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The Universal Shape of Economic Recession and Recovery after a Shock

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Abstract
We show that a simple and intuitive three-parameter equation fits remarkably well the evolution of the gross domestic product (GDP) in current and constant dollars of many countries during the times of recession and recovery. We then argue that it can be used to detect shocks and discuss its predictive power. Finally, a two-sector theoretical model of recession and recovery illustrates how the severity and length of recession depends on the dynamics of transfer rate between the growing and failing parts of the economy.

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1 Introduction

Explaining growth and recessions has been central to Economics ever since its beginning (Quesnay 1888; Smith 2000; Ricardo 2004; Keynes 2007; Solow 2000; Schumpeter 1980; Romer 1990; Robbins 2000). The recent collapse of the former block of European communist countries and their subsequent recovery gave much data to analyse and comment (Sachs 1996; Fischer and Sahay 2000; Stiglitz and Bhattacharya 2000; Popov 2006; Kolodko 2000; Cernat 2002). However, since recession and recovery are usually split into distinct periods in economic analysis, the factors of decline and growth have been investigated separately (e.g. Popov (2006); Kolodko (2000); Cernat (2002)) and little attention has been devoted to the intrinsic relationship between recession and recovery. We take the position that after a dramatic change in the economy, the very same process responsible for the recovery is already at work in the recession.

In section 2, we consider the yearly evolution of countries having experienced lasting recessions others than those due to wars, which include many of the former communist block economies following their liberalisation. We find that our “universal recession-recovery shape” fits all of them between shocks and that each additional shock brings a new episode fitted by our equation. Its accuracy is confirmed to high degree by quarterly data for Finland; even more, this equation can be used to detect automatically additional shocks.

In section 3, we introduce a simple two-sector model of growth with economic transfer. The main idea is that following dramatic events, large sectors previously dominating the economy start fading away while previously undeveloped sectors take over; grouping all the growing sectors on the one hand and all the fading ones on the other hand, the recession-recovery process is then completely determined by the value of the returns for the two aggregate sectors and the transfer rate of economic activity between them. We also discuss why a simple two sector model is able to reproduce faithfully the typical global dynamics of recession-recovery. Then we exploit this understanding in order to find an optimal dynamic schedule for the effective transfer rate between the fading and the taking-over sectors. More specifically, we are looking for an effective transfer rate that minimises the depth and duration of the recession, and maximises both the GDP value and the final growth rate. We finally propose a means to differentiate static from dynamical effective policies in historical data.

2 Data analysis

The economic activity of many countries shows dramatic and sudden decreases followed by a slow road to recovery, a pattern commonly known in Economics as L, U or J-shape depending on the state of unfolding of the J shape (Cernat 2002). Our dataset, taken from http://data.uno.org, starts in 1980. We retained the 23 countries having undergone recessions of at least three consecutive years, among which many of the previously communist Eastern European countries; Finland, because of the strong links between its economy and those of the Eastern Block, suffered from the same crisis; Sweden had a crisis of its own at about the same time, caused by the burst of a real estate and financial bubble. Bolivia, Bahamas and Chile follow the same pattern, at different times, for reasons unknown to us.
Figure 1: Time evolution of the GDP in current dollars of 23 countries, and the fits to Eq. (1)

Figure 2: Time evolution of the GDP in constant dollars of 23 countries and the fits to Eq. (1)
2.1 Yearly GDP data

We focus on gross domestic product (GDP) both in current and constant dollars. The latter is also called real GDP as it discounts inflation and makes it possible to better compare economic activity from year to year and between countries. As we shall see, however, it is more irregular, in part because of the dynamics of currency exchange rates, which in turn reflects partially that of interest rates and differences in budget deficits.

As it turns out, most of these recessions were caused by political and taxation reforms or financial crises; in other words, sudden shocks. One key assumption in the following is that the intrinsic economic parameters (growth and decay rates) are constant ever after a shock. We shall not attempt to model the occurrence and properties of shocks. Figure 1 reports the evolution of the GDP in current dollars of several countries, revealing a common pattern. These recessions can be characterised by their intensity (maximum loss of GDP), the time of the minimum GDP and the time to recover the previous level of economic production. The evolution of the GDP in constant dollars (Fig. 2) shows similar patterns.

Remarkably, all previously communist Eastern European and Soviet Union countries have experienced a lasting recession followed by a recovery. Some countries such as Romania, Bulgaria and the Czechia clearly display a double dip (Figs 1 and 2). As it happens, the onsets of the second dips of Romania and Bulgaria is unambiguously related to a change of power, suggesting that wrong economic policies or implementations can be blamed for further degradation of the situation.

The severity and duration of the recession varies widely between the countries: Poland has recovered very quickly (too much so to be shown in Figs. 1 and 2), while some countries such a Russia and Latvia have come back to their previous current-dollar GDP in 2006. The Republic of Moldova was still 50% down in 2006. These differences raise two questions: what is their causes? How efficient was the transition policy? We shall not try to find the causes of such differences, although our fitting equation directly provides information about the fraction of the economy which is decaying, but shall discuss various ways of optimising a policy with the help of a simple theoretical model in section 3.

For reasons explained below, we parametrise the GDP J shapes as displayed in Figs 1 and 2, in terms of the following formula

\[ W(t) = W(t_0)[f e^{\lambda_+ (t-t_0)} + (1-f) e^{\lambda_- (t-t_0)}], \]

where

- \( W(t_0) \) is the initial GDP at the time \( t_0 \) of the reform;
- \( f \) is the fraction of the economy that grows at rate \( \lambda_+ \);
- the rest of the economy \( (1-f) \) deflates at rate \( \lambda_- \).

A J-shaped \( W \) is obtained if \( W'(t_0) < 0 \), i.e. if \( f \lambda_+ + (1-f) \lambda_- < 0 \).

The fit of recession and recovery times of 23 countries appears remarkable (the details are reported in appendix A), and may a priori suggest a surprising degree of policy constancy; however, as discussed in section 4, dynamic effective policies can also be relatively well fitted with the same model: one needs more detailed data than the global GDP time series to detect them.

The fitting function of Eq. 1 can be considered as the simplest model of recession and recovery that is economically meaningful. Indeed, it only assumes that one part
of the economy shrinks while the other one grows, both exponentially. It does not include many other a priori relevant parameters. In passing, it might seem tempting to fit the dips with a parabola, which of course give terrible results as the curves are not symmetric and have an asymptotic constant exponential growth rate. Because of the auto-catalytic nature of economic growth and recessions, only a sum of exponential makes sense, which also excludes other candidates such as splines (which need many more than 3 parameters).

Given the simplicity of the fitting function and the complexity of the underlying process, it is to be expected that the fits should not be perfect: the recession part is the most problematic, which comes from the assumption that a single deflation rate is enough to describe faithfully a whole collapsing economy (see section 3.1 for more details), the recovery part often displays some systematic irregularities, most of them negative. Many countries experienced a temporary pause in their growth, sometimes even a short-lived recession. Because we have only annual data, and since one needs at least three consecutive points for a good fit of the recession part, we chose in some cases to fit the whole timeseries instead of fitting these episodes separately. The use of quarterly data will solve this problem. We could trace possible causes of some of them to additional shocks: Albania suffered from a bank crisis in 1996, and Finland from the burst of the 2000 internet bubble (see also subsection 2.4). The worst secondary shocks were born by Romania and Bulgaria (1996 elections), and Czechia (2000 bank crisis) which resulted into a second dip. This raises the question on whether the second reforms were successful or on the contrary detrimental: comparing the values of \( \lambda_+ \), \( \lambda_- \) and \( f \) before and after the secondary shock, one concludes that, according to our model, the crisis in Czechia had long-term positive effects, both the rates of expansion and decline having much improved, at the cost of the initial fraction of the expanding sector. The case of Romania is best described as bis repetita (non placuerunt): the second crisis leading to almost the same fitting parameters as the first one. Finally, Bulgaria has spurious results regarding the first shock (GDP in constant dollars), which is due to the fact that GDP was mostly decreasing, hence the fit could not assess correctly the growing part, judging it very small (from 0.2% to 2%), but doing very well, and whereas almost all of the economy was steadily decreasing. This result is clearly wrong but easily reproduceable with other countries if one restricts the data so as to include a very small part of the recovery. The figures obtained for the second shock are in line with all the other shocks.

2.2 Shape instead of causes

It is enlightening to look at a few well-known papers in Economics on the transition from communism to capitalism, e.g. Fischer and Sahay (2000); Sachs (1996); Popov (2006), which review the numerous aspects and precepts of economic transition and growth, together with various methodologies. On the one hand they are helpful reminders that an economy is an intricate system with many parameters of unknown influence, each of which being worth discussing, hence, that the parameters in our model are global measures of many processes of different types. On the other hand it is curious to note that, if most of them did plot GDP versus time, to our knowledge nobody tried to fit the time series of the GDP, which is all the more surprising since an equation similar in fine to Eq. (1) (but derived from other hypotheses) is found in an appendix of Popov (2006).

A major difference between the approach of the respected economists cited above and the present fitting function is that, very understandably, the former are concerned
with finding the causes of recession and recovery and in particular of the variations between countries. One of the tools used is factor analysis (known as multivariate linear fit in other disciplines) of the average growth in e.g. the recession part, where potentially relevant variables are guessed and then deemed actually relevant or not by statistical tests, yielding a regression coefficient \( R^2 \approx 0.5 \); this neglects the curvature of the GDP that cannot be described by two separate exponentials, hence the need for a superposition of at least two of them. Other means to assess the importance of reforms mostly come from abstract discussion of political economy.

For instance, Fischer and Sahay (2000) singles out Uzbekistan and Belarus, noting the apparent contradiction between their economic performance and lack of reforms, nevertheless concluding that “[…] it is reasonable to predict that they will grow more slowly than those who have undertaken more extensive reforms.” However, our fits indicate that their parameters are in line with those of Lithuania in current dollars and Latvia in constant dollars. If performed at the time this paper was written, they would have already given good estimates of the GDP to come.

As said above, we do not base our analysis on the search of the causes for the values of \( \lambda^+, \lambda^- \) and \( f \) in part because of our non-extensive knowledge of political economy, but on the typical temporal pattern or shape of recession and recovery after a shock (or the second one, when available). The form of Eq. (1), even if inspired by a much more complex model, is the simplest model that captures the superposition of exponential decay(s) and exponential growth (see also below, section 3.1, “Why our model works”), which are characteristic of autocatalytic systems. The fact that the apparent growth rate is not constant means that a factor analysis of the mean growth rate is unlikely to yield good results. That said, it does make sense to apply this method to the fitted parameters \((f, \lambda^+, \lambda^-)\) in order to determine why the economic initial conditions \((f, \lambda^\pm)\), using established economic indicators, were so different. We leave it to forthcoming publications.

2.3 Making predictions

Since this model fits well real data between two shocks, it must be able to make predictions assuming that no additional shock occurs, and by extension, should be able to detect an additional shock. Let us first start with noisy synthetic data in order to understand better its predictive power. Generating time series \( G(t) = [fe^{\lambda^+} + (1 - f)e^{\lambda^-}][1 + \eta(t)] \) where \( \eta(t) \) are drawn at random from a unit-variance Gaussian distribution with zero average and \( v \) is the strength of the noise. The issue is to determine the minimum length of data needed in order to determine faithfully the parameters, in particular if from a partial time series one can predict the future evolution of the GDP.

Choosing parameters that replicate the evolution of the quarterly real GDP of Finland \((f = 0.75, \lambda^+ = 0.0125, \lambda^- = -0.169)\), and \( v = 0.005 \) by eye inspection, we generate a single 200-time steps time series (50 years). Taking an in-sample size of \( t_0 \in \{5, \ldots, 200\} \), we then find in the out-sample \( t_{\text{pred}} > t_0 \) such that the relative difference between the prediction differs and the data at \( t_{\text{pred}} \) exceeds the tolerance \( p = 0.01, \cdots, 0.05 \). Even if \( t_{\text{pred}} \) as a function of \( t_0 \) depends on each realisation of the noise, a general pattern arises: at around \( t_0 = 15 - 17 \), which includes a part of the recovery, the prediction length increases tremendously, although at first with very large fluctuations that who details depend on the noise realisation, and reaches quickly the total length of the generated time series.
Figure 3: End time $t_{\text{pred}}$ of correct predictions of synthetic data (stars) and Finland’s real GDP as a function of in-sample size $t_0$ for various tolerance parameter $p$. Dashed and dotted lines are for eye guidance only.

Figure 4: Finland’s real GDP as a function of time, starting in October 1990. Red circles: quarterly data, green line: in-sample fit, black dashed line: out-sample prediction, blue line: fit starting from the 2001 slowdown, black dotted line: continuation of the pre-1990 GDP trend.
2.4 Detecting additional shocks

Armed with this positive conclusion, we apply the same procedure to the real quarterly, seasonally-adjusted, GDP of Finland. Fig. 2.3 clearly shows a saturation of $t_{\text{pred}} \simeq 42$ for $t_0 \geq 23$ even when the tolerance $p$ increases (at which point one can predict the GDP five years in advance) whereas the length of the time series is 71. Plotting the in- and out-sample fitted functions for $t_0 = 23$, one clearly sees that the GDP of Finland is remarkably fitted by our simple model until $t = 42$ (first quarter of 2001). Given the faithfulness of our model for the first 41 quarters (more than 8 years), one must conclude that something happened to the GDP dynamics. This can be traced to the weak growth of the world during these years, which resulted in a sharp decrease of demand for paper products and mobile phones, which contributed to half of the exports of the country at the time.

Finland’s data shows in a convincing way how good our model is provided that no internal or external shocks occurs; a contrario, being the simplest model of economic recession and recovery, it allows for the detection of shocks. As the modelling of shock requires data to which we do not have access, it is beyond the scope of this article. However, since one still has about 30 data points, nothing prevents us to fit the second episode. The prediction power in this episode, as determined by $t_{\text{pred}}$, is at least 9 quarters as soon as the in-sample size is equal or greater than 6 data points for $p \geq 0.03$. We find $f \simeq 0.093$, $\lambda_+ \simeq 0.0105 \pm 0.0006$ and $\lambda_- \simeq -0.143$, whereas $\lambda_+ \simeq 0.0125 \pm 0.0003$ from 1990 to 2001: both values are close to each other, which suggests that the global structure of the economy was not tremendously changed; but one consequence of this finding is that the GDP cannot catch up with its previous trend. As a final note, the Finland’s GDP was growing at a rate $\lambda_+ \simeq 0.0082 \pm 0.0001$ before 1990, hence the transition will be beneficial on the long run, provided that there are not too many additional slowdowns (current GDP is still 14% below the continuation of pre-1990 GDP trend as of June 2008).

2.5 Ukraine and Moldova

Finally, according to our fits based on yearly data, and provided that no dramatic event or change occurs, Ukraine will recover its 1990 current/constant dollars levels in 2009/2009; this may appear a risk-less prediction, but our data stops in 2006/2004. The fit for current-dollar GDP of Moldova is quite good and predicts a recovery in 2015, the one for constant-dollar GDP (whose data stops in 2004) is less trustable, but also gives 2009 as recovery year.

3 A simple theoretical model of economic activity transfer

The model used to fit data in the previous section can be derived from a simplification of the so-called AB model (Shnerb et al. 2000; Shnerb et al. 2001), a reaction-diffusion lattice model where discrete particles of two types diffuse, meet, reproduce and die auto-catalytically. Yaari et al. (2008) applied it recently to explain the temporal and spatial dynamics of economic growth in Poland. Whereas the latter work divided Poland into $N$ interacting geographical parts with diffusing elementary economic units, the present contribution is to show that the same model with $N = 2$ is able to explain the temporal dynamics of many countries in difficult times. This allows us to restrict
the number of parameters, hence, to explore more easily the dynamical properties of such models.

The rationale behind the fitting function used in the previous section is the following. The after-shock economy is supposed to consist in two sectors, one with activity $w_1$, growing intrinsically at rate $\alpha_1 > 0$, and the other one with activity $w_2$ but intrinsically shrinking ($\alpha_2 < 0$). They interact through economic activity transfer taking place at rate $\beta$, according to the difference of activity. Mathematically,

$$\frac{dw_1(t)}{dt} = \alpha_1 w_1(t) + \beta [\langle w(t) \rangle - w_1(t)] \quad (2)$$

$$\frac{dw_2(t)}{dt} = \alpha_2 w_2(t) + \beta [\langle w(t) \rangle - w_2(t)], \quad (3)$$

where $\langle w \rangle = (w_1 + w_2)/2$.

The actual result of the government’s and investor’s various policies is assumed to be equivalent to taking a fraction $\beta/2$ of the difference of activity between the two sectors from the largest sector and giving it to the smallest one. In other words, $\beta$ may not be the transfer rate wished for by the government, but the actual transfer rate (the distinction is valid for the rest of the discussion). This means in particular that, when the intrinsically expanding sector represents a small part of the economy, resources are transferred to it from the shrinking sector, thereby accelerating the transition. Note that because of redistribution, both sectors end up growing at the same rate. Therefore, it is wrong to think of the dynamics of this model as describing a growing sector and a declining sector since both have a growing and a declining part.

Solving the dynamics of this system is straightforward by computing the eigenvalues and associated eigenvectors. The two eigenvalues are

$$\lambda_{\pm} = \frac{\delta \sigma / \delta - \zeta \pm \sqrt{1 + \zeta^2}}{2} \quad (4)$$

where $\delta = \alpha_1 - \alpha_2$, $\sigma = \alpha_1 + \alpha_2$ and $\zeta = \beta / \delta$. These eigenvalues correspond to the rates measured in the previous section. The unnormalised eigenvectors are $(\zeta, -1 \pm \sqrt{1 + \zeta^2})$. Let us denote by $v_{\pm} = (v_{\pm 1}, v_{\pm 2})$ the respective orthonormal eigenvectors. Following standard procedure, one decomposes $w(t = 0)$ into the basis $v_{\pm}$, obtaining $w(t) = v_{\pm} \cdot e^{\lambda_{\pm} t}$ where $\omega_{\pm} = w(0)$. $v_{\pm}$ are the projections of the initial conditions onto the sector decomposition described above. In other words, both $w_1$ and $w_2$ have an increasing and a decreasing part. The steady state is reached when the importance of the negative component is vanishingly small compared to the positive component both for $w_1$ and $w_2$. The typical time for reaching this asymptotic regime is $O(1/(\lambda_{+} + |\lambda_{-}|))$ units of time. Then the two groups grow at the same rate, $\lambda_{+}$ (Fig. 8). In this regime, the growth of the negative component is entirely due to the transfer of wealth from the positive one. This may be due to taxation, or simply to trade taking place between the two sectors.

We shall be interested in this paper in the total economic activity $W = w_1 + w_2$ and shall consider the GDP as its proxy. Also we are interested in the dynamics of inequality between the sectors, measured by $\Delta = w_1/w_2$. Note that the empirical data determine only partially the parameters of Eq. (1) of previous section: while the rates $\lambda_{\pm}$ can be measured directly, more detailed information is needed in order to determine all three parameters $\alpha_1$, $\alpha_2$ and $\beta$. This is due to the fact that $f$ does not correspond directly to $w_1(0)$ since even at the beginning sector 2 has a growing part (i.e. $v_{+2}^2 \neq 0$).
3.1 Why this model works

The contrast between the intricacies of economic policy making and implementation (Fischer and Sahay 2000) and the simplicity of our model on the one hand, and the quality of our fits and the (relatively) poor explanatory power of factor-based growth analysis (Fischer and Sahay 2000; Popov 2006) on the other hand is perplexing. In order to understand the surprisingly good performance of the simple fitting function of Eq. (1), one needs to go back to the two-dimensional autocatalytic AB model of Snherb et al. (2000), which describes spatially-distributed and heterogeneous logistic systems. Its ability to reproduce both the spatial and temporal dynamics of Poland’s GDP is striking (Yaari et al. 2008); interestingly, it finds that the local level of education is the most relevant factor in growth, in line with Fischer and Sahay (2000). In the case of Poland, it predicted successfully the pattern of recession and recovery of the parts of Poland: the activity of each part of the country reaches its minimum at different times, while the final growth rate is the same for all parts, strongly suggesting that an economic activity transfer process is at work; in other words, plotting the economic activity evolution of various sectors as a function of time produces a whole variety of J-shaped time-series, all ending up with the same growth rate. The simplification to two parts, or two sectors, works because the economy is an autocatalytic, that is, multiplicative, process: the parts that reach their minima later than the best part often have shrunk so much that their contribution to the total GDP is negligible afterwards. This means that in principle the approximation of a simple two-sector model is less warranted in the recession part, but very reasonable in the recovery part. But the use of quarterly data for Finland, as shown above, seems to indicate that in some cases at least, the fitting equation we propose describes very well even the recession part of the GDP.

3.2 Static policy making

Assume that the rate $\alpha_1$ and $\alpha_2$ are constant and fixed by constraints beyond the control of the government. The government’s only influence is in the transfer rate through the tax rate policy. This in itself is a very powerful instrument that the government is pressed to use: indeed economic activity is linked to employment, and a fast-shrinking sector implies growing social inequality and voters dissatisfaction. If the rate of shrinking is much faster than the rate of labour transfer between the two sectors, inequality at the sector level translates into growing social inequality. In that sense, the inequality between sectors is an upper bound to social inequality. It should be noted that $\beta$ is the effective rate of transfer, not the one hoped for by the government; indeed, if the latter is not able to collect taxes or if its authority is undermined by inadequate rule of law due to the collapse of institutions, the effective $\beta$ may turn out much smaller.

The final growth rate depends much on the policy: increasing $\beta$ reduces both eigenvalues, hence the total growth rate in the steady state: maximal asymptotic economic growth is achieved when there are no transfer of wealth. This seems to substantiate the claims of the so-called supply-side economics (see e.g. Lucas (1990)). However, global growth rate is not the only success measure of a taxation policy: inequality is also to be taken into account.

Indeed, since $\lambda_- < 0$, group 2 would simply disappear in the absence of redistribution. Decision makers who only focus on growth will therefore take $\beta$ as small as socially responsible and electorally possible. Some others will try to minimise inequality between sectors. Since both $w_1$ and $w_2$ end up growing at the same speed, their
asymptotic ratio $\Delta = \lim_{t \to \infty} w_1(t)/w_2(t)$ is a measure of economic inequality. Using basic algebra, one finds that

$$\Delta = v_{+1}/v_{+2} = 1/(-1/\zeta + \sqrt{1 + \zeta^2}) \simeq 2/\zeta = 2(\alpha_1 - \alpha_2)/\beta$$

(5)

if $\zeta \ll 1$, in which case reducing the sector inequality by a half requires to double the transfer rate; in addition, sector inequality is proportional to the difference of growth rate.

Since the rates are fixed by assumption, sector inequality only depends on the transfer rate, not on initial conditions. Inequality ceases to exist only for large $\beta$, which is ideal communism, at the cost of growth rate.

Therefore, assuming fixed transfer rate, a head of state of a country about to convert from communism to capitalism may be able to choose between a small but long recession with anemic final growth, or a large but short-lasting recession with large final growth (Fig. 5). A cynical politician would ensure that the wealth of the majority of voters has increased by the end of his tenure or at least that the recovery has begun.

### 3.3 Gradualism versus shock therapy

All the Eastern European countries have experienced economic recession when switching from communism to capitalism. The variety of intrinsic growth and decline rates and policies yielded vast differences between speed of recovery and depth of recession of various countries. Understandably a large corpus of literature investigates what factors could explain this variety of behaviours (Sachs 1996; Fischer and Sahay 2000; Popov 2006; Cernat 2002). In particular, the technique of making the transition abrupt and short has been labelled as shock therapy (Kolodko 2000). The concept of shock therapy has been the focus on long debates which have not been settled to this very day (Lucas 1990). The other approach is called gradualism, and advocates to follow a more gentle rhythm (Kolodko 2000).

Our model makes it possible to investigate this issue. We shall assume that $\alpha_1$ and $\alpha_2$ are intrinsic to the economy and therefore constant; the government influences the economy by trying to adjust the effective transfer rate $\beta(t)$. The shock therapy consists in lowering abruptly $\beta$ from the high level of communism to the small level of capitalism. Gradualism implies a smoother mathematical function for $\beta(t)$. 

3.3.1 Constant policy: shock therapy

Figure 5 plots various scenarios for $W(t)$ at constant $\beta$ and shows the influence of $\beta$ on the outcome. The cases with small $\beta$ correspond to shock therapy. They are characterised by a deep recession and both a faster final growth rate and accordingly a higher GDP. Therefore, after many years, the tenants of this policy are vindicated since their courageous but harsh recommendations are proved correct as regards the growth rate of GDP and value compared to other static policies. This view is right, but only in a static context, as it maximises the final growth rate, not the instantaneous one, therefore not the actual GDP (see below), and deep recession ensues.

3.3.2 Dynamical policy: envelope

Few experiences are more frustrating for a politician than to have implemented a policy that will lead to the recovery of one’s country, but too late to be re-elected. Instead of heroically jeopardising one’s political career, one should ask how to implement a policy that would avoid most troubles.

There is another way of looking at this figure: what if one could stay on the upper envelope of all the scenarios and thereby avoiding as much as possible difficult times while maximising the final growth rate? This clearly needs a dynamical policy, i.e., $\beta(t)$. Running a thousand scenarios $W_i(t)$ with various $\beta_i$, and selecting at each time $t$ the value of $\beta$ that corresponds to the maximal $W$ yields $\beta_{env}(t) = \beta_{\arg\max_i W_i(t)}$ shown in Fig. 5: redistribution should be kept maximal for a while, then $\beta_{env}$ decreases exponentially fast in the region encompassing the worst phase of the recession, and then decreases faster than exponentially. Regrettfully for a head of state, this view is purely virtual: Figure 6 reports the GDP $W[\beta_{env}]$ actually obtained by using the policy $\beta_{env}(t)$, the envelope max $W_i(t)$ of Fig. 2 and an example of shock therapy with constant $\beta$ (forget $W_{opt}$ for the time being). The difference between the virtual and real $W$ come from the fact that it is impossible to stay on the envelope by controlling $\beta(t)$ on the basis of $W$ alone: when $W(t)$s of two scenarios cross, their components $w_1(t)$ and $w_2(t)$ are not equal. Thus shock therapy works better than trying to stay on the envelope.

Curiously, $W(t)$ actually obtainable by using this method is also relatively well fitted with Eq. 1, i.e. with constant parameters, and gives for the curve reported in Fig. 5 $\lambda_+ \approx 0.020$, $\lambda_- \approx -0.019$, and $f = 0.068$ with uncertainties smaller than a percent, whereas the initial values were 0.02, -0.05 and 0.1, respectively. In other words, the
effective shrinking rate is reduced, the rate of growth of the expanding sector remains unchanged (which is needed in order to retain the same final growth rate), while the apparent fraction of the expanding sector decreases considerably; interestingly, the difference between the fits of the envelope itself and the attainable $W(t)$ is limited to $f$: the envelope has the same apparent $f$ as the individual runs.

### 3.3.3 Optimal policy: maximal $W$

Another policy is to maximising $W$ at each time step, which reduces to the maximisation of the growth rate with respect to $\beta$: $\frac{\partial W}{\partial \beta} = 0$. This leads to a transcendental equation to be solved numerically at each time step. The resulting $W_{\text{opt}}$ is reported in Fig. 6, which shows unambiguously the benefits of the proposed optimal dynamical policy, that is, of gradualism with respect to shock therapy. Indeed, the value of the GDP in the recovery phase is increased several times with respect to static policies and with respect to envelope-based dynamical policies, while sharing the same asymptotic growth rate. We therefore claim that shock therapies are unadapted to economies in crises as regards GDP. Patience and gradualism are better solutions in this kind of situations.

Looking at the optimal value of $\beta$ (Fig. 7) reveals that indeed taxes should decrease rapidly, but not instantaneously. This means that the intuition behind shock therapies is correct, but only in the later stages of the time evolution. What matters is the road to minimum taxes, all the more since the economy follows multiplicative processes: optimising it may change tremendously the fate of countries and people, as shown by the results of envelope-based and optimal policies.

Fitting $W_{\text{opt}}$ with Eq. (1) yields $f \approx 0.80$, $\lambda_+ \approx 0.20$, and $\lambda_- \approx -0.027$. Therefore, the optimal policy both increases the apparent fraction of the growing part of the economy and decreases the apparent rate of shrinking of the decaying sector, while of course keeping constant the final rate of growth.

### 3.3.4 Detecting static, envelope-based, and optimal policies

A somewhat frustrating result of the previous two dynamical policies is the impossibility to distinguish them from a static one. Indeed, in the absence of additional information about the applied economic policies, one cannot reconstruct it from the GDP time series. For that purpose, one would need data about at least two sectors. Plotting $\Delta = w_1/w_2$ as function of time allows one to distinguish a static, envelope-
Figure 8: Sector inequality as a function of time for the optimal policy (black line), the envelope-based gradual policy (red line) and the shock therapy (dashed black line). Same parameters as in Fig 2.

Based and optimal policy, as reported in Fig. 8: a static policy has a negative curvature, while dynamic ones start with a flat line, followed with a positive curvature and then an inflexion point. All of them reach the same asymptotic values since one imposed a minimum $\beta = 0.00001$ in order to compare the three policies. It may be difficult in practice to discriminate with the naked eye an envelope-based policy from the optimal one, but easy to detect a static policy. However, in further investigations one could measure $w_1$ and $w_2$, and thus determine all the parameters of the model, including $\beta_{opt}(t)$.

4 Discussion

The data show that large-scale changes of policy or external shocks result first in an economic slowdown, possibly a recession, while yielding sometimes a larger asymptotic growth rate. Our analysis suggests that when a long lasting and smooth recession sets in, in the absence of additional shocks, the natural evolution of the GDP follows very closely a simple functional form.

How best to react to a shock causing a lasting recession is a hugely complex task whose outcome may not be entirely satisfactory. For instance, the transition from a fully centralised state to market economy left durable negative feelings to most of those who experienced it. Predictably, there is no consensus on how best to deal with it (Lucas 1990; Kolodko 2000), especially since standard economic indicators may not be very trustworthy and because institutions may also fail for lack of rule of law (Balcerowicz 1994). Nevertheless, our simplified model illustrates how much influence economic transfer rate has on the absolute value of the GDP.

Our approach contrasts with the traditional factor-based analysis where one must separate the two phases of the dynamics in order to extract the factors relevant to each phase (see e.g. Popov (2006); Kolodko (2000)); it suggests rather that this type of regressions should be made on the fitting parameters $f, \lambda, \mu$ rather than directly on the GDP; in passing this gives an additional parameter to discuss, $f$.

Even if very simple, our simple model reproduces well the typical patterns of recession and recovery. The usual caveats about using the understanding of the dynamics of a theoretical model to design a real-world policy apply as the insights it provides are

\footnote{It is clear that increasing taxes will also lead to a negative curvature; however, we assume that the transition from communism to capitalism needs a decrease of taxes.}
limited to its framework and to its control parameters. Nevertheless, we believe that the simplicity and the success of our model first to fit faithfully both recessions and recoveries and its ability to understand in a very simple way the respective advantages of two real-world policies brings a worthwhile contribution to the decade-old debate. It suggests that an optimal gradualist approach both maximises the final growth rate, the actual GDP and minimises the duration and severity of recession. In addition, one can predict during the recession the location of the minimum and the growth rate of the recovery phase provided as function of the tax policy. Beyond its success in reproducing the temporal dynamics of GDP, our model gives predictions regarding the dynamics of \( w_1/w_2 \) for instance, which will be tested in a forthcoming publication.

One of its important shortcomings is the assumption that the rates \( a_1 \) and \( a_2 \) are constant and fixed by uncontrollable factors. It is clear that in the long run, improvements to education or infrastructures for instance can alter them, and indeed events such as banking crises seem to change their values (within the framework of our model).

It remains that it is very likely difficult for a government to control, necessarily indirectly, \( \beta \) with precision, all the more in times of crisis. Arguably, governments’ ability to facilitate structural changes by economic activity transfer was much weakened more or less during the fall of the Iron Curtain. Accordingly, even if they had in mind the optimal policy (there is evidence that most of them did not), the result was beyond their crumbling control. However, one of the most important results of this paper is the existence of an optimal policy and the considerable speed at which the economic transfer rate should decrease; in practice however, there is a maximal speed of transition, due for instance to human workforce transfer between sectors (Balcerowicz 1994; Popov 2006), which may prevent from applying the optimal policy. However, as regards the GDP, only the effective rate of transfer matters: should for instance a government try to set a constant rate, but have an economic influence collapsing gracefully following the optimal path, it would have implemented unwillingly the optimal policy. This is to say that the timing of the policy has an enormous influence on the final GDP values: should the transition have been slightly less brutal in many if not all the considered countries, it would have been much closer to optimal. On the other hand, a too “gentle” transition policy might have lead to a worse final state. In short, the optimal policy is best described as gradual shock therapy.

References


A  Model fitting

In the following tables, SRS stands for square residuals sum, SRM for square residuals mean, RSRS for relative square residuals sum, RSRM for relative square residuals mean; years indicates the number of years along which the fit has been done. The table contains a wealth of data which can be further exploited and whose potential has been only scratched by the present publication.

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</table>

Table 2: GDP in constant dollars
Please note:

You are most sincerely encouraged to participate in the open assessment of this discussion paper. You can do so by posting your comments.

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The Editor