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Temporal interaction of information and belief

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Abstract
The temporal updating of an agent’s beliefs in response to a flow of information is modeled in a simple modal logic that, for every date \( t \), contains a normal belief operator \( B_t \) and a non-normal information operator \( I_t \) which is analogous to the ‘only knowing’ operator discussed in the computer science literature. Soundness and completeness of the logic are proved and the relationship between the proposed logic and the AGM theory of belief revision is discussed.

1 Introduction
Belief revision is a central topic in several fields. In game theory, belief revision is the main building block of two widely used solution concepts for dynamic (or extensive) games, namely perfect Bayesian equilibrium (see, for example, Battigalli [2], Bonanno [5] and Fudenberg and Tirole [9]) and sequential equilibrium (Kreps and Wilson [15]). The idea behind these solution concepts is that, during the play of the game, a player should revise his beliefs by using Bayes’ rule “as long as possible”. Thus if an information set has been reached that had positive prior probability, then beliefs at that information set are obtained by using Bayes’ rule (with the information being represented by the set of nodes in the information set under consideration). If an information set is reached that had zero prior probability, then new beliefs are formed more or less arbitrarily, but from that point onwards these new beliefs must be used in conjunction with Bayes’ rule, unless further information is received that is inconsistent with those revised beliefs. In computer science the theory of belief revision pioneered by Alchourron et al [1] (known as the AGM theory) has been studied extensively...
While in game theory beliefs are typically represented by a probability distribution over a set of states and belief revision is modeled in terms of Bayes’ rule, in the AGM theory beliefs are modeled syntactically as sets of formulas in a given language (called belief sets). Information is thought of as a formula in this language and belief revision is modeled as an operation that transforms a belief set into a new belief set that incorporates the information. Within the AGM tradition the issue of iterated belief revision has recently received considerable attention (see, for example, Nayak et al. [18]).

In this paper we propose a simple modal logic for iterated belief revision, extending the two-period framework of Bonanno [6]. For every date \( t \in \mathbb{N} \) (where \( \mathbb{N} \) is the set of natural numbers) we postulate a belief operator \( B_t \) and an information operator \( I_t \). The interaction of information and belief over time is captured by several axioms. We start with three simple axioms and show that the corresponding logic is sound and complete with respect to the class of Kripke structures that satisfy the iterative version of the qualitative content of Bayes’ rule. The addition of further axioms yields a logic which is sound and complete with respect to the class of structures that capture the basic postulates of the AGM theory. Finally, we show that a strengthening of this logic corresponds to the class of structures where any belief revision history can be rationalized in terms of a plausibility ordering of the set of states.

In the next section we begin with an example that illustrates the formal logic and structures analyzed in the remainder of the paper.

2 A motivating example

A doctor examines a patient who reports an outbreak of skin rashes. The patient claims not to have made any changes in his diet and gives the doctor a list of medications that he has been taking for a number of years. Based on her experience, the doctor narrows down the possible causes to four: bacterial infection (B), viral infection (V), allergic reaction to food (F) and allergic reaction to medication (M). An initial assessment of the case (Time 0) leads the doctor to believe that it is an infection. Since she knows of no effective treatment for a viral infection, she prescribes antibiotics. A few days later (Time 1) the patient reports that there has been no change in his symptoms. The doctor treats this report as information that it is not a case of bacterial infection and becomes convinced that it is a viral infection. She informs the patient that, unfortunately, there are no drugs that would be effective against a viral infection. The patient requests a blood test. A positive result would confirm the presence of an infection (which, however, could be either bacterial or viral), while a negative result would rule out an infection. The doctor yields to the patient’s request and a few days later (Time 2) the lab reports a negative result to the blood test. Based on this information, the doctor reaches the conclusion that the patient must have developed a sensitivity to one of the drugs and advises the patient to stop taking all his medications. A few days later (Time 3) the patient reports, once again, that there has been no change in his symptoms. The doctor then
concludes that it must be an allergic reaction to food and instructs the patient to keep a detailed food diary.

In this example the doctor’s beliefs evolve over time in response to information. The history of the doctor’s beliefs can be represented using a sequence of Kripke structures (Kripke [16]): the set of states or possible worlds is \( \Omega = \{B, V, M, F\} \) (where B denotes bacterial infection, V viral infection, M medication allergy and F food allergy) and at every date \( t \) the doctor’s beliefs can be represented by a binary relation \( B_t \) on \( \Omega \) as shown in Figure 1. In all the figures we represent a binary relation \( R \subseteq \Omega \times \Omega \) as follows: (1) if a rounded rectangle encloses a set of states then, for any two states \( \omega \) and \( \omega' \) in that rectangle, \( \omega R \omega' \) and (2) if there is an arrow from a state \( \omega \) to a rounded rectangle, then for any state \( \omega' \) in that rectangle, \( \omega R \omega' \). For example, in Figure 1 we have that \( B_0 = \{(B, B), (B, V), (V, B), (V, V), (M, B), (M, V), (F, B), (F, V)\} \), \( B_1 = \{(B, V), (V, V), (M, V), (F, V)\} \), etc.

![Figure 1](image_url)

**Figure 1**
The evolution of the doctor’s beliefs over time

Syntactically, let \( B_t \) be the belief operator at time \( t \), so that the interpretation of \( B_t \phi \) is “at time \( t \) the individual believes that \( \phi \)”. If \( \omega \) is a state and \( \phi \) a formula, we denote by \( \omega \models \phi \) the fact that \( \phi \) is true at state \( \omega \). The truth of the formula \( B_t \phi \) at state \( \omega \) is then determined as usual: \( \omega \models B_t \phi \) if and only, for every \( \omega' \) such that \( \omega B_t \omega' \), \( \omega' \models \phi \), that is, if \( \phi \) is true at every state that, at date \( t \), the individual considers possible at state \( \omega \). For example, if \( \phi \) is the proposition “the patient has an infection” then, in our example, it is true at -
and only at - states B and V. If the true state is M then at that state it is false that the patient has an infection and yet it is true that at date 0 the doctor believes that the patient has an infection ($M \models \neg \phi$ and $M \models B_0 \phi$).

Changes in the doctor’s beliefs are brought about by the receipt of new information. It would be desirable to represent the flow of information over time in the same way in which we represent beliefs, namely by means of a sequence of binary relations $I_t$ for every date $t$. We propose to model information in a way which is reminiscent of the notion of “only knowing” (Levesque [17]). Intuitively, we interpret “I am informed that $\phi$” as equivalent to “all I am told is $\phi$”. We can capture this interpretation of information by means of the following validation rule. Let $I_t$ be the time $t$ information operator, so that the interpretation of $I_t \phi$ is “at time $t$ the individual is informed that $\phi$”. Then we set $\omega \models I_t \phi$ if and only if two conditions hold: (1) for every $\omega'$ such that $\omega I_t \omega'$, $\omega' \models \phi$, and (2) for every $\omega' \in \Omega$, if $\omega' \models \phi$ then $\omega I_t \omega'$. That is, $I_t \phi$ is true at state $\omega$ if the set of states reachable from $\omega$ by means of the relation $I_t$ coincides with the truth set of $\phi$.\footnote{Thus our information operator plays the role of the conjunction of the two operators $K$ and $O$ proposed by Levesque [17] where $K \phi$ is interpreted as “the individual knows that $\phi$”, while $O \phi$ is interpreted as “the individual only knows that $\phi$”.
}

With this interpretation in mind, we can represent the flow of information received by the doctor by means of the sequence of binary relations depicted in Figure 2.

![Figure 2](image-url)

The doctor’s beliefs at time $t + 1$ are the result of the interaction between her beliefs at time $t$ and the information received at time $t + 1$. In our example, at time 0 the doctor believes that the patient has a (bacterial or viral) infection and at time 1 she is informed that the patient does not have a bacterial infection. Combining the two, the doctor modifies her beliefs and comes to the new belief that the patient has a viral infection. In a probabilistic setting, this new belief is what would be required by Bayes’ rule. The interaction of old beliefs and
new information in our example is shown in Figure 3, which puts together the structures of Figures 1 and 2.

![Diagram](image)

Figure 3
The interaction of beliefs and information over time

It is worth noting that, while the first piece of information received by the doctor ("it is not a bacterial infection") does not cause surprise — since it is compatible with the doctor’s initial belief (it could be a viral infection) — later pieces of information do cause surprise, since they contradict the doctor’s beliefs.

In the next section we propose a logic that is sound and complete with respect to the class of Kripke structures that satisfy the qualitative version of Bayes’ rule (the structure illustrated in Figure 3 belongs to this class). We then consider a strengthening of that logic, obtained by adding three hypotheses: that beliefs are consistent, that information is non-contradictory and that information is always believed (even when it contradicts current beliefs; the structure of Figure 3 satisfies all these hypotheses). We show that the individual’s belief revision over time satisfies the basic postulates of the AGM belief revision theory (see Alchourron et al [1]). Finally, we show that when information becomes more refined over time (so that every new piece of information implies earlier information, as is the case in the structure of Figure 3) the individual’s belief revision can be rationalized in terms of a plausibility ordering over the set of states: at every date the individual considers possible all and only those
states that are most plausible among the ones that are compatible with the new information received.

## 3 A logic for iterated belief revision

Let \( \mathbb{N} \) be the set of natural numbers. We consider a modal propositional logic based on the following operators: a belief operator \( B_t \) and an information operator \( I_t \), for every date \( t \in \mathbb{N} \), and a “global” operator\(^2\) \( A \). The intended interpretation is as follows:

- \( I_t \phi \): at time \( t \) all the individual is informed of is that \( \phi \)
- \( B_t \phi \): at time \( t \) (after revising his earlier beliefs in light of the information just received) the individual believes that \( \phi \)
- \( A \phi \): it is globally true that \( \phi \).

The formal language is built in the usual way from a countable set \( S \) of atomic propositions, the connectives \( \neg \) (for “not”) and \( \lor \) (for “or”) and the modal operators.\(^3\) Thus the set \( \Phi \) of formulas is defined inductively as follows: for every atomic proposition \( q \in S \), and if \( \phi, \psi \in \Phi \) then all of the following belong to \( \Phi \): \( \neg \phi, \phi \lor \psi, A\phi \) and, for every \( t \in \mathbb{N} \), \( B_t \phi \) and \( I_t \phi \).

We denote by \( \mathcal{L} \) the logic determined by the following axioms and rules of inference.

**AXIOMS:**

1. All propositional tautologies.

2. For every \( t \in \mathbb{N} \), axiom K for \( B_t \) and \( A \) (note the absence of an analogous axiom for \( I_t \)):

   \[
   \begin{align*}
   K_B & : B_t \phi \land B_t (\phi \rightarrow \psi) \rightarrow B_t \psi \\
   K_A & : A\phi \land A(\phi \rightarrow \psi) \rightarrow A\psi
   \end{align*}
   \]

3. S5 axioms for \( A \):

   \[
   \begin{align*}
   T_A & : A\phi \rightarrow \phi \\
   5_A & : \neg A\phi \rightarrow A\neg A\phi
   \end{align*}
   \]

4. For every \( t \in \mathbb{N} \), inclusion axiom for \( B_t \) (note the absence of an analogous axiom for \( I_t \)):

   \[
   \text{Incl. } A\phi \rightarrow B_t \phi
   \]

5. Axioms to capture the non-standard semantics for \( I \):

\[^2\]For a thorough discussion of the global (or universal) modality see Goranko and Passy [11].

\[^3\]See, for example, Blackburn et al [3]. The connectives \( \land \) (for “and”), \( \rightarrow \) (for “if ... then ...”) and \( \leftrightarrow \) (for “if and only if”) are defined as usual: \( \phi \land \psi = \neg (\neg \phi \lor \neg \psi) \), \( \phi \rightarrow \psi = \neg \phi \lor \psi \) and \( \phi \leftrightarrow \psi = (\phi \rightarrow \psi) \land (\psi \rightarrow \phi) \).
I_1. \((I_t \phi \land I_t \psi) \rightarrow A(\phi \leftrightarrow \psi)\)

I_2. \(A(\phi \leftrightarrow \psi) \rightarrow (I_t \phi \leftrightarrow I_t \psi)\)

RULES OF INFERENCE:

1. Modus Ponens: \(\frac{\phi, \phi \rightarrow \psi}{\psi}\) (MP)

2. Necessitation for A: \(\frac{\phi}{A\phi}\) (Nec_A)

On the semantic side, a frame is a collection \(\Omega, \{B_t\}_{t \in \mathbb{N}}, \{I_t\}_{t \in \mathbb{N}}\) where \(\Omega\) is a set of states and, for every \(t \in \mathbb{N}\), \(B_t\) and \(I_t\) are binary relations on \(\Omega\), whose interpretation is as follows:

\(\alpha B_t \beta\) at time \(t\) and state \(\alpha\) the individual considers state \(\beta\) possible
\(\alpha I_t \beta\) at state \(\alpha\), state \(\beta\) is compatible with the information received at time \(t\).

Let \(B_t(\omega) = \{\omega' \in \Omega : \omega B_t \omega'\}\) denote the set of states that, at date \(t\), the individual considers possible at state \(\omega\). Define \(I_t(\omega)\) similarly.

The connection between syntax and semantics is given by the notion of model. Given a frame \(\Omega, \{B_t\}_{t \in \mathbb{N}}, \{I_t\}_{t \in \mathbb{N}}\), a model is obtained by adding a valuation \(V : S \rightarrow 2^\Omega\) (where \(2^\Omega\) denotes the set of subsets of \(\Omega\), usually called events) which associates with every atomic proposition \(p \in S\) the set of states at which \(p\) is true.\(^4\) The truth of an arbitrary formula at a state is then defined inductively as follows (\(\omega \models \phi\) denotes that formula \(\phi\) is true at state \(\omega\); \(\|\phi\|\) is the truth set of \(\phi\), that is, \(\|\phi\| = \{\omega \in \Omega : \omega \models \phi\}\)):

- if \(q\) is an atomic proposition, \(\omega \models q\) if and only if \(\omega \in V(q)\),
- \(\omega \models \neg \phi\) if and only if \(\omega \notin \phi\),
- \(\omega \models \phi \lor \psi\) if and only if either \(\omega \models \phi\) or \(\omega \models \psi\) (or both),
- \(\omega \models B_t \phi\) if and only if \(B_t(\omega) \subseteq \|\phi\|\),
- \(\omega \models I_t \phi\) if and only if \(I_t(\omega) = \|\phi\|\),
- \(\omega \models A\phi\) if and only if \(\|\phi\| = \Omega\).

**Remark 1** Note that, while the truth condition for \(B_t \phi\) is the standard one, the truth condition of \(I_t \phi\) is unusual in that the requirement is \(I_t(\omega) = \|\phi\|\) rather than merely \(I_t(\omega) \subseteq \|\phi\|\). This is what establishes the similarity between our information operator and the “only knowing” operator discussed in the literature (see Levesque [17]).

\(^4\)Note that by making the truth of atomic propositions depend on the state only, rather than on the state and time, we restrict ourselves to situations of belief revision, where the objective state of the world does not change over time: only the epistemic state of the individual changes. The alternative case, where the truth of the atomic propositions is allowed to change over time, is known in the computer science literature as “belief update” (see Katsuno and Mendelzon [14]).
We say that a formula $\phi$ is valid in a model if $\omega \models \phi$ for all $\omega \in \Omega$, that is, if $\phi$ is true at every state. A formula $\phi$ is valid in a frame if it is valid in every model based on that frame. A logic is sound with respect to a class of frames if every theorem of the logic is valid in every frame in that class; it is complete with respect to a class of frames if every formula which is valid in every frame in that class is provable in the logic (that is, it is a theorem).

**Remark 2** Note that from (Nec$_A$) and (Incl) one obtains necessitation for $B_i$ as a derived rule of inference: $\frac{\Box \phi}{\Box \psi}$. Furthermore, from necessitation and axiom K one obtains the following derived rule of inference for both $A$ and $B_i$ (usually referred to as rule RK): $\frac{A \phi \rightarrow A \psi}{A \Box \phi \rightarrow A \Box \psi}$ and $\frac{B \phi \rightarrow B \psi}{B \Box \phi \rightarrow B \Box \psi}$. On the other hand, the necessitation rule for $I$ is not a rule of inference of logic $\mathfrak{L}$. Indeed necessitation for $I$ is not validity preserving; neither is rule RK for $I_i$. On the other hand, by Nec$_A$ and $I_2$, the following rule for $I_i$ (usually referred to as rule RE): $\frac{\Box \phi \rightarrow \Box \psi}{I_1 \phi \rightarrow I_1 \psi}$ is a derived rule of inference of $\mathfrak{L}$.

Note that, despite the non-standard validation rule, axiom K for $I_1$, namely $I_1 \phi \land I_1 (\phi \rightarrow \psi) \rightarrow I_1 \psi$, is trivially valid in every frame. It follows from the completeness part of Proposition 3 below that axiom K for $I_1$ ($I_1 \phi \land I_1 (\phi \rightarrow \psi) \rightarrow I_1 \psi$) is a theorem of logic $\mathfrak{L}$ (a syntactic proof is also easily obtained).

The following proposition is an extension of the two-period framework of Bonanno [6]. An outline of the proof is given in the Appendix.

**Proposition 3** Logic $\mathfrak{L}$ is sound and complete with respect to the class of all frames $\langle \Omega, \{B_i\}_{i \in \mathbb{N}}, \{I_i\}_{i \in \mathbb{N}} \rangle$.

We now consider extensions of logic $\mathfrak{L}$. The first extension, denoted by $\mathfrak{L}_{QBR}$, is obtained by adding to $\mathfrak{L}$ the following axioms:

- **Qualified Acceptance (QA):** $(-B_i \neg \phi \land I_{i+1} \phi) \rightarrow B_{i+1} \phi$
- **Persistence (P):** $(-B_i \neg \phi \land I_{i+1} \phi) \rightarrow (B_{i} \psi \rightarrow B_{i+1} \psi)$
- **Minimality (M):** $(I_{i+1} \phi \land B_{i+1} \psi) \rightarrow B_i (\phi \rightarrow \psi)$.

One of the axioms of the AGM theory of belief revision is the so-called Success or Acceptance axiom, which requires that information be believed, that is, that it be incorporated in the revised beliefs. Our Qualified Acceptance axiom...
is a weakening of this, in that it requires the individual who has been informed that $\phi$ to believe $\phi$ only if, before the receipt of information, he considered $\phi$ possible (that is, he did not believe $\neg \phi$). The Persistence axiom says that if the individual is informed of something that he previously considered possible, then he continues to believe everything that he believed before. Finally, the Minimality axiom states that beliefs should be revised in a minimal way, in the sense that no new beliefs should be added unless they are implied by the old beliefs and the information received.8

By **Qualitative Bayes Rule** (QBR) we mean the following property: $\forall \omega \in \Omega, \forall t \in \mathbb{N},$

$$\text{if } B_t(\omega) \cap I_{t+1}(\omega) \neq \emptyset \text{ then } B_{t+1}(\omega) = B_t(\omega) \cap I_{t+1}(\omega).$$

(QBR)

QBR says that if at a state the information received at time $t+1$ is compatible with the beliefs the individual had at time $t$, in the sense that there are states that he considered possible at date $t$ and are compatible with the information received at date $t+1$, then the states that are considered possible according to the revised beliefs at date $t+1$ are precisely those states. For example, the frame illustrated in Figure 3 of Section 2 satisfies QBR (vacuously after date 1).

In a probabilistic setting, let $P_{t,\omega}$ be the probability measure over $\Omega$ representing the individual’s beliefs at date $t$ and state $\omega$, let $F \subseteq \Omega$ be an event representing the information received by the individual at date $t+1$ and let $P_{t+1,\omega}$ be the posterior probability measure representing the revised beliefs at date $t+1$ and state $\omega$. Bayes’ rule says that, if $P_{t,\omega}(F) > 0$, then, for every event $E \subseteq \Omega$, $P_{t+1,\omega}(E) = \frac{P_{t,\omega}(E \cap F)}{P_{t,\omega}(F)}$. Bayes’ rule thus implies the following:

$$\text{if } \text{supp}(P_{t,\omega}) \cap F \neq \emptyset, \text{ then } \text{supp}(P_{t+1,\omega}) = \text{supp}(P_{t,\omega}) \cap F$$

where $\text{supp}(P)$ denotes the support of the probability measure $P$. If we set $B_t(\omega) = \text{supp}(P_{t,\omega})$, $F = I_{t+1}(\omega)$ and $B_{t+1}(\omega) = \text{supp}(P_{t+1,\omega})$ then we get the Qualitative Bayes Rule as stated above. Thus in a probabilistic setting the sentence “the individual believes $\phi$” would be interpreted as “the individual assigns probability 1 to the event $||\phi||$”.

The following proposition is an extension of the two-period framework of Bonanno [6]. An outline of the proof is given in the Appendix.

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8The Minimality axiom is trivially satisfied if information is surprising: suppose that at a state, say $\omega$, the individual at time $t+1$ is informed that $\phi$ ($\omega \models I_{t+1} \phi$) although he previously believed that $\phi$ was not the case ($\omega \models B_t \neg \phi$). Then, for every formula $\psi$, the formula ($\phi \rightarrow \psi$) is trivially true at every state that the individual considered possible at date $t$ and state $\omega$ ($B_t(\omega) \subseteq ||\phi \rightarrow \psi||$) and therefore he believed it ($\omega \models B_t(\phi \rightarrow \psi)$). Thus the axiom restricts the new beliefs only when the information received is not surprising, that is, only if $\omega \models \neg B_t \neg \phi \wedge B_{t+1} \phi$. 

Proposition 4 Logic $\mathcal{L}_{QBR}$ is sound and complete with respect to the class of frames $\langle \Omega, \{B_t\}_{t \in \mathbb{N}}, \{I_t\}_{t \in \mathbb{N}} \rangle$ that satisfy the Qualitative Bayes Rule.

We now consider stronger logics than $\mathcal{L}_{QBR}$. Let $\mathcal{L}_{AGM}$ be the logic obtained by adding to $\mathcal{L}$ the following axioms:

- **Acceptance or Success (A):**
  \[ (I_t \phi \land \neg A \neg \phi) \rightarrow B_t \phi \]
- **Persistence (P):**
  \[ (B_t \neg \phi \land I_{t+1} \phi) \rightarrow (B_t \psi \rightarrow B_{t+1} \psi) \]
- **Minimality (M):**
  \[ (I_{t+1} \phi \land B_{t+1} \psi) \rightarrow B_t (\phi \rightarrow \psi) \]
- **Consistency of beliefs ($D_B$):**
  \[ B_t \phi \rightarrow \neg B_t \neg \phi \]
- **Consistency of information ($C_I$):**
  \[ I_t \phi \rightarrow \neg A \neg \phi. \]

The Acceptance axiom says that if the agent is informed of $\phi$ and $\phi$ is a consistent formula ($\neg A \neg \phi$), then he believes $\phi$. It is clear that Qualified Acceptance can be derived from Acceptance (by axiom $Incl$, $\neg B_t \neg \phi \rightarrow \neg A \neg \phi$) and therefore $\mathcal{L}_{AGM}$ is an extension of $\mathcal{L}_{QBR}$.

It is well-known that axiom $D_B$ is characterized by seriality of $B_t$: $\forall t \in \mathbb{N}$, $\forall \omega \in \Omega$, $B_t(\omega) \neq \emptyset$. Given the non-standard validation rule for the $I_t$ operator, the corresponding axiom for $I_t$, namely $I_t \phi \rightarrow \neg I_t \neg \phi$, is not characterized by seriality of $I_t$. Seriality of $I_t$ is characterized by axiom $C_I$.

Remark 5 By axioms $C_I$ and $A$, the following strengthening of axiom $A$ is a theorem of $\mathcal{L}_{AGM}$: $I_t \phi \rightarrow B_t \phi$.

Definition 6 An AGM frame is a frame $\langle \Omega, \{B_t\}_{t \in \mathbb{N}}, \{I_t\}_{t \in \mathbb{N}} \rangle$ that satisfies the following properties: $\forall t \in \mathbb{N}$, $\forall \omega \in \Omega$,

1. $B_i(\omega) \subseteq I_i(\omega)$
2. if $B_i(\omega) \cap I_{i+1}(\omega) \neq \emptyset$ then $B_{i+1}(\omega) \subseteq B_i(\omega)$
3. $B_i(\omega) \cap I_{i+1}(\omega) \subseteq B_{i+1}(\omega)$
4. $B_i(\omega) \neq \emptyset$.

For example, the frame illustrated in Figure 3 of Section 2 is an AGM frame.

It is easy to show (see Lemma 21 in the Appendix) that the set of AGM frames is a subset of the set of frames that satisfy the Qualitative Bayes Rule. The following proposition is proved in the Appendix.

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9 A formula $\phi$ is characterized by a property $P$ of frames if (1) $\phi$ is valid in every frame that satisfies $P$, and (2) if $\phi$ is valid in a frame then the frame satisfies $P$.

10 While it is true that if $I_t$ is serial ($\forall t \in \mathbb{N}$, $\forall \omega \in \Omega$, $I_t(\omega) \neq \emptyset$) then the formula $I_t \phi \rightarrow \neg I_t \neg \phi$ is valid, the converse is not true. To see this, fix a frame where, $\forall t \in \mathbb{N}$, $\forall \omega \in \Omega$, $I_t(\omega) = \emptyset$. Fix an arbitrary model based on this frame and an arbitrary formula $\phi$. If $\|\phi\| \neq \emptyset$, then $\omega \not\models I_t \phi$ and therefore $\omega \models I_t \phi \rightarrow \psi$ for every formula $\psi$ (in particular for $\psi = \neg I_t \neg \phi$). On the other hand, if $\|\phi\| = \emptyset$, then $\omega \models I_t \phi$ and, since $\|\neg \phi\| = \Omega$, $\omega \not\models I_t \neg \phi$. Thus $I_t \phi \rightarrow \neg I_t \neg \phi$ is valid, despite the fact that $I_t$ is not serial.

11 Proof. Fix a model based on a frame where $I_t$ is serial, a state $\alpha$, a date $t$ and a formula $\phi$ and suppose that $\alpha \vdash I_t \phi$. Then $I_t(\alpha) = \|\phi\|$. By seriality of $I_t$, there exists a $\beta$ such that $\beta \in I_t(\alpha)$. Then $\beta \vdash \phi$ and, therefore, $\alpha \vdash \neg A \neg \phi$. Conversely, fix a frame where $I_t$ is not serial. Then there exists a state $\alpha$ such that $I_t(\alpha) = \emptyset$. For any model based on this frame and any atomic proposition $p$, $\|p \land \neg p\| = \emptyset$. Thus $\alpha \vdash I_t(p \land \neg p)$ and $\alpha \not\vdash \neg A \neg (p \land \neg p)$, thus axiom $C_I$ is falsified at $\alpha$ with $\phi = (p \land \neg p)$.  

10
Proposition 7 Logic $L_{AGM}$ is sound and complete with respect to the class of AGM frames.

The next proposition establishes the relationship between logic $L_{AGM}$ and the AGM theory of belief revision. First we recall the AGM postulates, which were developed within the framework of belief sets. Let $\Phi$ be the set of formulas in a propositional language. Given a subset $S \subseteq \Phi$, its PL-deductive closure $\lbrack S \rbrack^{PL}$ (where ‘PL’ stands for ‘Propositional Logic’) is defined as follows: $\psi \in \lbrack S \rbrack^{PL}$ if and only if there exist $\phi_1, \ldots, \phi_n \in S$ such that $(\phi_1 \land \ldots \land \phi_n) \rightarrow \psi$ is a truth-functional tautology (that is, a theorem of Propositional Logic). A belief set is a set $K \subseteq \Phi$ such that $K = \lbrack K \rbrack^{PL}$. A belief set $K$ is consistent if $K \neq \Phi$ (equivalently, if there is no formula $\phi$ such that both $\phi$ and $\neg \phi$ belong to $K$). Given a consistent belief set $K$ (thought of as the initial beliefs of the individual) and a formula $\phi$ (thought of as a new piece of information), the revision of $K$ by $\phi$, denoted by $K^*_{\phi}$, is a subset of $\Phi$ that satisfies the following conditions, known as the AGM postulates:

(K*1) $K^*_{\phi}$ is a belief set
(K*2) $\phi \in K^*_{\phi}$
(K*3) $K^*_{\phi} \subseteq \lbrack K \cup \{\phi\}\rbrack^{PL}$
(K*4) if $\neg \phi \notin K$, then $\lbrack K \cup \{\phi\}\rbrack^{PL} \subseteq K^*_{\phi}$
(K*5) $K^*_{\phi} = \Phi$ if and only if $\phi$ is a contradiction
(K*6) if $\phi \leftrightarrow \psi$ is a tautology then $K^*_{\phi} = K^*_{\psi}$
(K*7) $K^*_{\phi \land \psi} \subseteq \lbrack K^*_{\phi} \cup \{\psi\}\rbrack^{PL}$
(K*8) if $\neg \psi \notin K^*_{\phi}$, then $\lbrack K^*_{\phi} \cup \{\psi\}\rbrack^{PL} \subseteq K^*_{\phi \land \psi}$

The set of postulates (K*1) through (K*6) is called the basic set of postulates for belief revision (Gärdenfors, [10] p. 55). The next proposition, proved in the Appendix, shows that every model of logic $L_{AGM}$ satisfies the basic set of AGM postulates.

Proposition 8 Fix an arbitrary model that validates the axioms of logic $L_{AGM}$ (by Proposition 7 any model based on an AGM frame is such a model). Fix an arbitrary state $\omega$, an arbitrary date $t$ and let $K = \{\psi : \omega \models B_t\psi\}$. Suppose that there is a formula $\phi$ such that $\omega \models I_{t+1}\phi$ and define $K^*_{\phi} = \{\psi : \omega \models B_{t+1}\psi\}$. Then $K^*_{\phi}$ satisfies postulates (K*1) to (K*6).

AGM postulates (K*7) and (K*8), require that the revision of $K$ that includes both information $\phi$ and information $\psi$ (that is, $K^*_{\phi \land \psi}$) ought to be the same as the expansion of $K^*_{\phi}$ by $\psi$, so long as $\psi$ does not contradict the beliefs in $K^*_{\phi}$. In our framework we are able to model, at every date and state, only the information that is actually received by the individual and cannot capture the counterfactual of how the individual would have modified his beliefs if he had received a different piece of information. Thus we cannot compare the revised beliefs that the individual holds after first receiving information $\phi$ and
the following properties: 

\( \forall \) be the logic obtained from \( \omega \) successful and re-

\( \omega \) hypotheses of Proposition 12. Indeed every belief revision history \( \omega \) with 

simultaneously informed of both \( \phi \) and \( \psi \). However, by strengthening the logic 

further we can indirectly capture the full set of AGM postulates.

In the literature it has been shown that there is an equivalence between the 

AGM postulates and the notion of a plausibility ordering of the set of states 

(see Grove [12] and Board [4]). A plausibility ordering of \( \Omega \) is a binary relation 

\( \preceq \) on \( \Omega \) that is complete (\( \forall \omega , \omega' \in \Omega \), either \( \omega \preceq \omega' \) or \( \omega' \preceq \omega \)) and transitive (if 

\( \omega \preceq \omega' \) and \( \omega' \preceq \omega'' \) then \( \omega \preceq \omega'' \)). An initial belief set \( K \) can be thought of as 

a pair \((\alpha, E)\) in a model, with \( \alpha \in E \subseteq \Omega \), by taking \( K \) to be the set of formulas 

that are true at every state \( \omega \in E \). If \( \phi \) represents new information, then the 

revised belief set \( K_\alpha^* \) is defined as the set of formulas that are true at the states 

that (1) satisfy \( \phi \) and (2) are closest to \( \alpha \) according to the plausibility relation 

\( \preceq \). The next proposition shows that when information becomes more refined 

over time the belief revision history of the agent can indeed be rationalized by 

a plausibility ordering over the set of states.

Given a plausibility ordering \( \preceq \) of \( \Omega \) and a subset \( X \subseteq \Omega \), we denote by 

\( \min(\preceq, X) \) the set \( \{ \omega \in X : \omega \preceq \omega' \text{ for all } \omega' \in X \} \).

**Definition 9** A frame \((\Omega, \{B_t\}_{t \in \mathbb{N}}, \{I_t\}_{t \in \mathbb{N}})\) satisfies the property of 

information refinement over time if, for every \( t \in \mathbb{N} \) and \( \omega \in \Omega \), \( I_{t+1}(\omega) \subseteq I_t(\omega) \).

For example, the frame illustrated in Figure 3 of Section 2 is such a frame.

**Definition 10** Given a frame \((\Omega, \{B_t\}_{t \in \mathbb{N}}, \{I_t\}_{t \in \mathbb{N}})\) and a state \( \omega \in \Omega \), we 
call the sequence \( \{B_t(\omega), I_t(\omega)\}_{t \in \mathbb{N}} \) a belief revision history. The belief 
revision history \( \{B_t(\omega), I_t(\omega)\}_{t \in \mathbb{N}} \) is consistent, successful and refined if it satisfies 
the following properties: \( \forall t \in \mathbb{N}, (1) B_t(\omega) \neq \emptyset, (2) B_t(\omega) \subseteq I_t(\omega) \) and (3) 
\( I_{t+1}(\omega) \subseteq I_t(\omega) \).

**Definition 11** A plausibility relation \( \preceq \) on \( \Omega \) rationalizes the belief revision 
history \( \{B_t(\omega), I_t(\omega)\}_{t \in \mathbb{N}} \) if, for every \( t \in \mathbb{N} \), \( B_t(\omega) = \min(\preceq, I_t(\omega)) \).

The following proposition is proved in the Appendix.

**Proposition 12** Let \( \mathcal{F} = \{\Omega, \{B_t\}_{t \in \mathbb{N}}, \{I_t\}_{t \in \mathbb{N}}\} \) be a frame such that, for every 
\( \omega \in \Omega \), the corresponding belief revision history \( \{B_t(\omega), I_t(\omega)\}_{t \in \mathbb{N}} \) is consistent, 
successful and refined (see Definition 10). Then, for every \( \omega \in \Omega \), there exists a 
plausibility relation \( \preceq \) on \( \Omega \) that rationalizes the belief history \( \{B_t(\omega), I_t(\omega)\}_{t \in \mathbb{N}} \) 
if and only if \( \mathcal{F} \) is an AGM frame.

For example, the frame illustrated in Figure 3 of Section 2 satisfies the hy-
potheses of Proposition 12. Indeed every belief revision history \( \{B_t(\omega), I_t(\omega)\}_{t \in \{0,1,2,3\}} \) 
with \( \omega \in \{B, V, M, F\} \) is rationalized by the following plausibility ordering:


The class of frames considered in Proposition 12 can be axiomatized as fol-
lows. Let \( \mathcal{L}_{RP} \) (where ‘RP’ stands for ‘Rationalizable by a Plausibility relation’) 
be the logic obtained from \( \mathcal{L}_{AGM} \) by adding the following axiom:
\[ R. \quad (I_t \phi \land I_{t+1} \psi \land \neg A \neg \phi \land \neg A \neg \psi) \rightarrow A(\psi \rightarrow \phi) \]

The following proposition is proved in the Appendix.

**Proposition 13** Logic \( \Sigma_{RP} \) is sound and complete with respect to the class of AGM frames that satisfy information refinement over time (see Definition 9).

By Proposition 12, in this class of frames every belief history can be rationalized by a plausibility ordering.

The hypothesis of information refinement \((I_{t+1}(\omega) \subseteq I_t(\omega))\) is crucial for Proposition 12, as the example illustrated in Figure 4 shows. The frame of Figure 4 is not an AGM frame, since it violates the Qualitative Bayes Rule: \(B_1(\alpha) \cap I_2(\alpha) = \{\beta\} \neq \emptyset \) and yet \(B_2(\alpha) = \{\beta, \gamma\} \). However the belief revision history \(\{B_t(\alpha), I_t(\alpha)\}_{t \in \{0,1,2\}}\) is rationalized by the following plausibility relation \(\lesssim = \{(\alpha, \alpha), (\beta, \alpha), (\beta, \beta), (\beta, \gamma), (\gamma, \alpha), (\gamma, \beta), (\gamma, \gamma)\}\).

\[ \begin{array}{c|c|c|c} \alpha & \beta & \gamma \\ \hline I_0 & \bullet & \bullet & \bullet \\ B_0 & \bullet & \bullet & \bullet \\
\hline I_1 & \bullet & \bullet & \bullet \\ B_1 & \bullet & \bullet & \bullet \\
\hline I_2 & \bullet & \bullet & \bullet \\ B_2 & \bullet & \bullet & \bullet \\
\end{array} \]

Figure 4
A non-AGM frame which is rationalizable

### 4 Conclusion

The notions of static belief and of belief revision have been studied extensively in the literature. However, there is a surprising lack of uniformity in the two
approaches. In the philosophy and logic literature, starting with Hintikka’s seminal contribution, the notion of static belief has been studied mainly within the context of modal logic. The study of belief revision, on the other hand, has mainly followed the AGM approach where beliefs are modeled as sets of formulas in a given syntactic language and the issue is how a belief set ought to be modified when new information, represented by a formula \( \phi \), becomes available. A yet different approach can be found in the economics and game theory literature, where it is standard to represent beliefs by means of a probability measure over a set of states and belief revision is modeled using Bayes’ rule. With a few exceptions, the tools of modal logic have not been explicitly employed in the analysis of the interaction of belief and information over time. In this paper we have proposed a unifying framework for static beliefs and belief revision by bringing belief revision under the umbrella of modal logic. For a detailed discussion of the relationship between our approach and the existing literature the reader is referred to Bonanno [6].

### A Appendix

#### Outline of the proof of Proposition 3

Soundness is easily proved. The completeness proof is first carried out with respect to the class of augmented frames, which are defined as follows.

**Definition 14** An augmented frame is a collection \( \langle \Omega, \{B_t\}_{t \in \mathbb{N}}, \{I_t\}_{t \in \mathbb{N}}, A \rangle \) obtained by adding an equivalence relation \( A \) to a regular frame \( \langle \Omega, \{B_t\}_{t \in \mathbb{N}}, \{I_t\}_{t \in \mathbb{N}} \rangle \) with the additional requirement that \( B_t \subseteq A \) for every \( t \in \mathbb{N} \).

Let \( M \) be the set of maximally consistent sets (MCS) of formulas of \( \mathcal{L} \). Define the following binary relations \( A, B_t \subseteq M \times M \): \( \alpha A \beta \) if and only if \( \{ \phi : A \phi \in \alpha \} \subseteq \beta \) and \( \alpha B_t \beta \) if and only if \( \{ \phi : B_t \phi \in \alpha \} \subseteq \beta \). The relation \( A \) is an equivalence relation because of axioms \( T_A \) and \( S_A \) and, for every \( t \in \mathbb{N} \), \( B_t \) is a subrelation of \( A \) because of axiom \( Incl \). Furthermore, the following lemma is a consequence of axioms \( I_1 \) and \( I_2 \).

**Lemma 15** Let \( \alpha, \beta \in M \) be such that \( \alpha A \beta \) and let \( \phi \) be a formula such that \( I_\phi \in \alpha \) and \( \phi \in \beta \). Then, for every formula \( \psi \), if \( I_\psi \in \alpha \) then \( \psi \in \beta \), that is, \( \{ \psi : I_\psi \in \alpha \} \subseteq \beta \).

The definition of the relation \( I_t \) is more complicated, because of the non-standard validation rule for the operator \( I_t \). Let \( \omega_0 \) be an arbitrary object such that \( \omega_0 \notin M \), that is, \( \omega_0 \) can be anything but a MCS. Define the relation \( I_t \) on \( M \cup \{ \omega_0 \} \) as follows: \( \alpha I_t \beta \) if and only if (1) \( \alpha \in M \) and (2) either \( \beta \in M \) and, for some formula \( \phi \), \( I_t \phi \in \alpha \) and \( \phi \in \beta \), or for all \( \phi \), \( I_I \phi \notin \alpha \), and \( \beta = \omega_0 \).

The structure \( \langle M \cup \{ \omega_0 \}, \{B_t\}_{t \in \mathbb{N}}, \{I_t\}_{t \in \mathbb{N}}, A \rangle \) so defined is an augmented frame. For every \( \alpha \in M \), let \( A(\alpha) = \{ \omega \in M : \alpha A \omega \} \). Consider the canonical model based on this frame defined by \( \| p \| = \{ \omega \in M : p \in \omega \} \), for every atomic proposition \( p \). For every formula \( \phi \) define \( \| \phi \| \) according to the semantic rules.
given in Section 3, with the following modified truth conditions for the operators $I_t$ and $A$: $\alpha \models I_t \phi$ if and only if $I_t(\alpha) = \|\phi\| \cap A(\alpha)$ and $\alpha \models A \phi$ if and only if $A(\alpha) \subseteq \|\phi\|$.

The crucial step in the completeness proof is the following Truth Lemma (for a proof see Goranko and Passy [11] and Bonanno [6]).

**Lemma 16 (Truth Lemma).** For every $\omega \in M$ and for every formula $\phi$, $\omega \models \phi$ if and only if $\phi \in \omega$.

Note, in particular, that $\omega \models \phi$ can hold in two different cases: either (1) $I_t \phi \in \alpha$ and there exists a $\beta \in M$ such that $\phi \in \beta$ (in which case, by Lemmas 15 and 16, $I_t(\alpha) = \|\phi\| \cap A(\alpha) \subseteq M$) or (2) $I_t \phi \in \alpha$ and for every $\omega \in M$, $\phi \notin \omega$ (thus, by Lemma 16, $\|\phi\| = \emptyset$), which implies that $\neg \phi$ is a theorem of $L$. Note that, by definition of $I_t$, in the latter case, $I_t(\alpha) = \emptyset$. (A third possibility is $I_t \phi \notin \alpha$ for every formula $\phi$, in which case, by definition of $I_t$, $I_t(\alpha) = \{\omega_0\}$ with $\omega_0 \notin M$.)

With the aid of Lemma 16 it can be shown that logic $L$ is complete with respect to the class of augmented frames $\langle \Omega, \{B_t\}_{t \in N}, \{I_t\}_{t \in N}, A \rangle$. To complete the proof of Proposition 3, namely that logic $L$ is sound and complete with respect to the class of frames $\langle \Omega, \{B_t\}_{t \in N}, \{I_t\}_{t \in N}\rangle$, we only need to invoke the result (Chellas, 1984, Theorem 3.12, p. 97) that completeness with respect to the class of augmented frames (where $A$ is an equivalence relation) implies completeness with respect to the generated sub-frames (where $A$ is the universal relation). The latter are precisely what we called frames. In a frame where the relation $A$ is the universal relation the semantic rule $\alpha \models I_t \phi$ if and only if $I_t(\alpha) = \|\phi\| \cap A(\alpha)$ becomes $\alpha \models I_t \phi$ if and only if $I_t(\alpha) = \|\phi\|$ and the semantic rule $\alpha \models A \phi$ if and only if $A(\alpha) \subseteq \|\phi\|$ becomes $\alpha \models A \phi$ if and only if $\|\phi\| = \Omega$, since $A(\alpha) = \Omega$.

**Proof of Proposition 4. A Validity.** Fix a frame $\langle \Omega, \{B_t\}_{t \in N}, \{I_t\}_{t \in N}\rangle$ that satisfies QBR, that is, $\forall \omega \in \Omega, \forall t \in N$, if $B_t(\omega) \cap I_{t+1}(\omega) \neq \emptyset$ then $B_{t+1}(\omega) = B_t(\omega) \cap I_{t+1}(\omega)$. By Proposition 3 it is enough to show that the three axioms $QA$, $P$ and $M$ are valid in it. Fix an arbitrary model based on this frame and arbitrary state $\omega$, date $t$ and formulas $\phi$ and $\psi$. First we show that $\omega \models (\neg B_t \phi \land I_{t+1} \phi) \rightarrow B_{t+1} \phi$. Suppose that $\omega \models (\neg B_t \phi \land I_{t+1} \phi)$. Then $I_{t+1}(\omega) = \|\phi\|$ and $B_t(\omega) \cap I_{t+1}(\omega) \neq \emptyset$. By QBR, $B_{t+1}(\omega) \subseteq I_{t+1}(\omega)$ and therefore $\omega \models B_{t+1} \phi$. Thus axiom $QA$ is valid. Next we show that $\omega \models (\neg B_t \phi \lnot I_{t+1} \phi) \rightarrow (B_t \psi \rightarrow B_{t+1} \psi)$. Suppose that $\omega \models (\neg B_t \phi \land I_{t+1} \phi) \land B_t \psi$. Then $I_{t+1}(\omega) = \|\phi\|$, $B_t(\omega) \cap I_{t+1}(\omega) \neq \emptyset$ and $B_t(\omega) \subseteq \|\psi\|$. By QBR, $B_{t+1}(\omega) \subseteq B_t(\omega)$ and therefore $\omega \models B_{t+1} \psi$. Thus axiom $P$ is valid. Finally we show that $\omega \models (I_{t+1} \phi \land B_{t+1} \psi) \rightarrow B_t(\phi \rightarrow \psi)$. Suppose that $\omega \models I_{t+1} \phi \land B_{t+1} \psi$. Then $I_{t+1}(\omega) = \|\phi\|$ and $B_t(\omega) \subseteq \|\psi\|$. Fix an arbitrary $\omega' \in B_t(\omega)$. If $\omega' \models \neg \phi$, then $\omega' \models \phi \rightarrow \psi$; if $\omega' \models \phi$, then $\omega' \in B_t(\omega) \cap I_{t+1}(\omega)$ and by QBR, $B_t(\omega) \cap I_{t+1}(\omega) \subseteq B_{t+1}(\omega)$, so that $\omega' \models \psi$ and therefore $\omega' \models \phi \rightarrow \psi$. Hence $B_t(\omega) \subseteq \|\phi \rightarrow \psi\|$, that is, $\omega \models B_t(\phi \rightarrow \psi)$. Thus axiom $M$ is valid.

(B) Completeness. Let $M_{QBR}$ be the set of maximally consistent sets (MCS) of formulas of $L_{QBR}$. By Proposition 3 we only need to show that the frame
associated with the canonical model satisfies QBR. First we show that

$$\forall t \in \mathbb{N}, \forall \omega \in M_{QBR}, \text{ if } B_t(\omega) \cap I_{t+1}(\omega) \neq \emptyset \text{ then } B_{t+1}(\omega) \subseteq I_{t+1}(\omega).$$

Fix an arbitrary $\alpha \in M_{QBR}$ and suppose that $B_t(\alpha) \cap I_{t+1}(\alpha) \neq \emptyset$. Let $\beta \in B_t(\alpha) \cap I_{t+1}(\alpha)$. Since $B_t(\alpha) \subseteq M_{QBR}$, $\beta \in M_{QBR}$ and therefore, by definition of $I_t$, there exists a formula $\phi$ such that $I_{t+1}\phi \in \alpha$ and $\phi \in \beta$. Since $\beta \in B_t(\alpha)$, $\neg B_t\neg \phi \in \alpha$. Thus $B_{t+1}\phi \in \alpha$. We want to show that $B_{t+1}(\alpha) \subseteq I_{t+1}(\alpha)$. Fix an arbitrary $\gamma \in B_{t+1}(\alpha)$. By definition of $B_{t+1}$, $\{\psi : B_{t+1}\psi \in \alpha\} \subseteq \gamma$. In particular, since $B_{t+1}\phi \in \alpha$, $\phi \in \gamma$. By definition of $I_{t+1}$, since $I_{t+1}\phi \in \alpha$ and $\phi \in \gamma$, $\gamma \in I_{t+1}(\alpha)$.

Next we show that

$$\forall t \in \mathbb{N}, \forall \omega \in M_{QBR}, \text{ if } B_t(\omega) \cap I_{t+1}(\omega) \neq \emptyset \text{ then } B_{t+1}(\omega) \subseteq B_t(\omega).$$

Fix an arbitrary $\alpha \in M_{QBR}$ and suppose that $B_t(\alpha) \cap I_{t+1}(\alpha) \neq \emptyset$. Let $\beta \in B_t(\alpha) \cap I_{t+1}(\alpha)$. As shown above, there exists a $\phi$ such that $I_{t+1}\phi \in \alpha$, $\phi \in \beta$, and $\neg B_t\neg \phi \in \alpha$. By Persistence, for every formula $\psi$, $(I_{t+1}\phi \land \neg B_t\neg \phi) \rightarrow (B_t\psi \rightarrow B_{t+1}\psi) \in \alpha$. Thus

$$(B_t\psi \rightarrow B_{t+1}\psi) \in \alpha. \quad (1)$$

Fix an arbitrary $\gamma \in B_{t+1}(\alpha)$. Then, by definition of $B_{t+1}$, $\{\psi : B_{t+1}\psi \in \alpha\} \subseteq \gamma$. We want to show that $\gamma \in B_t(\alpha)$, that is, that $\{\psi : B_t\psi \in \alpha\} \subseteq \gamma$. Let $\psi$ be such that $B_t\psi \in \alpha$. By (1) $B_{t+1}\psi \in \alpha$ and therefore $\psi \in \gamma$.

Finally we show that

$$\forall t \in \mathbb{N}, \forall \omega \in M_{QBR}, B_t(\omega) \cap I_{t+1}(\omega) \subseteq B_{t+1}(\omega).$$

Fix arbitrary $\alpha, \beta \in M_{QBR}$ such that $\beta \in B_t(\alpha) \cap I_{t+1}(\alpha)$. Then there exists a $\phi$ such that $I_{t+1}\phi \in \alpha$ and $\phi \in \beta$. Fix an arbitrary $\gamma \in B_t(\alpha) \cap I_{t+1}(\alpha)$. We want to show that $\gamma \in B_{t+1}(\alpha)$, that is, that $\{\psi : B_{t+1}\psi \in \alpha\} \subseteq \gamma$. Let $\psi$ be an arbitrary formula such that $B_{t+1}\psi \in \alpha$. Then $(I_{t+1}\phi \land B_{t+1}\psi) \in \alpha$. By Minimality, $(I_{t+1}\phi \land B_{t+1}\psi) \rightarrow B_t(\phi \rightarrow \psi) \in \alpha$. Thus $B_t(\phi \rightarrow \psi) \in \alpha$. Since $\gamma \in B_t(\alpha)$, $(\phi \rightarrow \psi) \in \gamma$. Since $I_{t+1}\phi \in \alpha$ and $\gamma \in I_t(\alpha)$, $\phi \in \gamma$. Hence $\psi \in \gamma$.

In order to prove Proposition 7 we first note that Definition 6 is equivalent to the following definition (indeed properties (1) and (4) of Definition 6 imply properties (1), (4) and (5) of the following definition, and vice versa).

**Definition 17** An AGM frame is a frame $\langle \Omega, \{B_t\}_{t \in \mathbb{N}}, \{I_t\}_{t \in \mathbb{N}} \rangle$ that satisfies the following properties: $\forall t \in \mathbb{N}, \forall \omega \in \Omega$,

1. $I_t(\omega) \neq \emptyset$ then $B_t(\omega) \subseteq I_t(\omega)$
2. $I_t(\omega) \cap I_{t+1}(\omega) \neq \emptyset$ then $B_{t+1}(\omega) \subseteq B_t(\omega)$
\[(3) \, B_t(\omega) \cap I_{t+1}(\omega) \subseteq B_{t+1}(\omega) \]
\[(4) \, B_t(\omega) \neq \emptyset \]
\[(5) \, I_t(\omega) \neq \emptyset. \]

**Proof of Proposition 7.** By Proposition 4, it is sufficient to show that axioms \(A, D_B\) and \(C_I\) are valid in every AGM frame and that the canonical model satisfies properties (1), (4) and (5) of Definition 6. The proof of validity is straightforward and is omitted. The proof that, since \(D_B\) is an axiom, the canonical model satisfies property (4) of Definition 6 is well-known (see Blackburn et al [3] p. 203). Let \(M_{AGM}\) be the set of maximally consistent sets of logic \(\mathcal{L}_{AGM}\). In order to prove that property (1) holds we first start with the augmented canonical model \(\langle M_{AGM} \cup \{\omega_0\}, \{B_t\}_{t \in \mathbb{N}}, \{I_t\}_{t \in \mathbb{N}}, \mathcal{A}\rangle\) (where \(\mathcal{A}\) is an equivalence relation) and show that it satisfies the following property:

\[\forall \omega \in M_{AGM}, \forall t \in \mathbb{N}, \text{if } I_t(\omega) \cap \mathcal{A}(\omega) \neq \emptyset \text{ then } B_t(\omega) \subseteq I_t(\omega).\]

Fix arbitrary \(\alpha \in M_{AGM}\) and \(t \in \mathbb{N}\) and suppose that \(I_t(\alpha) \cap \mathcal{A}(\alpha) \neq \emptyset\). Let \(\beta \in I_t(\alpha) \cap \mathcal{A}(\alpha)\). Since \(\beta \in \mathcal{A}(\alpha)\), \(\beta \in M_{AGM}\). Therefore, since \(\beta \in I_t(\alpha)\), by definition of \(I_t\) there exists a \(\phi\) such that \(I_t(\phi) \subseteq \alpha\) and \(\phi \in \beta\). Thus \(I_t(\phi \land \neg A \neg \phi) \supseteq B_t(\phi) \in \alpha\). Since \(B_t(\phi) \in \alpha\) Fix an arbitrary \(\gamma \in I_t(\phi)\). Then, by definition of \(B_t\), \(\gamma \vdash \phi\) and, since \(B_t\) is a subrelation of \(\mathcal{A}\), \(\gamma \in \mathcal{A}(\alpha)\). Thus \(\gamma \in \|\phi\| \cap \mathcal{A}(\alpha)\) and therefore \(\gamma \in I_t(\alpha)\), since, by Lemmas 15 and 16, \(I_t(\alpha) = \|\phi\| \cap \mathcal{A}(\alpha)\). Taking the sub-frame generated by \(\alpha\), the above property becomes property (1) of Definition 17, since \(I_t(\omega) \cap \mathcal{A}(\omega) \neq \emptyset\) is equivalent to \(I_t(\omega) \neq \emptyset\) because \(\mathcal{A}\) is the universal relation. Finally we show that property (5) of Definition 17 is satisfied in the canonical model. Fix arbitrary \(\alpha \in M_{AGM}\) and \(t \in \mathbb{N}\). Suppose, by contradiction, that \(I_t(\alpha) = \emptyset\). Let \(p\) be an atomic proposition. Then, by lemma 16, \(I_t(p \land \neg p) \subseteq \alpha\), since \(|p \land \neg p| = \emptyset\). Since \(I_t(\phi) \rightarrow \neg A \neg \phi\) is an axiom of \(\mathcal{L}_{AGM}\), \(I_t(p \land \neg p) \rightarrow \neg A((p \land \neg p)) \subseteq \alpha\). Thus \(\neg A((p \land \neg p)) \in \alpha\) implying that there exists a \(\beta \in M_{AGM}\) such that \((p \land \neg p) \in \beta\), contradicting the definition of maximally consistent set.

**Proof of Proposition 8.** (K*1). We need to show that \(K^*_\phi\) is a belief set, that is, \(K^*_\phi = [K^*_\phi]^{PL}\). Clearly, \(K^*_\phi \subseteq [K^*_\phi]^{PL}\), since \(\psi \rightarrow \psi\) is a tautology. Thus we only need to show that \([K^*_\phi]^{PL}\) \subseteq \(K^*_\phi\). Let \(\psi \in [K^*_\phi]^{PL}\), i.e. there exist \(\phi_1, ..., \phi_n \in K^*_\phi\) such that \((\phi_1 \land ... \land \phi_n) \rightarrow \psi\) is a tautology. Thus, by Necessitation of \(B_{t+1}\) (cf. Remark 2), \(B_{t+1}((\phi_1 \land ... \land \phi_n) \rightarrow \psi)\) is a theorem of \(\mathcal{L}_{AGM}\) and therefore it is valid in the given model. Hence \(\omega \models B_{t+1}((\phi_1 \land ... \land \phi_n) \rightarrow \psi)\). By definition of \(K^*_\phi\), since \(\phi_1, ..., \phi_n \in K^*_\phi\), \(\omega \models B_{t+1}((\phi_1 \land ... \land \phi_n) \rightarrow \psi)\). By axiom \(K_B\), \(\omega \models B_{t+1}((\phi_1 \land ... \land \phi_n) \rightarrow \psi) \land B_{t+1}(\phi_1 \land ... \land \phi_n) \rightarrow B_{t+1} \psi\). Thus \(\omega \models B_{t+1} \psi\), that is, \(\psi \in K^*_\phi\).

(K*2). Since \(I_{t+1} \phi \rightarrow B_{t+1} \phi\) is a theorem of \(\mathcal{L}_{AGM}\) (see Remark 5), it is valid in the given model and, therefore, \(\omega \models I_{t+1} \phi \rightarrow B_{t+1} \phi\). Thus, since \(\omega \models I_{t+1} \phi\), \(\omega \models B_{t+1} \phi\), that is, \(\phi \in K^*_\phi\).
(K*3). Let $\psi \in K^*_\beta$, i.e. $\omega \models B_{t+1}\psi$. By Minimality, $\omega \models (I_{t+1}\phi \land B_{t+1}\psi) \rightarrow B_t(\phi \rightarrow \psi)$. By hypothesis, $\omega \models I_{t+1}\phi$. Thus $\omega \models B_t(\phi \rightarrow \psi)$, that is, $(\phi \rightarrow \psi) \in K$. Hence $\{\phi, (\phi \rightarrow \psi)\} \in K \cup \{\phi\}$ and, since $(\phi \land (\phi \rightarrow \psi)) \rightarrow \psi$ is a tautology, $\psi \in [K \cup \{\phi\}]^{PL}$.

(\text{K*4}. Suppose $\neg \phi \notin K$, that is, $\omega \models \neg B_t \neg \phi$. By Persistence, for every formula $\psi$, $\omega \models (I_{t+1}\phi \land \neg B_{t+1}\phi) \rightarrow (B_t \psi \rightarrow B_{t+1}\psi)$. Thus, since by hypothesis $\omega \models I_{t+1}\phi$,

$$\omega \models \neg B_t \psi \rightarrow B_{t+1}\psi$$

for every formula $\psi$. (2)

Let $\chi \in [K \cup \{\phi\}]^{PL}$, that is, there exist $\phi_1, \ldots, \phi_n \in K \cup \{\phi\}$ such that $(\phi_1 \land \ldots \land \phi_n) \rightarrow \chi$ is a tautology. We want to show that $\chi \in K^*_\beta$, i.e. $\omega \models B_{t+1}\chi$. Since $(\phi_1 \land \ldots \land \phi_n) \rightarrow \chi$ is a tautology, $\omega \models B_t((\phi_1 \land \ldots \land \phi_n) \rightarrow \chi)$.

If $\phi_1, \ldots, \phi_n \in K$, then $\omega \models B_t(\phi_1 \land \ldots \land \phi_n)$ and therefore $\omega \models B_t \chi$. Thus, by (2), $\omega \models B_{t+1}\chi$. If $\phi_1, \ldots, \phi_n \notin K$, then, by renumbering the formulas if necessary, we can assume that $\phi_1 = \phi$ and $\phi_2, \ldots, \phi_n \in K$. In this case we have $\omega \models B_t(\phi_2 \land \ldots \land \phi_n)$ and $\omega \models B_t((\phi_2 \land \ldots \land \phi_n) \rightarrow (\phi \rightarrow \chi))$, since $(\phi \land \phi_2 \land \ldots \land \phi_n) \rightarrow \chi$ is a tautology and it is equivalent to $(\phi_2 \land \ldots \land \phi_n) \rightarrow (\phi \rightarrow \chi)$. Thus $\omega \models B_t(\phi \rightarrow \chi)$. Hence, by (2) (with $\psi = (\phi \rightarrow \chi))$, $\omega \models B_{t+1}(\phi \rightarrow \chi)$. By Remark 5 $\omega \models I_{t+1}\phi \rightarrow B_{t+1}\phi$. From this and the hypothesis that $\omega \models I_{t+1}\phi$ it follows that $\omega \models B_{t+1}\phi$. By axiom $K_B$, $\omega \models B_{t+1}(\phi \rightarrow \chi) \land B_{t+1}\phi \rightarrow B_t \chi$. Thus $\omega \models B_{t+1}\chi$.

(K*5). We have to show that $K^*_\beta \neq \Phi$, unless $\phi$ is a contradiction (that is, $\neg \phi$ is a tautology). The possibility of contradictory information is ruled out by axiom $C_t$.\footnote{Our logic $\mathcal{L}_{AICM}$ excludes the possibility of contradictory information. Indeed, as pointed out by Friedman and Halpern [8], it is not clear how one could be informed of a contradiction.} Thus we only need to show that $K^*_\beta \neq \Phi$. Let $p$ be an atomic proposition. By Consistency of beliefs, $B_{t+1}p \rightarrow \neg B_{t+1}\neg p$; thus if $p \in K^*_\beta$ then $\neg p \notin K^*_\beta$ and therefore $K^*_\beta \neq \Phi$.

(K*6). We have to show that if $\phi \leftrightarrow \psi$ is a tautology then $K^*_\phi = K^*_\psi$. If $\phi \leftrightarrow \psi$ is a tautology, then $\|\phi \leftrightarrow \psi\| = \Omega$, that is, $\|\phi\| = \|\psi\|$. Thus, by axiom $I_2$, $\omega \models I\phi$ if and only if $\omega \models I\psi$. Hence, by definition of $K^*_\phi$, $K^*_\phi = K^*_\psi$.

In order to prove Proposition 12 we need some preliminary results.

**Lemma 18** Let $\preceq$ be a complete and transitive binary relation on $\Omega$ and $X \subseteq Y \subseteq \Omega$. If $\min(\preceq, Y) \cap X \neq \emptyset$ then $\min(\preceq, Y) \cap X = \min(\preceq, X) \cap X$.

**Proof.** First we show that $\min(\preceq, Y) \cap X \subseteq \min(\preceq, X)$. If $\min(\preceq, Y) \cap X = \emptyset$ there is nothing to prove. Therefore let $\beta \in \min(\preceq, Y) \cap X$. Then $\beta \in X$ and $\beta \preceq \gamma$ for all $\gamma \in Y$. Since $X \subseteq Y$, it follows that $\beta \in \min(\preceq, X)$. Next we show that if $\min(\preceq, Y) \cap X = \emptyset$ then $\min(\preceq, X) \subseteq \min(\preceq, Y) \cap X$. Let $\beta \in \min(\preceq, Y) \cap X$. Fix an arbitrary $\gamma \in \min(\preceq, X)$. Then $\gamma \in X$ and $\gamma \preceq \beta$. Suppose that $\gamma \preceq \min(\preceq, Y)$. Then there exists a $\delta \in Y$ such that $\delta \prec \gamma$ (that is, $\delta \preceq \gamma$ and $\gamma \not\preceq \delta$). By transitivity (since $\gamma \preceq \beta$), $\delta \prec \beta$, contradicting the fact that $\beta \in \min(\preceq, Y)$. \hfill \blacksquare
Lemma 19 Let $\langle \Omega, \{B_t\}_{t \in \mathbb{N}}, \{I_t\}_{t \in \mathbb{N}} \rangle$ be a QBR frame that satisfies information refinement over time (that is, $\forall t \in \mathbb{N}, \forall \omega \in \Omega$, $I_{t+1}(\omega) \subseteq I_t(\omega)$). Fix $\alpha \in \Omega$ and let $\{B_t(\alpha), I_t(\alpha)\}_{t \in \mathbb{N}}$ be the corresponding belief revision history. Let $T_0, T_1 \in \mathbb{N}$ be such that $T_0 < T_1$ and, $\forall t \in \mathbb{N}$ with $T_0 < t \leq T_1$, $B_{T_0}(\alpha) \cap I_t(\alpha) \neq \emptyset$. Then, $\forall t \in \mathbb{N}$ with $T_0 < t \leq T_1$, $B_t(\alpha) = B_{T_0}(\alpha) \cap I_t(\alpha)$.

**Proof.** We prove it by induction. The statement is clearly true for $t = T_0 + 1$, since by hypothesis $B_{T_0}(\alpha) \cap I_{T_0+1}(\alpha) \neq \emptyset$ and thus, by QBR, $B_{T_0+1}(\alpha) = B_{T_0}(\alpha) \cap I_{T_0+1}(\alpha)$. If $T_1 = T_0 + 1$ there is nothing else to prove. Suppose therefore that $T_1 > T_0 + 1$ and proceed with the induction step: suppose that the statement is true for every $t \in \mathbb{N}$ with $T_0 < t \leq T$ (with $T < T_1$). We want to show that it is true for $t = T + 1$. By the induction hypothesis, $B_T(\alpha) = B_{T_0}(\alpha) \cap I_T(\alpha)$. Thus $B_T(\alpha) \cap I_{T+1}(\alpha) = B_{T_0}(\alpha) \cap I_{T+1}(\alpha)$. Since $I_{T+1}(\alpha) \subseteq I_T(\alpha)$, $I_{T+1}(\alpha) \cap I_T(\alpha) = I_{T+1}(\alpha)$. Thus

$$B_T(\alpha) \cap I_{T+1}(\alpha) = B_{T_0}(\alpha) \cap I_{T+1}(\alpha). \quad (3)$$

By hypothesis, $B_{T_0}(\alpha) \cap I_{T+1}(\alpha) \neq \emptyset$. Hence, by (3),

$$B_T(\alpha) \cap I_{T+1}(\alpha) \neq \emptyset. \quad (4)$$

It follows from QBR that

$$B_{T+1}(\alpha) = B_T(\alpha) \cap I_{T+1}(\alpha). \quad (5)$$

From (3) and (5) we get that $B_{T+1}(\alpha) = B_{T_0}(\alpha) \cap I_{T+1}(\alpha)$. ■

Lemma 20 Given a belief revision history $\mathcal{H} = \{B_t(\alpha), I_t(\alpha)\}_{t \in \mathbb{N}}$ which is consistent, successful and refined (see Definition 10) there exists a binary relation $\preceq$ that rationalizes $\mathcal{H}$ if and only if $\mathcal{H}$ is qualitatively Bayesian, that is, if and only if, $\forall t \in \mathbb{N}$, if $B_t(\alpha) \cap I_{t+1}(\alpha) \neq \emptyset$ then $B_{t+1}(\alpha) = B_t(\alpha) \cap I_{t+1}(\alpha)$.

**Proof.** First we prove that if $\preceq$ rationalizes $\{B_t(\alpha), I_t(\alpha)\}_{t \in \mathbb{N}}$ then $\{B_t(\alpha), I_t(\alpha)\}_{t \in \mathbb{N}}$ is qualitatively Bayesian. Fix an arbitrary $t \in \mathbb{N}$ such that $B_t(\alpha) \cap I_{t+1}(\alpha) \neq \emptyset$. By hypothesis, $B_t(\alpha) = \min(\preceq, I_t(\alpha))$ and $B_{t+1}(\alpha) = \min(\preceq, I_{t+1}(\alpha))$. Since $I_{t+1}(\alpha) \subseteq I_t(\alpha)$ it follows from Lemma 18 (with $X = I_{t+1}(\alpha)$ and $Y = I_t(\alpha)$) that $B_{t+1}(\alpha) = B_t(\alpha) \cap I_{t+1}(\alpha)$.

Next we prove that if $\{B_t(\alpha), I_t(\alpha)\}_{t \in \mathbb{N}}$ is qualitatively Bayesian then there exists a complete and transitive binary relation $\preceq$ on $\Omega$ that rationalizes it. Define the function $\text{rank} : \Omega \rightarrow \mathbb{N}$ as follows:

$$\text{rank}(\omega) = \begin{cases} 0 & \text{if } \omega \in B_0(\alpha) \\ \infty & \text{if } \omega \in \Omega \setminus \bigcup_{t \in \mathbb{N}} B_t(\alpha) \\ t & \text{if } \omega \in B_t(\alpha) \text{ and } B_{t-1}(\alpha) \cap I_t(\alpha) = \emptyset \end{cases}$$

First we show that this function’s domain is indeed $\Omega$. Fix arbitrary $t' \in \mathbb{N} \setminus \{0\}$ and $\omega \in B_{t'}(\alpha)$. If $B_{t'-1}(\alpha) \cap I_{t'}(\alpha) = \emptyset$ then $\text{rank}(\omega) = t'$; if $B_{t'-1}(\alpha) \cap I_{t'}(\alpha) \neq \emptyset$ let $T = \{t \in \mathbb{N} : t < t' \text{ and } B_{t-1}(\alpha) \cap I_t(\alpha) = \emptyset\}$. If $T = \emptyset$, then, by Lemma 19, $\omega \in B_0(\alpha)$ and therefore $\text{rank}(\omega) = 0$. If $T \neq \emptyset$, then, by Lemma 19,
rank(ω) = ̂t where ̂t = maxT. Now define the binary relation ≤ on Ω as follows: ω ≤ ω′ if and only if rank(ω) ≤ rank(ω′). Clearly ≤ is complete and transitive. Now we show that ≤ rationalizes \{(B_t(α),I_t(α))\}_{t∈N}. Fix an arbitrary t₀. We want to show that B_{t₀}(α) = min(≤,I_{t₀}(α)), that is, for every ω ∈ B_{t₀}(α) and for every ω′ ∈ I_{t₀}(α), rank(ω) ≤ rank(ω′). If t₀ = 0 it follows from the fact that (1) B₀(α) ⊆ I₀(α) and (2) by construction rank(ω) ≥ 0 for every ω ∈ Ω and rank(ω) = 0 if and only if ω ∈ B₀(α). Suppose therefore that t₀ > 0. We need to consider two cases.

CASE 1: for every t ≤ t₀, B_{t⁻¹}(α) ∩ Iₜ(α) ≠ ∅. Then, by Lemma 19, B_{t₀}(α) = B₀(α) ∩ I₀(α) and therefore rank(ω) = 0 for every ω ∈ B_{t₀}(α).

CASE 2: for some t ≤ t₀ B_{t⁻¹}(α) ∩ Iₜ(α) = ∅. Let T = \{t ∈ N : t ≤ t₀ and B_{t⁻¹}(α) ∩ Iₜ(α) = ∅\} and let t’ = min T. Then, by Lemma 19, for every ω ∈ Bₜ(α) with t < t’, rank(ω) = 0, and, by construction, for every ω ∈ Bₜ(α), rank(ω) ≥ t’ and, for every ω ∈ Bₜ(α), rank(ω) = t’. Thus Bₜ(α) = min(≤,Iₜ(α)). If t₀ = t’ the proof is complete. Suppose therefore that t₀ > t’. If for every t with t₀ < t ≤ t’, Bₜ(α) ∩ Iₜ(α) ≠ ∅ then, by Lemma 19, B_{t₀}(α) = Bₜ(α) ∩ Iₜ(α) and thus, for every ω ∈ B_{t₀}(α), rank(ω) = t’ and hence B_{t₀}(α) = min(≤,I_{t₀}(α)). Otherwise repeat the argument: define T = \{t ∈ N : t ≤ t₀, t > t’ and B_{t⁻¹}(α) ∩ Iₜ(α) = ∅\} and let t” = min T’ and show that Bₜ(α) = min(≤,Iₜ(α)) and rank(ω) ≥ t” for every ω ∈ Iₜ(α) with t ≥ t”. By a finite repetition of this argument and Lemma 19 it follows that B_{t₀}(α) = min(≤,I_{t₀}(α)).

Lemma 21 Let \(\mathcal{F} = \langle Ω, \{B_t\}_{t∈N}, \{I_t\}_{t∈N}\rangle\) be a frame such that, for every \(ω ∈ Ω\), the corresponding belief revision history \{B_t(ω),I_t(ω)\}_{t∈N}\) is consistent (\(B_t(ω) ≠ ∅\)) and successful (\(B_t(ω) ⊆ I_t(ω)\)). Then \(\mathcal{F}\) is an AGM frame if and only if it satisfies the Qualitative Bayes Rule.

Proof. Let \(\mathcal{F}\) be an AGM frame. Fix arbitrary \(t ∈ N\) and \(ω ∈ Ω\) and suppose that \(B_t(ω) ∩ I_{t+1}(ω) ≠ ∅\). Then, by property (2) of Definition 17, \(B_{t+1}(ω) ⊆ B_t(ω)\). By property (1) (since \(I_{t+1}(ω) ≠ ∅\), \(B_{t+1}(ω) ⊆ I_{t+1}(ω)\). Thus \(B_{t+1}(ω) ⊆ B_t(ω) ∩ I_{t+1}(ω)\). By property (3), \(B_t(ω) ∩ I_{t+1}(ω) ⊆ B_{t+1}(ω)\). Thus \(B_{t+1}(ω) = B_t(ω) ∩ I_{t+1}(ω)\). Conversely, let \(\mathcal{F} = \langle Ω, \{B_t\}_{t∈N}, \{I_t\}_{t∈N}\rangle\) be a frame such that, for every \(ω ∈ Ω\), the corresponding belief revision history \{B_t(ω),I_t(ω)\}_{t∈N}\) is consistent (so that \(\mathcal{F}\) satisfies property (4) of Definition 17), successful (so that \(\mathcal{F}\) satisfies properties (1) and (5) of Definition 17) and satisfies the Qualitative Bayes Rule, that is, for every \(t ∈ N\), \(B_{t+1}(ω) = B_t(ω) ∩ I_{t+1}(ω)\). Then \(\mathcal{F}\) satisfies properties (2) and (3) of Definition 17 and therefore is an AGM frame.

Proof of Proposition 12. Let \(\mathcal{F} = \langle Ω, \{B_t\}_{t∈N}, \{I_t\}_{t∈N}\rangle\) be a frame such that, for every \(ω ∈ Ω\), the corresponding belief revision history \{B_t(ω),I_t(ω)\}_{t∈N}\) is consistent, successful and refined. By Lemma 21, \(\mathcal{F}\) is an AGM frame if and only if it satisfies the Qualitative Bayes Rule and by Lemma 20 this is necessary and sufficient for every belief history to be rationalizable by a plausibility ordering on Ω.
Proof of Proposition 13. By Proposition 7 it is enough to show that axiom $R$ is valid in every $AGM$ frame that satisfies information refinement and that the canonical model satisfies information refinement.

(A) Validity. Fix a frame that satisfies the information refinement property: $\forall t \in \mathbb{N}, \forall \omega \in \Omega, I_{t+1}(\omega) \subseteq I_t(\omega)$. Fix an arbitrary model based on it, arbitrary $t \in \mathbb{N}$, $\alpha \in \Omega$ and formula $\phi$ and suppose that $\alpha \models I_t \phi \land I_{t+1} \psi \land \neg A \neg \phi \land \neg A \neg \psi$. Then $I_t(\alpha) = \| \phi \|$ and $I_{t+1}(\alpha) = \| \psi \|$. Thus, by the property, $\| \psi \| \subseteq \| \phi \|$ and therefore $\| \psi \| = \Omega$. Hence $\omega \models A(\psi \to \phi)$.

(B) Completeness. Let $M_{RP}$ be the set of MCS of logic $\mathcal{L}_{RP}$ and let $\langle M_{RP} \cup \{ \omega_0 \}, \{ B_i \}_{i \in \mathbb{N}}, \{ I_t \}_{t \in \mathbb{N}}, A \rangle$ be the augmented canonical model. First we show that this augmented model satisfies the following property:

\[ WIR_1 \quad \forall t \in \mathbb{N}, \forall \omega \in M_{RP}, \text{ if } I_t(\omega) \cap A(\omega) \neq \emptyset \text{ and } I_{t+1}(\omega) \cap A(\omega) \neq \emptyset \text{ then } I_{t+1}(\omega) \cap A(\omega) \subseteq I_t(\omega) \cap A(\omega). \]

Fix arbitrary $t \in \mathbb{N}$ and $\alpha \in M_{RP}$ and suppose that $I_t(\alpha) \cap A(\alpha) \neq \emptyset$ and $I_{t+1}(\alpha) \cap A(\alpha) \neq \emptyset$. Let $\beta \in I_t(\alpha) \cap A(\alpha)$ and $\gamma \in I_{t+1}(\alpha) \cap A(\alpha)$. Then, by definition of $I_t$, there exists a formula $\phi$ such that $I_t \phi \in \alpha$ and $\phi \in \beta$. Thus, since $\beta \in A(\alpha)$, $I_t \phi \land \neg A \neg \phi \in \alpha$. Similarly, there exists a $\psi$ such that $I_{t+1} \psi \in \alpha$ and $\psi \in \gamma$, so that $I_{t+1} \psi \land \neg A \neg \psi \in \alpha$. Since $R$ is an axiom, $(I_t \phi \land I_{t+1} \psi \land \neg A \neg \phi \land \neg A \neg \psi) \to A(\psi \to \phi) \in \alpha$. Hence $A(\psi \to \phi) \in \alpha$. Fix an arbitrary $\delta \in I_{t+1}(\alpha) \cap A(\alpha)$ (this set is non-empty, because $\gamma$ belongs to it). Since $\delta \in A(\alpha)$ and $A(\psi \to \phi) \in \alpha$, $(\psi \to \phi) \in \delta$. We want to show that $\delta \in I_t(\alpha)$. Since $I_{t+1} \psi \in \alpha$, $I_{t+1}(\alpha) = \| \psi \| \cap A(\alpha)$, so that $\psi \in \delta$. From this and the fact that $(\psi \to \phi) \in \delta$, it follows that $\phi \in \delta$ and therefore, since $I_t(\alpha) = \| \phi \| \cap A(\alpha)$, $\delta \in I_t(\alpha)$. Taking the sub-frame generated by $\alpha$, the above property $WIR_1$ becomes (letting $\Omega = A(\alpha)$)

\[ WIR_2 \quad \forall t \in \mathbb{N}, \forall \omega \in \Omega \text{ if } I_t(\omega) \neq \emptyset \text{ and } I_{t+1}(\omega) \neq \emptyset \text{ then } I_{t+1}(\omega) \subseteq I_t(\omega) \text{ since } I_t(\omega) \cap A(\omega) \neq \emptyset \text{ is equivalent to } I_t(\omega) \neq \emptyset \text{ because } A \text{ is now the universal relation. Together with the fact that in the canonical model for the logic } \mathcal{L}_{AGM} \text{ (which is contained in the logic } \mathcal{L}_{RP} \text{) the relation } I_t \text{ is serial } (\forall t \in \mathbb{N}, \forall \omega \in \Omega, I_t(\omega) \neq \emptyset \text{) property } WIR_2 \text{ becomes the information refinement property: } \forall t \in \mathbb{N}, \forall \omega \in \Omega, I_{t+1}(\omega) \subseteq I_t(\omega). \]

References


