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A Residual-Based LM Test for Fractional Cointegration

Uwe Hassler und Jörg Breitung

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A Residual-Based LM Test
for Fractional Cointegration

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Abstract
Nonstationary fractionally integrated time series may possibly be fractionally cointegrated. In this paper we propose a test for the null hypothesis of no cointegration. It builds on a static cointegration regression of the levels of the variables as a first step. In a second step, a univariate LM test is applied to the single equation regression residuals. However, it turns out that the application of the LM test to residuals without further modifications does not result in a limiting standard normal distribution, which contrasts with the situation when the LM test is applied to observed series. Therefore, we suggest a simple modification of the LM test that accounts for the residual effect. At the same time it corrects for eventual endogeneity of the cointegration regression. The proposed modification guarantees a limiting standard normal distribution of the test statistic. Our procedure is completely regression based and hence easy to perform. Monte Carlo experiments establish its validity for finite samples.

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1 Introduction

Engle and Granger (1987) proposed in their pathbreaking paper to apply the Dickey-Fuller (DF) test to regression residuals in order to test the null hypothesis of no cointegration. A thorough asymptotic treatment was provided by Phillips and Ouliaris (1990). Both papers assume observed time series that are integrated of order one, I(1), and residuals that are I(1) under the null hypothesis. This test is designed against the alternative of integer integration, i.e. that the regression errors are I(0). Similarly, we assume time series that are all integrated of the same order $d$ and suggest a residual-based test for the null hypothesis of no cointegration that the residuals are I($d$) as well. The order of integration $d$ is allowed to be noninteger. The residual-based LM test introduced here is constructed against the alternative of fractional cointegration, i.e. under $H_1$ the residuals are I($d - b$), $b > 0$.

In most economic applications it is assumed that $d = 1$. Still, under cointegration the deviations must not necessarily be I(0) but may rather be fractionally integrated of order $d - b \neq 0$. Applied studies based on a fractional cointegration framework include Cheung and Lai (1993), Booth and Tse (1995) and Masih and Masih (1995, 1998), Baillie and Bollerslev (1994) and Dueker and Startz (1998). Typically, these papers treat small systems of only two variables where a residual-based single equation approach seems appropriate. The residual-based test considered here does not rely on the DF statistic because it is well documented that the DF test has little power against fractional alternatives, see Sowell (1990), Diebold and Rudebusch (1991), Hassler and Wolters (1994) and Krämer (1998). We rather adopt the LM test pioneered by Robinson (1991) and further studied and extended by Robinson (1994), Agiakloglou and Newbold (1994), Tanaka (1999) and Breitung and Hassler (2002). Similarly as the DF test the latter variant is based on regressions and therefore particularly simple to compute. In case of observed time series all those variants follow under the null hypothesis a limiting normal distribution and can be performed as one-sided or two-sided tests.
It should be noted that some recent theoretical papers discussed fractional cointegration testing, too. Hassler, Marmol and Velasco (2002) consider a residual-based log-periodogram regression relying on residuals from single equation regressions. Unfortunately, this semiparametric procedure is not very powerful. Moreover, there have been proposed two system analyses to determine the cointegration rank of a vector of fractionally time series. Robinson and Yajima (2002) suggest a frequency domain approach valid with stationary processes, while Breitung and Hassler (2002) consider a time domain approach designed for the nonstationary case.

The main contributions of this work are the following. First, we show that the LM test applied naively, i.e. without modifications, to regression residuals does not have a Gaussian limiting distribution. Second, we suggest a modification of the one-sided test by Breitung and Hassler (2002), which is in the spirit of Saikkonen (1991). It corrects for the residual effect as well as for the effect of eventual endogeneity of the regressors. It is shown that this modified residual-based LM test has a standard normal asymptotic distribution under the null hypothesis of no cointegration.

The rest of the paper is organized as follows. After the introduction our assumptions are presented and the LM test is introduced. In Section 3, it is shown that the LM test applied to regression residuals without modification results in a nonnormal limiting distribution depending on $d$. The fourth section deals with a simple regression based modification of the LM test applied to regression residuals that results in an asymptotic standard normal distribution. Finite sample properties of this fractional cointegration test are investigated by means of Monte Carlo experiments in Section 5. The final section concludes.

2 Preliminaries

Let the scalar $y_{1,t}$ and the $m$-dimensional vector $y_{2,t}$ be $I(d)$ processes, where $d > 0.5$ is known. More precisely, we assume the regression model

$$y_{1,t} = y_{2,t}' \beta + z_t, \quad t = 1, 2, \ldots, T, \tag{1}$$
\[ z_t \sim I(d - b), \quad b \geq 0. \] (2)

If \( b > 0 \) and \( \beta \neq 0 \), then \( y_{1,t} \) and \( y_{2,t} \) are called fractionally cointegrated. Notice that the observed series as well as the errors may be fractionally integrated, although in many economic applications \( d = 1 \) may hold. The null hypothesis to be tested is absence of cointegration,

\[ H_0 : b = 0 \text{ vs. } H_1 : b > 0. \]

The error term \( z_t \) may correlate with (lags and leads of) the regressors. The assumptions on the stochastic processes are the following, where \( L \) denotes the usual lag operator.

**Assumption 1:** Let \( y_{2,t} \) and \( z_t \) from (1) be fractionally integrated processes,

\[ (1 - L)^d y_{2,t} = v_{2,t}, \quad (1 - L)^{d-b} z_t = v_{1,t}, \quad b \geq 0, \]

with starting values \( y_{2,t} = 0 \) and \( z_t = 0 \) for \( t \leq 0 \), where \( w_t' = (v_{1,t}, v_{2,t}') \) is generated by a stationary and invertible process with zero mean, finite fourth moments and absolutely summable covariance function,

\[ \sum_{j=0}^{\infty} \|E(w_t w_{t-j}')\| < \infty. \]

Here, \( \| \cdot \| \) signifies the standard Euclidean norm. From this assumption it follows, see e.g. Saikkonen (1991), that there exists a stationary process \( x_t \) such that

\[ v_{1,t} = \sum_{k=-\infty}^{\infty} v_{2,t-k} \pi_k + x_t, \] (3)

where

\[ E(x_t v_{2,t-k}) = 0, \quad k = 0, \pm 1, \pm 2, \ldots, \]

\[ \sum_{j=0}^{\infty} |E(x_t x_{t-j})| < \infty, \quad \sum_{k=-\infty}^{\infty} \|\pi_k\| < \infty. \]
If \( z_t \) was observable, an LM test against the alternative of fractional cointegration would build on the differences under \( H_0 \),

\[
\zeta_t := (1 - L)^d z_t.
\]

Under the alternative \( H_1 \), \( \zeta_t \) is \( I(-b) \), \( (1 - L)^{-b} \zeta_t = v_{1,t} \). The LM variant proposed by Breitung and Hassler (2002) further requires the weighted sum of past values,

\[
\zeta_{t-1}^* := - \frac{\partial \zeta_t}{\partial b} \bigg|_{b=0} = \sum_{j=1}^{t-1} \frac{\zeta_{t-j}}{j}, \quad t = 2, 3, \ldots, T. \tag{4}
\]

Under the null, \( \zeta_t = v_{1,t} \) is \( I(0) \), and due to the choice of the weights \( 1/j \), \( \zeta_{t-1}^* \) is asymptotically stationary.

Let us assume for the moment that \( v_{1,t} \) is white noise. Then \( \zeta_t \) and \( \zeta_{t-1}^* \) are uncorrelated under \( H_0 \). Therefore, the ordinary least squares (OLS) regression,

\[
\zeta_t = \hat{\phi} \zeta_{t-1}^* + \hat{e}_t \tag{5}
\]

results in a limiting normal distribution when testing for \( \phi = 0 \),

\[
t_{\phi} = \frac{\hat{\phi}}{\sqrt{\frac{1}{T-1} \sum \zeta_t^2}} \frac{\sqrt{\sum (\zeta_{t-1}^*)^2}}{\sqrt{T-1}} \overset{d}{\rightarrow} \mathcal{N}(0, 1), \tag{6}
\]

where \( \text{Var}(\zeta_t) \) is estimated under the null hypothesis\(^1 \) (\( \phi = 0 \)). The cointegration test against \( b > 0 \) should be performed as a one-sided test rejecting \( H_0 \) for too small values of \( t_{\phi} \), see Tanaka (1999, Theorem 1).

If \( \zeta_t = v_{1,t} \) is a stable AR\((p)\) process under \( H_0 \), then following Agiakloglou and Newbold (1994), an appropriately augmented version of (5) might be used, see Breitung and Hassler (2002).

\(^1\)Breitung and Hassler (2002) consider the usual \( t \) statistic with \( \frac{1}{T-2} \sum \hat{e}_t^2 \) instead of \( \frac{1}{T-1} \sum \zeta_t^2 \). In large samples the difference is negligible, in small samples we collected experimental evidence that the present version of the test statistic is superior in terms of size.
In practice, the coefficient vector \( \beta \) is usually unknown and, therefore, the error \( z_t \) is not observable. The traditional residual-based cointegration test suggested by Engle and Granger (1987) uses the residuals of the cointegration regression instead of the unobservable errors. In the following section we investigate the asymptotic properties of a test based on the OLS residuals

\[
\hat{z}_t = y_{1,t} - \hat{\beta}' y_{2,t} = z_t - (\hat{\beta} - \beta)' y_{2,t}
\]

instead of the unobservable errors \( z_t \).

3 Estimated Parameters

Even under very restrictive assumptions the effect of using residuals \( \hat{z}_t \) instead of true errors \( z_t \) is not negligible. The test statistic \( t_\phi \) from (6) with \( \zeta_t \) and \( \zeta_t^* - 1 \) replaced by

\[
\hat{\zeta}_t := (1 - L)^d y_{1,t}, \quad \hat{\zeta}_t^* := \sum_{j=1}^{t-1} \frac{\hat{\zeta}_{t-j}}{j}
\]

does not result in a limiting normal distribution. In fact, the asymptotic distribution depends on \( d \), and hence percentiles are difficult to tabulate. These statements will be made more precise now.

For the sake of simplicity the analysis in this section is restricted to simple regressions (\( m = 1 \)). This special case suffices to make our point clear, and it allows to shorten the derivation by relying on a corresponding result by Cappuccio and Lubian (1997).

**Assumption 2:** Let \( y_{2,t} \) and \( z_t \) from (1) with \( m = 1 \), \( \beta = 0 \) and \( 0.5 < d < 1.5 \) be fractionally integrated noise processes,

\[
(1 - L)^d y_{1,t} = (1 - L)^d z_t = v_{1,t} \sim iid(0, \sigma_1^2)
\]

\[
(1 - L)^d y_{2,t} = v_{2,t} \sim iid(0, \sigma_2^2),
\]

where \( v_{1,t} \) and \( v_{2,s} \) are independent of each other for all \( t \) and \( s \).
Assumption 2 corresponds to the spurious regression setup of Cappuccio and Lubian (1997). They prove that the OLS regression of (1) results in

$$\hat{\beta} \overset{d}{\to} \frac{\sigma_1}{\sigma_2} \beta_d,$$

(8)

where $\beta_d = (\int_0^1 W_{2,d}(a)da)^{-1} \int_0^1 W_{1,d}(a)W_{2,d}(a)da$, $W_{1,d}(a)$ and $W_{2,d}(a)$ are independent fractional Brownian motions.

In the Appendix we prove the following theorem.

**Theorem 1:** Let the null hypothesis of no cointegration and Assumption 2 hold true. Replacing $\zeta_t$ and $\zeta_{t-1}$ in (6) by the residual-based analogs in (7), the limiting distribution of the test statistic $t_\phi$ as $T \to \infty$ is given by

$$\frac{\mathcal{Z}_1 + \beta_d^2 \mathcal{Z}_2 - \sqrt{2} \beta_d \mathcal{Z}_3}{1 + \beta_d^2},$$

where $\mathcal{Z}_i$, $i = 1, 2, 3$ are independent standard normally distributed random variables.

Even under the highly restrictive assumption that errors and regressor are stochastically independent the asymptotic normality does not carry over to the case that $t_\phi$ is simply computed from residuals of a cointegrating regression. This is due to the fact that $\hat{\beta}$ does not converge to zero in case of spurious regressions. If the limit $\beta_d$ from (8) was zero, then a limiting $\mathcal{N}(0,1)$ distribution would arise, as we can see from Theorem 1. If we allow for general $m \geq 1$ in Assumption 2, then it can be shown by generalizing the result in (8) to multiple regressions that the limit of $t_\phi$ depends not only on $d$ but also on the number of regressors, $m$.

For practical purposes the theorem implies that standard normal inference is not a valid guideline when the LM test is applied without further modifications to OLS residuals in order to test for the null of no cointegration. According to the Monte Carlo evidence in Section 5, size distortions indicating cointegration too often will result if the LM test is applied naively to regression residuals.
The nonnormality of the LM test applied to residuals without correction is not restricted to the time domain variant discussed in Breitung and Hassler (2002). It can be shown that the frequency domain variant by Robinson (1994) suffers from the same shortcoming when applied to regression residuals. In order to save space we avoid the notation required for the frequency domain test here, and consider instead the equivalent time domain approximation, see Robinson (1994, p.1422). Robinson’s (1994) LM test builds on the statistic

\[ R = \frac{\sqrt{6T}}{\pi \hat{\sigma}^2} a, \quad \hat{\sigma}^2 = \frac{1}{T} \sum_{t=1}^{T} \zeta^2_t, \quad (9) \]

\[ a = \sum_{j=1}^{T-1} \frac{1}{j} \left( \frac{1}{T-j} \sum_{t=1}^{T-j} \zeta_t \zeta_{t+j} \right). \]

If \( R \) was computed from the unobserved \( \zeta_t = (1 - L)^d z_t \), then under \( H_0 \): \( R \overset{d}{\to} N(0, 1) \). Replacing \( \zeta_t \) by \( \hat{\zeta}_t \), however, changes the limiting distribution according to Theorem 1. The following corollary is proven in the appendix.

**Corollary:** Replacing \( \zeta_t \) in (9) by the residual-based analogs in (7) under the assumptions of Theorem 1, the limiting distribution of the test statistic \( R \) as \( T \to \infty \) is given in Theorem 1.

### 4 Correcting for residual effect and endogeneity

Under \( H_0 \) the variables from (7) are

\[ \hat{\zeta}_t = (1 - L)^d \left( z_t - y_{2,t} (\hat{\beta} - \beta) \right) = v_{1,t} - v_{2,t} (\hat{\beta} - \beta), \]

\[ \hat{\zeta}^*_t = \sum_{j=1}^{T-1} \frac{v_{1,t-j} - v_{2,t-j} (\hat{\beta} - \beta)}{j} = v_{1,t-1}^* - v_{2,t-1}^* (\hat{\beta} - \beta), \]

where \( v_{1,t-1}^* \) and \( v_{2,t-1}^* \) are defined analogously to (4). The residual-based LM test without further modifications does not result in limiting normality because \( \hat{\zeta}_t \) and \( \hat{\zeta}^*_t \) are correlated. First, if \( v_{1,t} \) and \( v_{2,s} \) are iid and independent of each other for all \( t \) and \( s \), then \( v_{1,t} \) and \( v_{2,t} \) are independent of \( v_{1,t-1}^* \) and \( v_{2,t-1}^* \).
and $v_{2,t-1}^*$. Nevertheless, $\hat{\zeta}_t$ and $\hat{\zeta}_{t-1}^*$ are correlated via $\hat{\beta}$, and this is the effect studied in Section 3. Second, if $v_{1,t}$ and $v_{2,s}$ are iid and independent of each other for all $t \neq s$ but $E(v_{1,t}v_{2,t}) \neq 0$, then $v_{1,t}$ and $v_{2,t}$ are still independent of $v_{1,t-1}^*$ and $v_{2,t-1}^*$. This means that contemporaneous correlation of $v_{1,t}$ and $v_{2,t}$ does not imply additional correlation between $\hat{\zeta}_t$ and $\hat{\zeta}_{t-1}^*$. But it is reasonable to assume with economic applications that endogeneity introduces correlation of $v_{1,t}$ and $v_{2,s}$ even for $t \neq s$. Therefore, we consider, third, that $v_{1,t}$ and $v_{2,s}$ are iid but $E(v_{1,t}v_{2,t-j}) \neq 0$ and $E(v_{1,t}v_{2,t+j}) \neq 0$. If $j > 0$, this implies that $v_{1,t}$ and $v_{2,t-1}^*$ as well as $v_{2,t}$ and $v_{1,t-1}^*$ correlate, which causes, in addition to the residual effect, correlation between $\hat{\zeta}_t$ and $\hat{\zeta}_{t-1}^*$ due to endogeneity. Therefore, we now propose to correct for the residual effect as well as for endogeneity in order to obtain a simple modification of the residual-based LM test that has an asymptotic Gaussian distribution.

With (3) one may approximate for large $K$

\[
\hat{\zeta}_t = x_t + \sum_{k=-\infty}^{\infty} v_{2,t-k}^* \pi_k - v_{2,t}^*(\hat{\beta} - \beta) \\
\approx x_t + \sum_{k=-K}^{K} v_{2,t-k}^* \pi_k - v_{2,t}^*(\hat{\beta} - \beta),
\]

because $\|\pi_k\| \to 0$ for $|k| \to \infty$. Motivated by the work of Saikkonen (1991), this suggests to project $\hat{\zeta}_t$ on $K$ leads and lags of $v_{2,t} = (1 - L)^d y_{2,t}$ in order to obtain scalar residuals $\tilde{x}_t$ that are approximately iid. To this end define the $(2K + 1)m$ vector $W_t$,

\[
W_t' = (v_{2,t-K}', \ldots, v_{2,t}', \ldots, v_{2,t+K}').
\]

After computing in a first step cointegration regression residuals $\hat{\zeta}_t$, consider as a second step the regression of $\hat{\zeta}_t$ on $W_t$:

\[
\hat{\zeta}_t = W_t' \tilde{\theta} + \tilde{x}_t, \ t = K + 1, \ldots, T - K, \tag{10}
\]

with residuals $\tilde{x}_t \approx x_t$ that are used to compute analogously to (4)

\[
\tilde{x}_{t-1}^* := \sum_{j=1}^{t-1} \tilde{x}_{t-j}/j.
\]
In a third step we perform the LM regression of $\tilde{x}_t$ on $\tilde{x}_{t-1}^*$ analogously to (5) in order to compute the test statistic

$$\tilde{t}_\phi = \frac{\sum \tilde{x}_t \tilde{x}_{t-1}^*}{\sqrt{\sum (\tilde{x}_{t-1}^*)^2} \sqrt{\frac{1}{T-2K} \sum \tilde{x}_t^2}}.$$  

(11)

If $K$ in (10) grows with an appropriate rate to infinity, then the residual and endogeneity effects will be negligible. We adopt from Saikkonen (1991), Said and Dickey (1984) and Berk (1974) the assumption

$$K \to \infty, \quad K^3/T \to 0.$$  

(12)

Further, the truncation of the infinite sum from (3) in the regression (10) requires that $\pi_k$ dies out sufficiently fast. More precisely, we maintain the following assumption also employed in Saikkonen (1991):

$$\sqrt{T} \sum_{|k|>K} \|\pi_k\| \to 0.$$  

(13)

The appendix contains the proof of the following result.

**Theorem 2:** Let model (1), the null hypothesis of no cointegration, Assumption 1, (12), and (13) hold true. If furthermore $x_t$ from (3) is iid, then for $\tilde{t}_\phi$ from (11) we have $\tilde{t}_\phi \overset{d}{\to} \mathcal{N}(0,1)$, as $T \to \infty$.

**Remark A:** We suggest to compute $\tilde{t}_\phi$ in three steps: Run regression (1), correct for residual effect and endogeneity by means of regression (10), and compute the test statistic $\tilde{t}_\phi$ from the LM regression analogous to (5). Alternatively, one may consider a two step procedure where the correction for residual and endogeneity effects is performed in the LM regression. Hence, the second and last step could be

$$\tilde{\zeta}_t = \tilde{\phi} \tilde{\zeta}_{t-1}^* + W_t \tilde{\theta} + \tilde{e}_t,$$

from that the $t$ statistic for $\phi = 0$ could be used to test for no cointegration. Experimentally, however, we found the performance of the proposed three step procedure superior in finite samples.
Remark B: The assumption in Theorem 2 that $x_t$ is iid was made to facilitate the proof. If $x_t$ follows a stable AR($p$) process one may correct for the serial correlation as proposed in Agiakloglou and Newbold (1994), which requires a simple fourth step. We take the residuals from the second step (10) and perform, thirdly, an autoregression,

$$\tilde{x}_t = \hat{\rho}_1 \tilde{x}_{t-1} + \cdots + \hat{\rho}_p \tilde{x}_{t-p} + \tilde{\varepsilon}_t,$$

and compute

$$\tilde{\varepsilon}_{t-1}^* = \sum_{j=1}^{t-p-1} \frac{\tilde{\varepsilon}_{t-j}}{j}.$$ 

The last step consists of an augmented LM regression of $\tilde{\varepsilon}_t$ on $\tilde{\varepsilon}_{t-1}^*$ and $\tilde{x}_{t-i}$:

$$\tilde{\varepsilon}_t = \phi \tilde{\varepsilon}_{t-1}^* + \sum_{i=1}^{p} \psi_i \tilde{x}_{t-i} + e_t.$$ 

The $t$ statistic for $\phi = 0$ from this fourth step may again be used to test for no cointegration with percentiles from the standard normal distribution.

5 Monte Carlo evidence

To begin with we consider the case of exogenous regressors and investigate the residual-based LM test, first without correction, and second with correction for the residual effect only ($K = 0$). The Monte Carlo study is based on a bivariate OLS regression of $I(1)$ variables, i.e. $m = 1$, and $d = 1$. More precisely, the model is given by

$$y_{1,t} = y_{2,t} + z_t, \quad t = 1, 2, \ldots, T, \quad (14)$$

$$(1 - L) y_{2,t} = v_{2,t}, \quad v_{2,t} \sim iidN(0, 1), \quad (15)$$

$$(1 - L)^{d-b} z_t = v_{1,t}, \quad v_{1,t} \sim iidN(0, 1), \quad (16)$$
Table 1: 5% size and power under exogeneity ($K = 0$)

<table>
<thead>
<tr>
<th></th>
<th>$b = 0$</th>
<th>$b = 0.1$</th>
<th>$b = 0.2$</th>
<th>$b = 0.3$</th>
<th>$b = 0.4$</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>$T=100$</td>
<td>$(0.111)$</td>
<td>$0.335$</td>
<td>$0.716$</td>
<td>$0.932$</td>
</tr>
<tr>
<td></td>
<td>$T=250$</td>
<td>$0.53$</td>
<td>$(0.096)$</td>
<td>$0.601$</td>
<td>$0.983$</td>
</tr>
</tbody>
</table>

Note: Given are the percentages of rejection at the nominal 5% level. The simulated model is (14) - (16). Under $H_0$ we include in brackets rejection frequencies of the LM test applied to residuals without correction. Further information is given in the text.

where $v_{1,t}$ is independent of $v_{2,s}$. First, we compute OLS residuals,

$$\hat{z}_t = y_{1,t} - \hat{\alpha} - \hat{\beta} y_{2,t}$$

and run the LM regression corresponding to (5) with and without correcting for the residual effect. Finally, $t$ statistics are computed as in (6) or (11). Table 1 reports the number of rejections at the 5% level based on 5000 trials. The column for $b = 0$ (size) includes in brackets the rejection frequencies of the LM test applied naively to regression residuals without correction, where the second step of the projection on $\Delta y_{2,t}$ is omitted.

Table 1 supports that the correction introduced in the previous section is essential even with exogenous regressors. Without this correction moderate size distortions are observed. However, if the LM test is applied to the residuals after projecting on $\Delta y_{2,t}$, the size distortions are marginal. Moreover, the experimental evidence reveals that the correct LM test is very powerful even for alternatives close to the null hypothesis.

Next, we study two extensions. First, the error $z_t$ is correlated with the regressor (endogeneity), and second, the error term as well as the regressor may have a short memory autoregressive structure in addition to be integrated. Specifically, we let

$$v_{1,t} = c v_{2,t} + \sqrt{1-c^2} u_t, \text{ with } u_t = a_1 u_{t-1} + \varepsilon_{1,t}, \varepsilon_{1,t} \sim iid \mathcal{N}(0,1), \quad (17)$$

and

$$v_{2,t} = a_2 v_{2,t-1} + \varepsilon_{2,t} \text{ with } \varepsilon_{2,t} \sim iid \mathcal{N}(0,1), \quad (18)$$

12
where $\varepsilon_{1,t}$ and $\varepsilon_{2,t}$ are independent white noise. Note that for $c \neq 0$ and $a_2 \neq 0$, the innovations $v_{1,t}$ are correlated with all regressor innovations $v_{2,t-k}$, $k \geq 0$. In practice, the choice of $K$ is not at all obvious and might require some experimentation. Large values of $K$ will reduce the power of the test. To study the size properties for a parsimonious choice of $K$, we fix $K = 1$ in what follows. Due to the autoregressive serial correlation of $v_{1,t}$ and $v_{2,t}$, the LM test requires one further step to correct for autocorrelation (see Remark B of Theorem 2).

Table 2 reports the number of rejections at the 5% level based on 5000 replications for $c = 0.5$. Almost identical findings are observed (but not reported) for $c = -0.5$, while the case of exogeneity ($c = 0$) results in slightly better size and power properties. The autoregressive parameters $a_1$ and $a_2$ are taken from $\{0.5, 0, -0.5\}$; a closer correspondence of the nominal size with the experimental one was observed for the set $\{0.7, 0, -0.7\}$.

From Table 2 several conclusions can be drawn. First, the test is slightly oversized. Second, for the case $a_2 = 0$, where the regression error $z_t$ is not correlated with past values of the regressor, the test is more powerful than for the case $a_2 \neq 0$. Third, if the autocorrelation of the innovations is of opposite sign, $a_2 = -a_1$, then the power is poor for $b$ close to zero, while for $b = 0.4$ highest rates of rejection are observed. In general, there is less power than reported in Table 1 for $K = 0$.

Finally, it is of interest to compare the finite sample performance of the residual-based LM test with its competitors. Breitung and Hassler (2002) presented experimental evidence for a system approach in the time domain to fractional cointegration testing. It should be noted that system test is two-sided by construction, whereas the residual approach allows for testing one-sided alternatives. The results of the upper panel in Table 2 from Breitung and Hassler (2002) correspond in the present notation to the case $c = 0$, $a_1 = 0$, $T = 100$ and $|a_2| = 0, 0.5$. We observe that in our bivariate setup the residual-based LM test is more powerful than their system approach, which in turn is more powerful than the semiparametric residual-based procedure proposed by Hassler, Marmol and Velasco (2002).
Table 2: 5% size and power under endogeneity, $K = 1$

<table>
<thead>
<tr>
<th></th>
<th>$T = 100$</th>
<th>$T = 250$</th>
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<tr>
<td></td>
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<td>$a_1 = 0.5$ $a_1 = 0$ $a_1 = -0.5$</td>
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<tr>
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<td>$a_2 = 0.5$</td>
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<tr>
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<td>0.063 0.064 0.061</td>
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<td>0.4</td>
<td>0.324 0.807 0.938</td>
<td>0.760 0.997 1.000</td>
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Note: Given are the percentages of rejection at the nominal 5% level. The simulated model is (14), (15), (16), (17) and (18) with $c = 0.5$. Further information is given in the text.

6 Summary

We propose a test against the alternative that nonstationary time series integrated of order $d$ are fractionally cointegrated, i.e. a linear combination is integrated of order $d - b$ with $b > 0$. Neither $d$ nor $d - b$ have to be integer. Under the null hypothesis of no cointegration $b = 0$.

In a first step, residuals from a static cointegration regression of the levels are computed. Second, the LM test in the tradition of of Robinson (1991, 1994), Agiagloklo and Newbold (1994), Tanaka (1999) and Breitung and
Hassler (2002) is applied to regression residuals. However, while the limiting distribution of the LM test applied to observed series is standard normal, this is no longer true when it is applied to regression residuals without further modifications. Moreover, the distribution arising from regression residuals is shown to depend on $d$, and hence it is cumbersome to tabulate. Therefore, we propose a simple modification of the LM test applied to residuals. It accounts for the residual effect and corrects for eventual endogeneity of the cointegration regression at the same time. This modified residual-based LM test follows again an asymptotic standard normal distribution. Our procedure relies solely on regression techniques and is hence easy to use. Its validity in finite samples is established through Monte Carlo experiments.

Appendix

Proof of Theorem 1:

Using
\[
\hat{\xi}_t = v_{1,t} - v_{2,t} \hat{\beta} \\
\hat{\xi}_{t-1} = \sum_{j=1}^{t-1} \frac{v_{1,t-j} - v_{2,t-j} \hat{\beta}}{j} = v_{1,t-1}^* - v_{2,t-1}^* \hat{\beta},
\]
we obtain
\[
T^{-1} \sum (\hat{\xi}_{t-1}^*)^2 = T^{-1} \sum \left( (v_{1,t-1}^*)^2 + (v_{2,t-1}^* \hat{\beta})^2 - 2 v_{1,t-1}^* v_{2,t-1}^* \hat{\beta} \right),
\]
\[
T^{-0.5} \sum \hat{\xi}_t \hat{\xi}_{t-1}^* = T^{-0.5} \sum \left( v_{1,t} v_{1,t-1}^* - v_{1,t} v_{2,t-1}^* \hat{\beta} - v_{2,t} v_{1,t-1}^* \hat{\beta} + v_{2,t} v_{2,t-1}^* \hat{\beta} \right).
\]
As shown in Breitung and Hassler (2002, Theorem 1) we have
\[
T^{-1} \sum (v_{1,t-1}^*)^2 \xrightarrow{p} \sigma_1^2 \pi^2 / 6 = \lim_{T \to \infty} E(v_{1,T}^*)^2,
\]
\[
T^{-1} \sum (v_{2,t-1}^*)^2 \xrightarrow{p} \sigma_2^2 \pi^2 / 6 = \lim_{T \to \infty} E(v_{2,T}^*)^2,
\]
\[ T^{-0.5} \sum_{t} v_{1,t} v_{1,t-1}^* \xrightarrow{d} \frac{\sigma_1^2 \pi}{\sqrt{6}} Z_1, \]

\[ T^{-0.5} \sum_{t} v_{2,t} v_{2,t-1}^* \xrightarrow{d} \frac{\sigma_2^2 \pi}{\sqrt{6}} Z_2, \]

where \( Z_1 \) and \( Z_2 \) are standard normally distributed random variables. Furthermore, since \( v_{1,t} \) and \( v_{2,t} \) are independent sequences, it follows with \( Z_3^* \) and \( Z_4^* \) being standard normal:

\[ T^{-0.5} \sum_{t} v_{1,t} v_{2,t}^* \xrightarrow{d} \frac{\sigma_1 \sigma_2 \pi}{\sqrt{6}} Z_3^* \]

\[ T^{-0.5} \sum_{t} v_{2,t} v_{1,t}^* \xrightarrow{d} \frac{\sigma_1 \sigma_2 \pi}{\sqrt{6}} Z_4^*. \]

Those four standard normal random variables are independent of each other. This can be shown from the assumption that \( v_{1,t} \) and \( v_{2,t} \) are independent white noise sequences:

\[
E\left( v_{1,t} v_{1,t-1}^* v_{j,s} v_{i,s-1}^* \right) = 0, \quad (j, i) \in \{(2, 2), (1, 2), (2, 1)\},
\]

\[
E\left( v_{2,t} v_{2,t-1}^* v_{j,s} v_{i,s-1}^* \right) = 0, \quad j \neq i,
\]

\[
E\left( v_{1,t} v_{2,t}^* v_{j,s} v_{1,s-1}^* \right) = 0,
\]

for all \( t \) and \( s \).

Collecting these results we obtain with (8)

\[ T^{-1} \sum (\tilde{\zeta}_{t-1})^2 \xrightarrow{d} \frac{\sigma_1^2 \pi^2}{6} (1 + \beta_d^2) \]

\[ T^{-0.5} \sum \tilde{\zeta}_t \tilde{\zeta}_{t-1}^* \xrightarrow{d} \frac{\sigma_1^2 \pi}{\sqrt{6}} Z_1 + \frac{\sigma_2^2 \pi \beta_d^2}{\sqrt{6}} Z_2 - \frac{\sigma_1^2 \pi \beta_d}{\sqrt{6}} (Z_3^* + Z_4^*), \]

and thus with \( Z_3^* + Z_4^* = \sqrt{2} Z_3 \),

\[ \frac{\sum \tilde{\zeta}_t \tilde{\zeta}_{t-1}^*}{\sqrt{\sum (\tilde{\zeta}_{t-1})^2}} \xrightarrow{d} \frac{\sigma_1}{\sqrt{1 + \beta_d^2}} \left( Z_1 + \beta_d Z_2 - \sqrt{2} \beta_d Z_3 \right). \]

Finally, it is straightforward to show that

\[ T^{-1} \sum \tilde{\zeta}_t^2 \xrightarrow{d} \sigma_1^2 (1 + \beta_d^2), \]

which completes the proof.
Proof of Corollary:

Replacing $\zeta_t$ in $a$ from (9) by $\hat{\zeta}_t$ we define

$$a^* = \sum_{j=1}^{T-1} \frac{1}{j} \left( \frac{1}{T-j} \sum_{t=1}^{T-j} \hat{\zeta}_t \hat{\zeta}_{t+j} \right).$$

Note from Brockwell and Davis (1987, Theo. 11.2.2) that

$$\sqrt{T} \left( \frac{1}{T-j} \sum_{t=1}^{T-j} v_{1,t} v_{2,t+j} \right) \overset{d}{\rightarrow} N(0, \sigma_1^2 \sigma_2^2),$$

$$\text{Cov} \left( \sqrt{T} \frac{1}{T-j} \sum_{t=1}^{T-j} v_{1,t} v_{2,t+j}, \sqrt{T} \frac{1}{T-k} \sum_{t=1}^{T-j} v_{1,t} v_{2,t+k} \right) \rightarrow 0, \ j \neq k.$$

Hence, for any finite $m$,

$$\sqrt{T} \sum_{j=1}^{m} \frac{1}{j} \left( \frac{1}{T-j} \sum_{t=1}^{T-j} v_{1,t} v_{2,t+j} \right) \overset{d}{\rightarrow} N \left( 0, \sum_{j=1}^{m} \frac{1}{j^2} \sigma_1^2 \sigma_2^2 \right),$$

and, therefore, by Bernstein’s lemma (cf. Robinson, 1994, p.1434)

$$\sqrt{T} \sum_{j=1}^{T-1} \frac{1}{j} \left( \frac{1}{T-j} \sum_{t=1}^{T-j} v_{1,t} v_{2,t+j} \right) \overset{d}{\rightarrow} N \left( 0, \frac{\pi^2}{6} \sigma_1^2 \sigma_2^2 \right).$$

Note that this result for the cross covariances also holds for the autocovariances, $i = 1, 2$,

$$\sqrt{T} \sum_{j=1}^{T-1} \frac{1}{j} \left( \frac{1}{T-j} \sum_{t=1}^{T-j} v_{i,t} v_{i,t+j} \right) \overset{d}{\rightarrow} N \left( 0, \frac{\pi^2}{6} \sigma_i^4 \right).$$

Given $\hat{\zeta}_t \hat{\zeta}_{t+j} = (v_{1,t} - \nu_{2,t} \widehat{\beta})(v_{1,t+j} - \nu_{2,t+j} \widehat{\beta})$ it thus follows with (8) and the notation introduced in the proof of Theorem 1:

$$\sqrt{T} a^* \overset{d}{\rightarrow} \sigma_1^2 \frac{\pi}{\sqrt{6}} \left( Z_1 + \beta_d Z_2 - \sqrt{2} \beta_d Z_3 \right).$$
Further, with \( \hat{\zeta}_t \) instead of \( \zeta_t \),
\[
s^2 = \frac{1}{T} \sum_{t=1}^{T} \hat{\zeta}_t^2 \overset{p}{\to} \sigma_1^2 (1 + \beta_d^2).
\]
Hence, for the residual-based statistic \( R^* \),
\[
R^* = \frac{\sqrt{6T}}{\pi s^2} a^*,
\]
the limiting distribution from Theorem 1 arises, which proves the Corollary.

**Proof of Theorem 2:**

We first establish a technical Lemma A.1 that is used to proof Lemma A.2. Theorem 2 will be an immediate consequence of the latter lemma.

Define the matrix norm \( \|A\|_M \) of a square matrix defined as Euclidean norm with a conformable vector \( b \), see Berk (1974), Said and Dickey (1984) and Saikkonen (1991):
\[
\|A\|_M = \sup \left\{ \|Ab\| : \|b\| \leq 1 \right\}.
\]

**Lemma A.1:** Under the assumptions of Theorem 2:

(i) \( \|(T - 2K)^{-0.5} \sum W_t x_t\| = O_p(K^{0.5}) \),
(ii) \( \|(T - 2K)^{-1} \sum W_t' W_t\|_M = O_p(1) \),
(iii) \( \|(T - 2K)^{-0.5} \sum W_t^* x_t\| = O_p(K^{0.5}) \),
(iv) \( \|(T - 2K)^{-0.5} \sum W_t^* x_{t-1}\| = O_p(K^{0.5}) \),
(v) \( \|(T - 2K)^{-0.5} \sum W_t^* x^*_t\| = O_p(K^{0.5}) \),
(vi) \( \|(T - 2K)^{-1} \sum W_t^* W_{t-1}\| = O_p(K^{0.5}) \),
(vii) \( \|(T - 2K)^{-1} \sum W_{t-1} W_t^*\|_M = O_p(1) \).

**Proof:** (i) Consider
\[
E \left[ \left( (T - 2K)^{-0.5} \sum_{t=K+1}^{T-K} W_t x_t \right)^2 \right] = E \left[ \sum_{k=-K}^{K} \sum_{i=1}^{m} (T - 2K)^{-1} \left( \sum_{t=k+1}^{T-K} v_{i,t-k}^{(i)} x_t \right)^2 \right]
\]
\[
= (T - 2K)^{-1} \sum_{k=-K}^{K} \sum_{i=1}^{m} E \left[ \sum_{t=k+1}^{T-K} v_{i,t-k}^{(i)} x_t \right]^2 ,
\]

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where $v_{2,t-k}^{(i)}$, $i = 1, \ldots, m$, stands for the $i$th component of the $m$-dimensional vector $v_{2,t-k}$. Notice that

$$E \left( \sum_{t=K+1}^{T-K} v_{2,t-k}^{(i)} x_t \right)^2 = \sum_{t=K+1}^{T-K} E \left( v_{2,t-k}^{(i)} x_t \right)^2 + 2 \sum_{t=K+1}^{T-K} \sum_{s=t+1}^{T-K} E \left( v_{2,t-k}^{(i)} x_t v_{2,s-k}^{(i)} x_s \right)$$

$$= O(T - 2K)$$

because for all $t$ and $k$

$$E \left( v_{2,t-k}^{(i)} x_t \right)^2 < \infty, \quad \left| \sum_{s=t+1}^{T-K} E \left( v_{2,s-k}^{(i)} x_t v_{2,s-k}^{(i)} x_s \right) \right| < \infty.$$

This proves

$$E \left\| (T - 2K)^{-0.5} \sum_{t=K+1}^{T-K} W_t x_t \right\|^2 = O((2K + 1)m),$$

and hence the required result.

(ii) Define $\hat{R} = (T - 2K)^{-1} \sum_{t=K+1}^{T-K} W_t W_t^\prime$ and $R = E(W_t W_t^\prime)$ with

$$\left\| \hat{R}^{-1} \right\|_M = \left\| \hat{R}^{-1} + R^{-1} - R^{-1} \right\|_M \leq \left\| R^{-1} \right\|_M + \left\| \hat{R}^{-1} - R^{-1} \right\|_M.$$

With $R^{-1}$ being the inverse of the autocovariance matrix of a stationary and invertible process, $\left\| R^{-1} \right\|_M$ is bounded, see Berk (1974, (2.14)). Moreover, we can adopt the proof of Berk (1974, Lemma 3) or Said and Dickey (1984, Theorem 4.1) and show that under (12)

$$\left\| \hat{R}^{-1} - R^{-1} \right\|_M = o_p(K^{-0.5}).$$

This proves the result.

(iii), (iv) and (v) Similar to (i).

(vi) Define $\hat{R} = (T - 2K)^{-1} \sum_{t=K+1}^{T-K} W_{t-1}^* W_{t-1}^* \prime$ and $R = E(W_{t-1}^* W_{t-1}^* \prime)$ with

$$\left\| \hat{R} \right\|_M = \left\| \hat{R} + R - R \right\|_M \leq \left\| R \right\|_M + \left\| \hat{R} - R \right\|_M.$$
With $R$ being the autocovariance matrix of a stationary and invertible process, $\|R\|_M$ is bounded, see Berk (1974, (2.14)). Moreover, we can adopt the proof of Said and Dickey (1984, Lemma 4.1) and show that under (12): $\|\hat{R} - R\|_M = o_p(K^{-0.5})$. This proves the result.

(vii) Similar to (vi).

Lemma A.2: Under the assumptions of Theorem 2 with $x_t \sim iid(0, \sigma^2)$:

(i) $(T - 2K)^{-1} \sum \tilde{x}_t^2 = (T - 2K)^{-1} \sum x_t^2 + o_p(1)$,

(ii) $(T - 2K)^{-0.5} \sum \tilde{x}_t \tilde{x}_{t-1}^* = (T - 2K)^{-0.5} \sum x_t x_{t-1}^* + o_p(1)$,

(iii) $(T - 2K)^{-1} \sum (\tilde{x}_{t-1}^*)^2 = (T - 2K)^{-1} \sum (x_{t-1}^*)^2 + o_p(1)$.

Proof: Define

$$
\pi' = (\pi_{-K}', \ldots, \pi_{-1}', \pi_0', (\hat{\beta} - \beta)', \pi_1', \ldots, \pi_K'),
$$

$$
\rho_t = \sum_{|k| > K} \nu_{t-k}^* \pi_k,
$$

where $\pi_k$ are from (3). Hence, the residuals from the cointegration regression may be rewritten as

$$
\hat{\varepsilon}_t = x_t + W_t' \pi + \rho_t.
$$

The residuals from the projection on $W_t$ thus yield

$$
\tilde{x}_t = x_t - W_t' \left( \sum W_t W_t' \right)^{-1} \sum W_t x_t + \rho_t - W_t' \left( \sum W_t W_t' \right)^{-1} \sum W_t \rho_t,
$$

where according to Saikkonen (1991) under (13)

$$
E(\rho_t^2) = o(T^{-1}).
$$

(19)
(i) First, it should be noted that \( \rho_t \) does not affect the probability limit of \( (T - 2K)^{-1} \sum \tilde{x}_t^2 \). To illustrate this consider e.g.

\[
\sum \rho_t W_t' \left( \sum W_t W_t' \right)^{-1} \sum W_t x_t.
\]

With the Cauchy-Schwarz inequality

\[
E \left\| \sum_{t=K+1}^{T-K} \rho_t W_t \right\| \leq \sum_{t=K+1}^{T-K} E|\rho_t| \|W_t\| \leq \sum_{t=K+1}^{T-K} \left( E(\rho_t^2) E\|W_t\|^2 \right)^{1/2}.
\]

Because of (19) and \( E\|W_t\|^2 = O(m(2K + 1)) \) we arrive at

\[
(T - 2K)^{-1} E \left\| \sum_{t=K+1}^{T-K} \rho_t W_t \right\| = o \left( (K/T)^{0.5} \right).
\]

Together with Lemma A.1, (i) and (ii), this results in

\[
(T - 2K)^{-1} \sum \rho_t W_t' \left( \sum W_t W_t' \right)^{-1} \sum W_t x_t = o_p \left( (K/T)^{0.5} \right) O_p \left( (K/(T - 2K))^{0.5} \right) = o_p(1).
\]

With \( \rho_t \) being thus negligible one obtains

\[
\sum \tilde{x}_t^2 = \sum x_t^2 - \sum x_t W_t' \left( \sum W_t W_t' \right)^{-1} \sum W_t x_t + o_p(T - 2K).
\]

With Lemma A.1, (i) and (ii), this reduces to

\[
(T - 2K)^{-1} \sum \tilde{x}_t^2 = (T - 2K)^{-1} \sum x_t^2 - (T - 2K)^{-1} O_p(K^{0.5}) O_p(1) O_p(K^{0.5}) + o_p(1)
\]

\[
= (T - 2K)^{-1} \sum x_t^2 - O_p \left( K/(T - 2K) \right) + o_p(1),
\]

which is the required result because \( K/(T - 2K) \to 0 \).

(ii) With

\[
\tilde{x}_{t-1}^* = x_{t-1}^* - W_{t-1}' \left( \sum W_t W_t' \right)^{-1} \sum W_t x_t + \rho_{t-1}^* - W_{t-1}' \left( \sum W_t W_t' \right)^{-1} \sum W_t \rho_t
\]

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we obtain

\[
\sum \tilde{x}_t \tilde{x}^*_t - 1 = \sum x_t x^*_t - \sum x_t W'_t \left( \sum W_t W'_t \right)^{-1} \sum x_t W^*_t - 1 + \sum x_t W'_t \left( \sum W_t W'_t \right)^{-1} \sum x_t W_t - 1
\]

and Lemma A.1 yields

\[
(T - 2K)^{-0.5} \sum \tilde{x}_t \tilde{x}^*_t = (T - 2K)^{-0.5} \sum x_t x^*_t - o_p((T - 2K)^{0.5}) + o_p(1),
\]

which proves the stated result because \(K/(T - 2K)^{0.5} \to 0\) by (12).

(iii) Similar to (ii).

\[\blacksquare\]

Given Lemma A.2, Theorem 1 in Breitung and Hassler (2002) implies under (12)

\[
(T - 2K)^{-1} \sum \tilde{x}^2_t \xrightarrow{p} \sigma^2,
\]

\[
(T - 2K)^{-0.5} \sum \tilde{x}_t \tilde{x}^*_t \xrightarrow{d} \mathcal{N}(0, \sigma^4 \pi^2 / 6),
\]

\[
(T - 2K)^{-1} \sum (\tilde{x}^*_t - 1)^2 \xrightarrow{p} \sigma^2 \pi^2 / 6,
\]

which in turn implies Theorem 2.

References


Sowell, F. (1990), The Fractional Unit Root Distribution; Econometrica 58, 495-505.

Tanaka, K. (1999), The Nonstationary Fractional Unit Root; Econometric Theory 15, 549-582.