

Lux, Thomas

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The Multi-Fractal Model of Asset Returns: Its Estimation via GMM and Its Use for Volatility Forecasting

by Thomas Lux



Christian-Albrechts-Universität Kiel

Department of Economics

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Thomas Lux*

Abstract: Multi-fractal processes have been proposed as a new formalism for modeling the time series of returns in finance. The major attraction of these processes is their ability to generate various degrees of long memory in different powers of returns - a feature that has been found to characterize virtually all financial prices. Furthermore, elementary variants of multi-fractal models are very parsimonious formalizations as they are essentially one-parameter families of stochastic processes. The aim of this paper is to provide the characteristics of a *causal* multi-fractal model (replacing the earlier combinatorial approaches discussed in the literature), to estimate the parameters of this model and to use these estimates in forecasting financial volatility. We use the auto-covariances of *log increments* of the multi-fractal process in order to estimate its parameters consistently via GMM (Generalized Method of Moment). Simulations show that this approach leads to essentially unbiased estimates, which also have much smaller root mean squared errors than those obtained from the traditional ‘scaling’ approach. Our empirical estimates are used in out-of-sample forecasting of volatility for a number of important financial assets. Comparing the multi-fractal forecasts with those derived from GARCH and FIGARCH models yields results in favor of the new model: multi-fractal forecasts dominate all other forecasts in one out of four cases considered, while in the remaining cases they are head to head with one or more of their competitors.

Keywords: multi-fractality, financial volatility, forecasting

JEL classification: C20, G12

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Address of author:

Department of Economics, University of Kiel, Olshausenstr. 40, 24118 Kiel, Germany
lux@bwl.uni-kiel.de

1. Introduction

While so-called uni-fractal or self-similar processes, such as fractional Brownian motion, have been known for quite some time in empirical finance, more general multi-fractal processes have been considered only very recently. After some earlier attempts at recovering traces of multi-fractal behavior (Vassilicos, Demos and Tata, 1993, Ghasghaie, S. *et al.*, 1996) this topic has also been taken up in a couple of recent papers. Among these contributions, Schmitt, Schertzer and Lovejoy (1999) and Vandewalle and Ausloos (1998a, b) concentrate on statistical analyses suggesting the multi-fractal nature of various financial records. Mandelbrot, Fisher and Calvet (1997), Mandelbrot (1999) and Calvet and Fisher (2002a) proceed one step further by proposing a compound stochastic process as a generating mechanism of stock returns and exchange rate changes in which a multi-fractal cascade plays the role of a time transformation. The message of these papers is unequivocal in indicating that the data under consideration consistently exhibit features that have been found to characterize multi-fractality in other environments (e.g. statistical analyses of turbulence¹). However, the methods employed by these authors differ quite fundamentally from the usual techniques used to estimate and evaluate time series models in economics. Although a comparison of simulated multi-fractal processes with empirical data (Fisher, Calvet and Mandelbrot, 1997; Mandelbrot, 1999) suggests that they are, in fact, able to reproduce to a large extent the empirical characteristics of financial returns, no assessment of goodness-of-fit is provided in these early papers. A comparison of the performance of multi-fractals with, for example, GARCH processes as a candidate alternative, was particularly hampered by the fact, that ‘time series’ of this first vintage of multi-fractal processes have been generated by algorithms that are of a combinatorial nature rather than by truly iterative mechanisms.

The purpose of this paper is to go one (modest) step towards such an assessment of the empirical performance of multi-fractal cascade models. Following similar approaches by Breymann *et al.* (2000) and Calvet and Fisher (2001, 2002b), we first set up a causal counterpart of one variant of the combinatorial multi-fractal model analyzed by Calvet and Fisher (2002a). The iterative nature of this process allows simulations of arbitrary length. We show that this process preserves the scaling laws of moments characterizing its combinatorial predecessor, so that we can also apply the ‘scaling estimator’ of Calvet and Fisher for estimating the parameters of the causal process. As an alternative, potentially more efficient framework for parameter estimation we consider Generalized Method of Moments (GMM) estimation. We discuss under what circumstances GMM might be applicable to this new class of long-memory models. For a certain selection of moment conditions, we explore the finite-sample properties of the GMM estimators via Monte Carlo simulations. As it turns out, the root mean-squared error (RMSE) from this procedure is much smaller than that of the

¹ The similarities in the time series characteristics of financial data and data from turbulent flows has stimulated a discussion about potential similarities in the underlying data generating mechanisms among physicists, cf. Vassilicos, 1995; Gashghaie *et al.*, 1996, and Mantegna and Stanley, 1996.

standard heuristic estimation method. Furthermore, the decrease of RMSE under increasing sample size nicely exhibits $T^{1/2}$ consistency for all parameter choices and sets of moment conditions we have explored. When increasing the number of moment conditions, we find a continuous improvement in terms of mean squared errors of parameter estimates albeit with decreasing marginal returns from additional moment conditions. As concerns the distribution of the statistic used in Hansen's related test of overidentifying restrictions, we found almost no variation with sample size, parameter values and number of moment conditions. Unfortunately, the distribution of p-values seems to have too much mass on the extreme left-hand side even for relatively large samples up to 1000 observations, and, therefore, too often rejects the underlying model.

Equipped with these results, we estimate the parameters of the causal multi-fractal process for daily variations of various financial data: two stock market indices (the German DAX and the New York Stock Exchange Composite Index), an exchange rate (Deutsche Mark/U.S.\$), and the daily price of gold from the London Precious Metal Exchange. Since the multi-fractal model allows to capture the long-term dependence of volatility and the scaling of various moments, one might also expect that it can be used as a tool for forecasting the time development of volatility over short and medium time horizons. The use of the multi-fractal (MF) model to this end is, however, hampered by the lack of identification of the individual volatility components (this unsolved task is known as the inverse multi-fractal problem in physics). Nevertheless, even without being able to identify the ruling individual components of the volatility dynamics, we can devise a best linear predictor using the aggregate information available in our time series. To this end, we construct best linear forecasts for future volatility within time horizons ranging from 1 day to 100 days. For comparison, we compute similar forecasts based on historical volatility (HV), GARCH and FIGARCH models. Overall, the performance of the MF model compares quite well to that of its competitors. It beats all other forecasts for the U.S.\$-DEM exchange rate, while in forecasting the volatility of the gold price, it comes in second in a very narrow race with one specification of the FIGARCH model. Furthermore, while the gain in MSEs is probably negligible for small forecasting horizons in these cases, the gap between the multi-fractal (or the multi-fractal and the FIGARCH model) and alternative methods also widens with increasing time horizon and becomes quite sizable for larger forecasting horizons. For the two stock indices, results from HV, GARCH, FIGARCH and the multi-fractal model are almost indistinguishable, which might be explained by the tremendous increase of volatility in our out-of-sample period 1997/98.

Our aims of constructing iterative multi-fractal cascades and developing rigorous estimation methods are shared by three other recent entries in the literature. Breymann *et al.* (2000) have developed a model very similar to the present one and explore some of its scaling characteristics. Another closely related version of a causal multi-fractal model is studied in Calvet and Fisher (2001, 2002b). In contrast to the present entry, they assume that the multipliers are drawn from a Binomial distribution which allows maximum likelihood estimation based on the Hamilton filter for

Markov-switching processes. Most interestingly, they have also been the first to investigate the performance of a multi-fractal model in forecasting volatility. However, for the one-day forecasting horizons considered in their paper, they were unable of finding an advantage of MF against standard GARCH models. We will point to the similarities and differences between our approach and results and theirs repeatedly over the course of the presentation.

The paper proceeds as follows: sec. 2 introduces both the original combinatorial multi-fractal model with Lognormal multipliers as well as its causal counterpart used in the present study. Sec. 3 presents the scaling estimator introduced by Calvet and Fisher (2002a) while sec. 4 develops our alternative GMM estimator and provides a comparative Monte Carlo study of the performance of both estimators. Sec. 5 deals with some problems of empirical implementation of the GMM approach and reports the results of estimating the multi-fractal model for four different financial time series. Sec. 6 continues with the forecasting competition between the MF model and three alternative approaches. Sec. 7 concludes. The Appendix contains derivations of various analytical moments of the multi-fractal process used in both GMM estimation and forecasting as well as details on our GARCH and FIGARCH estimates used in sec. 6.

2. The Multi-Fractal Model: Combinatorial and Causal Versions

The multi-fractal model put forward in Mandelbrot, Calvet and Fisher (1997) and Calvet and Fisher (2002a) postulates that returns $\{x(t)\}$ follow a compound process:

$$(1) x(t) = B_H[\theta(t)].$$

In this notation, $B_H[\]$ is a fractional Brownian motion with index H , and $\theta(t)$ is the distribution function of a multi-fractal measure which plays the role of a time-deformation. Both component processes are assumed to be independent of each other. With a time-homogeneous Brownian process B_H , the multi-fractal measure $\theta(t)$ is responsible for changes in the scale of the fluctuations which generate heteroskedasticity of the overall dynamics. In contrast to the GARCH and stochastic volatility models and their descendants, the above cascade model is scale-free and, therefore, one and the same specification can be applied to data of different sampling frequencies. This feature is highlighted by Calvet and Fisher in their analysis of both high-frequency and daily returns of the Deutschmark/U.S.\$ exchange rate.

In our application, we simplify the general compound model by setting $H = 0.5$. This means we restrict the price process assuming that (in transformed time) the logs of prices follow a (Wiener) Brownian motion instead of fractal Brownian motion with arbitrary H . The reason is that empirical evidence in favor of $H \neq 0.5$ is weak: statistical tests can usually not reject the null hypothesis $H =$

0.5 for raw returns (cf. Lo, 1991; Goetzman, 1991; Mills, 1993),² while absolute and squared returns have values of H significantly exceeding 0.5. Hence, the picture from the literature (as well as from a preliminary analysis of our time series) is that long-term dependence (which shows up in an estimate $H > 0.5$) is confined to various powers of returns, but is almost absent in the raw data. In order to model long-term dependence in the powers, we do not need to assume a fractional Brownian motion of returns. This feature of the data can be accounted for by the introduction of the multi-fractal time-transformation alone.

Inspired by the multi-fractal models for turbulent flows in physics several models of multiplicative cascades have been applied for modeling the time-transformation $\theta(t)$. Mandelbrot, Calvet and Fisher focus on the so-called Binomial and Log-normal cascades, while Schmitt, Schertzer and Lovejoy (1999) estimate the parameters of the Log-Levy model for a number of foreign exchange rates. To get a basic idea of this approach, it is useful to first have a look at one of the simplest cases, the Binomial model.

In their original form, multi-fractal cascades are operations performed on probability measures.³ The ‘cascade’ starts with assigning uniform probability to the interval $[0,1]$. In the first step, this interval is split up into two subintervals of equal length, which receive a fraction m_0 and $1 - m_0$, respectively, of the total probability mass. In the next step, each subinterval is again split up into two subintervals, which again receive fractions m_0 and $1 - m_0$ of the probability mass of their ‘mother’ intervals. In principle, this procedure is, then, repeated *ad infinitum*.

It is easy to envisage more or less complicated variants of this general procedure: first, the probabilities could be assigned in a systematic fashion (e.g. always assigning probability m_0 to the left hand descendant and $1 - m_0$ to the right-hand descendant of a mother interval). Alternatively, this assignment could be made randomly. Going beyond the Binomial model, one could think of more than two subintervals to be generated in each step (which leads to multinomial cascades) or of generating random numbers for m_0 in each iteration instead of using the same constant value throughout the formation of the cascade. The Log-normal and Log-Levy models mentioned above are examples of the latter type of multi-fractal measures.

In the resulting final stage of the creation of a combinatorial cascade process consisting of, say, k such operations, the remaining subintervals all have size 2^{-k} and do possess mass identical to the product of their k multipliers chosen at different levels of the cascade:

² It is also well-known that the R/S and other estimation methods are positively biased around $H = 0.5$ which may explain some (seemingly significant) findings of H in excess of one half in the earlier literature (cf. North and Halliwell, 1994).

³ Tel (1988), Falconer (1990) and Evertz and Mandelbrot (1992) are recommendable introductory sources to multi-fractal measures.

$$(2) \quad \theta_j = \prod_{i=1}^k m_j^{(i)},$$

with j a partition of the unit interval, i.e. j is an index of subintervals with constant mass: $\{\theta_j := \theta[(j-1) \cdot 2^{-k}, j \cdot 2^{-k}], j = 1, 2, \dots, 2^k\}$.

Depending on the type of process, the $m_j^{(i)}$ may represent independent draws from a Binomial, Lognormal or any other distribution one considers useful in this context. The defining characteristic of these measures is their non-linear scaling of moments, i.e.

$$(3) \quad E[\theta_j^q] = (2^{-k})^{\tau(q)+1}$$

with $\tau(q)$ a non-linear function of q . Various scaling functions for different underlying distributions of the multipliers can be found in Calvet, Fisher and Mandelbrot (1997). Defining $\tau(q) = q \cdot H_q - 1$, we can highlight the key difference between uni-fractal and multi-fractal processes: for the former H_q is a constant and, hence, $\tau(q)$ is linear in q . For multi-fractal processes, on the contrary, the nonlinear shape of $\tau(q)$ implies non-constant H_q . It is this feature which makes the later formalism an attractive model of financial returns. In fact, variability of H over various powers has been found to be a pervasive feature of financial data. The first systematic inquiry into the behavior of various measures of long-term dependence with varying powers q has been contributed by Ding, Engle and Granger (1993) and their findings have been confirmed in a number of other studies recently (Lux, 1996; Mills, 1997). The consensus now is that this feature appears in virtually all financial prices (Anderson and Bollerslev, 1997; Lobato and Savin, 1998). It is noteworthy that, although the above authors did not refer to multi-fractality in their papers, they did already point to empirical regularities of the type depicted in eq. (3) that are consistent with the multi-fractal model. Their basic message is, therefore, very similar to that of the recent contributions by Fisher, Calvet and Mandelbrot (1997), Schmitt, Schertzer and Lovejoy (1999), and Calvet and Fisher (2001, 2002a, b). The progress made by the later papers is, however, to go beyond a description of stylized facts and to propose a new class of models that genuinely allows to capture these facts.

The approach proposed by Calvet and Fisher (2002a) consists in interpreting the order of the subsets of a multi-fractal measure within the interval $[0, 1]$ as an ordering along the time axis so that θ_j can be used as a transformation of homogenous clock-time or, in an equivalent interpretation, as the local volatility of the process governing stock price changes. It is immediately obvious that one important limitation of this approach is the finite support of the resulting compound process. Although one imposes a temporal order on the subintervals, the whole ‘time path’ is still obtained

(or simulated) in one act which leaves no room for predicting the likely future development after the end of the current cascade. Furthermore, with an underlying cascade extending over k steps, we have exactly 2^k different subintervals at our disposal and, therefore, could lodge only time series which are no longer than that. It is not clear how one should proceed when reaching the end point $T = 2^k$, since starting with a new cascade, for example, would amount to a structural break at T without any dependence between the parts of the time series before and after that point.⁴ This underscores the need for an iterative framework instead of the traditional combinatorial approach.

Expanding on a recent proposal by Breymann *et al.* (2000) and a similar approach found in Calvet and Fisher (2001, 2002b), we replace the non-causal construction outlined above by an iterative mechanism that preserves its essential features. This approach conserves the hierarchical nature of the volatility process but allows for stochastic changes of its individual components over time. The volatility components, $m_t^{(i)}$ at time t (chronological time t now replacing the ordering j within the unit interval), are, then, replaced over time by new multipliers with certain probabilities. To replicate the structure of a binary cascade, the probability of replacement would have to be:

$$(4) \quad \text{Prob}(\text{new } m_t^{(i)}) = 2^{-(k-i)}.$$

This implies that the last multiplier would be replaced with probability $\text{Prob}(\text{new } m^{(k)}) = 1$ at each time step, while the first, $i = 1$, would be replaced with probability $\text{Prob}(\text{new } m^{(1)}) = 2^{-(k-1)}$. Keeping in line with the spirit of the original non-causal model, replacement of an element $m_t^{(p)}$ would also have the consequence of replacement of all subordinated multipliers $p+1, p+2, \dots, k$ at t . This is in contrast to the approach of Calvet and Fisher (2002b) who assume independent replacement operations at all levels of the cascade.

The construction of our iterative cascade process is illustrated in Fig. 1. The first and second panel exhibit the developments of the multipliers of levels 2 and 6. The basic difference with respect to the combinatorial models is that their renewal occurs in irregular intervals determined as random events. For example, in a simulation of the same length the second level multiplier would have exactly four different realizations of exactly equal duration in the framework of Calvet and Fisher (2002a), while here it has 5 realizations of very different duration. The third panel shows the overall volatility process resulting from the superimposition of all active multipliers, while the bottom panel exhibits the dynamics of returns as a compound process with an incremental Wiener

⁴ Muzy *et al.* (2001) construct an iterative ‘multi-fractal random walk’ assuming a finite depth of its underlying volatility cascade and extract the number of valid multipliers, k , from the ‘zero-crossing’ of the auto-correlation function of absolute returns. However, under ‘true’ long-memory, autocorrelations should remain positive over all lags. In any case, even if there were a finite correlation length, the ‘zero-crossing’ might be hard to identify due to the noisiness of the autocorrelation function at long lags.

Brownian motion sampled at unit time intervals. This illustration is, in fact, similar to Fig. 1 in Calvet and Fisher (2001) although the model presented there is based on a continuous-time Poisson process governing the replacement of multipliers. In its discretized version, the later is equivalent to the process studied here.

Insert Fig. 1 about here

As a consequence of our construction, on average 2^{k-1} adjacent time steps share the same multiplier at level 1, 2^{k-2} the same multiplier at level 2 etc. Note that in the non-causal binary cascade model, there are (with a process consisting of k iterations) *exactly* 2^{k-1} adjacent subintervals with the same multiplier at level 1, 2^{k-2} subintervals with the same multiplier at level 2 etc. The iterative process, therefore, preserves the average duration of hierarchical components but allows for stochastic fluctuations in their realized durations. Like in the standard model, many choices for the selection of the $m_t^{(i)}$ are possible. For the sake of comparability, a particularly well-known model is chosen here, the Lognormal model. This means that when a new multiplier is needed at any level, it will be determined via a random draw from a Log-Normal distribution:

$$(5) \quad m_t^{(i)} \sim \text{LN}\left(-\lambda \ln(2), s^2 \ln(2)^2\right),$$

where the normalization of the parameters of the Lognormal distribution via multiplication by $\ln(2)$ stems from consideration of binary intervals in the combinatorial process. To facilitate comparison with earlier literature, we keep this convention in our causal setting.

Note, that in (5), the scale parameter, s^2 , of the Lognormal distribution must be determined from the restriction⁵ $E[M] = 0.5$, which in the combinatorial model is necessary to preserve average mass of the interval $[0, 1]$ during the evolution of the cascade, and, therefore, prevents nonstationarity of the multi-fractal cascade dynamics (explosion to infinity or collapse to zero upon addition of further volatility components). With this restriction, we can substitute $s^2 = 2(\lambda - 1)/\ln(2)$ and the Lognormal volatility process therefore, boils down to a one-parameter model which is fully defined by the parameter λ .

To see the similarity to the model analyzed in Mandelbrot, Calvet and Fisher (1997) and Calvet and Fisher (2002a), we compute the unconditional moments of the resulting process. Let us denote by μ_t the causal multi-fractal process:

$$(6) \quad \mu_t = \prod_{i=1}^k m_t^{(i)}$$

⁵ Note that without such restriction $E[M] = \exp(-\lambda \ln(2) + 0.5 s^2 (\ln(2))^2)$

with replacement rule (4). Its q -th moment is given by:

$$(7) \quad E[\mu_t^q] = E\left[\left(m_t^{(1)} m_t^{(2)} \dots m_t^{(k)}\right)^q\right] = E\left[\left(m_t^{(i)}\right)^{k \cdot q}\right]$$

since all the $m_t^{(i)}$ are independent. For the Log-normal model, this leads to:

$$(8) \quad E[\mu_t^q] = \exp\left(k\left(-q\lambda \ln(2) + q^2(\lambda - 1)\ln(2)\right)\right)$$

which can be transformed into:

$$(9) \quad E[\mu_t^q] = \left(2^{-k}\right)^{\tau(q)+1} \quad \text{with: } \tau(q) = q\lambda - q^2(\lambda - 1) - 1.$$

Since $\tau(q)$ is the celebrated scaling function of the Log-Normal model for turbulence first proposed in Mandelbrot (1974), the behavior of unconditional moments is identical to that of the traditional combinatorial model. Since the unconditional moments of the resulting volatility model are not affected by our randomization of replacement times, we can apply the traditional ‘scaling estimator’ built upon this relationship to estimate the parameters of the causal model (cf. Calvet and Fisher, 2002a). However, we will see that this estimator has relatively large bias and root mean squared error in finite samples and is dominated by a GMM estimator to be introduced in section 4 below.

Using the iterative version of the multi-fractal model instead of its combinatorial predecessor in the process (1), and confining attention to unit time intervals, the resulting dynamics can also be seen as a particular version of a *stochastic volatility* model. Rescaling the volatility dynamics in a way to preserve a mean value equal to 1 of the cascade, we can write returns over unit time intervals as the product of local volatility and Normally distributed increments:

$$(10) \quad x_t = \sqrt{2^k \prod_{i=1}^k m_t^{(i)}} \cdot \sigma \cdot u_t,$$

in which the factor 2^k compensates for the mean value equal to 0.5 of the k multipliers, u_t is a standard Normal random variate $u_t \sim N(0,1)$, and σ is the standard deviation of the incremental process.

3. Estimation of the Multi-Fractal Parameters: The Scaling Approach

In the physics literature, multi-fractal behavior is usually identified via analysis of the so-called partition function $S(\Delta t, q)$ of a time series. Denoting by $p(t)$ the logarithm of the asset price at time t , it summarizes the behavior of moments q of increments (returns) computed over various time horizons Δt :

$$(11) \quad S(\Delta t, q) = \sum_{t=1}^{\text{int}[T/\Delta t]} \{|p(t + \Delta t) - p(t)|\}^q \sim \Delta t^{\tau(q)}$$

In the pertinent literature, the parameters of multi-fractal cascades are usually not estimated directly from the scaling function $\tau(q)$, but rather from its Legendre transformation:

$$(12) \quad f(\alpha) = \arg \min_q [q\alpha - \tau(q)].$$

The resulting function $f(\alpha)$ can be interpreted as the distribution of so-called local Hölder exponents α (which as a continuum of local scaling factors replaces the unique Hurst exponent of uni-fractal processes such as fractional Brownian motion). In the case of the Log-normal model, both the $\tau(q)$ and $f(\alpha)$ functions depend on one parameter, the location parameter λ of the Lognormal distribution $\text{LN}(-\lambda \ln(2), 2(\lambda - 1) \ln(2))$ from which the volatility components are drawn. The pertinent fractal spectrum is given by (cf Calvet and Fisher, 2001a):

$$(13) \quad f_\mu(\alpha) = 1 - \frac{(\alpha - \lambda)^2}{4(\lambda - 1)}.$$

In estimating the multi-fractal spectrum of returns time series, we note that under the assumption of Brownian motion of price changes in transformed time the spectrum of the compound process $x(t) = B_H[\theta(t)]$ is related to the spectrum of the multi-fractal time-transformation $\mu(t)$ in the following way (cf. Mandelbrot, Calvet and Fisher, 1997):

$$(14) \quad f_x(\alpha) = f_\mu(\alpha H) = f_\mu(\alpha/2).$$

Fig. 2 illustrates the traditional method of estimating the key parameter λ of the multi-fractal model. One starts with the empirical *partition functions* $S(\Delta t, q)$ which are, then, used to estimate the scaling function $\tau(q)$ from regressions in log co-ordinates. The upper panel of Fig. 2 shows a selection of partition functions for some low (left-hand side) and higher moments (right-hand side)

for the German stock market index DAX.⁶ As can be observed, the empirical behavior is very close to the presumed linear shape for moments of small order, while the fluctuations around the regression line become more pronounced for higher powers. This is, however, to be expected as the influence of chance fluctuations is magnified with higher powers q . The resulting scaling function for moments in the range $[-10, 20]$ is exhibited in the lower left panel of *Fig. 2*,⁷ For comparison, the broken line shows the behavior expected with Wiener Brownian motion, i.e. scaling according to $q/2 - 1$. There is a clear deviation from pure Brownian motion. The qualitative picture is the same found by Mandelbrot *et al.* as well as Schmitt, Schertzer and Lovejoy. Finally, the last step consists in computing the multi-fractal $f(\alpha)$ spectrum. The lower right-hand panel of *Fig. 2* is a visualization of the Legendre transformation. The spectrum is obtained by drawing lines of slope q and intercept $-\tau(q)$ for various q . If the underlying data indeed exhibits multi-fractal properties, these lines would turn out to constitute the envelop of the distribution $f(\alpha)$. As can be seen, a convex envelope emerges from our scaling functions. It seems worthwhile to emphasize that this outcome is shared by all other studies available hitherto, which may suggest that such a shape of the spectrum is a robust feature of financial data.

Insert Fig. 2 about here

For fitting the empirical spectrum by its theoretical counterpart, the inverted parabolic shape of the Lognormal cascade (13), we have to keep in mind, that the cascade model is used for the volatility or time deformation $\mu(t)$ and that the returns themselves result from the compound process $B_{\cdot 5}[\mu(t)]$. We, therefore, have to take into account the shift in the spectrum as detailed in eq. (14). In order to arrive at parameter estimates for λ , the common approach pursued in physical applications is to compute the best fit to (14) for the empirical spectrum using a least square criterion. To this end, we restrict our attention to the positively sloped, left-hand part of the spectrum. The reason is, that the right-hand arm is computed from partition functions with negative powers and is, therefore, strongly affected by chance fluctuations due to the Brownian process. In fact, performing experiments with synthetic data from multi-fractal processes, we find that the location of the downward sloping part is strongly biased and, even with a symmetrical theoretical spectrum, often shows the same skewness as our empirical spectra. As a consequence, a fit based on the left-hand arm alone seems preferable.⁸ Empirical results from this procedure are exhibited below in *Table 4*.

⁶ Plots from the other three time series are almost identical.

⁷ Negative moments are only shown for illustration, but are discarded in the ensuing statistical analyses.

⁸ It may be added that fits with both arms gave inferior results throughout and sometimes even led to violations of the restrictions of the underlying model. Note also that a bias towards skewness on the right implies also that our empirical $f(\alpha)$ shape does not necessarily speak against the symmetric shape implied by the Log-normal model.

The physics literature notes biases and other problems of the scaling method (cf. Ouillon and Sornette, 1996; and Veneziano *et al.*, 1995), but to our knowledge, no systematic inquiry into the reliability and performance of the resulting estimates is available. In order to arrive at an assessment of the quality of the estimates and, in particular, to be able to compare it with that of the upcoming GMM estimates, we performed Monte Carlo experiments with simulated data. For these experiments, the set-up was as follows: 1,000 replications were run for six values of λ (running from 1.05 to 1.30 in increments of 0.05) and sample sizes T equal to 2,000, 5,000 and 10,000. Each data set has been obtained as a random subsample from a longer simulation run with 10^5 iterations and underlying $k = 15$. A visual comparison with the upcoming results for the GMM estimator is provided in Fig. 3. Detailed results are shown in Table 1. Because of the similarity of our results from different parameter values, we only provide data for three entries of λ : 1.1, 1.2, and 1.3. As can be seen, for all parameter values, the estimates of λ are positively biased, while the reduction of the RMSE is often much slower than $T^{-1/2}$ (the more so, the higher the true parameter λ).

Insert Table 1 and 2 about here

4. GMM Estimation of Multi-Fractal Models

Unfortunately, no results on the consistency and asymptotic distribution of the $f(\alpha)$ estimates seem to be available in the relevant literature. This approach also does not provide us with estimates of the standard deviation σ of the incremental Brownian motion nor of the number of steps k to be used in the cascade. The later omission is somewhat natural since the underlying physical models assume an infinite progression of the cascade which is also the reason for their initially scale free approach.

Besides that, the $\tau(q)$ and $f(\alpha)$ fits also require judgmental selection of the number and location of steps used for the scaling estimates of the moments and the non-linear least-square fit of the spectrum. However, in principle, the fitting of the spectrum amounts to matching the moments of the theoretical process. This may lead to the question whether one could not resort to the methodology introduced under the heading of *Generalized Methods of Moments* by Hansen (1982). The advantage of this later approach consists in the availability of results on the asymptotic distribution of the estimates as well as the possibility of testing well specified null hypotheses. We will discuss shortly, under what conditions we are allowed to apply GMM for the estimation of the multi-fractal model.

In the GMM approach, the vector of parameter estimates of a model, say ϕ , is obtained as

$$(15) \quad \hat{\phi}_T = \arg \min_{\phi \in \Omega} f_T(\phi)' A_T f_T(\phi),$$

where Ω is the parameter space, $f_T(\phi)$ is the vector of differences between sample moments and analytical moments, and A_T is a positive definite and possibly random weighting matrix. Under ‘suitable regularity conditions’, detailed, for example in Harris and Mátyás (1999), $\hat{\phi}_T$ is consistent and asymptotically Normal with

$$(16) \quad T^{1/2}(\hat{\phi}_T - \phi_0) \sim N(0, \Xi), \text{ with covariance matrix } \Xi = (\bar{F}_T' \bar{V}_T^{-1} \bar{F}_T)^{-1}$$

and ϕ_0 the true parameter vector, $\hat{V}_T^{-1} = T \text{var} f_T(\hat{\phi}_T)$ the covariance matrix of the moment conditions, $F_T(\phi) = \frac{\partial f_T(\phi)}{\partial \phi'}$ the matrix of first derivatives of the moment functions, and \bar{V}_T and \bar{F}_T the constant limiting matrices to which \hat{V}_T and F_T converge. Knowledge about this asymptotic distribution can be used to construct a test of the null hypothesis that the model is the true data-generating process. With the number of moment conditions (say q) exceeding the number of model parameters (say p), we can test the model using Hansen’s statistic: $J_T = T \cdot f_T(\hat{\phi})' \hat{A}_T f_T(\hat{\phi})$, which under the null hypothesis can be shown to converge to a χ^2 distribution with $q-p$ degrees of freedom.

Now turn to the question of applicability of the GMM procedure. For models incorporating long-term dependence, applicability of the ‘usual regularity conditions’ of GMM and other estimators is often questionable or simply not known. In fact, to the best of our knowledge, no rigorous proof of applicability of GMM to stochastic volatility models (even without the long-memory feature) has been provided in the literature so far.⁹ To see what kind of difficulties one encounters in the present framework, consider the following sets of conditions for consistency and asymptotic Normality of GMM estimators (cf. Harris and Mátyás, 1999). First, *weak consistency* can be shown to hold if: (i) $E[f_T(\phi)]$ exists for all ϕ and is finite, (ii) there exists a ϕ_0 such that $E[f_T(\phi)] = 0$ if and only if $\phi = \phi_0$, (iii) the difference between average sample and population moments uniformly converges to zero in probability (i.e., $f_T(\phi)$ satisfies a weak law of large numbers), and (iv) the sequence of (random) weighting matrices converges in probability to a constant matrix \bar{A}_T . For *strong consistency*, the assumed convergence in probability in (iii) and (iv) would have to be replaced by convergence almost surely. Furthermore, asymptotic Normality requires the following additional or sharper conditions: (v) $f_T(\phi)$ needs to be continuously differentiable, (vi) the matrix of first

⁹ Melino and Turnbull (1990) note difficulties in evoking the usual large sample limit.

derivatives $F_T(\varphi)$ should converge to a constant matrix \bar{F}_T for $\varphi \rightarrow \varphi_0$, and (vii) $f_T(\varphi)$ now needs to satisfy a central limit theorem (cf. Harris and Mátyás, 1999).

Immediate problems may arise with (vii) and (iv): first, given the genuine long-memory features of the process under consideration, the moment functions will probably *not* satisfy a central limit law. In fact, whether or not a central limit law holds depends on the degree of dependence (cf. Beran, 1994, c. 3). Unfortunately, the estimated parameters for the long-term dependence in, for example, absolute returns usually fall into the range of non-applicability of these central limit laws. If that is true, the usual estimators for the covariance matrix V_T do also not fall into the classes for which consistency is guaranteed and will possibly not converge to a constant limiting matrix. One may circumvent this problem by resorting to other choices of the weighting matrix, e.g. a constant matrix, in order to guarantee consistency. However, abandoning the usual weighting according to the precision of the individual entry in the vector of moment conditions would greatly reduce the intuitive appeal of GMM.

A possible way out of this dilemma is provided by differencing the data. As shown in the technical Appendix, log differences of either the multi-fractal process itself or the compound process for (absolute) returns yield a stationary stochastic process which definitely has no long memory. As is shown in the Appendix, this process, in fact, only has non-zero autocovariances at the first lag. For our GMM estimation approach, we, therefore, select moments of the transformed process:¹⁰

$$(17) \quad \xi_{t,T} = \ln|x_t| - \ln|x_{t-T}|.$$

From (10), this transformation amounts to:

$$(18) \quad \xi_{t,T} = \ln \left(\sqrt{2^k \prod_{i=1}^k m_t^{(i)} \cdot \sigma \cdot |u_t|} \right) - \ln \left(\sqrt{2^k \prod_{i=1}^k m_{t-T}^{(i)} \cdot \sigma \cdot |u_{t-T}|} \right) =$$

$$0.5 \sum_{i=1}^k (\epsilon_t^{(i)} - \epsilon_{t-T}^{(i)}) + \ln|u_t| - \ln|u_{t-T}|, \quad \text{with } \epsilon_t^{(i)} = \ln(m_t^{(i)})$$

With all the entries on the right-hand side stemming from random Normal variates drawn at times t and $t-T$, it is almost obvious that this is a particularly harmless process which should be unproblematic in terms of the regularity conditions of GMM. One drawback (similar to the $f(\alpha)$ methodology) is that this transformation only allows to estimate the parameter λ of the Lognormal

¹⁰ In an earlier version of the paper, moments of raw differences instead of log differences have been used for GMM estimation. However, closer inspection showed that this transformation did still preserve the long-memory property of the multi-fractal model. Similar moment conditions have also been used for SMS (simulated method of moment) estimation in Calvet and Fisher (2002b).

distribution while the standard deviation from the Normally distributed increments drops out when computing log differences, and the depth of the cascade, k , as a discrete parameter is not amenable to GMM estimation anyway. Nevertheless, as shown in our simulation, this approach provides a tremendous reduction of bias and root mean squared error so that it seems worthwhile to pursue this avenue. In practical applications, the standard deviation of the time series can be used as an estimate of σ . As concerns the number of multipliers, k , we will try to extract a rough estimate from a chain of GMM estimates for λ as detailed below.

Our choice of moment conditions tries to exploit the scaling properties of the multi-fractal processes. Like the original scaling estimator, our alternative GMM estimator, therefore, uses information over various time horizons, albeit for the log differenced process instead of the original one. In particular, we select covariances of the powers of $\xi_{t,T}$, i.e., moments of the following type:

$$(19) \quad M(T, q) = E[\xi_{t+T, T}^q \cdot \xi_{t, T}^q] \quad \text{for different } T \text{ and } q = 1, 2.$$

Analytical expressions for all the relevant moments are to be found in the Technical Appendix. In order to assess the quality of the GMM estimates, we performed a chain of Monte Carlo simulations using lags $T = 1, 5, 10$, and 20 . We started with a set of two moment equations, $M(T=1, q=1)$ and $M(T=1, q=2)$, i.e. autocovariances of the absolute and squared values of log differences computed over one lag. In order to see the influence of the number of moment conditions, we have subsequently enlarged the set of moments by including $M(T=5, q=1)$ and $M(T=5, q=2)$ when using four moments, $M(T=10, q=1)$ and $M(T=10, q=2)$ when using six moments, and finally, $M(T=20, q=1)$ and $M(T=20, q=2)$ when using eight moments.

Now turn to the results of our Monte Carlo simulations. The design of our experiments is as follows: we have again chosen three sample sizes: $T = 2,000, 5,000$, and $10,000$ in all cases. Each sample is again generated as a randomly drawn subsample from a longer simulation with $k = 15$ (with a length of 10^5 observations). As with the $f(\alpha)$ Monte Carlo experiments, the parameter λ was allowed to vary from 1.05 to 1.30 using increments of size 0.05 . Again, we only show the cases $\lambda = 1.2, 1.2$, and 1.3 in Table 2 since behavior of the other cases is almost identical. Note that increasing the parameter λ amounts to generating more pronounced bursts of volatility. As is routinely done in the literature, we computed the optimal weighting matrix from the covariance matrix for which we applied the Newey-West autocorrelation and heteroskedasticity consistent estimator (which should be a consistent estimator for the covariance matrix of the moments of the transformed process). Furthermore, we used the iterative GMM in which a new weighting matrix is computed and the whole estimation process repeated until one gets convergence of *both* the estimates and the weighting matrix (cf. Hansen, Heaton and Yaron, 1996).

As it turned out, results were almost identical over parameter values in terms of biases and root mean-squared errors. At most, one recovers a very slight tendency towards increasing RMSEs with higher λ . Furthermore, we found a continuous reduction of both the bias and the mean-squared error when increasing the number of moment conditions, albeit with a decreasing rate of return in terms of relative improvement per added moment. Hence, at least from our chosen set of up to eight moments, there seems to be no reason for restricting the number of moment conditions to be used in GMM estimation. This is in contrast to the results on GMM estimation of the stochastic volatility model, for which it has been shown by Andersen and Sørensen (1996) that using too many moment conditions leads to deterioration of the results.¹¹

Unfortunately, the results with respect to the p-values of Hansen's test of overidentifying restrictions were rather disappointing (cf. Table 3). In particular, over all sampling horizons, parameter values, and moment conditions, a pronounced skewness on the left-hand side of the distributions of p-values was found. Closer inspection of the histograms, in fact, reveals, that the largest deviation from the expected Chi-square distribution always occurs in the leftmost ten or so percent of the data, while the remainder of the distribution is rather well-behaved. It, therefore, seems that with respect to Hansen's test, asymptotic theory does not provide a good guidance for samples as large as 10,000 data points. One of the reasons for this poor behavior might be the influence of the borderline solution $\lambda = 1$ at which the iterative GMM typically stops and fails to reinject the parameter estimates into the sensible region $\lambda > 1$

Insert Fig. 3 about here.

In summary, our Monte Carlo experiments suggest the following conclusions:

- (i) GMM by far outperforms the $f(\alpha)$ methodology in all cases. First, while the $f(\alpha)$ estimates have a large bias for all parameter values and sample sizes, the GMM estimates are essentially unbiased even with small sample size and few moments to match. Second, the RMSE of GMM estimates is also always smaller than that of the $f(\alpha)$ estimates at all sample sizes. When using only two moments, the RMSE can already be reduced by about 30 to 50 percent with GMM compared to that of the scaling estimator. When using more than two moment conditions, the ratio of the RMSEs becomes even higher. In the case of eight

¹¹ Results of our earlier analysis of moments of raw differences were different in many respects: (i) similar to the $f(\alpha)$ estimates, the former GMM estimates of λ had large biases which were increasing in the underlying true parameter value, (ii) there was definitely no indication of $T^{1/2}$ consistency, (iii) RMSEs were smaller (larger) than the present ones for small (large) λ , (iv) best results were found with only few moment conditions with results deteriorating with an increase of the number of moments (similar to the findings of Andersen and Sørensen for stochastic volatility models)

moments, the RMSE of the GMM estimates is only of the order of 10 percent or less of that of the scaling estimator. It is worth emphasizing that this occurs despite the use of even *more* information in the $f(\alpha)$ approach since the later estimate is based on a much higher number of scaling laws for various powers q . Note also that GMM with eight conditions is still by far faster than the scaling approach.

- (ii) The decrease in RMSE with sample size for the Binomial model is in good overall harmony with $T^{1/2}$ consistency: proceeding from 10,000 to 5,000 and further to 2,000 observations, the root mean-squared error, in fact, increases roughly with factors of about $\sqrt{2}$ and $\sqrt{2.5}$, respectively. Reduction of the (generally much larger) RMSEs from $f(\alpha)$ often occurs more slowly (particularly so for high values of the parameter λ).
- (iii) Turning to the distribution of p-values, we found that in all our scenarios, the GMM estimators suffer from skewness on the left-hand side (i.e., too many rejections of the null hypothesis). However, in contrast to the findings of Andersen and Sørensen (1996) for stochastic volatility models, there seems to be no trade-off between the preferred number of moments for RMSE (small) and specification tests (somewhat larger) in our setting.
- (iv) It also seems worth noting that in contrast to the case of stochastic volatility models, problems of non-convergence of the estimates were altogether absent in the present setting. On the contrary, it could be observed that the iterative GMM procedure very reliably converged to the same set of estimates with different choices of initial conditions. For extreme initial conditions, the number of iterations sometimes became relatively large (> 10) before the process eventually found its way to the apparent global minimum.

5. Parameter Estimation and Forecasting of Volatility

Equipped with these encouraging findings we proceed to empirical applications. Our empirical analysis uses data from four different financial markets: the New York Stock Exchange Composite Index, the German share price index DAX, the U.S. \$-Deutsche Mark exchange rate and the price of gold. The stock market series were obtained from the New York and Frankfurt Stock Exchanges, the exchange rate and precious metal series were obtained from the financial database at the University of Bonn. Our sample covers twenty years starting on 1 January 1979 and ending on 31 December 1998. For in-sample estimates we use the years 1979 to 1996 and leave the two remaining years for out-of-sample forecasts of volatility. This gives a number of in-sample observations of about 4,400 and 500 out-of-sample entries (with slight variations of the numbers between markets depending on the number of active days).

Following the results of the Monte Carlo simulations, we attempt to estimate the parameter λ from the largest set of eight moment conditions after demeaning the data and filtering out linear

dependence. In estimating the multi-fractal model with empirical data, the question of appropriate selection of the depth of the cascade, i.e. the number k of multipliers, emerges. Of course, one would like to have some data-driven selection of k . Since multi-fractal processes with varying k can be viewed as nested alternatives, the following procedure seems a natural choice: estimate λ with varying k and record the value of Hansen's statistic $J_T = T \cdot f_T(\hat{\phi})' \hat{A}_T f_T(\hat{\phi})$. From this chain of estimates, choose the one with the minimum J_T which apparently seems to provide the best fit of the underlying moments. Unfortunately, Monte Carlo simulations indicate that this algorithm would not work properly. We tried this method with 'true' k 's ranging from 4 to 14, a data size of $T = 5000$, and 500 replications for each k . 'Estimation' was done in each trial with k ranging from 1 to 20. Unfortunately, the J_T minimizing choice showed no correlation at all with the 'true' parameter k but was strongly attracted towards the extreme ends of the admissible spectrum. In all cases considered we found a concentration at small values ($k \leq 3$, accounting for about sixty percent of all experiments independent of true k) and at $k = 20$ (about twenty percent). Another chain of Monte Carlo experiments was carried out with different 'true' k 's ($k = 1, 2, 3, 5, 10, 15, 20$) and 'assumed' k 's used in estimating λ (the same values were used for the hypothesized number of multipliers). Combining all 'true' and 'assumed' k 's we found that the J test has very limited power against these closely related alternatives for sample size like those used in our empirical application.

Since we found no indication of revelation of the true k with this approach, we resorted to heuristically choosing k from a chain of GMM estimates (again ranging from $k = 1$ to 20) as the value from which onward the estimated λ practically remains constant. In fact, we typically found large variations of λ when initially increasing the number of cascade steps starting at $k = 1$, but after a number of steps, the outcome of the estimation did remain practically unchanged with addition of cascade branches. This could be taken as an indication of the number of relevant steps the algorithm could find in the data, and so we have chosen to select k as that value at which the estimated λ did not change by more than 0.001 compared to its value at $k-1$. Of course, one could imagine that the underlying process has a much larger number of volatility branches, but due to the limited size of the available time series, most of the higher multipliers are constant so that their influence remains invisible. However, in such a situation, it would probably be useful to only rely on the number of multipliers whose influence can be detected in the data when, for example, trying to forecast volatility. Luckily, misspecification of the model in the sense of using the wrong number of cascade steps, seems to be relatively harmless within a rather large range of choices for k . This can be seen in another Monte Carlo experiment whose results are shown in Table 3. Similarly like in Tables 1 and 2, the underlying data are generated from a model with 'true' $k = 15$, but now λ has been estimated under the assumptions of $k = 5, 10$, and 20. As can be seen, the misspecifications $k = 10$ and $k = 20$ do almost no harm to the resulting estimates we have generated. Ironically, the misspecified model with $k = 20$ even comes out marginally better with $\lambda = 1.1$ and 1.2 than the true model. For the very different $k = 5$, the RMSE with eight moment conditions is in the range of what

one gets from the true model with two or four moments. However, both the bias and mean squared error are still much smaller than those of the scaling method.¹²

Insert Table 3 about here

These results seem encouraging enough to proceed with empirical estimation whose results are given in Table 4 together with the estimates produced from the $f(\alpha)$ estimator.

With the scaling estimator, results show quite some variation ranging from a very low value of 1.02 for the U.S. \$-DEM exchange rate to the high 1.57 obtained for the NYSE index. Admittedly, our estimates are obtained by mechanical implementation of the scaling estimator based on (11) to (14) with a fixed number of moments and time steps used. In physical applications, typically much emphasis is laid on checking the visual appearance of the scaling behavior. However, while the visual appearance as illustrated in Fig. 1 seems in harmony with what one expects, different set-ups, in fact, sometimes lead to wide variations of the results. Comparison with the estimates obtained by Calvet and Fisher (1997) for the Lognormal model with the DM/U.S.\$ exchange rate shows quite big a gap between our $\lambda = 1.016$ and their estimate of 1.09 for the case $H = 0.5$. The sources of this remarkable differences could only be recovered by a re-investigation of their data set. However, the large root mean-squared errors that we get in our Monte Carlo simulations for the estimates of the multipliers from the $f(\alpha)$ method may provide a partial explanation of the differences.

With the GMM approach, a certain difficulty was encountered with the German stock index DAX for which at all k , the iterative GMM with eight moment conditions converged to an estimate of $\hat{\lambda} = 1$. We conjecture that this is one of the cases where the GMM fails to reinject the estimate into the sensible parameter region after it had hit the lower boundary. In order to be able to report an estimate different from the degenerate and useless $\hat{\lambda} = 1$ for this case as well¹³, we used two different approaches: first, we reduced the number of moment conditions until we eventually obtained convergence to some $\hat{\lambda} > 1$ with only two moment conditions left, second, we also report results obtained with a weighting matrix equal to the identity matrix (since this is not really a GMM estimation, the reported objective function is relatively large in the later case).

Comparing the numerical estimates obtained from the scaling and GMM estimator, we find that they differ more for the stock indices, but are relatively similar for the exchange rate and the price of

¹² Interestingly, for this grossly misspecified model, RMSE also declines much slower than $T^{1/2}$, while for $k = 10$ and $k = 20$, $T^{1/2}$ consistency is nicely preserved. Note that we also checked for the influence of the choice of k (and pertinent estimate of λ) in our forecasting exercise reported below. Results paralleled those exhibited in Fig. 3 in that practically no differences in MSEs were obtained for alternative k 's in the vicinity of the original choice

¹³ Note that according to eq. (10), $\lambda = 1$ effectively implies that returns are drawn from a standard Normal distribution.

gold. Remarkably, Hansen's test is not able to reject the multi-fractal model as the underlying data generating process for any of our time series (except for the case of the identity matrix as the 'weighting' matrix used for the DAX) at any conventional level of significance! This good fit is the more remarkable as we have seen that the test of overidentifying restrictions produces a large number of false rejections of the null in Monte Carlo simulations. It shows that the MF model provides a reasonable fit of the chosen moment conditions. It is interesting to note, that Lux (2001) was also unable to reject the MF model in tests of the Kolmogorov-Smirnov type for identity of the hypothesized unconditional distribution from the combinatorial MF model and the empirical distribution, for the same underlying time series. Comparing the results with those obtained from the standard GARCH(1,1) model and a GARCH model with Student- t innovations, he also found the MF model to dominate in terms of the Kolmogorov-Smirnov distance.

Insert Table 4 about here

6. Forecasting Volatility: A Competition between MF, GARCH, FIGARCH and Historical Volatility

According to the above results, the multi-fractal model appears capable of producing good fits to both the unconditional distribution and the conditional moments of empirical data.¹⁴ However, estimating the parameters of a new model alone does not prove that it might be a useful addition to the existing tool-box of empirical finance. Since the main motivation of the multi-fractal model is to capture the supposed hierarchical structure of the volatility dynamics, one of its contributions should be an improved ability to *forecast* financial volatility. In order to see how our estimates perform on this task, we have carried out a competition between forecasts of volatility derived from the Lognormal multi-fractal model with a number of well-known alternatives. Given that one of the virtues of the multi-fractal model is incorporation of long memory in various powers of returns, we found that we should test its forecasting performance over relatively long time horizons. Like many forecasting competitions, we start with 1 day and 5 day forecasts, but then proceed via 10 day increments to forecasts up to 100 periods ahead.

The competitors of our multi-fractal forecasts are (1) the naïve forecasts formed on the base of historical volatility, (2) forecasts computed from the standard GARCH(1,1) model and (3) forecasts derived from the FIGARCH(1,d,1) model first proposed by Baillie *et al.* (1996). Inclusion of the latter seems sensible since it also has built-in long memory of volatility and, therefore, should be the

¹⁴ Of course, it remains to be shown whether estimates produced from different sets of moments are in harmony with each other.

main rival of the new multi-fractal model. While the derivation of efficient forecasts from GARCH and FIGARCH models is well-known, it is not clear how to construct efficient predictors from the new multi-fractal model. In principle, one would like to identify the ruling multipliers within the observable realizations of the process (in fact, identification of the multipliers within the last available entry of the time series would be sufficient), and from this knowledge, could probably compute most efficient forecasts on the base of expected future replacements of individual volatility components. Unfortunately, this identification problem (known as the inverse multi-fractal problem in physics) is still unsolved for the combinatorial models. Of course, our approach also provides no solution to this problem for the more complicated causal structures analyzed here. What one can do, however, is deriving forecasts based on best *linear* predictors for the multi-fractal model. The later only need analytical solutions for the autocovariances of x_t^2 which are provided in the Technical Appendix.

With this information, forecasts of future volatility can be computed following the standard approach for best *linear* forecasts outlined, for example, in Brockwell and Davis (1991, c.3). Assuming that the data under scrutiny follow a stationary process $\{X_t\}$ with mean zero, h -step forecasts are obtained as:

$$(19) \quad \hat{X}_{n+h} = \sum_{i=1}^n \phi_{ni}^{(h)} \cdot X_{n+1-i} = \boldsymbol{\phi}_n^{(h)} \cdot \mathbf{X}_n$$

with the vector of weights $\boldsymbol{\phi}_n^{(h)} = (\phi_{n1}, \phi_{n2}, \dots, \phi_{nn})'$ being any solution of $\boldsymbol{\Gamma}_n \boldsymbol{\phi}_n^{(h)} = \boldsymbol{\gamma}_n^{(h)}$, $\boldsymbol{\gamma}_n^{(h)} = (\gamma(h), \gamma(h+1), \dots, \gamma(n+h-1))'$ being the autocovariances for the data generating process of X_t at lags h and beyond, and $\boldsymbol{\Gamma}_n = [\gamma(i-j)]_{i,j=1,\dots,n}$ the pertinent variance-covariance matrix. It is well known, that this is the best linear estimator under the criterion of minimization of mean squared error. It is also known that for long-memory processes, one should use as much information as available, i.e., the vector \mathbf{X}_n should contain all past realizations of the process under study. In our application, the realizations X_t are given by:

$$(20) \quad X_t = x_t^2 - E[x_t^2] = x_t^2 - \hat{\sigma}^2$$

with $\hat{\sigma}$ the standard deviation of the time series which as an elementary estimate for the standard deviation of the incremental process enters besides our above estimates of λ and k . Note that the HV predictor can be interpreted as a special case of (19) and (20) which emerges if weights of all past observations are identical equal to zero and, hence, one assumes absence of temporal dependency in the volatility dynamics. The computational burden of these predictors is immensely reduced by using the generalized Levinson-Durbin algorithm developed in Brockwell and Dahlhaus (2002, particularly their algorithm 6).

GARCH and FIGARCH estimates are obtained on the base of (quasi-) maximum likelihood estimates of the parameters of the following standard formalizations:

$$(21) \quad x_t = \mu + \rho \cdot x_{t-1} + h_t \varepsilon_t \quad \text{with } \varepsilon_t \sim N(0, 1)$$

and

$$(22) \quad h_t = \omega + \alpha_1 x_{t-1}^2 + \beta_1 h_{t-1}, \quad \omega > 0, \alpha_1, \beta_1 \geq 0$$

or

$$(23) \quad h_t = \omega + \beta_1 h_{t-1} + (1 - \beta_1 L - (1 - \phi_1 L)(1 - L)^d) \varepsilon_t^2$$

for the GARCH(1,1) and FIGARCH(1,d,1) specification of the volatility dynamics, respectively. In GARCH and FIGARCH estimation, we have also demeaned the raw data and removed linear dependence (through eq. 21) as we did when developing the MF and HV forecasts.

With respect to the FIGARCH model, we should note that the underlying concept and implementation has been extensively discussed in recent literature (cf. Chung, 2002; Zumbach, 2002). Despite certain recently emphasized ambiguities of their parameterization, we stick to the original framework of Baillie *et al.* in our empirical implementation. With respect to the infinite number of lags incorporated in the fractional difference we followed most of the available literature by using a truncation lag of 1000 past observations in both estimation and forecasting (together with 1000 presample values set equal to the variance of the in-sample observations). Alternatively, we also tried estimation and forecasting using all available past data (again with 1000 presample observations), but results were practically identical.

Before considering the results of our competition in detail, a short review of available empirical evidence on the forecasting performance of long-memory processes is in order. To our great surprise, despite the immense literature on volatility forecasting (surveyed recently by Poon and Granger, 2003), entries comparing the forecasts from FIGARCH and more traditional GARCH models are extremely scarce and those available do not yield a clear indication for the long-memory variant to provide an advantage in this respect. Basically, only two papers with a direct comparison of FIGARCH and GARCH seem to be available at present: Vilasuso (2002) and Zumbach (2002), both considering forecasting of volatility in foreign exchange markets. While Vilasuso uses daily data of five currencies against the U.S. dollar, Zumbach's data base consists of intra-daily variations of the Swiss Franc against the U.S. dollar. The later finds, that the original FIGARCH model as well as a variety of closely related specifications of long-memory models have a higher log-likelihood

than the basic GARCH(1,1) model, but provide only very modest gains in forecasting daily volatility on the order of 1 to 2 percent of MSE. Vilasuso, on the other hand, does not report figures for model selection criteria, but notes relatively large reductions of both mean squared error and mean absolute errors for all currencies over forecasting horizons of 1, 5, and 10 days. The advantage of FIGARCH versus GARCH (as well as EGARCH) reported in this paper increases with forecasting horizon with the difference ranging between 8 and 37 percent at the 10 day horizon. To date, this study appears to be the only entry in the literature reporting a clear advantage of the FIGARCH model over simpler specifications (however, we were unable to replicate his results for the U.S. Dollar-DEM exchange rate). Another interesting comparison in our context is that by Calvet and Fisher (2002b) between GARCH, Markov-Switching GARCH and one variant of a causal multi-fractal model. They find, that their Binomial model mostly dominates GARCH and MS-GARCH in terms of AIC and BIC model selection criteria (data are again daily returns of four currencies against the U.S. dollar). However, when it comes to forecasting at daily horizons, it mostly does marginally worse than GARCH(1,1).

Under the light of the above review of similar literature, our ensuing results should be of interest under a variety of aspects: first, what evidence exists concerning the case of GARCH versus FIGARCH (or, more generally, short-memory vs. long-memory models), is limited to foreign exchange markets so that the analysis of stock and precious metal markets would give us some clue on whether the above results are typical or not. Second, evidence concerning the performance of multi-fractal models versus GARCH is confined to the recent entry by Calvet and Fisher (2002b), while it is non-existing for the MF versus FIGARCH case. The later, should, however, be particularly interesting since both models share the long-memory property observed in empirical data. Third, we also do have only comparative evidence on forecasting competitions for relatively small horizons (mostly one day comparisons). However, from their very construction, long-memory models should be able to play out their advantages more clearly over longer time horizons. To see whether they have any use, it would, therefore, be of relevance to compare their forecasting performance for long horizons with that of short-memory (GARCH) or no-memory (HV) approaches.

With this background, turn to the results of our comparison. GARCH and FIGARCH estimates are given in Table A1 in the Appendix. We see that AIC and BIC selection criteria prefer FIGARCH for both stock indices as well as the price of gold, while for the exchange rate, GARCH seems more appropriate. A particularly interesting case, is, however, that of gold. For this time series, we actually could find two maxima of the FIGARCH log-likelihood: one global maximum at a corner solution with $d = 0.999$ (i.e. practically identical to an EGARCH specification) which

dominates an interior local maximum with $d = 0.41$.¹⁵ In our forecasting experiments, we report results from both specifications.

The forecasting results are conveniently summarized graphically in Figs. 4 a to d. for the mean squared errors obtained for the four (five) models over forecasting horizons ranging from 1 day to 100 days. Results for absolute errors are qualitatively similar so that we dispense with a detailed consideration of this quantity here.¹⁶ Starting with the NYSE composite index, we find a mixed picture: while FIGARCH and MF seem to dominate over GARCH and HV over short horizons. However, from about 30 days onward, HV comes in best followed by MF, GARCH, and FIGARCH, although differences appear to be negligible. The picture is only slightly different for the second stock index, the German DAX: here the time series models have also almost indistinguishable performance, but are uniformly somewhat better than historical volatility.

More interesting differences appear with the two remaining series: For the U.S. dollar-DEM exchange rate, the MF seems to dominate over all time horizons with the gap between its forecasts and those of all alternative models continuously increasing with forecasting horizon. Second comes FIGARCH which in turn is by far better than GARCH at long horizons (although the simpler GARCH would have been favored by model selection criteria). HV first provides the weakest forecasts, but from a horizon of about 30 days, dominates GARCH and eventually also gets a slight advantage against FIGARCH at the 100 day horizon. If we look at some of the details, we see that initially all the time series models have very similar MSEs which provide an improvement against HV of about 11 percent. However, while the advantage of GARCH is fading away quite quickly, FIGARCH and particularly MF manage to keep a certain advantage against HV for rather long forecasting horizons. In the case of MF, the difference is declining very slowly and stays in the range between 5 and 6 percent for all time horizons between 20 and 100 days. Taking into account, that HV uses the same estimate of the unconditional variance, this advantage has to be attributed to a successful extraction of long-memory features.¹⁷

¹⁵ Parameter estimation was carried out under the restriction $0 < d \leq 0.999$, and repeated ten times with different starting values. Except for gold, we found only apparently unique maxima.

¹⁶ We also computed R^2 's from regression of actual volatility on its various forecasts. As it turned out, results were almost uncorrelated with the very clear picture that emerged from comparisons of MSE and MAE. Inspection suggests that the obvious violation of the linear model invalidates any inference drawn from this popular measure of forecasting accuracy.

¹⁷ It should also be mentioned, however, that we were unable to replicate the dramatic reductions of MSE and AME from the FIGARCH model against GARCH at 1, 5, and 10 day horizons reported for the same data by Vilasuso (2002). Note that we have chosen exactly the same in-sample and out-of-sample periods. Although our time series is from a different source, we would not expect this to exert such a large influence on empirical results. One difference in specification is that Vilasuso only uses a truncation lag of 250 past observations. We have repeated our exercise with this choice. What we found was, on the one hand, parameter estimates closer to the ones reported in his study, but, on the other hand, no change in forecasting quality.

The case of gold also speaks in favor of the value added by long-memory models albeit with some differences in its details. First, the dominant FIGARCH1 specification performs very poorly and is the worst of all time series models considered, while the local maximum of FIGARCH2 is head to head with (and, in fact, slightly better than) MF. Both are again much better than GARCH and HV. Here, the use of time series models in fact, leads to dramatic reductions of MSE against the naïve HV model. Initially, at the 1 day horizon, all models have MSEs as small as about 37 percent of that of HV. Although some of the advantage is melting away with higher time horizons, at lag 100 we still have 8 percent difference between GARCH and HV and as much as 40 and 45 percent difference between MF and FIGARCH2, and HV, respectively. Again, this is a clear indication of the potential usefulness of long-memory models for long-term volatility predictions.¹⁸

Our results for the exchange rate and the price of gold underscore the value of long memory models for volatility predictions. Although it seems very natural that these models should play out their advantage at relatively long forecasting horizons, little supporting evidence had been brought forward for this conjecture in the available literature so far. The failure of both FIGARCH and MF to improve on the forecasting accurateness of GARCH and HV for the two stock market indices calls for more comparative research along the previous lines. The striking difference in the results is the more puzzling since the huge body of time series literature on volatility models did find only minor differences in the volatility dynamics of stock markets and foreign exchange markets. One potential reason for the lack of improvement for the NYSE and DAX indices might be a structural break occurring near the beginning of our out-of-sample period. In fact, volatility has increased dramatically for both markets in 1997/98 while it remained much closer to earlier periods for the exchange rate and for gold (this difference in out-of-sample periods can already be seen in the behavior of HV in Figs. 4a. – d.).

As concerns the multi-fractal model as the main focus of this paper, we see that in those cases where we find any remarkable differences in forecasting performance at all, its forecasts come out very favorably. It dominates all other forecasts over long horizons for the U.S.\$-DEM, and is only slight worse than FIGARCH2 for gold (however note that the later would have been discarded in favor of the poorly performing FIGARCH1 when selecting according to information criteria). This outcome seems the more promising taking into account, that for GARCH and FIGARCH we have used the most efficient forecasts under these data generating processes, while we have used only

¹⁸ One might ask, how the estimates obtained from the scaling estimator would have performed when used for forecasting future volatility. Somewhat ironically, results are not much different from those obtained with the GMM estimates. This similarity may have different sources: in the case of the stock markets, MSEs are apparently dominated by the increase in volatility in 1997/98 which all methods have difficulties to cope with. Hence, another MF estimator adds another time series model which is similarly insufficient to make any gain compared to its competitors. In the case of the exchange rate and the price of gold, the particular parameter estimates are not too different between the scaling estimator and GMM, so that forecasts are rather similar.

best linear forecasts for MF. There seems, thus, even scope for improvements on the performance of the new MF model.

Insert Fig. 4 about here

7. Conclusion

This paper has been concerned with estimation of a particular causal variant of the recently proposed new multi-fractal model for financial returns and its application in forecasting future volatility. From their very construction, multi-fractal processes account for the pervasive finding of long-memory effects in volatility. They also capture a broader spectrum of dependence structures than models of the uni-fractal type in that different degrees of auto-correlation in various powers of returns can be explained *within* these models.

One of the contributions of this paper consisted in the development of consistent GMM estimators for the key parameter characterizing the underlying distribution of the multipliers. It could be shown that this estimator had much better small sample properties than the traditional scaling method adopted from statistical physics. It should be straightforward to develop similar GMM estimators for various alternative multi-fractal models, e.g., the Binomial and Log-Levy types discussed in the literature. Our estimation method still shares one of the drawbacks of the scaling method: it does not deliver a GMM estimate of the number of cascade steps together with the distributional parameter. In order to complement our estimated parameter set, we, therefore, had to resort to a more heuristic approach for an assessment of the relevant number of multipliers. However, Monte Carlo simulations have also shown that misspecification within a certain range of the model at this end seems to do be rather harmless.

Equipped with these results, we have estimated multi-fractal parameters for four important financial time series and used these estimates in out-of-sample forecasting of volatility over various time horizons. Although results were not uniform, they indicate a certain potential of improvement over no-memory (HV) and short-memory (GARCH) approaches. While results for the U.S. and German stock market do not indicate a clear advantage of any of the four forecasts, for the U.S.\$-DEM and gold price, we can see a clear advantage of long-memory models. Furthermore, at least in one case, MF has the lead against FIGARCH. As an interesting additional insight, our results also indicate that model choice according to standard information criteria does not necessarily favor those models which provide the best forecasting performance. Note that if we would have only chosen the preferred member of the (FI)GARCH family as the rivals of the MF model, we could have reported a much clearer advantage for the later.

Our results underscore that the new family of hierarchical volatility models of the multi-fractal type should be a useful addition to the tool-box of financial economists. The early stage of research on these models suggests a number of avenues for future work: many alternative multi-fractal models with different numbers of states, different distributions of the volatility components and different marginal distributions could be explored along the above lines. Furthermore, one would like to see whether forecasting performance could be further improved by developing non-linear predictors taking account of the hierarchical nature of the underlying process. One would surely also like to know in how far our striking differences obtained for stock markets, on the one hand, and for foreign exchange and precious metal markets, on the other hand, are reflections of intrinsic difference or are rather governed by the particular time interval chosen for out-of-sample forecasting exercise.

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Table 1: Simulated Biases, Standard Errors and RMSEs for Scaling and GMM Estimators

	Method	n	Bias($\hat{\lambda}$)	SE($\hat{\lambda}$)	RMSE($\hat{\lambda}$)
$\lambda = 1.1$	Scaling	2.000	0.120	0.185	0.220
		5.000	0.074	0.125	0.145
		10.000	0.067	0.115	0.133
	GMM(2)	2.000	0.007	0.119	0.120
		5.000	0.002	0.083	0.083
		10.000	0.002	0.065	0.065
	GMM(4)	2.000	-0.011	0.071	0.072
		5.000	-0.001	0.046	0.046
		10.000	0.001	0.032	0.032
	GMM(6)	2.000	-0.005	0.050	0.050
		5.000	-0.000	0.030	0.030
		10.000	0.003	0.021	0.022
	GMM(8)	2.000	-0.007	0.040	0.041
		5.000	0.001	0.024	0.024
		10.000	0.003	0.017	0.017
$\lambda = 1.2$	Scaling	2.000	0.115	0.240	0.266
		5.000	0.086	0.199	0.216
		10.000	0.067	0.147	0.161
	GMM(2)	2.000	-0.028	0.142	0.145
		5.000	-0.009	0.100	0.100
		10.000	-0.003	0.070	0.071
	GMM(4)	2.000	-0.019	0.082	0.084
		5.000	-0.004	0.052	0.052
		10.000	0.003	0.036	0.036
	GMM(6)	2.000	-0.015	0.058	0.060
		5.000	-0.003	0.034	0.034
		10.000	0.001	0.024	0.024
	GMM(8)	2.000	-0.012	0.047	0.049
		5.000	-0.000	0.029	0.029
		10.000	0.001	0.019	0.019
$\lambda = 1.30$	Scaling	2.000	0.125	0.263	0.291
		5.000	0.060	0.208	0.217
		10.000	0.044	0.176	0.181
	GMM(2)	2.000	-0.035	0.169	0.173
		5.000	-0.012	0.109	0.109
		10.000	0.003	0.072	0.072
	GMM(4)	2.000	-0.026	0.091	0.094
		5.000	-0.006	0.055	0.055
		10.000	-0.002	0.038	0.038
	GMM(6)	2.000	-0.020	0.065	0.068
		5.000	-0.005	0.040	0.040
		10.000	0.000	0.025	0.025
	GMM(8)	2.000	-0.017	0.055	0.057
		5.000	-0.004	0.032	0.032
		10.000	0.000	0.022	0.022

Note: see main text for the design of the scaling estimator and the moment conditions used for GMM estimation. The depth of the cascade has been set equal to $k = 15$, the standard deviation of the increments is $\sigma = 1$.

Table 2: Simulated Fractiles of p Values for the Test of Overidentifying Restrictions

	Method	n	0.05	0.1	0.5	0.9	0.95
$\lambda = 1.1$	GMM(2)	2.000	0.181	0.262	0.623	0.940	0.974
		5.000	0.129	0.184	0.596	0.939	0.975
		10.000	0.120	0.176	0.535	0.906	0.950
	GMM(8)	2.000	0.185	0.237	0.500	0.865	0.940
		5.000	0.137	0.183	0.458	0.834	0.917
		10.000	0.103	0.144	0.434	0.843	0.923
$\lambda = 1.2$	GMM(2)	2.000	0.171	0.213	0.598	0.917	0.964
		5.000	0.115	0.154	0.543	0.915	0.965
		10.000	0.102	0.157	0.552	0.914	0.949
	GMM(8)	2.000	0.187	0.238	0.520	0.880	0.955
		5.000	0.130	0.166	0.475	0.892	0.947
		10.000	0.111	0.155	0.481	0.869	0.931
$\lambda = 1.3$	GMM(2)	2.000	0.127	0.182	0.575	0.930	0.960
		5.000	0.107	0.168	0.541	0.901	0.953
		10.000	0.100	0.151	0.550	0.917	0.962
	GMM(8)	2.000	0.135	0.176	0.485	0.877	0.932
		5.000	0.144	0.200	0.500	0.884	0.938
		10.000	0.110	0.145	0.495	0.894	0.942

Note: see main text for the moment conditions used for GMM estimation. The results are obtained with the same Monte Carlo simulations from which the results of Table 2 have been extracted. Hence, the depth of the cascade is $k = 15$, and the standard deviation of the increments is $\sigma = 1$. Because of the homogeneity of the results over different sets of moments, only those for the sets of two and eight moment conditions are shown.

Table 3: Estimating λ with the Wrong Number of Multipliers

	k used in GMM	n	Bias($\hat{\lambda}$)	SE($\hat{\lambda}$)	RMSE($\hat{\lambda}$)
$\lambda = 1.1$, true k = 15,	5	2.000	0.013	0.048	0.049
		5.000	0.021	0.030	0.037
		10.000	0.023	0.021	0.031
	10	2.000	-0.005	0.040	0.041
		5.000	0.003	0.025	0.025
		10.000	0.004	0.017	0.018
	20	2.000	-0.006	0.041	0.041
		5.000	0.003	0.024	0.024
		10.000	0.003	0.016	0.017
$\lambda = 1.2$, true k = 15,	5	2.000	0.027	0.052	0.058
		5.000	0.038	0.032	0.050
		10.000	0.040	0.024	0.047
	10	2.000	-0.011	0.047	0.048
		5.000	0.000	0.028	0.028
		10.000	0.003	0.019	0.019
	20	2.000	-0.013	0.046	0.048
		5.000	-0.002	0.028	0.028
		10.000	0.001	0.019	0.019
$\lambda = 1.3$, true k = 15,	5	2.000	0.035	0.061	0.070
		5.000	0.054	0.038	0.066
		10.000	0.056	0.027	0.062
	10	2.000	-0.015	0.054	0.056
		5.000	-0.004	0.032	0.032
		10.000	0.002	0.022	0.022
	20	2.000	-0.020	0.054	0.058
		5.000	-0.005	0.033	0.033
		10.000	0.001	0.022	0.022

Note: in this set of experiments, we investigate the behavior of the estimate of λ with misspecified depth parameter k. The ‘true’ k is equal to 15 in all experiments, $\sigma = 1$, and GMM specification is GMM(8).

Table 4: In-Sample Parameter Estimates from Scaling Estimator and GMM

Data	$\hat{\lambda}$ from $f(\alpha)$	$\hat{\lambda}$ from GMM(8) (t-statistic)	\hat{k}	J (p-value)
NYCI	1.567	1.043 (41.441)	9	5.364 (0.616)
DAX	1.172	1.045 ^a (47.324)	10	9142.815 (0.000)
		1.036 ^b (11.184)	6	0.035 (0.852)
US\$-DEM	1.016	1.049 (44.082)	10	7.029 (0.426)
Gold	1.117	1.123 (43.438)	10	8.387 (0.300)

Note: The scaling estimator is implemented in the following way: 25 time increments Δt ranging from $\Delta t = 5$ to $\Delta t = T/5$ (T the length of the time series) have been used which are equally spaced in logs (i.e. the next Δt is computed as $\Delta t' = \exp(\ln(\Delta t) + \ln(T/5)/25)$), only positive moments are used, $q = 0.1, 0.2 \dots (0.1) \dots 3, 3.5, \dots (0.5), \dots 10$, and the estimate of λ is found by minimizing the squared deviation between the theoretical and empirical spectrum at the α coordinates of the empirical spectrum. For GMM estimation, the eight moment conditions listed in the main text have been used. In the case of the DAX, iterative GMM estimation with 8 moment conditions produced only degenerate results (estimated $\lambda = 1$). In this case, results reported here have been obtained via the following modifications of the original set-up: a. estimation with only two moment conditions, $M(T=1, q=1, 2)$, and b. estimation with eight moment conditions, but with the identity matrix used as the ‘weighting’ matrix. The number of volatility components, k , is estimated via a chain of GMM runs with underlying k ranging from 1 to 20. When the estimate of λ changes by no more than 0.001 in successive steps, we choose the last k as the relevant number of multipliers. $\hat{\lambda}$ and J are reported for this particular GMM run. The in-sample entries extend from 1 January 1979 to 31 December 1996.

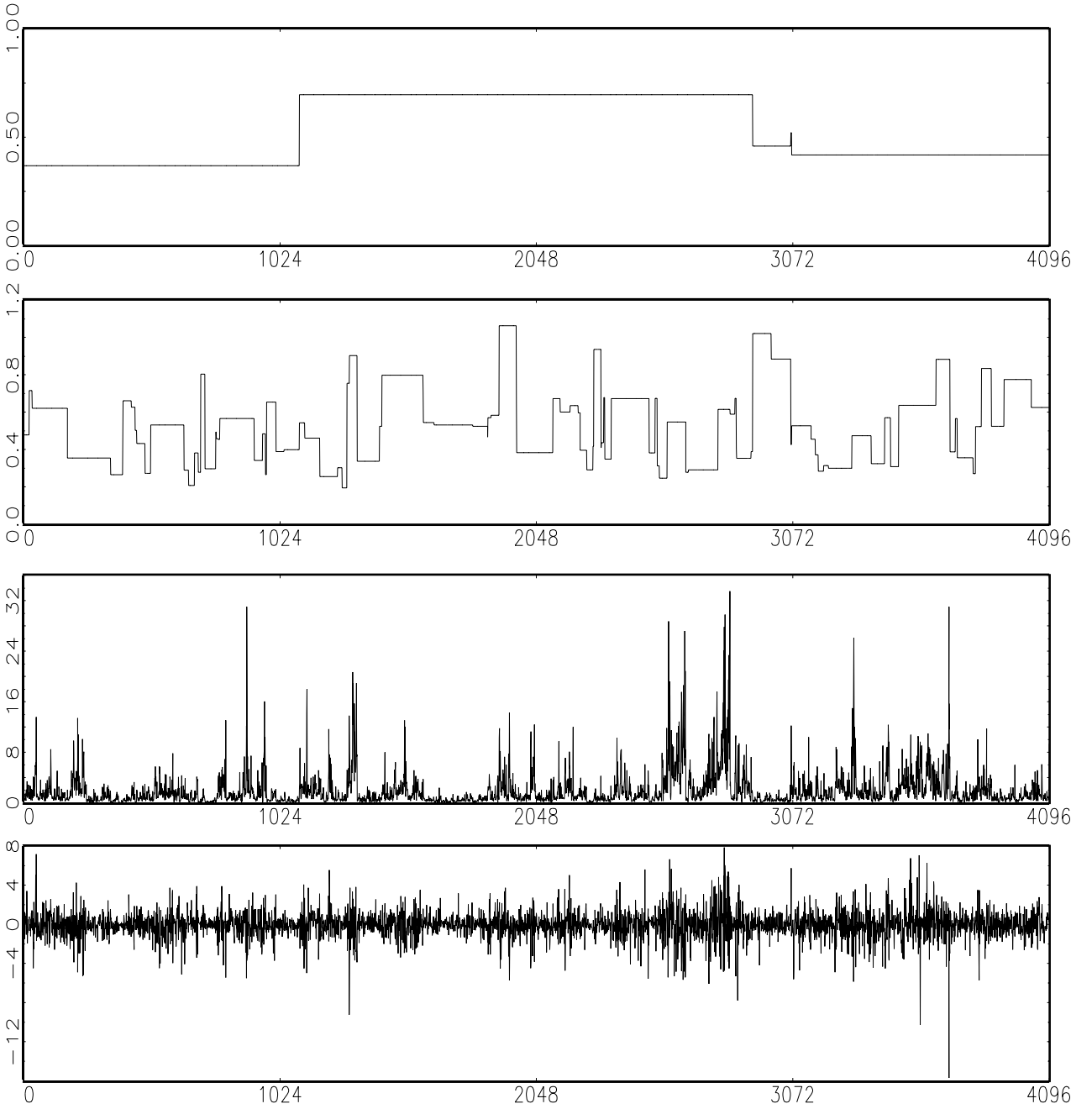


Fig. 1: Simulation of a Causal Lognormal Cascade and its Use as a Local Volatility Process.

For a cascade with $k = 12$ levels and parameter $\lambda = 1.1$, the upper panels of the figure show (from top to bottom) the time development of the multipliers of level 2 and 6, and the product of all 12 multipliers. Note that with the original combinatorial cascade, one would expect evenly spaced change periods of the multipliers while here we have random survival times. In the lower panel, a compound process is illustrated in which the same cascade is used as a local volatility process. Superimposed is a Wiener Brownian motion ($H = 0.5$).

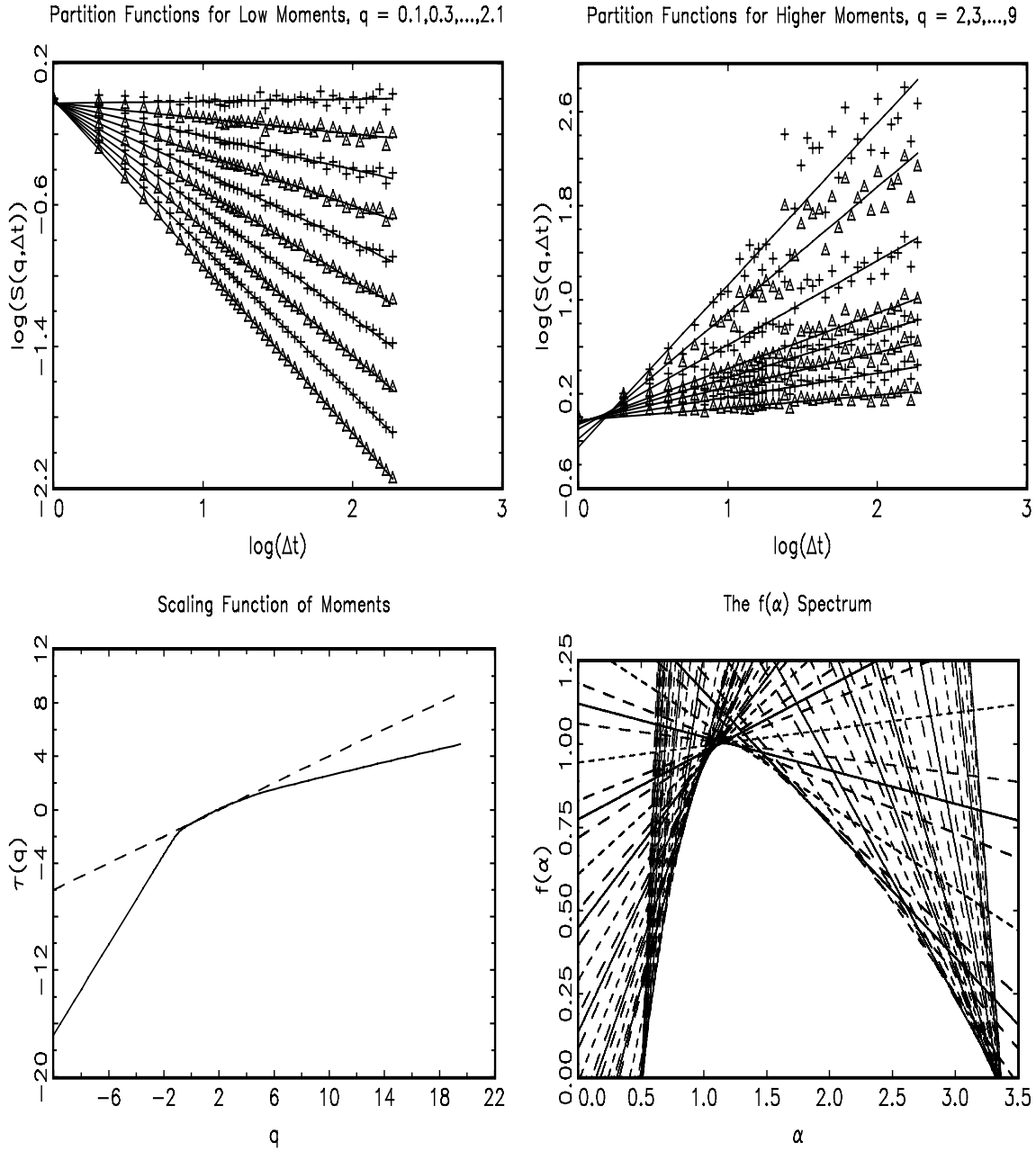


Fig. 2: Scaling and Multi-Fractal Spectrum of DAX Returns. The *upper panel* shows the partition functions obtained for a variety of (positive) moments ranging from $q = 0.1$ to $q = 9$. While we observe an almost perfectly linear relationship for the lower moments, there is more randomness in the scaling of higher moments. The *bottom panel* shows that the deviation from the expected behavior $\tau(q) = q/2 - 1$ under Brownian motion (*left*), and the $f(\alpha)$ spectrum of Hölder exponents obtained from the Legendre transformation (*right*).

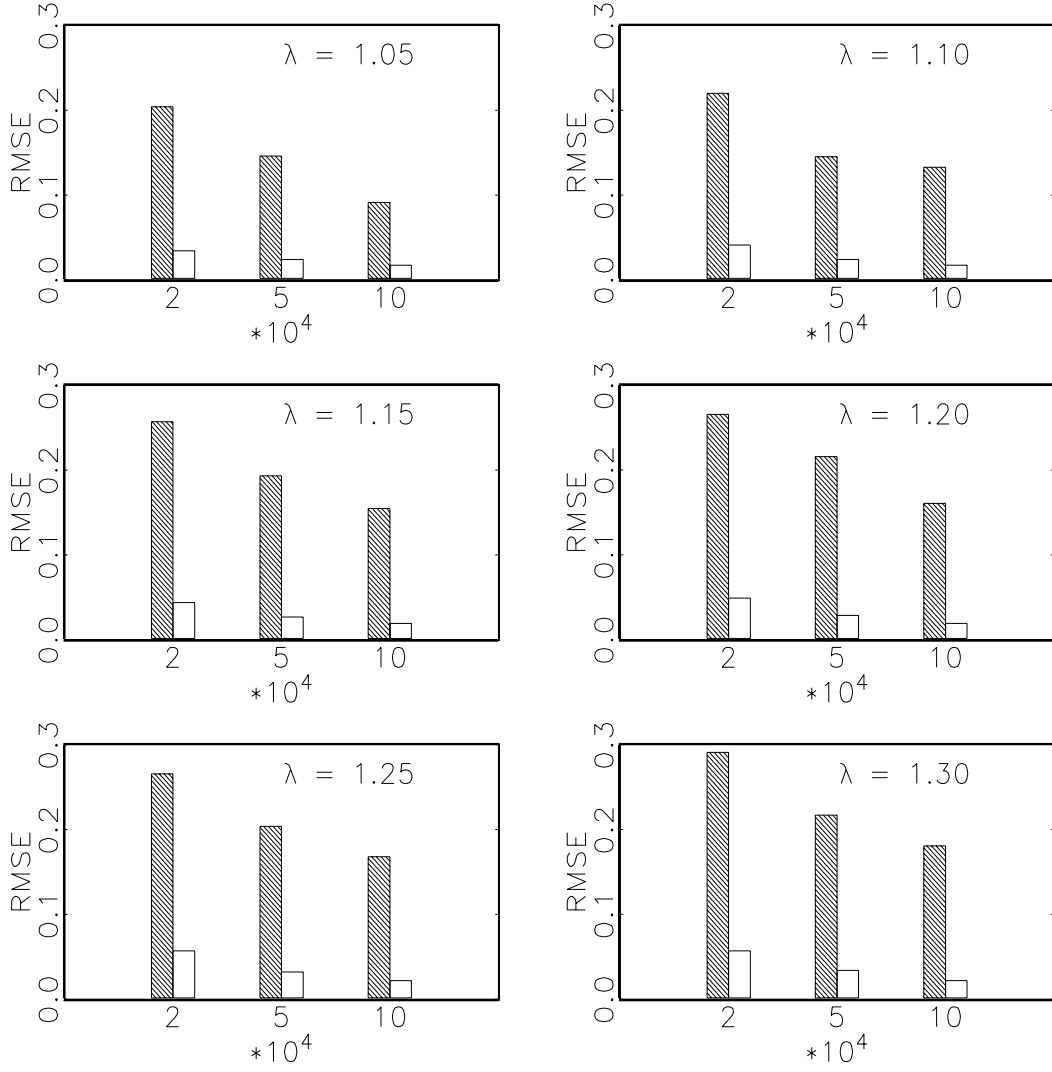


Fig. 3: RMSE of $f(\alpha)$ and GMM estimators of the parameter λ of the Lognormal multi-fractal model. The shaded bars illustrate the development of the RMSE with sample size for the scaling estimator, the unshaded bars illustrate that of the GMM estimator.

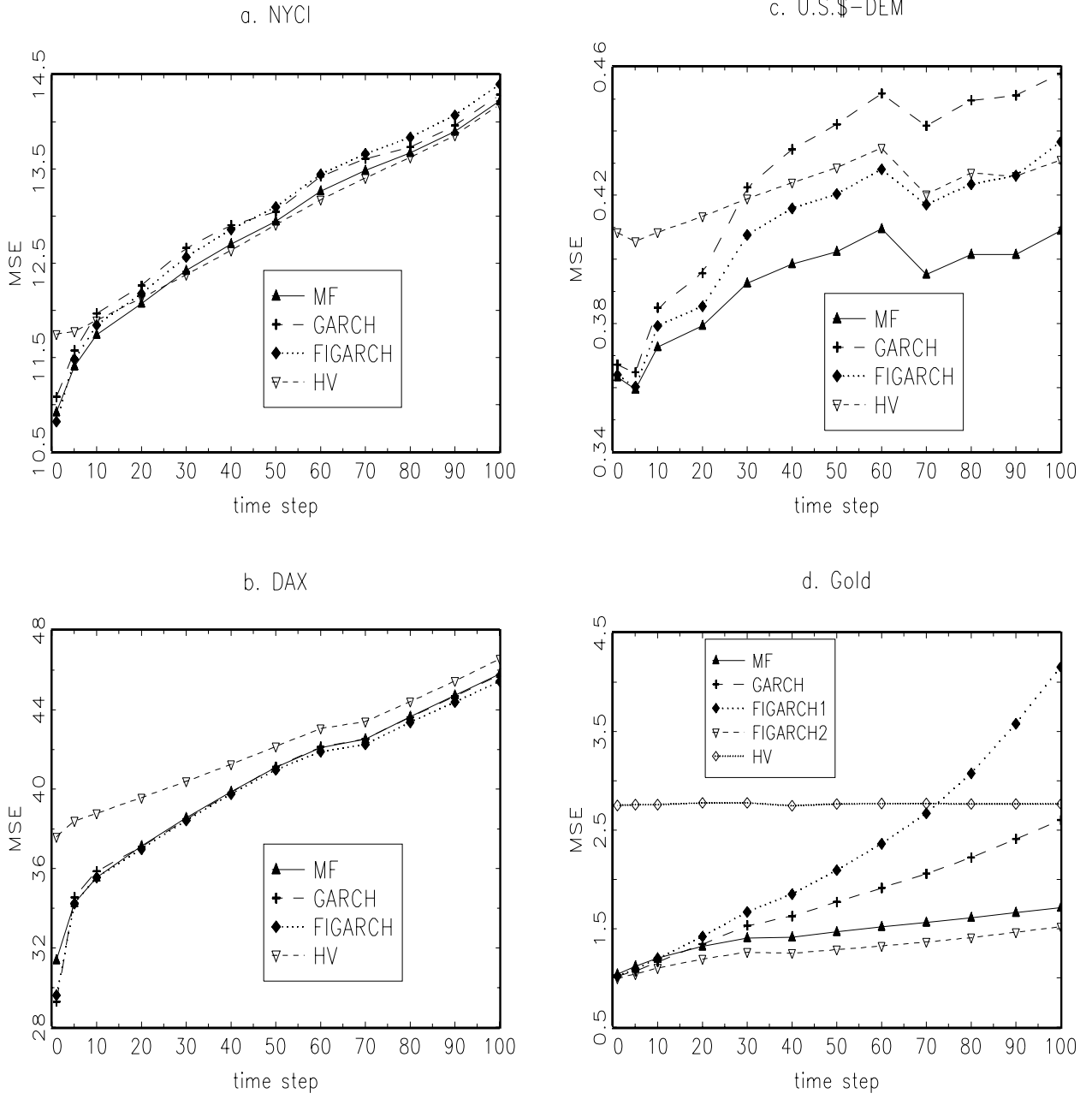


Fig. 4: Mean squared errors of volatility forecasts based on historical volatility (HV), GARCH (1,1), FIGARCH(1,d,1), and the Lognormal multi-fractal model (MF). Time horizons are: 1 day, 5, 10, 20, ..., 100 days. Estimates are based on the period 01/01/1979 to 12/31/1996 and out-of-sample forecasts are computed for the time period 01/01/1997 to 12/31/1998.