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ABSTRACT

Team Structure and the Effectiveness of Collective Performance Pay

The adoption of performance related pay schemes has become increasingly popular in the public sector of several countries. In the UK, the scheme designers favoured collective performance pay with the aim to foster cooperation across offices. The resulting team structure included several offices (subteams) within the same team, defined by the remuneration scheme. In this paper we analyse the strategic interactions across subteams created by a two-level team structure, in order to assess whether rewarding collective performance necessarily promotes cooperation. We show that such team structure creates conflicting incentives to free-ride across and within subteams. Moreover, the relative size of subteams can be a powerful means to deliver incentives when funds for performance rewards are limited. Using data for one of the incentive schemes piloted in the UK, we analyse the role of the target level and of the relative size of subteams on subteams’ performance.

JEL Classification: M52, M54, J33

Keywords: incentives, teams performance, sub-teams, cooperation

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1 Introduction

The use of performance related pay (PRP) has become very popular in the civil service of several countries. It is estimated that two-thirds of OECD member countries have implemented PRP or are in the process of doing so (OECD, 2004a). Over the past few years one of the common trends emerging across the OECD countries has been the "...increase in the use of collective or group performance schemes, at team/unit or organisational level."  

The rationale behind the adoption of group performance incentive schemes relies on the limitations of individual PRP schemes, for example with regard to measuring individual performance, which is particularly difficult in the public sector. Public services are typically delivered through complex organisations, consisting of multiple divisions and a widespread network of offices. In these contexts, output, even when it is quantifiable, may be very costly to measure at individual level, as sophisticated data management systems are required. As a result, only aggregate measures may be available. The United Kingdom is one of the countries who have strongly encouraged the move towards a more collective approach to PRP. A number of departments have been piloting team-based schemes since 2001, following the recommendations of the Makinson report (Makinson, 2000). A common feature of these trial schemes is the definition of a team on the basis of administrative considerations. In particular, teams have been created by the reward system, at the level of a division, comprising different offices, although there are no apparent operational links within those offices. Informal discussions with some of the designers of these schemes revealed that one of their main concerns was to create collaboration across offices, which, for this reason, were included in the same team.

This paper addresses some important issues arising from such an incentive scheme design. Setting targets and assessing performance at the level of a division creates interdependencies among the offices in the same division. In fact, the expected reward of an office for hitting the target depends on how far actual performance at division level is from the target. This is determined by all offices’ output. However, production occurs at the level of offices, where complementarities in production may be at work (final output may depend on the effort of different colleagues). Hence the structure of the team is quite complex, and results in a two-level team: ”natural” teams or subteams (offices) are included within ”reward” teams (divisions). Both the theoretical and empirical literature focus on teams defined by the production process, by the nature of the activities performed or by some common interest or motivation that may drive teamwork. In Holmström’s (1982) seminal paper a team is either defined by the production process, or on the basis of some common uncertainty which affects the measurement of individual out-

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1 See OECD, 2004b, p. 6.
2 The office would be a team à la Holmström (1982), identified by complementarities in production.
puts. The individual choice of effort in teams is also analysed in contexts where teamwork emerges as the result of implicit incentives, such as peer pressure (Kandel-Lazear (1992) and Encinosa et al (1997)), or long-term repeated interactions among workers (Che and Yoo, 2001), or intrinsic motivation, when cooperation among workers spontaneously arise because workers care about the output of the organisation (Francois, 2000). The nature of tasks and individual preferences towards tasks may also motivate the optimal adoption of teamwork (Itoh, 1991). In these settings teams are endogenous, identified by the implicit incentives that might be at work in the different contexts. In this paper we consider teams like the ones defined in the pilot schemes introduced in the UK government agencies, i.e. exogenously created by an externally imposed reward scheme. Given the recent adoption of similar incentive schemes in the OECD member countries, the analysis provides, to our knowledge, a novel contribution which can supply testable predictions and inform the design of incentives mechanisms in the public sector.

We address two main issues arising from incentive schemes in two-level teams. We examine i) what kind of interdependencies in effort choice can be triggered across subteams when these are rewarded on the basis of their aggregate output (team output), and ii) how does the relative size of subteams affect the team’s output for different levels of the bonus. In particular, we consider a situation where resources to be used for the award of the bonus are limited and hence the principal cannot set the first-best level of the bonus.

Results show that the design of the scheme has important implications not only on the level of effort chosen by single subteams, but also on the nature of subteams’ interdependencies. In particular, the reaction function of each subteam differs for different target levels. Whether subteams’ efforts are positively or negatively related or completely independent depends on the magnitude of the target, as this affects the probability of success and hence the expected marginal benefit of effort of the subteam. Hence cooperation across subteams is not automatically created by rewarding subteams on the basis of their aggregate output. One implication of our results is that the relative size of subteams can be a powerful means to deliver incentives: instead of increasing the bonus the principal can alter the relative size of subteams to foster positive interdependencies in subteams’ effort. This alternative incentive tool may be particularly valuable in the presence of budgetary constraints in the allocation of bonuses, when the principal cannot increase financial rewards to improve outcomes as optimally required. If the bonus has to be set at a low level, there is a unique value of asymmetry in subteams’ size that allows the principal to get the highest level of output (second-best). If the principal can set a high bonus, then the first-best can be achieved with perfect symmetry. This suggests that the size of subteams shouldn’t be taken as given by the scheme designers, but should be a strategic variable like the targets and the bonus.

We organise the paper as follows. In the next section we discuss the design of three
incentive schemes, piloted in the UK government between April 2001 and March 2003. Section 3 presents a simple ad-hoc model that captures the two-level team structure of the incentive mechanisms discussed in section 2. In section 4, the best response of the subteam (office) is derived. The principal’s optimal choice of the incentive parameters is analysed in section 5. Section 6 considers the subteams’ relative size as a strategic variable for a principal with limited resources to reward performance. In section 7 we test the impact of the target level and of the asymmetry in subteams’ size on team’s performance, using data from one of the public agencies’ schemes mentioned above. Results are summarised in the conclusion.

2 The introduction of team-based incentives in the UK public sector: characteristics of the schemes

The incentive schemes we present in this section were part of a programme to reform public service delivery, started in the UK in 1997 and aimed at improving efficiency and productivity of the public sector. The idea of piloting a team-based incentive scheme in public agencies dates back to the Makinson report (2000). John Makinson (then Group Finance Director of Pearson plc) was recruited to the Public Service Productivity Panel to analyse how performance-based incentives operated in four public organisations (Benefits Agency, Employment Service, HM Custom and Excise, and Inland Revenue) and how they might be improved. In his report particular emphasis was placed on the use of team-based incentives, with the view that teamwork better reflects the way in which most public servants actually work. Most of the recommendations of the report were taken on board by the scheme designers of three governmental agencies: Child Support Agency, Jobcentre Plus and HM Customs and Excise. In particular, incentives related to targets already embodied in the Public Service agreements (PSA) of the respective agencies, as we shall consider below. There were up to five targets and if these were reached extra bonuses would be paid, separated out from basic pay and not consolidated into salaries. Teams were defined within the administrative boundaries of a division/district, comprising different offices in different locations.

In Child Support Agency the scheme ran from April 2001 to end of March 2002. Teams were defined at Business Unit (BU) level, in that the targets were defined at BU level and all workers within the BU received the bonus if the target was hit, regardless of individual performance. These teams were very big; there were only six BUs covering the whole

\[3\] For a quantitative evaluation of these schemes see Burgess et al. (2004, 2005, 2008).

\[4\] These are performance indicators introduced in 1998 by the Comprehensive Spending Review (CSR), to drive improvements in outcomes in the public sector.
of the country, varying in size from 10 to 24 offices in the team and 1350 to 1650 staff in the team. There were three sets of targets, assessed on a quarterly basis. Each of the three sets of targets accrued 0.5 of salary bonus for each quarterly checkpoints, with a maximum achievable bonus of 5% of salary. In common with the other two agencies, the bonus was paid for hitting the target, but no further increase for additional output was available. Thus incentives were very sharp at output levels just below the target threshold, but weaker further below and flat for output levels above the threshold.

The scheme for HM Customs and Excise was implemented in six trial sites and ran for nine months from April 2002 through December 2002. The unit chosen by HMCE as the team was a Division, which typically comprised a small number of offices. The teams had five targets to reach. These were a subset of the annual PSA targets setting a baseline level of performance and to which a stretch of 5% performance improvement was applied for incentive purposes. Two different reward schemes were implemented. In one case the bonus varied according to the individual’s job band. In the other case, the bonus paid was equal across all team members including the team manager. On average, the bonus was worth about 3% of salary.

In Jobcentre Plus the scheme ran from April 2002 to the end of March 2003. The team unit was the district. Once again, these were big teams - there were only 90 districts covering the whole of the country, varying in size from 5 to 39 offices in the team, and from 264 and 1535 people within a team. 17 out of the 90 districts were selected for the incentive scheme. The incentive targets consisted of the annual PSA Jobcentre Plus targets, to which a stretch factor was added (5% or 7.5% depending on the district). In total there were five incentivised targets, each of one carrying a fixed bonus for each team member, varying according to their grade. The District had to hit at least two targets to get any bonus, and if all 5 were reached, 50% of the standard rate per grade was paid as an addition.

An important characteristic, common across all three schemes, is that outcomes are produced, measured and assessed at different levels in the hierarchy of the organisations. This has important implications on the structure of the teams and ultimately on the effective delivery of incentives. Incentive targets and rewards for achieving those targets are set at team level. Teams are defined within the administrative boundaries of a division/district, comprising different offices in different locations. Setting targets and assessing performance at the level of a division/district creates interdependencies among

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5In the pair of trial teams evaluated, there were up to 6 offices and up to 158 staff in the team.

6Our conversations with HMCE officials suggested that it was seen by the managers as a worthwhile amount for the extra effort to achieve the targets.

7This meant that if all five targets were hit, the bonus that a worker could gain would vary from £750 to £3,750.
the offices in the same division/district. In fact, the expected reward of an office for hitting the target depends on how far actual performance at team level is from the target. And this is determined by all offices’ output. Production occurs at individual level, or, if members of staff in an office interact with each other and contribute to the same outcome, at office level. We were informed that in all three organisations there are no apparent operational links within offices belonging to the same division/district, so that they do not contribute to the same outcome.

Hence we have teams created by the reward system at the level of a division/district whereas output is produced at the level of an office. The structure of the teams is quite complex, and results in a two-level team: natural teams (offices), which contribute to a common output, are included within reward teams (divisions/districts). In the next section we model such a team structure, created by the incentive scheme and analyse the best response at the level of a subteam (office). We shall address two questions: 1) Is subteams’ cooperation necessarily encouraged by rewarding team performance? 2) What implications can be drawn on the optimal incentive scheme?

3 The model

We define a subteam as a natural team, where complementarities in production are present. We can think of it in terms of an office. A team is, instead, the unit upon which output is assessed for incentive purposes. Let

\[ q_i = f(N_i, e_i) + \varepsilon_i \tag{1} \]

be subteam \( i \)'s total output, where \( N_i \) is the number of staff in subteam \( i \), \( e_i \) is the mean effort level, and \( \varepsilon_i \) is an idiosyncratic random shock. The total number of staff in the team is \( \sum N_i = N \).

We define \( B \) as the bonus which is payable if the target on performance is achieved. As in the schemes we presented above, we model the bonus as a fixed amount (for example a fixed proportion of salary, as in the schemes mentioned above), paid for hitting the target, but with no further increase for additional output. So the payoff at team level is:

- \( NB \) if \( \sum q_i \geq (1 + \gamma)\overline{q} \)
- 0 otherwise

where \( \overline{q} = \sum \overline{q}_i \) is last year performance or some minimum standard expected within the organisation (like the baseline PSA target) and \( \gamma \) is the improvement in performance aimed to be reached on the top of last year’s or some minimum performance.
The expected payoff for office $i$ is:

$$V_i(e_i) = \Pr(\sum q_i \geq (1 + \gamma)N_iB - C(N_i, e_i))$$

(2)

where $C(N_i, e_i)$ is the cost of effort for subteam $i$.

### 3.1 Basic assumptions

- We consider a simple setting where there are two subteams within a team, of different size $\alpha_i$, with $\alpha_1 = \alpha$ and $\alpha_2 = (1 - \alpha)$ and $\alpha \geq 1/2$.

- The total number of staff in the team is normalised to 1, i.e. $N = 1$, so that $\alpha_i$ is the relative size of subteam $i$.

- There are two possible outcomes of the production process: a subteam’s output can either be successful or fail. It is successful when output reaches a given critical level: to minimise the parameters of the model we assume that such a level is $q_i = \alpha_i$.

A successful outcome depends on the average effort of a subteam and we assume it occurs with probability $p(e_i) = e_i$. Failure occurs when $q_i = \overline{q}_i$ and this happens with probability $(1 - p(e_i)) = (1 - e_i)$.

- The cost of effort is quadratic in effort and subteam size: $C_i = \frac{c}{2}(\alpha i e_i)^2$

### 3.2 Office output, target levels and probability of success

We now define output in each subteam and at team level, the targets and the probability of reaching the target.

**Output**

Under the assumption we made on the possible outcomes, or states of the world, there are four possible ranges of output, at subteam and team level:

<table>
<thead>
<tr>
<th>Possible outcomes</th>
<th>Subteam 1 output</th>
<th>Subteam 2 output</th>
<th>Aggregate output</th>
</tr>
</thead>
<tbody>
<tr>
<td>$e_1e_2$</td>
<td>$\alpha$</td>
<td>$(1 - \alpha)$</td>
<td>1</td>
</tr>
<tr>
<td>$e_1(1 - e_2)$</td>
<td>$\alpha$</td>
<td>$\overline{q}_2$</td>
<td>$\alpha + \overline{q}_2$</td>
</tr>
<tr>
<td>$(1 - e_1)e_2$</td>
<td>$\overline{q}_1$</td>
<td>$(1 - \alpha)$</td>
<td>$(1 - \alpha) + \overline{q}_1$</td>
</tr>
<tr>
<td>$(1 - e_1)(1 - e_2)$</td>
<td>$\overline{q}_1$</td>
<td>$\overline{q}_2$</td>
<td>$\overline{q}_1 + \overline{q}_2$</td>
</tr>
</tbody>
</table>

In Figure 1 we represent these possible ranges of aggregate output.

**Targets**
Given these possible values of aggregate output, there are three possible ranges where the targets can lie: $\gamma_L, \gamma_M, \gamma_H$.

1) $\gamma_L < (1 - \alpha) + \bar{q}_1$
2) $(1 - \alpha) + \bar{q}_1 < \gamma_M < \alpha + \bar{q}_2$
3) $\gamma_H > \alpha + \bar{q}_2$

- We illustrate these three ranges in figure 1.

Figure 1: Aggregate output defining intervals where the target can lie.

- Probability of reaching the target:

The interval where the target lies determines the probability that total output will be greater than the threshold. In fact:

If $\gamma < (1 - \alpha) + \bar{q}_1$, then

$$Pr(q_1 + q_2 \geq (1 + \gamma)(\bar{q}_1 + \bar{q}_2)) = 1 - (1 - e_1)(1 - e_2)$$  \hspace{1cm} (3)

This implies that the target is met if at least one subteam is successful

If $(1 - \alpha) + \bar{q}_1 < \gamma < \alpha + \bar{q}_2$, then

$$Pr(q_1 + q_2 \geq (1 + \gamma)(\bar{q}_1 + \bar{q}_2)) = e_1$$  \hspace{1cm} (4)

This implies that the target it met if at least the largest subteam succeeds,

If $\gamma > \alpha + \bar{q}_2$, then

$$Pr(q_1 + q_2 \geq (1 + \gamma)(\bar{q}_1 + \bar{q}_2)) = e_1e_2$$  \hspace{1cm} (5)

This implies that the target is met only if both subteams achieve a successful outcome.
4 Optimal effort choice at subteam level

In this section we derive the optimal response of a subteam to the incentive mechanism we introduced in the previous section. Our aim is to analyse whether rewarding aggregate performance necessarily increases sub-teams cooperation as was the objective of the UK public sector scheme designers. In order to do this, we need to calculate the reaction function of each separate sub-unit of the team. Note that we abstract from any free-riding considerations at the level of the office. Our aim is to examine interactions across subteams and not within teams. In the schemes we presented in section 2, the district manager is responsible for the district and devolves the targets to managers in the different offices. Output is measured at office level. So we can think of an office manager as our ”aggregate unit” of effort decision. Our aim is to examine the impact of the introduction of team bonuses on offices’ aggregate output.

The expected bonus for each subteam will depend on the probability that the target at team level is met, and this depends on the magnitude of the target. We can distinguish three cases.

Case 1: \( \gamma = \gamma_L < (1 - \alpha) + q_1 \). Each subteam will solve the following maximisation problem:

\[
\max_{e_i} [1 - (1 - e_1)(1 - e_2)](1 - e_2)B - \frac{c}{2}(\alpha_i e_i)^2
\]

The reaction function for each subteam, derived from the first order condition is:

\[
e_{1RF} = \min \left\{ \frac{\beta(1 - e_2)}{\alpha} \right\}, 1
\]

\[
e_{2RF} = \min \left\{ \frac{\beta(1 - e_1)}{(1 - \alpha)} \right\}, 1
\]

with \( \beta = \frac{B}{c} \). In what follows we assume that the cost parameter \( c \) is constant across all teams, so that the value of \( \beta = \frac{B}{c} \) is determined by the bonus \( B \).

The subteam effort choice is negatively affected by its size and positively by the level of the bonus, relative to the constant cost parameter. We should point out that here there is no assumption on complementarity or substitutability of effort between subteams, as there are no operational links within offices. So any relation between subteams’ effort is only due to the way the incentive scheme is designed. In this case, when the target is low, a higher effort by one subteam induces a lower effort by the other subteam, as equation (7) shows.

The equilibrium levels of effort depend on the magnitude of \( \beta \) relative to \( \alpha \). In particular, there are three cases:

If the bonus is relatively low, i.e. \( \beta < 1 - \alpha < \alpha \) - the bonus is not enough to even reward a successful output of the smallest team- there is unique equilibrium. From
the reaction functions (7) we get:

\[ e_1^* = \frac{\beta(\alpha - \beta)}{\alpha(1 - \alpha) - \beta^2} > e_2^* = \frac{\beta(1 - \alpha - \beta)}{\alpha(1 - \alpha) - \beta^2} \]  

(8)

The bigger subteam will exert more effort

For intermediate values of the bonus, i.e. if \( 1 - \alpha < \beta < \alpha \), the bonus is enough to reward a successful outcome of the smallest team, but not sufficient to reward a successful outcome of the largest team - there is a unique equilibrium and only the smaller subteam will exert effort:

\[ e_1^* = 0, \quad e_2^* = 1 \]  

(9)

If the bonus is relatively high, i.e. \( \beta > \alpha \), there are three possible equilibria:

\[ e_1^* = 0, \quad e_2^* = 1 \]  

(10)

\[ e_1^* = 1, \quad e_2^* = 0 \]  

(11)

\[ e_1^* = \frac{\beta(\beta - \alpha)}{\beta^2 - \alpha(1 - \alpha)} < e_2^* = \frac{\beta(1 - (1 - \alpha))}{\beta^2 - \alpha(1 - \alpha)} \]  

(12)

But only (10) and (11) are stable.

We represent these equilibria in Figure 2, first column.

**Result 1** If the target is low, such that it is sufficient that only one subteam achieves a successful outcome in order for the team target to be met, there will be negative strategic interactions in the subteams’ effort choice. Greater effort by one subteam will induce less effort by the other subteam.

In this case the aggregate reward system is not enough to enhance cooperation across subteams, and some form of monitoring will be necessary.

Depending on the level of the bonus, it is possible that the best strategy for the smallest sub-team - whose contribution to aggregate output (and hence to the likelihood of meeting the target) is smaller - may be to fully free-ride and exert zero effort. Hence it is not necessarily the case that sub-teams of smaller size supply greater effort: incentives to free-ride across sub-teams may conflict with incentive to free-ride within sub-teams, when the team target is set too low.

**Case 2:** \((1 - \alpha) + \widetilde{\theta}_1 < \gamma = \gamma_M < \alpha + \widetilde{\theta}_2\). Each subteam will solve the following maximisation problem:

\[ \max_{e_i} e_i \alpha_i B - \frac{c}{2}(\alpha_i e_i)^2 \]  

(13)
and the resulting reaction functions are:

\[ e_{1}^{RF} = \frac{\beta}{\alpha} \]
\[ e_{2}^{RF} = 0 \] \hspace{1cm} (14)

The effort choice of the largest subteam is negatively affected by its size and positively by the level of the bonus, relative to the constant cost parameter. In this case efforts are unrelated to each other and the smaller subteam will always choose a zero level of effort. The equilibrium levels of effort for the larger subteam depends on the bonus:

- if the bonus is relatively low, i.e. \( \beta = \beta_{L} < 1 - \alpha < \alpha \), or has intermediate values, i.e. if \( 1 - \alpha < \beta = \beta_{M} < \alpha \), there is a unique equilibrium:

\[ e_{1}^{*} = \frac{\beta}{\alpha} > e_{2}^{*} = 0 \] \hspace{1cm} (15)

- if the bonus is relatively high, i.e. \( \beta = \beta_{H} > \alpha \), there is a unique equilibrium:

\[ e_{1}^{*} = 1, e_{2}^{*} = 0 \] \hspace{1cm} (16)

We represent these equilibria in Figure 2, second column.

**Result 2** If the target can be reached whenever the largest subteam is successful, subteams will choose their effort independently. The smaller subteam will always choose zero effort and only the larger subteam will exert positive effort. This will be an increasing function of the bonus and a decreasing function of the relative size of the subteam.

**Case 3:** \( \gamma = \gamma_{H} > \alpha + \bar{q}_{2} \). Each subteam will solve the following maximisation problem:

\[ \max_{e_{i}} \alpha_{i} B - \frac{c}{2} (\alpha_{i} e_{i})^{2} \]

and the resulting reaction functions are:

\[ e_{1}^{RF} = \max \left\{ \frac{\beta}{\alpha} e_{2}, 1 \right\} \] \hspace{1cm} (18)
\[ e_{2}^{RF} = \max \left\{ \frac{\beta}{(1 - \alpha)} e_{1}, 1 \right\} \]

The effort choice of each subteam depends negatively on \( \alpha \), the size of the subteam and positively on \( \beta = \frac{B}{\bar{c}} \), the value of the bonus relative to the constant parameter of the cost function. Notice that in this case a higher effort by one subteam induces higher effort by the other subteam. The equilibrium levels of effort are:

- if the bonus is relatively low, i.e. \( \beta = \beta_{L} < 1 - \alpha < \alpha \), there is a unique equilibrium and none of the subteams will exert effort:

\[ e_{1}^{*} = 0, e_{2}^{*} = 0 \] \hspace{1cm} (19)
- for intermediate values of the bonus, i.e. if $1 - \alpha < \beta = \beta_M < \alpha$, there two sub-cases:

  if $\beta^2 < \alpha(1 - \alpha)$ there is a unique equilibrium and none of the subteams will exert effort:

  $$e^*_1 = 0, \ e^*_2 = 0$$  \hspace{1cm} (20)

if $\beta^2 > \alpha(1 - \alpha)$ there are two possible equilibria

  $$e^*_1 = 0, \ e^*_2 = 0$$  \hspace{1cm} (21)

  $$e^*_1 = \frac{\beta}{\alpha}, \ e^*_2 = 1$$  \hspace{1cm} (22)

But only (22) is stable.

- if the bonus is relatively high, i.e. $\beta = \beta_H > \alpha$, there are two possible equilibria:

  $$e^*_1 = 0, e^*_2 = 0$$  \hspace{1cm} (23)

  $$e^*_1 = 1, \ e^*_2 = 1$$  \hspace{1cm} (24)

But only (24) is stable.

We represent these equilibria in Figure 2, third column.

**Result 3** If the target is very high, such that it can be met only if both subteams are successful, the effort choice of each subteam is positively affected by the other subteam. There are two possibilities: if the bonus is too low, then none of the subteams will exert effort. For high enough values of the bonus - $\beta^2 \geq \alpha(1 - \alpha)$- both subteams will exert effort, and either the smaller subteam will exert more effort or they will both exert the same level of effort.

In conclusion, rewarding aggregate performance does not necessarily induce complementarities in the effort choice of each subteam. Each subteam’s behaviour depends crucially on the level of the target, which determines the probability of team success, and hence the marginal net benefit of effort. Cooperation among subteams is the best strategy only if the target is high, such that each subteam’s outcome has to be successful, and the bonus is generous. When the target is sufficiently low, such that it is sufficient that at least one of the two subteams produces a successful outcome, cooperation is not a best strategy and subteams’ effort will be negatively related. The best and stable strategy for the smallest subteam, whose contribution to aggregate output (and hence to the likelihood of meeting the target) is smaller, will be to fully free-ride and exert zero effort. Hence, there are incentives to free-ride across subteams that conflict with incentives to free-ride within the same subteam: given the reward system, a smaller subteam, where the free-rider problem could be less problematic, does not necessarily provide a higher effort.
5 Optimal solution for the principal

In this section we derive the optimal contract for the principal, given the best-reply correspondence of each subteam.

We assume that the principal aims to maximise expected output. Given the optimal effort choice of the two subteams ($e_1^*$ and $e_2^*$), we define the expected output at team level as:

$$ExpQ^* = \alpha e_1^* + (1 - \alpha) e_2^*$$

(25)

The principal’s programme writes as:

$$\max_{\beta, \gamma} \alpha e_1^* + (1 - \alpha) e_2^*$$

(26)

By substituting the equilibrium levels of effort, as derived in the previous section, in (26) we can determine what is the best target corresponding to each level of the bonus. In figure 2 we represent for each combination of bonus and target level, the effort chosen by each subteam and the corresponding expected output at team level.

We fix the target levels and assume that these have been optimally set, so that $\gamma_L, \gamma_M$ and $\gamma_H$ are optimal values and allow $\beta = \frac{B}{c}$ to vary. We identify for each range of $\beta$

---

**Figure 2:** Optimal effort and optimal expected output for each subteam.
whether it is better to set a low, $\gamma = \gamma_L$, a medium, $\gamma = \gamma_M$ or a high target ($\gamma = \gamma_H$).

We highlight the optimal solution for the principal in Figure 2. We can distinguish four different cases:

1) If the bonus is low, i.e. $\beta < 1 - \alpha < \alpha$, (first row of the table) then the optimal target is $\gamma^* = \gamma_L$, as this maximises expected output.

2) If the bonus is of intermediate level, i.e. $1 - \alpha < \beta < \alpha$ (second row in the table) and $\beta^2 < \alpha(1 - \alpha)$, then the optimal target is $\gamma^* = \gamma_M$.

3) If the bonus is of intermediate level, i.e. $1 - \alpha < \beta < \alpha$ (second row in the table) and $\beta^2 \geq \alpha(1 - \alpha)$, then the optimal target is $\gamma^* = \gamma_H$.

4) If the bonus is high, i.e. $\beta > \alpha$ (third row) then the optimal target is $\gamma^* = \gamma_H$.

If the principal is initially at the top left corner of the table, setting a low target and low bonus, she is not at a first best. She can be better off at the bottom right corner of the table, setting a high target and high bonus. In this case, in fact, the expected output is 1, the maximum attainable. The problem of attaining this equilibrium is that the principal might have limited resources to use for the bonus payment and hence may not be able to increase the bonus. An alternative way of reaching the first best is to reduce the degree of asymmetry in subteams size, $\alpha$, until $\beta > \alpha$.

**Result 4** If the principal aims at enhancing cooperation among subteams by use of aggregate reward systems, the first-best contract requires to set high targets and generous bonuses. The relative size of subteams is also an important decision variable for the principal, when bonuses cannot be too generous. In this case, in fact, the principal can vary the relative size of the subteams to reach a first-best solution.

Hence the composition of a team should not be exogenously determined by some administrative considerations, but should rather be optimally selected by the scheme designers, together with the amount of the bonus and the targets. The relative subteams’ size assumes a strategic role, especially when there are monetary constraints on the level of the bonus to be awarded. We explore this issue more in detail in the next section.

## 6 Subteams’ relative size as a strategic variable

In this section we consider a situation where the amount of the bonus is fixed and cannot be chosen. We can either think of a situation where only limited resources can be devoted to the payment of bonuses, or to a case where the bonuses are exogenously set by a body that does not have any choice on the targets and she takes them as given. This would happen when the targets are optimally set by a body that is different from the designers of the scheme, as it may occur in organisations like government agencies, where targets are set in concurrence with the managers of the organisation while the funding of the scheme is independently decided by the Treasury.
different authority\textsuperscript{9}. We fix $\beta = \beta^* < \frac{1}{2}$ and examine what is the optimal subteam relative size, which maximises expected output for the principal.

In Figure 3, we represent the four regions where the bonus can lie, as a function of $\alpha$. For each of these four regions we report the information on the value of optimal expected output, the optimal target and the corresponding probability of reaching the target. This latter depends on the value of the target and is calculated by substituting the optimal effort choice of each subteam in equations (3)-(5). When $\beta = \beta^* < \frac{1}{2}$, the first-best cannot be attained, as the bonus is too low and there is no margin to adjust the value of alpha to get a first-best, i.e. such that $\beta > \alpha$.

In this scenario, there are three possibilities:

1) If the bonus is low, i.e. $\beta < 1 - \alpha$ (this corresponds to region 1 in Figure 3), the optimal target is low, $\gamma_L$, the effort choices of the two subteams are negatively related and the expected output is:

$$Q^* = \frac{\beta [\alpha^2 + (1 - \alpha)^2 - \beta]}{\alpha (1 - \alpha) - \beta^2}$$

which is increasing in $\alpha$.

\textsuperscript{9}This is the case in the trial schemes we mentioned above, where the amount of the bonus was decided by the Treasury for all three government agencies.

Figure 3: Optimal expected output, probability of success and target for each range of $\beta$ and different $\alpha$. 
2) For \((1 - \alpha) < \beta < \alpha\), and \(\beta^2 < \alpha(1 - \alpha)\) (this corresponds to region 2 in Figure 3), the optimal target is medium, \(\gamma_M\), the effort choice of the two subteams are independent and the expected output is constant and equal to:

\[
Q^* = \beta
\]

3) For \((1 - \alpha) \leq \beta < \alpha\), and \(\beta^2 > \alpha(1 - \alpha)\) (this corresponds to region 3 in Figure 3), the optimal target is high, \(\gamma_H\), the two subteams cooperate in the effort choice and expected output is decreasing in \(\alpha\).

\[
Q^* = \beta + (1 - \alpha)
\]

If we compare these three levels of output, the highest is \(Q^* = \beta + (1 - \alpha)\) when \(\beta^2 = \alpha(1 - \alpha)\). For \(\beta^2 > \alpha(1 - \alpha)\), \(Q^*\) starts decreasing if we increase \(\alpha\). For \(\beta^2 < \alpha(1 - \alpha)\), \(Q^*\) is increasing in \(\alpha\).

In terms of Figure 3, if we fix a value of \(\beta = \beta < \frac{1}{2}\) and start with two symmetric subteams, \(\alpha = \frac{1}{2}\), the expected output for the principal can be increased by increasing \(\alpha\). In fact, up to \(\alpha_1\) (region 1) expected output is an increasing function of \(\alpha\). Between \(\alpha_1 \leq \alpha < \alpha_2\) (region 2) the expected output is \(Q^* = \beta\) and above \(\alpha_2\) (region 3) it starts decreasing with \(\alpha\). The highest output is at \(\alpha_2\), when \(\beta^2 = \alpha(1 - \alpha)\) and \(Q^* = \beta + (1 - \alpha)\).

Hence the best solution for the principal, faced with a limited budget for the bonus at \(\beta < \frac{1}{2}\), is to set a high target and a sufficiently high degree of asymmetry in subteams’ size (such that \(\beta^2 = \alpha(1 - \alpha)\)). A lower degree of asymmetry does not lead to subteams’ cooperation - as either i) the conditions \((1 - \alpha) < \beta < \alpha\) and \(\beta^2 < \alpha(1 - \alpha)\) hold and subteam effort is independent, or ii) the condition \(\beta < 1 - \alpha\) holds and the effort choices of the subteams are substitutes. A degree of asymmetry that is higher than \(\beta^2 = \alpha(1 - \alpha)\) does involve cooperation across subteams, but provides a lower output to the principal.

Note that in the absence of a financial constraint on the level of the bonus, i.e. \(\beta \geq \frac{1}{2}\), a more symmetric size is preferable to the principal. In fact, if \(\alpha = \frac{1}{2}\) we can be sure to be in region 4 of Figure 3, where a first-best can be reached. A higher degree of asymmetry can instead lead to region 3, where expected output is lower.

In the schemes we mentioned in section 2, the relative size of the subteams was not chosen by the scheme designers, but was exogenously taken as an organisational feature of the public agency. The bonus was set by the HM Treasury. Although we can imagine the scheme designers were involved in the decision about the level of the bonus, they surely did not have complete control over its level. Hence it is possible that the incentive schemes were not optimally set to induce greater cooperation across offices.
Testing the predictions of our theoretical model using the empirical evidence from the schemes we mentioned above is not so straightforward. One very important issue of those schemes, which is absent in our model, is the multitasking problem. The bonus was awarded only if all or at least a set of the incentive targets were met, depending on the organisation. In our model we abstract from multitasking issues in order to focus on the role of subteams’ relative size on their effort choice. Nevertheless, we can look at which were the teams among the incentivised ones who hit their incentive targets and examine whether more/less symmetric teams were more likely to hit their targets. We can also check how the degree of asymmetry in team size and the level of the target affected subteams’ output. We do this in the next section.

7 Empirical evidence from Jobcentre Plus

Among the schemes introduced in the UK government agencies we mentioned above, we select the Jobcentre Plus scheme, as this is the only scheme for which two different incentive target levels were used. Jobcentre Plus is also the only public agency for which we have office-level (sub-teams level) data.

Jobcentre Plus was launched in October 2001, amalgamating the functions of two agencies: the Benefits Agency (BA), responsible for administering benefits to the unemployed, lone parents and others, and the Employment Service (ES), responsible for job placement. The method of delivering these services also began to change with the introduction in November 2001 of 56 new ‘Pathfinder’ offices providing an integrated service, combining the work of the original, separate, benefits offices and employment offices. This major reorganisation meant redesigning districts, setting new performance targets and changing the way of delivering business. The incentive scheme ran from April 2002 to April 2003, in 17 out of the 90 districts. These 17 districts (teams) were selected on the basis of containing at least one Pathfinder office. The incentivised districts were grouped into two categories: Band A districts, which contained up to 20% of Pathfinder offices over the total number of offices, and Band B districts, with more than 21% of Pathfinder offices. Two different target levels were applied to the two categories: for Band A districts the incentive target consisted of 5% increase in the baseline output target (PSA target), whereas for Band B districts it was a 7.5% increase. The incentive scheme included targets for five different functions: job placements, customer service, employer service, other business delivery functions, and reducing benefit calculation error and fraud. In this analysis we shall focus on the outcome job placements, as it is the only quantitative outcome measured at office level. Job placements, job entries in Jobcentre Plus’ terminology, are measured as weighted numbers of clients who are found work by the office. This measure is based on a points system, which varies with the priority of the clients as imposed by the government.
- for example, a jobless lone parent attracts 12 points, compared to 4 points for a short-
term unemployed claimant, and 1 point for an already-employed worker. Extra points
also accrue if the worker is not back on unemployment benefit within four weeks, and also
in certain priority areas. In the analysis below we shall consider job entry points as the
output of an office, as this is the measure used to assess performance for the incentive
scheme. Nine of the incentivised districts were Band A districts\textsuperscript{10} and the remaining eight
districts were Band B districts\textsuperscript{11}. There were 962 offices producing job entries in total. Of
these, 740 were not incentivised and 222 were incentivised. Of the 222, 74 were in Band
B districts, whereas the remaining 148 were in Band A districts.

We first consider the incentivised teams and distinguish between those who hit their
targets for job entries and those who didn’t. We do this with a view to see whether the
level of the target and the office size dispersion had a clear role for the success of the
team. The questions we address are: 1) Are the successful teams composed by offices of
similar size? 2) Are the successful teams concentrated in the Band B districts (those who
were assigned a higher target)?.

Unfortunately we only deal with a very small sample size, which is going to limit
our analysis. In Table 1 we consider how the dispersion in office size varied across all
incentivised districts, distinguishing those districts who reached their targets with an
asterisk (and in bold red). We choose the Gini coefficient as a measure of dispersion
of office size in each district. On this purpose, for each district, we ranked offices from
small to large and calculated the cumulative percentage of staff in the offices and the
cumulative distribution of offices. An index equal to zero would mean perfect equality in
office size within the district, whereas an index equal to one would mean the total staff
is concentrated in one office. So we have one Gini coefficient for each district. The
Gini coefficient varies from 0.24 and 0.57\textsuperscript{12}. If we divide the interval $[0, 1]$ of the Gini
coefficient into quantiles, the incentivised teams who managed to reach the targets have
values concentrated in the second quantile, though the number of observations prevent
us from drawing any solid insights into how asymmetry in team size might have affected
the likelihood of hitting the targets. Three of the five successful districts (Bridgend,
Grampain and Wirral) were in Band B districts, whereas two (Manchester and Lothian)
were in Band A districts. Hence, also for the role of the target level on the team’s success,
we do not obtain a clear pattern.

As an alternative measure of office size asymmetry we considered a measure of dom-

\textsuperscript{10}Band A districts were: Birmingham and Solihull, Derbyshire, Devon, Essex, Hampshire, London
Central South, Lothian and Borders, Manchester, Renfrews Inverclyde Argyll Bute.
\textsuperscript{11}Band B districts were: Bridgend, Calderdale, East Lacashire, Gateshead, Grampian, London North
West, Shropshire and Wirral.
\textsuperscript{12}The lowest value of the Gini coefficient in the non-incentivised teams is 0.16 and the highest is 0.62.
Table 1: The Gini coefficient in the incentivised districts at Jobcentre Plus

<table>
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<th>Gini</th>
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<td>BIRMINGHAM AND SOLBULL</td>
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<td>BRIDGEND AND RHONDDA CYNON TAF</td>
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<td>RENFREWS INVERCLYDE-ARAYLL BUTE</td>
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</table>

Figure 4: The Gini coefficient in the incentivised districts at Jobcentre Plus

inance. For each district, we ranked each office within the district by their size. The $n$ largest offices per district were selected; where $n = 25\%$ of total offices (so in a district with 4 offices, the largest 1 is selected). The sum of staff in the $n$ offices was taken as a percentage of total staff in the district, obtaining in this way a measure of dominance which goes from 0 to 1. However, also in this case, we were not able to draw any clear conclusion on the role of team asymmetry on the likelihood of hitting the targets. The incentivised teams who hit the targets do not have a specific degree of dominance that distinguishes them from those who did not hit the targets. One possibility is that the sample size undermines our analysis. In what follows, we consider the office output as a proxy for the effort choice of each sub-team, in order to check how the target level and the team asymmetry affects the office response to the incentive scheme.

7.1 Impact of different target levels on the subteams’ outcome

In this section we consider the impact of the target level on the office’s output. Given that we are going to estimate the impact of the incentive scheme on output it is important to clarify how offices were selected to the treatment and how we intend to identify this effect. As already mentioned, the 17 incentivised districts were selected into treatment on the basis of containing at least one Pathfinder office. The choice of which office was to become a Pathfinder office was based on the rationale that the locations of the Pathfinder offices were to be spread across all 11 Jobcentre Plus regions. The specific sites in each region were chosen by Field Directors and their District Managers on the grounds that their
management would be able to cope well with the demands of the new structure. Also, the selected offices were to reflect a "cross-section of different communities and customer bases, i.e. from large inner-city offices to those in smaller towns, suburbs and rural areas." This suggests that the treatment assignment is stratified random: it is indeed correlated to outcomes for Pathfinder offices, given the choice made on their location. However, it is likely that assignment is random for all the other offices as these are in the pilot incentive scheme because they are in the same district as the Pathfinder offices, hence on grounds entirely unrelated to their own performance and characteristics. One could argue against this argument with the view that some of the districts might have been more prepared than others for the structural change, thanks to a good district manager or to the presence of good offices overall, and hence might have been chosen on those grounds. According to this view, all offices within a Pathfinder district would systematically perform better than others even without the incentive scheme. However, the fact that the selected Pathfinder offices had to reflect a cross-section of different communities and customer bases limits these arguments, as the emphasis was more on the customers of the organisation rather than the quality of the office. Also, the fact that offices tend to be self-contained and there are few operational links between offices in a district rules out any kind of spillover-effects of good performing offices on the rest of the district. Obviously, it would be ideal to test any systematic difference in the quality of offices across districts before the introduction of the incentive scheme, but we cannot do it in the absence of past data on performance, as the districts were redesigned shortly before the introduction of the scheme. Therefore, in what follows we assume random assignment to treatment for offices other than Pathfinder offices and we include in our analysis all offices except for Pathfinder offices.

We consider the (log) job entry points as the output of an office. We run OLS regressions using monthly data at office level. In order to isolate the effect of the incentive scheme, we control for office characteristics that may affect output but are not due to the incentive scheme. In particular, we control for the type and size of office, the quality of staff and the labour market conditions. For the type of office, we distinguish between Headquarter (HQ) offices and other offices, in that Headquarter offices had central administrative functions and hence were a bit different than other offices. We also control for any organisational change during the period of observation: the dummy jcp status is to pick up the fact that during the observation period offices may have become Jobcentre Plus offices (with the same organisational structure of the Pathfinder offices). As a

\(^{13}\text{Private communication.}\)

\(^{14}\text{We were informed that there are few operational links between offices in a district. In particular, the work of non-Pathfinder offices is largely unaffected by the presence of Pathfinder offices in the districts, and different offices are largely self-contained.}\)
measure of the quality of staff, we consider the private-public wage gap in the local area - a high wage gap implying a lower quality workers in the public sector. The state of demand in the labour market is measured as the ratio of the inflow of vacancies relative to job seekers\(^\text{15}\). Questions we want to address are: once we control for any observable influences on office performance, can we detect a different impact of the scheme on office performance depending on the level of the target? Is the impact of the target level affected by the absolute and relative office size? Table 2 presents our results\(^\text{16}\).

Column 1 in Table 2 considers the impact of the target level on the output measure. The dummy *Lower stretch* identifies the incentivised offices which were subject to the lower target (5% stretch on annual performance as defined by the PSA target), whereas the dummy *Top stretch* identifies the incentivised offices which were subject to the higher target (7.5% stretch). Hence the analysis is relative to non-incentivised offices. Results suggest a significative difference of the impact of the two target levels on offices’ performance. A low target does not seem to have a statistically significant impact on output, whereas the higher target positively affects output. In columns 2 and 3 we consider the office relative size, defined as the ratio of staff in the office over the total staff in the district where the office is located. Results on the interactions between the office relative size and the target level in column 3 suggest that the impact of the higher target is not affected by the relative size, whereas offices subject to the lower stretch tend to do better if their relative size is bigger. This could confirm the theoretical prediction of Result 1, according to which, when the target level is low, greater effort by one office induces lower effort by the other and it is possible that a smaller office contributes less than a bigger office, given that the expected return to effort is smaller, i.e. the impact of a marginal increase in effort on the probability of reaching the target is less than for a bigger office.

In columns 4 and 5 we consider the absolute size and distinguish between big and small offices, a big offices being an office with a bigger size than the average size (calculated across all offices in all districts). In column 4 we consider small offices relative to big

\(^{15}\)Our variable is derived from the Labour Force Survey Small Areas dataset. We constructed the wage gap between the private sector and the public sector for each local authority looking at the relative hourly wage of full-time workers. This was matched to the office postcode. Using the postcode (zip code) for each JP office, we locate each office in a Travel To Work Area (TTWA98). We then extract claimant inflow and vacancy inflow data from NOMIS for each TTWA and for each month. Whilst the matching function uses the unemployment and vacancy stocks, we cannot take these as exogenous as they are influenced by the outflow rate, our dependent variable. So we use the inflow, both of unemployed claimants and of vacancies, and take the latter divided by the former. Note that the state of the labour market plays two roles - first it provides the ‘raw material’ necessary for the office to produce job entries. Second, it proxies labour market tightness and hence the ease or otherwise of placing claimants in jobs.

\(^{16}\)We also control for time trends and consider dummies for each of the nine months of the incentive scheme. We omit the results for lack of space. These are available at request from the authors.
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</tr>
<tr>
<td>Constant</td>
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<td>3.78</td>
<td>3.835</td>
<td>6.67</td>
<td>5.649</td>
</tr>
<tr>
<td></td>
<td>(0.081)**</td>
<td>(0.087)**</td>
<td>(0.092)**</td>
<td>(0.034)**</td>
<td>(0.033)**</td>
</tr>
<tr>
<td>Observations</td>
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<td>8868</td>
<td>8868</td>
<td>8868</td>
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</tr>
<tr>
<td>R-squared</td>
<td>0.59</td>
<td>0.6</td>
<td>0.6</td>
<td>0.41</td>
<td>0.41</td>
</tr>
</tbody>
</table>

Robust standard errors in parentheses, * significant at 5% ; * * significant at 1%

Figure 5: Table 2. Regression analysis: the role of office size and target level on the impact of the incentive scheme
offices and interact the dummy “Small Office” with the two target levels. Our aim is to check whether the impact of the target level depends on the absolute size of an office. In column 5 we consider the dummy “Big Office”. However, the interactions with the two target levels are not significant, suggesting that the impact of the target level does not depend on the absolute size of offices.

Hence results suggest a higher performance of those incentivised offices which were subject to a higher target, independently of their relative or absolute size. For the incentivised offices subject to a lower target, the incentive scheme seems to work only in offices with a bigger relative size (the effect is increasing in the size of the office relative to the total size of the district).

7.2 The impact of team asymmetry and subteams’ size on subteams’ output

Next we consider the degree of asymmetry in the distribution of offices’ size in the same district (team). We do not have information on the level of the bonus (was it set at an optimal high level?). Hence we would not be able to test our predictions on the optimal degree of asymmetry in subteam size. However, we are interested in checking if in teams where the incentive scheme seems to work better (where offices where subject to a higher target) the distribution of the relative size of offices did have any impact on the effect of the scheme. More precisely, the questions we address here are: does the degree of asymmetry in subteams’ size play any role on the effect of the incentive scheme in those teams where incentives did work? Does the effect of the incentive scheme change if offices are relatively smaller(bigger) and belong to more symmetric(asymmetric) teams?

Note that in our theoretical model we only had two subteams in a team, hence the relative size of the subteam also measured the degree of asymmetry in the distribution of the subteams’ size. Our data includes several offices within the same team, hence the relative size of an office cannot be used to measure the degree of asymmetry in the distribution of offices size in the same district. We use the Gini coefficient to measure the dispersion in subteams’ size, i.e. the degree of team (a)symmetry (every office in the same district will have the same Gini coefficient). In table 3, the dummy Top stretch identifies the offices subject to the higher incentive target, hence now the analysis is relative to all other non incentivised offices and to the incentivised offices where the scheme did not seem to work. Column 1 considers the interaction between the higher target and the degree of asymmetry in team size, which is not statistically significant. Hence the impact of the target level does not seem to be affected by the distribution in subteams’ size. In column 2 we consider districts with a gini coefficient below the mean (Low Gini dummy) relative
to the others and interact this dummy with the relative size of subteams (rel_staff) and the high target level (this interaction dummy is the variable HStrLowG_relsize). The question we address in this specification is: in more symmetric teams, is it better to be a relatively smaller or a relatively bigger office for the impact of the scheme? Results suggest that incentivised offices located in teams which are more symmetric (where the subteams’ size is more equally distributed) tend to do better if they are smaller relative to all other offices in the same team. In column 3 we consider the dummy High Gini (identifying offices in districts with a higher Gini coefficient than the average) and interact it with the top stretch dummy and the relative size of the office (dummy HStrHG_relsize). Results suggest that incentivised offices in more asymmetric teams tend to do better if they are relatively bigger than the other offices within the same team. Hence the impact of the high target does depend on the relative size of offices once we distinguish between more symmetric/asymmetric teams. It is not necessarily the case that small offices tend to perform better than big offices. The two-level structure of the team makes the effect of the incentive scheme more difficult to evaluate, as the asymmetry in the distribution of the relative size of offices in the team also affects the impact of the scheme. In more symmetric teams, smaller offices tend to perform better than the others, whereas in more asymmetric teams, relatively bigger offices outperform the others. How to interpret those results? We can imagine that in more symmetric teams the contribution of each office to the team output is more similar and hence a marginal increase in effort will have a similar impact on the probability of reaching the target. Given that the bonus does not change with the size of an office, this implies that the expected benefit of a marginal increase in effort is very similar in offices which have a similar relative size. However, in more asymmetric teams, a bigger office will have a larger expected benefit of a marginal increase in effort (due to a greater impact on the probability of reaching the target), and hence will be more motivated to increase effort if subject to an incentive scheme. This confirms that a two-level team structure triggers some important interdependencies in effort choices across subteams, that may imply better performance for bigger subteams, the opposite argument than the free-riding argument in a single-level team.
Table 3. Teams’ asymmetry, subteams size and the impact of the incentive scheme.

8 Conclusion

We have considered the implications of setting incentive schemes for teams defined by the reward system and based on administrative boundaries, comprising different units of production (subteams). In a simple two-subteam model, we show that the way the scheme is designed creates important interdependencies in the effort choice between subteams and setting targets on aggregate output does not necessarily create cooperation among sub-teams. In fact, we show that interdependencies in effort choice depend on the level of the target: if the target is low enough (relative to the subteams’ output) so that it can be reached by one of the two sub-teams, then the optimal choice of each sub-team is negatively affected by the other sub-team’s effort and cooperation has to be induced externally, for example by some form of monitoring. For a medium level of the target, subteams’ efforts are independent and only when high targets are set, a greater effort by one subteam induces greater effort by the other subteam. We derive the optimal solution for the principal, which requires setting high targets and high bonuses. When high bonuses can be awarded, then the degree of asymmetry in subteams’ size should be minimum and should guarantee that the value of the bonus is higher than the value
of the output of the biggest sub-team. If the principal faces financial constraints and cannot freely set the level of the bonus, then a first-best solution cannot be achieved. In this case, the relative size of sub-teams becomes a crucial variable to deliver incentives. The principal can adjust the relative size of subteams to increase expected output. The second-best requires a critical value of the subteams’ relative size, which should not be perfectly symmetric. Hence the way the team is designed (dispersion in sub-units size) is very important for the final outcome of the scheme, above all when the principal cannot freely set the level of the bonuses. This implies that teams should not be exogenous: their composition (relative size of sub-units) should be optimally selected by the scheme designers.

Using data for one of the incentive schemes implemented in a public organisation in the UK, we consider the effects of two different target levels on subteams’ (offices’) output. Results confirm the theoretical predictions that incentivised offices outperform non-incentivised offices only in teams with a higher target level. We also find that in districts with a lower (than average) degree of asymmetry in sub-teams size, the relative size of offices negatively affects performance. Whereas in districts with a higher (than average) degree of asymmetry, the scheme is more successful in relatively bigger offices. This suggests that the impact of the scheme does indeed depend on the distribution of offices’ size in the team and not only on their relative size. Moreover, bigger subteams may outperform the others, suggesting that the argument in favour of a smaller size to tackle free-riding issue does not necessarily apply in two-level teams and some conflicting free-riding issues may be at work.
References


