots + F_{X_n}^{-1}(U).
$$

(39)

Then we state the following two corollaries:

**Corollary 2.4** If $X \leq_{sl} Y$, then the risk measure characterized in Corollary 2.2, satisfies $\pi[X] \leq \pi[Y]$.

**Proof:** Because $e^{tx}$ is non-decreasing and convex for all $t \geq 0$, we have by the definition of stop-loss order that $X \leq_{sl} Y$ implies $X \leq_{e} Y$ and therefore $\pi[X] \leq \pi[Y]$. □

**Corollary 2.5** The risk measure characterized in Corollary 2.2 is superadditive for sums of comonotonic r.v.‘s, i.e. it holds that

$$
\pi[X_1] + \ldots + \pi[X_n] \leq \pi[F_{X_1}^{-1}(U) + \ldots + F_{X_n}^{-1}(U)].
$$

(40)

**Proof:** Recall (39) and notice that because of the arbitrariness of the random vector $(X_1, \ldots, X_n)$, this inequality also applies to the case in which $X_1, \ldots, X_n$ are independent. Then the proof of the corollary follows by application of Corollary 2.4 and the additivity property of $\pi[\cdot]$. □

## 3 Conclusion

This paper gives an axiomatic characterization of the mixed exponential principle. This premium principle is additive for independent random variables. In contrast to the well-known mixed Esscher principle, this principle is monotonic in the sense that it preserves
stochastic dominance. In order to prove the representation theorem, we provide a *comonotonic image* of the axiom of additivity for independent random variables.

Note that if the risk measure (18), which is the weighted average of premiums quoted by exponential decision makers, is to be used as an insurance premium, including in it the premiums asked by risk-lovers is to be regarded as unsound business practice. For this case, (36) is better suited, but it is quite conceivable that economic scenarios can be found where use of (18) is appropriate.
References


