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On Modified Mellin Transforms, Gauss-Laguerre Quadrature, and the Valuation of American Call Options

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Abstract

We extend a framework based on Mellin transforms and show how to modify the approach to value American call options on dividend paying stocks. We present a new integral equation to determine the price of an American call option and its free boundary using modified Mellin transforms. We also show how to derive the pricing formula for perpetual American call options using the new framework. A recovery of a result due to Kim (1990) regarding the optimal exercise price at expiry is also presented. Finally, we apply Gauss-Laguerre quadrature for the purpose of an efficient and accurate numerical valuation.

Keywords: Modified Mellin transform, American call option, Integral representation.

JEL Classification: G13
Mathematics Subject Classification (2000): 44A15, 60H30

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1 Introduction

Analytical pricing of European-style derivatives has been made possible by the seminal results of Black and Scholes (1973) and Merton (1973). However, many of today’s most common derivatives are American-style and are therefore subject to early exercise. The main difficulty in valuing these derivatives analytically is the presence of the early exercise boundary that specifies the conditions under which the contract should be exercised optimally prior to maturity. The optimal exercise policy is not known ex ante and must be determined simultaneously as part of the underlying valuation problem. This fact makes the pricing and hedging of American-style derivatives interesting and challenging.

Besides a great literature on numerical methods based on either finite differences, binomial trees or simulation techniques (see for example Brennan and Schwartz (1978), Cox et al. (1979), Boyle et al. (1997), Broadie and Glasserman (1997) or Longstaff and Schwartz (2001)) two main categories of analytical pricing approaches can be specified. These pricing approaches can be used to derive several but mathematically equivalent formulations of the American option pricing problem.

The first method, similar to the solution of the Stefan’s problem from physics, expresses the price of the American option as the solution of a partial differential equation (PDE). The PDE formulation goes back to Merton (1973) who first gives an economic interpretation although McKean (1965) presents a first solution of the free boundary problem in form of an integral expression. Many alternative methods based on the PDE approach were proposed for the purpose of pricing the American option and the free boundary by approximation. These methods include the works of Barone-Adesi and Whaley (1987), Geske and Johnson (1984), Bunch and Johnson (1992), Allegretto et al. (1995) or Ju and Zhong (1999) among others.

The second set of methods comes from probability theory. It focuses on
expressing the current price of an American option as a discounted expectation of the specific option’s pay-off under the risk-neutral measure. This optimal stopping characterization is perhaps the most intuitive description of the problem. A complete formulation goes back to Bensoussan (1984) and Karatzas (1988). See also Myneni (1992) for a reference.

At the beginning of the 1990s a breakthrough was achieved by characterizing the American option as the corresponding European option and the early exercise premium. These integral representations due to Kim (1990), Jacka (1991), and Carr et al. (1992) are exact solutions and were the starting point to derive new approximations for the American option price and/or the free boundary. Huang et al. (1996) for example use Richardson extrapolation to solve the integral expression. Ju (1998) approximates the early exercise boundary by a piece-wise exponential function and Bunch and Johnson (2000) derive new expressions for the early exercise boundary using a new characterization of the option’s price in terms of its time derivative.


The purpose of this article is to extend the works of Panini and Srivastav (2004) and Frontczak and Schöbel (2008) and develop a new method for characterizing American call option prices and exercise boundaries using a modified version of the Mellin transform. The extension is non-trivial in the sense that the original Mellin transform will not work for call options due to convergence problems.

The rest of the paper is organized as follows. In Section 2 we develop a pric-
ing formula for European call options to demonstrate the new framework. In a second step the formula will be used to decompose the American call into the early exercise premium and its European counterpart. This is done in Section 3. Here we present a new integral representation of the American call option and its free boundary. Section 4 is devoted to further analysis and applications. We show how to use the new framework to derive the valuation formula for perpetual American call options on dividend-paying stocks. Theoretical results due to Kim (1990) regarding the optimal exercise price at expiry are also recovered. In Section 5 we make some numerical experiments. More precisely, we apply Gauss-Laguerre quadrature for the purpose of valuation of American call options and compare our results to other existing approaches. Section 5 concludes.

2 The European Call Option

In a first step we develop a valuation formula for European call options which will be used in the next section to decompose the American call price. In our economy the dynamics of the asset price \( S_t, t \in [0, T] \), are given by the stochastic differential equation (SDE):

\[
dS_t = (r - q) S_t \, dt + \sigma S_t \, dW_t,
\]

with initial value \( S_0 \in (0, \infty) \), and where \( r \) is the riskless interest rate, \( q \) is the dividend yield, \( \sigma > 0 \) is the volatility, and \( W_t \) is a one-dimensional Brownian motion.

A European call option is an option that can be only exercised at maturity and has a linear payoff given by the difference between the terminal asset price and the strike price of the option

\[
C^E(S,T) = \max(S(T) - X, 0).
\]
Standard arbitrage arguments show that any derivative \( V = V(S,t) \) written
on \( S \) must satisfy the partial differential equation (PDE) (see for example
Wilmott et al. (1993)):

\[
\frac{\partial V}{\partial t} + (r - q)S \frac{\partial V}{\partial S} + \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} - rV = 0. \tag{2.3}
\]

This is the fundamental PDE due to Black/Scholes and Merton whose solutions depend on boundary and terminal conditions. If \( V \) is a European call option, i.e. \( V(S,t) = C^E(S,t) \), we have the conditions

\[
\lim_{S\to\infty} C^E(S,t) = \infty \quad \text{on } [0,T), \tag{2.4}
\]

\[
C^E(S,T) = \theta(S) = \max(S(T) - X, 0) \quad \text{on } [0,\infty), \tag{2.5}
\]

and

\[
C^E(0,t) = 0 \quad \text{on } [0,T). \tag{2.6}
\]

The celebrated solution is known as the (extended) Black-Scholes-Merton valuation formula and is given by

\[
C^E(S,t) = Se^{-q(T-t)}N(d_1(S,X,T-t)) - Xe^{-r(T-t)}N(d_2(S,X,T-t)) \tag{2.7}
\]

where

\[
d_1(S,X,T-t) = \frac{\ln \frac{S}{X} + (r - q + \frac{1}{2} \sigma^2)(T-t)}{\sigma \sqrt{T-t}}, \tag{2.8}
\]

\[
d_2(S,X,T-t) = d_1(S,X,T-t) - \sigma \sqrt{T-t}, \tag{2.9}
\]

and \( N(x) \) denotes the cumulative standard normal distribution function at
the point \( x \).

The objective of this section is to derive a valuation formula for European call options using Mellin transform techniques. Recall that for a locally Lebesgue integrable function \( f(x) \) defined over positive reals the Mellin transform \( M(f(x),\omega) \) is defined by the equation

\[
M(f(x),\omega) := \tilde{f}(\omega) = \int_{0}^{\infty} f(x) x^{\omega-1} dx.
\]

4
The Mellin transform is a complex valued function defined on a vertical strip in the ω-plane, whose boundaries are determined by the asymptotic behavior of \( f(x) \) as \( x \to 0^+ \) and \( x \to \infty \). The largest strip \((a, b)\) in which the integral converges is called the fundamental strip. The conditions
\[
f(x) = O(x^u) \quad \text{for} \quad x \to 0^+
\]
and
\[
f(x) = O(x^v) \quad \text{for} \quad x \to \infty
\]
when \( u > v \), guarantee the existence of \( M(f(x), \omega) \) in the strip \((-u, -v)\). Thus, the existence is granted for locally integrable functions, whose exponent of the order at 0 is strictly larger than the exponent of the order at infinity. Conversely, if \( f(x) \) is an integrable function with fundamental strip \((a, b)\), then if \( c \) is such that \( a < c < b \) and \( f(c + it) \) is integrable, the equality
\[
f(x) = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \tilde{f}(\omega) x^{-\omega} d\omega
\]
holds almost everywhere. Moreover, if \( f(x) \) is continuous, then the equality holds everywhere on \((0, \infty)\). For a proof see for example Titchmarsh (1986) or Sneddon (1972). The functions \( f(x) \) and \( \tilde{f}(\omega) \) are called a Mellin transform pair. Now, observe that since
\[
C^E(S, t) = O(1) \quad \text{for} \quad S \to 0^+
\]
and
\[
C^E(S, t) = O(S) \quad \text{for} \quad S \to \infty
\]
the Mellin transform for call options does not exist since the integral does not converge. Therefore we propose the modified Mellin transform for call options defined by
\[
M(C^E(S, t), -\omega) = \tilde{C}^E(\omega, t) := \int_0^\infty C^E(S, t) S^{-\omega-1} dS, \quad (2.10)
\]
where $1 < Re(\omega) < \infty$. Conversely, the inverse of the modified Mellin transform is given by

$$C^E(S, t) = M^{-1}(\tilde{C}^E(\omega, t)) = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \tilde{C}^E(\omega, t) S^\omega d\omega,$$

(2.11)

with $1 < c < \infty$.

Applying the modified Mellin transform to PDE (2.3) gives

$$\frac{\partial \tilde{C}^E(\omega, t)}{\partial t} + \frac{1}{2} \sigma^2 Q(\omega) \tilde{C}^E(\omega, t) = 0$$

(2.12)

where

$$Q(\omega) = \omega^2 - \omega(1 - \kappa_2) - \kappa_1,$$

(2.13)

and $\kappa_1 = \frac{2r}{\sigma^2}$ and $\kappa_2 = \frac{2(r-q)}{\sigma^2}$. The general solution of this ODE is given by

$$\tilde{C}^E(\omega, t) = c(\omega) \cdot e^{-\frac{1}{2} \sigma^2 Q(\omega)t}$$

(2.14)

where $c(\omega)$ a constant depending on the boundary conditions. Now, the terminal condition gives

$$c(\omega) = \tilde{\theta}(\omega, t) \cdot e^{\frac{1}{2} \sigma^2 Q(\omega)T}$$

(2.15)

where

$$\tilde{\theta}(\omega, t) = \tilde{\theta}(\omega) = X^{-\omega+1}\left(\frac{1}{\omega-1} - \frac{1}{\omega}\right)$$

(2.16)

is the modified Mellin transform of the terminal condition (2.5). Finally, using (2.11), we see that the price of a European call option equals

$$C^E(S, t) = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \tilde{C}^E(\omega, t) S^\omega d\omega$$

$$= \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \tilde{\theta}(\omega, t) \cdot e^{\frac{1}{2} \sigma^2 Q(\omega)(T-t)} S^\omega d\omega$$

(2.17)

with $(S, t) \in (0, \infty) \times [0, T)$, $c \in (1, \infty)$ a constant, $\{\omega \in \mathbb{C} \mid 1 < Re(\omega) < \infty\}$, and $\tilde{\theta}(\omega, t)$ and $Q(\omega)$ as defined in equations (2.16) and (2.13), respectively. The next proposition summarizes the results and gives the connection to the BSM-formula.
Proposition 2.1 Equations (2.17) and (2.7) are equivalent.

Proof: First, using (2.16), observe that

\[ C^E(S, t) = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} S\left(\frac{S}{X}\right)^{\omega-1} \frac{1}{\omega-1} e^{\frac{1}{2}\sigma^2 Q(\omega)(T-t)} d\omega \]

\[ -\frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} X\left(\frac{S}{X}\right)^{\omega} \frac{1}{\omega} e^{\frac{1}{2}\sigma^2 Q(\omega)(T-t)} d\omega. \]

Now write \( \omega = c + iy, 1 < c < \infty \) and \( \zeta = \frac{1}{2}\sigma^2(T-t) \) to get

\[ C^E(S, t) = I_1(S, X, T-t) - I_2(S, X, T-t), \]

with

\[ I_1(S, X, T-t) = S e^{-r(T-t) + \zeta c^2 + c(\alpha - 2\zeta)} - \ln(S/X) \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{c-1-iy}{(c-1)^2 + y^2} e^{-\zeta y^2 + iy\alpha} dy, \]

where we have set \( \alpha = \ln\left(\frac{S}{X}\right) + \zeta(2c + \kappa_2 - 1). \)

Similarly,

\[ I_2(S, X, T-t) = X e^{-r(T-t) + \zeta c^2 + c(\alpha - 2\zeta)} \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{c-iy}{c^2 + y^2} e^{-\zeta y^2 + iy\alpha} dy. \]

Using Euler’s theorem for the complex valued exponential function \( e^{ix} = \cos(x) + i\sin(x) \) we can simplify further and get

\[ I_1(S, X, T-t) = X e^{-r(T-t) + \zeta c^2 + c(\alpha - 2\zeta)} \frac{1}{\pi} \int_{0}^{\infty} e^{-\zeta y^2 (c-1)} \cos(\alpha y) + y \sin(\alpha y) \frac{(c-1)^2 + y^2}{(c-1)^2 + y^2} dy, \]

and

\[ I_2(S, X, T-t) = r X e^{-r(T-t) + \zeta c^2 + c(\alpha - 2\zeta)} \frac{1}{\pi} \int_{0}^{\infty} e^{-\zeta y^2} \frac{c \cos(\alpha y) + y \sin(\alpha y)}{c^2 + y^2} dy, \]

where we have used that \( \cos(x) \) and \( \sin(x) \) are even and odd functions, respectively. From Gradshteyn and Ryzhik (2007), p.504 we have: For \( a > 0, \ Re(\beta) > 0, \) and \( Re(\gamma) > 0: \)

\[ \int_{0}^{\infty} e^{-\beta x^2} \sin(ax) \frac{x}{\gamma^2 + x^2} dx = -\frac{\pi}{4} e^{\beta a^2} \left[ 2\sin a\gamma + e^{-\gamma^2} \Phi\left(\gamma \sqrt{\beta} - \frac{a}{2\sqrt{\beta}}\right) - e^{-\gamma^2} \Phi\left(\gamma \sqrt{\beta} + \frac{a}{2\sqrt{\beta}}\right) \right] \quad (2.18) \]
\[ \int_0^\infty e^{-\beta x^2} \cos(ax) \frac{dx}{\gamma^2 + x^2} = \frac{\pi}{4\gamma} e^{\beta \gamma^2} \left[ 2 \cosh a \gamma - e^{-\gamma \alpha} \Phi \left( \gamma \sqrt{\beta} - \frac{a}{2\sqrt{\beta}} \right) - e^{-\gamma \alpha} \Phi \left( \gamma \sqrt{\beta} + \frac{a}{2\sqrt{\beta}} \right) \right] \] (2.19)

where \( \Phi(x) \) is the error function defined by

\[ \Phi(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} \, dt. \]

Inserting \( \beta = \zeta, a = \alpha, \gamma = c - 1 \) and \( \gamma = c \), respectively, and simplifying yields to

\[ I_1(S, X, T - t) = X e^{-r(T-t)+2\alpha+2(c-2\alpha \zeta)} \frac{1}{2} e^{c(c-1)^2} \left( \cosh((c-1)\alpha) - \sinh((c-1)\alpha) - e^{-(c-1)\alpha} \Phi \left( (c-1)\sqrt{\zeta} - \frac{\alpha}{2\sqrt{\zeta}} \right) \right) \]

\[ = X e^{-r(T-t)+2\alpha+2(c-2\alpha \zeta)} e^{c(c-1)^2-2(c-1)\alpha} \frac{1}{2} \left( 1 - \Phi \left( (c-1)\sqrt{\zeta} - \frac{\alpha}{2\sqrt{\zeta}} \right) \right), \]

where in the last step we have used the relation \( \cosh(x) - \sinh(x) = e^{-x} \). In the same manner we obtain for \( I_2(S, X, T - t) \)

\[ I_2(S, X, T - t) = rX e^{-r(T-t)+2\alpha+2(c-2\alpha \zeta)} e^{c(c-1)^2-2(c-1)\alpha} \frac{1}{2} \left( 1 - \Phi \left( c\sqrt{\zeta} - \frac{\alpha}{2\sqrt{\zeta}} \right) \right). \]

Now, the exponentials can be simplified further to get

\[ I_1(S, X, T - t) = S e^{-q(T-t)} \frac{1}{2} \left( 1 - \Phi \left( (c-1)\sqrt{\zeta} - \frac{\alpha}{2\sqrt{\zeta}} \right) \right), \]

and

\[ I_2(S, X, T - t) = r X e^{-r(T-t)} \frac{1}{2} \left( 1 - \Phi \left( c\sqrt{\zeta} - \frac{\alpha}{2\sqrt{\zeta}} \right) \right). \]

The final step in our proof is to use the connection between the error function \( \Phi(x) \) and the normal distribution function \( N(x) \) given by the relation

\[ \Phi(x) = 2N(\sqrt{2}x) - 1, \]
and observing that
\[
\frac{\alpha}{\sqrt{2\zeta}} - (c - 1)\sqrt{2\zeta} = \frac{\ln \left( \frac{S}{\bar{X}} \right) + \zeta(\kappa_2 + 1)}{\sigma\sqrt{T - t}} = d_1(S, X, T - t),
\]
and
\[
\frac{\alpha}{\sqrt{2\zeta}} - c\sqrt{2\zeta} = \frac{\ln \left( \frac{S}{\bar{X}} \right) + \zeta(\kappa_2 - 1)}{\sigma\sqrt{T - t}} = d_2(S, X, T - t).
\]
This completes the proof. \(\square\)

3 The American Call Option

The main difference between European and American options is that an American option can be exercised by its holder at any time before and including expiry. This early exercise feature makes the pricing (and hedging) of American-styled derivatives mathematically more complex, and became a prominent problem in finance and applied mathematics throughout the last thirty years. Nevertheless, analytical closed-form solutions turned out to be rare except in very few cases. For instance, the perpetual American put option problem was separately solved by McKean (1965) and Merton (1973). Samuelson (1965) derived a closed-form expression for the perpetual American warrant. McKean (1965) presented a first solution to the free boundary problem inherent in American option pricing. His form is a valid mathematical representation, however, it allows no economic interpretation for the early exercise premium. Merton (1973) also showed that the American call option on a non-dividend paying stock equals its European counterpart, since the privilege of early exercise is worthless.

The pricing of American options can be seen under several mathematical aspects, leading to different but equivalent mathematical formulations of the problem. The most prominent are

- Optimal stopping formulation
• Free boundary formulation
• Integral equation formulation
• Linear complementarity formulation
• Primal-dual formulation
• Viscosity solution formulation.

For a detailed survey of the different formulations the reader is referred to Firth (2005). As indicated above, the early exercise feature creates a free boundary problem. The free boundary is given by the critical stock price \( S^*(t) \) which specifies the conditions under which the option should be exercised prematurely. Formally, it can be defined as an optimal solution of a problem of first passage through a boundary, see for example Bunch and Johnson (2000). The set of critical stock prices is a function of time and separates the domain \((0, \infty) \times [0, T]\) into a continuation region and an exercise region. At any time \( t \in [0, T] \) it is optimal to exercise the option prematurely and receive the payoff \( S(t) - X \) if \( S^*(t) \leq S(t) < \infty \). On the other hand, it is optimal to hold the option if \( 0 < S(t) < S^*(t) \). Then the option price is the solution to the fundamental BSM PDE from (2.3). Following Kwok (1998) we extend the domain of the PDE by setting \( C^A(S, t) = S(t) - X \) for \( S^*(t) \leq S(t) < \infty \). Then \( C^A = C^A(S, t) \) satisfies the non-homogeneous PDE:

\[
\frac{\partial C^A}{\partial t} + (r - q) S \frac{\partial C^A}{\partial S} + \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 C^A}{\partial S^2} - r C^A = f
\]  

(3.1)

with

\[
f = f(S, t) = \begin{cases} 
  rX - qS, & \text{if } S^*(t) \leq S(t) < \infty \\
  0, & \text{if } 0 < S(t) < S^*(t)
\end{cases}
\]  

(3.2)

on \((0, \infty) \times [0, T]\). Furthermore, we have the boundary conditions

\[
\lim_{S \to \infty} C^A(S, t) = \infty \quad \text{on} \quad [0, T),
\]  

(3.3)
\[ C^A(S, T) = \theta(S) = \max(S(T) - X, 0) \quad \text{on} \quad [0, \infty) \quad (3.4) \]

and
\[ C^A(0, t) = 0 \quad \text{on} \quad [0, T). \quad (3.5) \]

Arbitrage arguments show that the option’s price must also satisfy the ”smooth pasting conditions” at \( S^*(t) \) (see Wilmott et al. (1993)):
\[ C^A(S^*, t) = S^*(t) - X \quad \text{and} \quad \frac{\partial C^A}{\partial S} \bigg|_{S(t) = S^*(t)} = 1. \quad (3.6) \]

The modified Mellin transform of (3.1) is given by
\[ \frac{\partial \tilde{C}^A(\omega, t)}{\partial t} + \frac{1}{2} \sigma^2 Q(\omega) \tilde{C}^A(\omega, t) = \tilde{f}(\omega, t) \quad (3.7) \]

where
\[ \tilde{f}(\omega, t) = \frac{rX}{\omega} (S^*(t))^{-\omega} - \frac{q}{\omega - 1} (S^*(t))^{-\omega+1}, \quad (3.8) \]

and \( Q(\omega) \) is defined in equation (2.13). The general solution to this non-homogeneous ODE is given by

\[ \tilde{C}^A(\omega, t) = c(\omega) e^{-\frac{1}{2} \sigma^2 Q(\omega)t} - \int_t^T \tilde{f}(\omega, t) e^{\frac{1}{2} \sigma^2 Q(\omega)(x-t)} \, dx \]
\[ = \tilde{\theta}(\omega) e^{\frac{1}{2} \sigma^2 Q(\omega)(T-t)} \]
\[ + \int_t^T \frac{q}{\omega - 1} (S^*(x))^{-\omega+1} e^{\frac{1}{2} \sigma^2 Q(\omega)(x-t)} \, dx \]
\[ - \int_t^T \frac{rX}{\omega} (S^*(x))^{-\omega} e^{\frac{1}{2} \sigma^2 Q(\omega)(x-t)} \, dx, \]

where \( Q(\omega) \) is defined in equation (2.13) and \( \tilde{\theta}(\omega) \) is the terminal condition given in equation (2.16). Once again, the application of the modified Mellin inversion yields

\[ C^A(S, t) = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \tilde{\theta}(\omega) \cdot e^{\frac{1}{2} \sigma^2 Q(\omega)(T-t)} S^\omega \, d\omega \]
\[ + \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \int_t^T \frac{qS^*}{\omega - 1} \left( \frac{S}{S^*(x)} \right)^\omega e^{\frac{1}{2} \sigma^2 Q(\omega)(x-t)} \, dx \, d\omega \]
\[ - \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \int_t^T \frac{rX}{\omega} \left( \frac{S}{S^*(x)} \right)^\omega e^{\frac{1}{2} \sigma^2 Q(\omega)(x-t)} \, dx \, d\omega. \quad (3.9) \]
Notice that the first term in equation (3.9) is the European call price from (2.17) and the last two terms capture the early exercise premium. Therefore, we finally arrive at the new integral representation

\[
C_A(S, t) = C_E(S, t) + \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \int_t^T \frac{qS^*(x)}{\omega - 1} \left( \frac{S}{S^*(x)} \right)^\omega e^{\frac{1}{2}\sigma^2Q(\omega)(x-t)} \, dx \, d\omega \\
- \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \int_t^T \frac{rX}{\omega} \left( \frac{S}{S^*(x)} \right)^\omega e^{\frac{1}{2}\sigma^2Q(\omega)(x-t)} \, dx \, d\omega.
\]

(3.10)

where \((S, t) \in (0, \infty) \times [0, T), c \in (1, \infty), \{\omega \in \mathbb{C} | 1 < Re(\omega) < \infty\}, \) and

\[
Q(\omega) = \omega^2 - \omega(1 - \kappa_2) - \kappa_1
\]

with \(\kappa_1 = \frac{2r}{\sigma^2}\) and \(\kappa_2 = \frac{2(r-q)}{\sigma^2}\). The free boundary is given by

\[
S^*(t) - X = C_E(S^*(t), t) + \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \int_t^T \frac{qS^*(x)}{\omega - 1} \left( \frac{S^*(t)}{S^*(x)} \right)^\omega e^{\frac{1}{2}\sigma^2Q(\omega)(x-t)} \, dx \, d\omega \\
- \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \int_t^T \frac{rX}{\omega} \left( \frac{S^*(t)}{S^*(x)} \right)^\omega e^{\frac{1}{2}\sigma^2Q(\omega)(x-t)} \, dx \, d\omega.
\]

(3.11)

It is pointed out that equation (3.10) is equivalent to the early exercise representation due to Kim (1990)\(^1\). More explicitly, we prove the following proposition.

**Proposition 3.1** Equation (3.10) is equivalent to the following integral rep-
presentation derived by Kim (1990)

\[ C_A(S, \tau) = C_E(S, \tau) \]
\[ + \int_0^\tau qS e^{-q(\tau-\xi)} N(d_1(S, S^*(\xi), \tau - \xi)) d\xi \]
\[ - \int_0^\tau rX e^{-r(\tau-\xi)} N(d_2(S, S^*(\xi), \tau - \xi)) d\xi \]  
(3.12)

where \( \tau = T - t, S = S(\tau), S \leq S^*(\tau), \) and

\[ d_1(x, y, t) = \frac{\ln \frac{x}{y} + (r - q - \frac{1}{2} \sigma^2)t}{\sigma \sqrt{t}}, \]
\[ d_2(x, y, t) = d_1(x, y, t) - \sigma \sqrt{t}. \]

Proof: A direct proof of the equivalence is very similar to that one presented in the previous section so we just give the main idea. First we use \( \tau = T - t \) and \( \xi = \tau - x \) and write for the American call price in (3.10)

\[ C_A(S, \tau) = C_E(S, \tau) + \int_0^\tau I_1(\xi) d\xi - \int_0^\tau I_2(\xi) d\xi, \]  
(3.13)

with

\[ I_1(\xi) = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \frac{qS^*(\tau - \xi)}{\omega - 1} \omega e^{\frac{1}{2} \sigma^2 \xi d\omega} \]  
(3.14)

and

\[ I_2(\xi) = \frac{rX}{2\pi i} \int_{c-i\infty}^{c+i\infty} \frac{1}{\omega} \left( \frac{S(\tau)}{S^*(\tau - \xi)} \right) \omega e^{\frac{1}{2} \sigma^2 \xi d\omega}. \]  
(3.15)

Now, with \( \omega = c + iy, 1 < c < \infty \) and \( \zeta = \frac{1}{2} \sigma^2 \xi \) we have

\[ I_1(\xi) = qS^*(\tau - \xi) e^{-\xi \zeta + \alpha} \left( \frac{c - 1 - i\zeta}{(c - 1)^2 + \zeta^2} \right) \right) e^{-\zeta^2 + i\alpha} dy, \]  
(3.16)

where we have set

\[ \alpha = \ln \left( \frac{S(\tau)}{S^*(\tau - \xi)} \right) + \zeta(2c + \kappa_2 - 1). \]  
(3.17)
Similarly,

\[ I_2(\xi) = rXe^{-r\xi+c^2+c(\alpha-2\zeta_2)} \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{c-iy}{c^2+y^2} e^{-\zeta y^2+iy\alpha} dy. \] (3.18)

From now on the argumentation goes along the same lines as in the proof from the previous section and straightforward calculations establish the result. □

4 Further Analysis and Applications

In this section we extend our analysis of the new integral representation for the American call option and its free boundary. As special cases of equations (3.10) and (3.11), respectively, we recover theoretical properties of the option’s price and the early exercise boundary using the new approach. First we consider the infinite living American call option. We derive the closed-form (and well-known) expressions for the free boundary and the price of the option. Next, we show how the new framework can be used to recover a result derived by Kim (1990) regarding the optimal exercise price of American call options at expiry.

Proposition 4.1 If \( T \to \infty \) the free boundary of the perpetual American call option is given by

\[ S^*_\infty = X \frac{\omega_1}{\omega_1 - 1}, \] (4.1)

where

\[ \omega_1 = \frac{1}{2} - \frac{\kappa_2}{2} + \frac{\sqrt{(1-\kappa_2)^2 + 4\kappa_1}}{2}, \] (4.2)

and the closed-form solution for the perpetual American call option equals

\[ C^A_{\infty}(S, t) = \left( \frac{S}{S^*_\infty} \right)^{\omega_1} (S^*_\infty - X). \] (4.3)

Proof: The roots of \( Q(\omega) \) defined in (2.13) are given by

\[ \omega_{1/2} = \frac{1}{2} - \frac{\kappa_2}{2} \pm \frac{\sqrt{(1-\kappa_2)^2 + 4\kappa_1}}{2}. \]
Thus, we have \( Q(\omega) = (\omega - \omega_1)(\omega - \omega_2) \) with \(-\kappa_1 \leq \omega_2 \leq 0\) and \(1 \leq \omega_1 < \infty\). The limiting cases \( \omega_1 = 1 \) and \( \omega_2 = -\kappa_1 \) are special roots for \( q = 0 \). We will determine the unknown critical stock price \( S^*(t) \) using the second smooth pasting condition from equation (3.6).

Notice, that for the valuation formula (3.10) to hold as \( T \to \infty \), it is necessary that \( \text{Re}(Q(\omega)) < 0 \), i.e. \( 1 < \text{Re}(\omega) < \omega_1 \).

Using the second smooth pasting condition we obtain as \( T \to \infty \)

\[
1 = \frac{\partial C^A}{\partial S} \bigg|_{S=S^*} = \frac{\partial C^E}{\partial S} \bigg|_{S=S^*} + \frac{\partial C_1}{\partial S} \bigg|_{S=S^*} + \frac{\partial C_2}{\partial S} \bigg|_{S=S^*} \tag{4.4}
\]

where the free boundary \( S^* = S_{\infty}^* \) is now independent of time, and \( C_1 \) and \( C_2 \) denote the second and third term in the valuation formula (3.10), respectively.

Now, the delta of a European call option on a dividend-paying stock is determined as

\[
\frac{\partial C^E}{\partial S} = e^{-q(T-t)} N(d_1(S,X,T - t))
\]

with \( d_1(S,X,T - t) \) given in equation (2.8). It follows\(^2\) that as \( T \to \infty \)

\[
\frac{\partial C^E}{\partial S} \bigg|_{S=S_{\infty}^*} \to 0.
\]

Now consider the \( C_1 \) term. The limit \( T \to \infty \) gives

\[
\frac{\partial C_1}{\partial S} = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \int_t^{\infty} \frac{q \omega}{\omega - 1} \left( \frac{S}{S_{\infty}^*} \right)^{-1} e^{\frac{1}{2} \sigma^2 Q(\omega)(x-t)} \, dx \, d\omega.
\]

Therefore

\[
\frac{\partial C_1}{\partial S} \bigg|_{S=S_{\infty}^*} = \frac{\kappa_2 - \kappa_1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \frac{\omega}{(\omega - 1)(\omega - \omega_1)(\omega - \omega_2)} \, d\omega. \tag{4.5}
\]

\(^2\)Observe that this is not true if \( q = 0 \). In this case we have

\[
\frac{\partial C^E}{\partial S} \bigg|_{S=S_{\infty}^*} \to 1.
\]
Similarly, the $C_2$ term is determined as
\[
\frac{\partial C_2}{\partial S} = -rX \int_{c-i\infty}^{c+i\infty} \int_t^\infty \frac{1}{S} \left( \frac{S}{S_\infty} \right)^\omega e^{\frac{1}{2}\sigma^2 Q(\omega)(x-t)} \, dx \, d\omega,
\]
and we have
\[
\left. \frac{\partial C_2}{\partial S} \right|_{S=S_\infty} = \kappa_1 \frac{X}{S_\infty} \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \frac{1}{(\omega - \omega_1)(\omega - \omega_2)} \, d\omega. \tag{4.6}
\]
An application of the residue theorem (see Freitag and Busam (2000)) gives
\[
\left. \frac{\partial C_1}{\partial S} \right|_{S=S_\infty} = (\kappa_2 - \kappa_1) \left( \frac{1}{(1 - \omega_1)(1 - \omega_2)} + \frac{\omega_2}{(\omega_2 - 1)(\omega_2 - \omega_1)} \right) \tag{4.7}
\]
and
\[
\left. \frac{\partial C_2}{\partial S} \right|_{S=S_\infty} = \kappa_1 \frac{X}{S_\infty} \frac{1}{(\omega_2 - \omega_1)}. \tag{4.8}
\]
Finally, we get for the critical stock price
\[
S_\infty^* = X \frac{\kappa_1}{\omega_2 + \kappa_1} = X \frac{\omega_1}{\omega_1 - 1}. \tag{4.9}
\]
Now, the perpetual American call can be expressed as
\[
C^A_\infty(S,t) = \frac{\kappa_2 - \kappa_1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \left( \frac{S}{S_\infty^*} \right)^\omega \frac{S_\infty^*}{(\omega - 1)(\omega - \omega_1)(\omega - \omega_2)} \, d\omega
+ \kappa_1 \frac{X}{2\pi i} \int_{c-i\infty}^{c+i\infty} \left( \frac{S}{S_\infty^*} \right)^\omega \frac{1}{\omega(\omega - \omega_1)(\omega - \omega_2)} \, d\omega.
\]
Another application of the residue theorem gives us the closed-form solution for the perpetual American call option:
\[
C^A_\infty(S,t) = \left( \frac{S}{S_\infty^*} \right)^{\omega_1} \frac{X}{\omega_1 - 1}
= \left( \frac{S}{S_\infty^*} \right)^{\omega_1} (S_\infty^* - X).
\]
This completes the proof. \qed

Remark 4.2 Observe that for $q = 0$ the critical stock price of the perpetual American call option becomes infinite and the $C^A_\infty(S,t) = S(t)$. 

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Next, we show that Kim’s (1990) result concerning the behavior of the free boundary at expiry is a special case of (3.11). The first part of the proof partially follows Chiarella et al. (2004).

**Proposition 4.3** If $t \to T$ it follows from equation (3.11) that

$$\lim_{t \to T} S^*(t) = \max \left( X, \frac{r}{q} X \right).$$

**Proof:** Change the time variable in (3.11), $\tau = T - t$, to obtain

$$S^*(\tau) - X = C^E(S^*(\tau), \tau)$$

$$+ \frac{1}{2\pi i} \int_0^\tau \int_{c-i\infty}^{c+i\infty} qS^*(x) \frac{S^*(\tau)}{S^*(x)} \frac{\omega}{\omega - 1} e^{\frac{1}{2} \omega^2 Q(\omega)(\tau-x)} d\omega dx$$

$$- \frac{1}{2\pi i} \int_0^\tau \int_{c-i\infty}^{c+i\infty} rX \frac{S^*(\tau)}{S^*(x)} \frac{\omega}{\omega - 1} e^{\frac{1}{2} \omega^2 Q(\omega)(\tau-x)} d\omega dx.$$ 

Straightforward manipulations give an implicit equation for $S^*(\tau)$:

$$\frac{S^*(\tau)}{X} = \frac{1 - e^{-r\tau} N(d_2(S^*(\tau), X, \tau)) - r \cdot I_1(\tau)}{1 - e^{-q\tau} N(d_1(S^*(\tau), X, \tau)) - q \cdot I_2(\tau)}$$

(4.11)

where

$$I_1(\tau) = \frac{1}{2\pi i} \int_0^\tau \int_{c-i\infty}^{c+i\infty} \frac{1}{\omega} \frac{S^*(\tau)}{S^*(x)} \frac{\omega}{\omega - 1} e^{\frac{1}{2} \omega^2 Q(\omega)(\tau-x)} d\omega dx$$

(4.12)

and

$$I_2(\tau) = \frac{1}{2\pi i} \int_0^\tau \int_{c-i\infty}^{c+i\infty} \frac{1}{\omega} \frac{S^*(\tau)}{S^*(x)} \frac{\omega - 1}{\omega - 1} e^{\frac{1}{2} \omega^2 Q(\omega)(\tau-x)} d\omega dx.$$ 

(4.13)

Notice first that the critical stock price satisfies $S^*(\tau) \geq X, \forall \tau > 0$. To find the value $S^*(0^+) = \lim_{\tau \to 0^+} S^*(\tau)$, in a first step we evaluate the limits involving $d_1$ and $d_2$. We have

$$\lim_{\tau \to 0^+} d_1(S^*(\tau), X, \tau) = \begin{cases} 0, & \text{for } S^*(0^+) = X \\ \infty, & \text{for } S^*(0^+) > X. \end{cases}$$
Similarly,

\[
\lim_{\tau \to 0^+} d_2(S^*(\tau), X, \tau) = \begin{cases} 
0, & \text{for } S^*(0^+) = X \\
\infty, & \text{for } S^*(0^+) > X.
\end{cases}
\]

If \(\lim_{\tau \to 0^+} S^*(\tau) = X\) we have

\[
\lim_{\tau \to 0^+} N(d_1(S^*(\tau), X, \tau)) = \lim_{\tau \to 0^+} N(d_2(S^*(\tau), X, \tau)) = \frac{1}{2}
\]

and

\[
\lim_{\tau \to 0^+} \frac{S^*(\tau)}{X} = \frac{1}{2} - r \lim_{\tau \to 0^+} I_1(\tau) - \frac{1}{2} - q \lim_{\tau \to 0^+} I_2(\tau).
\]

It is easily verified that both expressions \(I_1(\tau)\) and \(I_2(\tau)\) tend to zero as \(\tau \to 0^+\). As a result we have \(\lim_{\tau \to 0^+} S^*(\tau) = X\) being a possible solution.

In the second case where

\[
\lim_{\tau \to 0^+} S^*(\tau) > X,
\]

the implicit equation for \(S^*(\tau)\) reads

\[
\lim_{\tau \to 0^+} \frac{S^*(\tau)}{X} = \frac{r}{q} \cdot \lim_{\tau \to 0^+} \frac{I_1(\tau)}{I_2(\tau)}.
\]

But

\[
I_1(\tau) = \int_0^\tau \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \frac{1}{\omega} \left( \frac{S^*(\tau)}{S^*(x)} \right)^{\omega} e^{\frac{1}{2} \sigma^2 Q(\omega)(\tau-x)} d\omega dx
\]

and a simple application of the residue theorem (see for example Freitag and Busam (2000)) shows that the inner integral equals

\[
\frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \frac{1}{\omega} \left( \frac{S^*(\tau)}{S^*(x)} \right)^{\omega} e^{\frac{1}{2} \sigma^2 Q(\omega)(\tau-x)} d\omega = e^{-r(\tau-x)}
\]

and thus

\[
I_1(\tau) = \frac{1}{r} \left( 1 - e^{-r\tau} \right).
\]

In the same manner we apply the residue theorem to the second integral to get

\[
I_2(\tau) = \frac{1}{q} \left( 1 - e^{-q\tau} \right).
\]
Obviously, the above calculations can be used to prove the limits in the first case, i.e. for \( \lim_{\tau \to 0^+} S^*(\tau) = X \), as well. Putting the results together we arrive at

\[
\lim_{\tau \to 0^+} S^*(\tau) = \frac{r}{q} \cdot \lim_{\tau \to 0^+} \frac{1}{q} \left( 1 - e^{-r\tau} \right) = \lim_{\tau \to 0^+} \frac{1 - e^{-r\tau}}{1 - e^{-q\tau}}.
\]  

(4.18)

Now, use the rule of d’Hospital to establish the second assertion. Recalling that the result holds only when \( S^*(0^+) > X \), it follows that \( r > q \). Combining both results confirms Kim’s formula.

\[ \square \]

**Remark 4.4** We see that when the dividend yield \( q \) tends to zero the critical stock price becomes infinite and from equation (3.10) we observe that early exercise becomes worthless, i.e. for \( q = 0 \) the American call equals its European counterpart. This is a recovery of Merton’s (1973) result on American calls.

## 5 Numerical Experiments

In this section we show how to use Gauss-Laguerre quadrature for an efficient and accurate pricing of American call options. From (3.13), (3.16) and (3.18) we have

\[
C^A(S, \tau) = C^E(S, \tau) + \int_0^\tau I_1(\xi) d\xi - \int_0^\tau I_2(\xi) d\xi,
\]  

(5.1)

with

\[ I_1(\xi) = qS^*(\tau - \xi)e^{-r\xi - \zeta c^2 + co} \frac{1}{\pi} \int_0^\infty e^{-\zeta y^2} \frac{(c - 1) \cos(\alpha y) + y \sin(\alpha y)}{(c - 1)^2 + y^2} dy,
\]  

(5.2)

and

\[ I_2(\xi) = rXe^{-r\xi - \zeta c^2 + co} \frac{1}{\pi} \int_0^\infty e^{-\zeta y^2} \frac{c \cos(\alpha y) + y \sin(\alpha y)}{c^2 + y^2} dy,
\]  

(5.3)
where again we have set
\[ \alpha = \ln \left( \frac{S(\tau)}{S^*(\tau - \xi)} \right) + \zeta(2c + \kappa_2 - 1). \] (5.4)

From Gradshteyn and Ryzhik (2007), p.228 and p.229 we have:
\[
\int e^{ax} \sin(bx) \, dx = \frac{e^{ax}(a \sin(bx) - b \cos(bx))}{a^2 + b^2} \quad (5.5)
\]
and
\[
\int e^{ax} \cos(bx) \, dx = \frac{e^{ax}(a \cos(bx) + b \sin(bx))}{a^2 + b^2} \quad (5.6)
\]
so the equations for \( I_1(\xi) \) and \( I_2(\xi) \) become, respectively:
\[
I_1(\xi) = qS^*(\tau - \xi)e^{-r\xi - \zeta c^2 + \alpha} \frac{1}{\pi} \left( \int_0^\infty \int_0^\infty e^{-\zeta y^2} e^{-(c-1)x} \cos(\alpha y) \cos(xy) \, dy \, dx 
+ \int_0^\infty \int_0^\infty e^{-\zeta y^2} e^{-(c-1)x} \sin(\alpha y) \sin(xy) \, dy \, dx \right),
\]
and
\[
I_2(\xi) = rXe^{-r\xi - \zeta c^2 + \alpha} \frac{1}{\pi} \left( \int_0^\infty \int_0^\infty e^{-\zeta y^2} e^{-cx} \cos(\alpha y) \cos(xy) \, dy \, dx 
+ \int_0^\infty \int_0^\infty e^{-\zeta y^2} e^{-cx} \sin(\alpha y) \sin(xy) \, dy \, dx \right).
\]
Now, we use product rules for the sine and cosine function, respectively,
\[
\sin(x) \sin(y) = \frac{1}{2} \left( \cos(x - y) - \cos(x + y) \right)
\]
\[
\cos(x) \cos(y) = \frac{1}{2} \left( \cos(x - y) + \cos(x + y) \right)
\]
to obtain
\[
I_1(\xi) = A_1 \frac{1}{\pi} \left( \int_0^\infty \frac{1}{2} e^{-(c-1)x} \int_0^\infty e^{-\zeta y^2} \left( \cos(y(\alpha - x)) + \cos(y(\alpha + x)) \right) \, dy \, dx 
+ \int_0^\infty \frac{1}{2} e^{-(c-1)x} \int_0^\infty e^{-\zeta y^2} \left( \cos(y(\alpha - x)) - \cos(y(\alpha + x)) \right) \, dy \, dx \right),
\]
20
\[ I_2(\xi) = A_2 \frac{1}{\pi} \left( \int_0^\infty \frac{1}{2} e^{-cx} \int_0^\infty e^{-\xi y^2} \left( \cos(y(\alpha - x)) + \cos(y(\alpha + x)) \right) dy dx \right. \\
+ \left. \int_0^\infty \frac{1}{2} e^{-cx} \int_0^\infty e^{-\xi y^2} \left( \cos(y(\alpha - x)) - \cos(y(\alpha + x)) \right) dy dx \right) \]

where we have set
\[ A_1 = qS^* (\tau - \xi) e^{-r\xi - \zeta c^2 + c\alpha} \]
and
\[ A_2 = rX e^{-r\xi - \zeta c^2 + c\alpha} . \]

Again, from Gradshteyn and Ryzhik (2007), p.488 we have for \( \text{Re} (\beta) > 0 \):
\[ \int_0^\infty e^{-\beta x^2} \cos(bx) \, dx = \frac{1}{2} \sqrt{\pi} \frac{e^{b^2/4\beta}}{\beta} , \] 
(5.7)
and the last equations for \( I_1 \) and \( I_2 \) can be simplified to
\[ I_1(\xi) = A_1 \frac{1}{2 \sqrt{\pi \xi}} \int_0^\infty e^{-(c-1)x} e^{-\frac{(\alpha-x)^2}{4\xi}} \, dx \] 
(5.8)
and
\[ I_2(\xi) = A_2 \frac{1}{2 \sqrt{\pi \xi}} \int_0^\infty e^{-cx} e^{-\frac{(\alpha-x)^2}{4\xi}} \, dx . \] 
(5.9)

Finally, observe that the last integrals can be approximated accurately using Gauss-Laguerre quadrature, i.e.
\[ \int_0^\infty e^{-(c-1)x} e^{-\frac{(\alpha-x)^2}{4\xi}} \, dx = \frac{1}{c-1} \int_0^\infty e^{-x} f \left( \frac{x}{c-1} \right) \, dx \] 
\[ \approx \frac{1}{c-1} \sum_{i=1}^n \omega_i f \left( \frac{x_i}{c-1} \right) , \] 
(5.10)
and
\[ \int_0^\infty e^{-cx} e^{-\frac{(\alpha-x)^2}{4\xi}} \, dx = \frac{1}{c} \int_0^\infty e^{-x} f \left( \frac{x}{c} \right) \, dx \] 
\[ \approx \frac{1}{c} \sum_{i=1}^n \omega_i f \left( \frac{x_i}{c} \right) , \] 
(5.11)
where \( f \) equals
\[
f(x) = e^{-(\alpha-x)^2} \quad (5.12)
\]
and \( \omega_i \) and \( x_i, i = 1, 2, \ldots n, \) correspond to the weights and abscissa of the Gauss-Laguerre quadrature. As a final result we have the following approximation for the American call option:
\[
C^A(S, \tau) = C^E(S, \tau) + \int_0^\tau I_1(\xi) \, d\xi - \int_0^\tau I_2(\xi) \, d\xi, \quad (5.13)
\]
with
\[
I_1(\xi) = qS^*(\tau - \xi)e^{-r\xi - \zeta c^2 + \alpha} \frac{1}{2(c-1)\sqrt{\pi\zeta}} \sum_{i=1}^n \omega_if\left(\frac{x_i}{c-1}\right) \quad (5.14)
\]
and
\[
I_2(\xi) = rXe^{-r\xi - \zeta c^2 + \alpha} \frac{1}{2c\sqrt{\pi\zeta}} \sum_{i=1}^n \omega_if\left(\frac{x_i}{c}\right), \quad (5.15)
\]
with \( 1 < c < \infty, \zeta = 1/2\sigma^2\xi, \) and \( \alpha \) and \( f \) given in equations (5.4) and (5.12), respectively. The weights \( \omega_i, i = 1, \ldots, n, \) are determined by
\[
\omega_i = \frac{1}{x_i(L_n'(x_i))^2} = \frac{1}{(n+1)^2(L_{n+1}(x_i))^2},
\]
with \( L_n(x) \) the n-th Laguerre polynomial defined by
\[
L_n(x) = \frac{e^x}{n!} \frac{d^n}{dx^n}(e^{-x}x^n).
\]
The integrals in equation (5.13) are determined using the trapezoidal rule. Additionally, in equation (5.13) we assume that the critical stock price \( S^*(\tau) \) is known for all \( \tau \). The calculation is performed using equation (3.11) where the complex integrals are approximated recursively using an n-point Gauss-Laguerre scheme and the time integral is evaluated using the trapezoidal rule.

As a specific numerical example, we value a six months American call option.
with strike price $X = 100$. The parameters $S$, $r$, $q$, and $\sigma$ are varied. For the valuation we use a 16-point Gauss-Laguerre scheme combined with a 300 time step approximation of the time integral. Furthermore we fix the parameter $c = 4$. The results are shown in Table 1 at the end of this article. We compare our results to nine other numerical and analytical approaches known in the literature. The numerical results show that our method provides accurate comparable prices and that the new framework can be regarded as a good alternative to existing methods.

6 Conclusion

We have extended a technique proposed by Panini and Srivastav (2004) and introduced a modified version of Mellin transforms for the purpose of valuing American call options. Using the new framework we have derived a new integral representation for European and American call options on dividend-paying stocks. To emphasize the generality of our results, we have shown the equivalence of the new integral representation and a classical integral characterization due to Kim (1990). Additionally, we have recovered important theoretical properties of American call options using the new method. Finally, we have proposed Gauss-Laguerre quadrature for an accurate pricing and showed that the numerical scheme is a good alternative to other approaches existing in the literature.

The analysis presented in this contribution is based on the Black/Scholes and Merton framework. The valuation formulas for the American call option and its free boundary may be used to derive new approximations of the option’s price and the free boundary. Also, the method can be extended to pricing more complex European- and American-styled derivatives. Extensions are also possible to other stochastic price processes, stochastic volatility models, and jump diffusions.
Table 1: This table provides American call option prices computed ten different ways: The "True" value is based on a binomial tree method with \(N = 10000\) time steps. The following columns represent the method proposed by Barone-Adesi and Whaley (1987) (BAW), the four-point method of Geske and Johnson (1984) (GJ4), the modified two-point Geske-Johnson approach of Bunch and Johnson (1992) (BJ2), the four-point schemes of Huang et al. (1996) (HSY4), the lower and upper bound approximation of Broadie and Detemple (1996) (LUBA), the four-point randomization method of Carr (1998) (RAN4), the three-point multi-piece exponential boundary approximation of Ju (1998) (EXP3), an approximation of Ju and Zhong (1999) (JZ), and the numerical procedure based on Gauss-Laguerre quadrature of this article, respectively.

<table>
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<tr>
<th>((S, r, q, \sigma))</th>
<th>True</th>
<th>BAW</th>
<th>GJ4</th>
<th>BJ2</th>
<th>HSY4</th>
<th>LUBA</th>
<th>RAN4</th>
<th>EXP3</th>
<th>JZ</th>
<th>GALA</th>
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<td>0.2194</td>
<td>0.2300</td>
<td>0.2191</td>
<td>0.2186</td>
<td>0.2199</td>
<td>0.2195</td>
<td>0.2188</td>
<td>0.2196</td>
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<td>0.2185</td>
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<tr>
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<td>1.4050</td>
<td>1.3849</td>
<td>1.3818</td>
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<td>1.3862</td>
<td>1.3802</td>
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<tr>
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<td>4.7821</td>
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