

Chade, Hector; Swinkels, Jeroen M.

Article

The no-upward-crossing condition, comparative statics, and the moral-hazard problem

Theoretical Economics

Provided in Cooperation with:

The Econometric Society

Suggested Citation: Chade, Hector; Swinkels, Jeroen M. (2020) : The no-upward-crossing condition, comparative statics, and the moral-hazard problem, Theoretical Economics, ISSN 1555-7561, The Econometric Society, New Haven, CT, Vol. 15, Iss. 2, pp. 445-476, <https://doi.org/10.3982/TE2937>

This Version is available at:

<https://hdl.handle.net/10419/253448>

Standard-Nutzungsbedingungen:

Die Dokumente auf EconStor dürfen zu eigenen wissenschaftlichen Zwecken und zum Privatgebrauch gespeichert und kopiert werden.

Sie dürfen die Dokumente nicht für öffentliche oder kommerzielle Zwecke vervielfältigen, öffentlich ausstellen, öffentlich zugänglich machen, vertreiben oder anderweitig nutzen.

Sofern die Verfasser die Dokumente unter Open-Content-Lizenzen (insbesondere CC-Lizenzen) zur Verfügung gestellt haben sollten, gelten abweichend von diesen Nutzungsbedingungen die in der dort genannten Lizenz gewährten Nutzungsrechte.

Terms of use:

Documents in EconStor may be saved and copied for your personal and scholarly purposes.

You are not to copy documents for public or commercial purposes, to exhibit the documents publicly, to make them publicly available on the internet, or to distribute or otherwise use the documents in public.

If the documents have been made available under an Open Content Licence (especially Creative Commons Licences), you may exercise further usage rights as specified in the indicated licence.



<https://creativecommons.org/licenses/by-nc/4.0/>

The no-upward-crossing condition, comparative statics, and the moral-hazard problem

HECTOR CHADE

Department of Economics, Arizona State University

JEROEN SWINKELS

Kellogg School of Management, Northwestern University

We define and explore no-upward-crossing (NUC), a condition satisfied by every parameterized family of distributions commonly used in economic applications. Under smoothness assumptions, NUC is equivalent to log-supermodularity of the negative of the derivative of the distribution with respect to the parameter. It is characterized by a natural monotone comparative static and is central in establishing quasi-concavity in a family of decision problems. As an application, we revisit the first-order approach to the moral-hazard problem. NUC simplifies the relevant conditions for the validity of the first-order approach and gives them an economic interpretation. We provide extensive analysis of sufficient conditions for the first-order approach for exponential families.

KEYWORDS. Log-supermodularity, quasi-concavity, moral hazard, first-order approach.

JEL CLASSIFICATION. D81, D86.

1. INTRODUCTION

In this paper, we introduce, motivate, and show the usefulness of a condition on a parameterized family of distributions. We term the condition no-upward-crossing (NUC), a choice of terminology that we justify shortly. NUC is satisfied for every distribution that we are aware of that is commonly used in economic applications. Indeed, NUC holds if and only if an intuitive comparative static holds, and, hence, while one can construct examples where NUC fails, such examples are necessarily somewhat artificial. NUC simplifies the analysis of some important economic problems, including the question of when the first-order condition is sufficient for a global optimum in a variety of problems and when some natural comparative statics results hold. NUC also allows for economic interpretations of otherwise hard-to-interpret technical conditions.

To be concrete, consider the family of distributions $\{F(\cdot|a)\}_{a \in A}$ on the reals, parameterized by $a \in A \subset \mathbb{R}$, where we speak of the argument x as the “outcome” and often

Hector Chade: hector.chade@asu.edu

Jeroen Swinkels: j-swinkels@northwestern.edu

We are grateful to John Conlon, Ian Jewitt, Ohad Kadan, and three anonymous referees for very helpful comments and suggestions that significantly improved the paper.

refer to a as the “effort.” We assume that F satisfies strict first-order stochastic dominance (FOSD). That is, increases in effort strictly decrease the probability of an outcome below any given interior output.

To see the motivation and definition of NUC, consider two ordered pairs of effort, $a_l < a'_l$ and $a_h < a'_h$, where $a_l \leq a_h$ and $a'_l \leq a'_h$ (and where, in the interesting case, at least one of the later two inequalities is strict). For example, a might be the amount of exercise a subject gets, where a_l is “completely sedentary” and a'_l is “occasionally goes for a stroll,” while a_h is “walks regularly” and a'_h is “jogs on a regular basis.” Let x be the number of miles the subject is able to cover on foot in a particular 30-minute period.

Now fix a threshold t and compare the probabilities of various types coming in above or below the threshold. Consider first a low threshold t , say 1 mile. Then both the walker and the jogger will almost surely exceed t , and so $F(t|a_h) - F(t|a'_h)$ will be small. But there is likely to be a significant increase in the probability that the occasional stroller versus the sedentary subject exceeds the threshold, so that $F(t|a_l) - F(t|a'_l)$ is larger. Alternatively, if we take the threshold t to be 3 miles, then the opposite will hold, as covering 3 miles in 30 minutes is probably almost impossible for either of the unfit types, but more likely to discriminate between the two fitter types. Driven by this intuition, the condition we impose, NUC, is simply that the ratio of these two probability differences rises with the threshold. That is, *NUC holds if*

$$\frac{F(t|a_h) - F(t|a'_h)}{F(t|a_l) - F(t|a'_l)}$$

is increasing in t .

When F is twice continuously differentiable, NUC holds *if and only if* $-F_a$ (which is positive by FOSD) is log-supermodular (lsm) in output and effort. Since $-F_a$ is a measure of the marginal return to effort, this characterization says that if extra effort has diminishing marginal returns at given x , then in proportionate terms these returns fall more slowly above x . If extra effort has increasing marginal returns at x , then in proportionate terms they rise even faster above x .

The condition that $-F_a$ is lsm is in turn equivalent to the condition that for each real number τ and for each effort a , $F_{aa}(\cdot|a) - \tau F_a(\cdot|a)$ is *never first strictly negative and then strictly positive*. This version of NUC is useful in many applications and the property is the genesis of the name.¹

We next turn to sufficient conditions for NUC. These are useful in practice, both to check NUC and to tie NUC to well known classes of distributions, and also help to build our intuition. We provide a set of such conditions, interpret them economically, and show that exponential families satisfy the most stringent such condition. Along the way, we show that NUC is automatic for any distribution that satisfies the monotone likelihood ratio property (MLRP) and is totally positive of order 3 (TP₃).²

¹In the moral-hazard context, a weaker version of this condition appears in one result in [Jung and Kim \(2015a\)](#) as sufficient to justify the first-order approach. We discuss this paper further below.

²TP₃ has appeared in the literature on the first-order approach to the moral-hazard problem, most prominently in [Jewitt \(1988, p. 1182\)](#) (where one can find a definition and discussion), and also in [Jung and Kim \(2015a\)](#).

In information economics, it is so standard as to be barely commented on to assume MLRP, which is that the density or probability distribution f associated with F is lsm. This is not because MLRP is without loss of generality. Rather, MLRP is invoked because it both has a clear economic motivation and simplifies the analysis. We think of NUC in the same way. As for MLRP, NUC is not without loss (although we argue the loss is pretty mild). But, as for MLRP, we show that NUC has a clear economic motivation and usefully simplifies both analysis and interpretation. Indeed, NUC is MLRP's fraternal twin. To see the family relationship, note that when F is differentiable, MLRP is the condition that F_x is lsm and, hence, each condition is a log-supermodularity condition on one of the derivatives of F .

One central reason for our belief in the naturalness of NUC is that it holds if and only if an intuitive comparative static holds, one somewhat related to a statistical thought experiment discussed by [Jewitt et al. \(2008\)](#). Consider a university department with junior faculty of varying ability who face a tenure standard that depends on whether their research output exceeds some given threshold t , where t is set exogenously, for example, by the central administration. The department gets a negative payoff when low-ability faculty are tenured and gets a positive payoff when their ability is above some threshold. It can offer the junior faculty more or less aid in their research—mentoring, research assistants, equipment—with research output being stochastically distributed according to $F(\cdot|\alpha(a, \delta))$, where α is an increasing function of ability, a , and the amount of aid received, δ . The department faces the trade-off that more aid makes it more likely that high-ability faculty make the tenure threshold, which the department likes, but also makes it more likely that low-ability faculty make the hurdle, which the department dislikes.

The comparative static that we want is that *if the tenure standard is raised, then the optimal amount of research aid to offer does not go down*. This seems to us very intuitive: When the tenure threshold is low, the high-ability faculty are likely to exceed the threshold without help, so giving aid predominantly helps the low-ability faculty. Hence, the optimal amount of aid is low. When the threshold is higher, the low-ability faculty are unlikely to exceed the threshold even with substantial aid, but aid may well lift the high-ability faculty above the threshold. Thus, the optimal level of aid will be higher. We show that this comparative static—that optimal aid rises with the tenure standard—holds for all relevant settings if and only if NUC holds.

We also explore when NUC might fail.³ At a mathematical level, such examples are easy to construct; indeed, we provide a recipe for doing so. Exploring examples suggests that failing NUC while satisfying MLRP is hard. We show that NUC fails most naturally in a situation where F is a mixture of two distributions, where each distribution satisfies NUC, but the mixture does not.⁴

A main application of NUC is the following. Imagine that one receives utility $v(x)$ from outcome x , but that effort comes at some utility cost $c(a)$, so that one wishes to

³We are very grateful to two referees who helped us to think about the intuition for when NUC might fail.

⁴This is related to the fact that the mixture of two distributions each satisfying MLRP need not itself do so.

maximize $U(a) = \int v(x) dF(x|a) - c(a)$ by choice of a .⁵ The central question is under what conditions is U strictly quasi-concave, so that a solution to $U_a(a) = 0$ is also a global maximizer of U .⁶

NUC very much simplifies the analysis of this problem. We show that where $U_a = 0$,

$$U_{aa}(a) = - \int v'(x) (F_{aa}(x|a) - \tau F_a(x|a)) dx,$$

where $\tau = c_{aa}(a)/c_a(a)$. By one of the equivalent characterizations of NUC, $F_{aa}(\cdot|a) - \tau F_a(\cdot|a)$ does not go from negative to positive. Hence, if v is increasing and concave, then v' puts more weight on $F_{aa}(\cdot|a) - \tau F_a(\cdot|a)$ where it is positive and less where it is negative. But then a sufficient condition for U to be strictly quasi-concave is that $\int (F_{aa}(x|a) - \tau F_a(x|a)) dx > 0$, which by integration by parts is equivalent to

$$\frac{(\mathbb{E}[x|a])_{aa}}{(\mathbb{E}[x|a])_a} < \frac{c_{aa}(a)}{c_a(a)}.$$

Hence, a *single* integral involving $F_{aa} - \tau F_a$ needs to be checked, and the relevant inequality has the simple and clean economic interpretation that expected output is (in proportionate terms) less convex in effort than c . Obviously, if F_{aa} is positive and c is convex in a , then the result is immediate.⁷ A convenient implication of NUC is that an almost equally simple argument yields U_{aa} negative without convexity requirements in F and c .

If v is not concave, then we show that it is enough to find a strictly increasing and differentiable function q such that v'/q' is decreasing and such that the expectation of q is less convex than c . This generalization turns out to be very useful when we turn to the moral-hazard problem.

One way to satisfy these assumptions is to assume expected output is concave in effort and cost is convex. We view this as unnecessarily restrictive. To see why, note first that there is no reason why the economically natural way to write down such a problem leads to a convex c . For instance, one might think about effort expended on a given day writing a paper; the cost per minute of effort initially decrease as one “gets into” the problem and then eventually strongly increase, yielding a c , which is initially concave and then convex. One could also imagine a setting where F does not lead to a concave expected outcome, but one is willing to assume convexity in c that is sufficient to overcome this.

A highly relevant application of the results just described is the question of the validity of the first-order approach (FOA) in the classical moral-hazard problem (Hölmstrom 1979, Mirrlees 1999) in which a risk-averse agent chooses effort, but a principal

⁵In this paper, an integral \int without delimiters is understood to be over the entire range of relevant values.

⁶We actually analyze a slightly more general setup where there is an unknown state θ distributed according to Γ and, thus, the decision maker chooses an action a (independent of θ) that maximizes $\int \int v(x, \theta) dF(x|a, \theta) d\Gamma(\theta) - c(a)$. The conditions we are about to describe must then apply pointwise for each θ .

⁷In the moral-hazard context, Rogerson (1985) showed that F convex in a validates the first-order approach.

can see—and reward—only a noisy signal of that effort.⁸ Implementing a specific effort by the agent requires the design of an optimal contract that deters *all* possible deviations, a decidedly intractable problem. The FOA focuses on the relaxed problem that considers only local deviations in effort. The question is when does a solution to this problem satisfy all of the omitted constraints. But that is exactly the problem considered above, where the extra interest comes because v is itself endogenous.

We first show how a version of the central result of [Jewitt \(1988\)](#) falls out as an immediate corollary to our analysis. In particular, mimicking Jewitt, under the right conditions on the curvature of the agent's utility function and likelihood ratio, the agent's utility from income, v , is concave in output for the optimal contract that solves the relaxed problem for any given effort. But then, from above, the agent's expected utility is a quasi-concave function of effort as long as expected output is less convex in effort than c , and so the FOA is validated.

Except for the fact that we incorporate the curvature of c , our goal here is not to generalize ([Jewitt 1988](#)).⁹ Rather, it is to show how NUC simplifies both the application and the interpretation of his central result. First, for each a , rather than a continuum of integrals (of the form $\int_{\underline{x}}^x F_{aa}(s|a) ds$ for each x), only a single integral must be checked. Second, as discussed above, this integral has the correct sign if and only if expected output is less convex in effort than c , and, hence, the condition takes on a simple economic interpretation.

We then turn to a version of a central result of [Jung and Kim \(2015a\)](#), who focus on the distribution of the likelihood ratio rather than on the distribution of the outcome itself. Indeed, fix any given action \hat{a} and consider the likelihood ratio function \hat{l} evaluated at that \hat{a} . If the expectation of the function \hat{l} is concave in effort (that is, \hat{l} continues to be evaluated at \hat{a} , but the expectation is taken with respect to $f(\cdot|a)$ as a varies), then we show that as an immediate consequence of the construction involving v'/q' , one can drop Jewitt's condition on the shape of the likelihood ratio.¹⁰ Furthermore, the concavity condition on the expected likelihood ratio is weaker than that on the expected outcome. Here again, our role is not to generalize ([Jung and Kim 2015a](#)), but to show how NUC clarifies the analysis.

We are not the first researchers to make the observation that F_{aa} may be well behaved and that this can simplify checking the Jewitt conditions or the Jung and Kim

⁸If the talent of the agent is unknown, as in the standard two-period career-concern model of [Dewatripont et al. \(1999\)](#) without explicit contracts, then the setting described in [footnote 6](#) applies.

⁹[Brown et al. \(1986\)](#) provide some limiting curvature and complementarity conditions on the agent's utility for wage and effort (not necessarily additively separable). Simultaneous work by [Jung and Kim \(2015b\)](#) also looks at the curvature of c , but follows a different approach, which relies on a double-crossing property between the agent's utility for income and disutility of effort. Note that an alternative to including the curvature of c is to linearize it by rescaling effort, thus folding any curvature of c into F . But while this is conceptually straightforward, inverting the relevant cost function may be intractable and the resulting conditions may be hard to check and interpret. Forcing c to be linear also makes it essentially impossible to build a model where the expected cost to the principal of inducing effort is continuous at zero effort, since effort zero can be implemented with a flat contract, while, since the marginal cost of effort is positive at zero, implementing any positive effort requires imposing a strictly positive amount of risk on the agent.

¹⁰This condition has a slightly less economically intuitive interpretation, but extends the analysis beyond a concave likelihood function.

variations to them. Indeed, the related idea that it is useful that F_{aa} crosses zero appropriately already appears in [Jung and Kim \(2015a\)](#) as one of the conditions that help to justify the FOA (see their Proposition 7 and Lemma 2) by showing that the sufficient conditions in [Jewitt \(1988\)](#) hold. Less directly, the observation is at the heart of the simplification that [Jewitt \(1988, Corollary 1\)](#) makes when discussing exponential families (which satisfy NUC). Our main contribution is to explore the considerable generality with which NUC holds, and to explore and understand its foundations and implications. Also, our analysis shows that by exploiting NUC, one can show *directly* that the FOA is valid, without the need to show that (the continuum of integrals in) Jewitt's conditions hold. This has pedagogical value, since our proof of the validity of FOA is only slightly more difficult than that of [Rogerson \(1985\)](#), but without the restrictive convexity of F .

The final part of our paper is devoted to a deeper exploration of the exponential families. In particular, we examine the question of when the expectation of the likelihood ratio is indeed less convex in effort than c . Since exponential families subsume many of the most common distributions used in applications and have a number of other desirable properties for the modeler, a complete off-the-shelf result on the FOA in this setting is of considerable practical use.

The paper proceeds as follows. [Section 2](#) presents the model. [Section 3](#) defines NUC, characterizes it for twice continuously differentiable functions, and presents several sufficient conditions for NUC. [Section 4](#) discusses the relationship between NUC and comparative statics. [Section 5](#) shows how NUC aids in the analysis of the quasi-concavity of the objective function of an optimization problem. [Section 6](#) discusses when NUC fails. [Section 7](#) applies those results to the validity of the FOA in the moral-hazard problem. Finally, [Section 8](#) discusses exponential families. Proofs omitted from the main text are given in the [Appendix](#).

2. THE SETTING

Let \mathcal{A} be a subset of \mathbb{R} and let X be an interval of \mathbb{R} with infimum \underline{x} and supremum \bar{x} in the extended reals. We often speak of $a \in \mathcal{A}$ as the effort taken by an agent and of $x \in X$ as the outcome, reflecting that one central use of our ideas is in principal-agent settings. The outcome x has cumulative distribution (cdf) conditional on a , $F(\cdot|a) : X \rightarrow [0, 1]$, with, as appropriate, density or probability distribution function $f(\cdot|a)$.¹¹ We assume that $F_a(x|\cdot) < 0$ for all interior x , so that first-order stochastic dominance (FOSD) strictly holds. Regarding f , we occasionally also assume the stronger condition that f is strictly log-supermodular (lsm) in a and x (or, equivalently, satisfies strict MLRP), so that $f(\cdot|a_h)/f(\cdot|a_l)$ is strictly increasing in x when $a_h > a_l$. When f is differentiable in a , this is equivalent to $l(\cdot|a) \equiv f_a(\cdot|a)/f(\cdot|a)$ being strictly increasing in x . We are very explicit when we impose MLRP.¹²

¹¹When f is a density, we freely impose high-order differentiability assumptions on f and F in the interest of simplicity and clarity, although many of the results in this paper rely on less. We also assume that the functions f_a , f_{aa} , F_a , and F_{aa} are integrable, and take for granted the validity of interchanging differentiation and integration, which can be justified under mild conditions (see [Chade and Swinkels 2019](#)).

¹²We use increasing, decreasing, convex, concave, etc. in the weak sense, adding “strictly” when appropriate. A twice continuously differentiable real-valued function g with domain on a rectangle of the plane

3. THE NO-UPWARD-CROSSING CONDITION

Say that F satisfies no-upward-crossing (NUC) if, for all $\{a_l, a'_l, a_h, a'_h\}$ with $a_l < a'_l$, $a_h < a'_h$, $a_l \leq a_h$, and $a'_l \leq a'_h$,

$$\frac{F(x|a'_h) - F(x|a_h)}{F(x|a'_l) - F(x|a_l)} \quad (1)$$

is increasing in x (recall that we use “increasing” in the weak sense). We justify the choice of nomenclature below.

In words, F satisfies NUC if the ratio by which an increase in action from a_h to a'_h versus an increase in action from a_l to a'_l affects F goes up with the outcome x . That is, changes in effort between two lower effort levels matter relatively more to F at low outcomes, while changes in effort between two higher effort levels matter relatively more at high outcomes.

3.1 NUC for continuous distributions

Under some smoothness assumptions on F , NUC has a simple characterization.

PROPOSITION 1. *Let A and X be intervals, and let F be C^2 . Then the following statements are equivalent:*

- (i) *NUC.*
- (ii) *The function $-F_a$ is log-supermodular in a and x .*
- (iii) *For each $a \in A$ and $\tau \in \mathbb{R}$, $F_{aa}(\cdot|a) - \tau F_a(\cdot|a)$ never crosses 0 from below on the interior of X .*

The proof is given in [Appendix A.1](#). To show that (i) and (ii) are equivalent, one expresses the ratio in (1) as a ratio of integrals of $-F_a$, and then shows that the derivative of this ratio with respect to x has the sign of the difference of the expectation of $f_a(x|\cdot)/F_a(x|\cdot)$ over $[a_h, a'_h]$ and $[a_l, a'_l]$ with respect to the (artificial) density on a given by

$$\xi(a) = \frac{-F_a(x|a)}{\int (-F_a(x|s)) ds}.$$

Since $a'_h \geq a'_l$ and $a_h \geq a_l$ (with at least one inequality strict except in the trivial case), this difference is always positive if and only if $f_a(x|\cdot)/F_a(x|\cdot)$ is increasing, which is equivalent to $-F_a$ lsm.

Condition (iii) is very useful in applications and is the progenitor of the term NUC. Under NUC, $z(\cdot, \tau, a) \equiv F_{aa}(\cdot|a) - \tau F_a(\cdot|a)$ has only three possible sign patterns: for any

is supermodular if $\partial^2 g / \partial x \partial y \geq 0$ and it is log-supermodular if $\log g$ is supermodular. We use the notation $g \geq 0$, etc. to mean that $g(x) \geq 0$ for all x . For simplicity, we often omit the argument of functions when it causes no confusion. We also use $=_s$ to mean “has strictly the same sign as.”

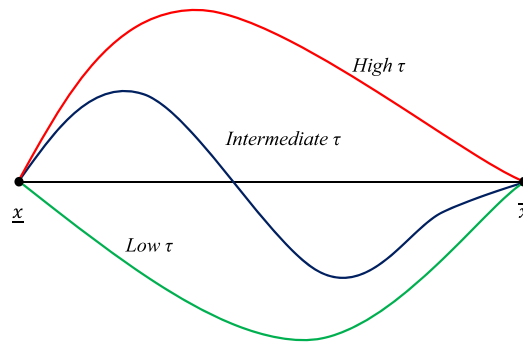


FIGURE 1. NUC. The figure depicts the behavior of the function $z(\cdot, \tau, a)$ for three different levels of τ : depending on τ it can be always negative, always positive, or first positive and then negative. In all cases, it starts and ends at 0.

given a and depending on τ , it can be everywhere positive, everywhere negative, or first positive and then negative (see Figure 1). It has, in particular, no-upward-crossing on the interior of X .

Condition (ii) helps our intuitive understanding of NUC. Note that $-F_a$ is the amount by which extra effort raises the probability of an outcome above x , and, thus, $-F_{aa}/(-F_a)$ measures the proportionate change in the benefit of extra effort as effort is increased. By (ii), NUC is equivalent to this proportional change being more favorable at higher outcomes. That is, at points x where $F_{aa} > 0$, so that extra effort has diminishing marginal returns, $-F_{aa}/(-F_a)$ is becoming less negative: the diminishing returns are smaller at higher outputs. Similarly, if $F_{aa} < 0$, so that there are increasing marginal returns to effort at x , then the increasing returns are yet larger at higher x .¹³

Using Proposition 1, we see that MLRP and NUC are in the same spirit. In particular, MLRP is the condition that F_{ax}/F_x is increasing in x , while NUC is the condition that F_{aa}/F_a is increasing in x . Thus, MLRP asks that F_x be log-supermodular in a and x , while, given FOSD, NUC asks for the same condition on $-F_a$. Each condition fails in specific examples (see below), but imposes useful regularity on the problem. Indeed, in the location families $F(x|a) = Q(x - a)$, we have $F_x(x|a) = Q'(x - a) = -F_a(x|a)$, and so MLRP and NUC reduce to the same condition.

REMARK 1. As suggested by the example in the Introduction, our intuition for the monotonicity of the expression in (1) is strongest when $a'_l < a_h$. It can be seen from the proof of Proposition 1 (see in particular (17)) that even if one weakened the definition of NUC to consider only cases where $a'_l < a_h$, NUC would remain equivalent to $-F_a$ lsm. Hence, for $F \in \mathcal{C}^2$, the two definitions agree.

¹³Since log-supermodularity is robust to an increasing transformation of x or a , so is NUC. The proof of this assertion is immediate and, thus, is omitted.

3.2 Three sufficient conditions for NUC

In this section, we provide three increasingly strong conditions that imply NUC. We continue to assume that A and X are intervals, and we take F to be \mathcal{C}^5 . These conditions help to check NUC in examples and to build intuition.

PROPOSITION 2. *Assume strict MLRP and let F be \mathcal{C}^5 . Then*

$$(\log f)_{ax} \text{ lsm} \implies f^2(\log f)_{ax} \text{ lsm} \implies F^2(\log F)_{ax} \text{ lsm} \implies \text{NUC}.^{14}$$

The proof is provided in [Appendix A.2](#).¹⁵ Note that $(\log f)_{ax} > 0$ is equivalent to the condition that f is strictly lsm (strict MLRP). Hence, the conditions on f in this proposition can be interpreted as repeated applications of lsm.

The condition $(\log f)_{ax} \text{ lsm}$ is most stark when we consider *exponential families*. In [Section 8](#), we show that for such families, $(\log(\log f)_{ax})_{ax} = 0$ (and, indeed, that only the exponential families satisfy this condition). Leading examples of exponential families are the exponential, Poisson, gamma, normal, and beta distributions, and truncations thereof.

To interpret the condition $(\log f)_{ax} \text{ lsm}$, fix a and, for ε small, note that the likelihood ratio of a versus $a - \varepsilon$ given x is (recall that $l = f_a/f$ is the likelihood ratio in differential form)

$$\frac{f(x|a)}{f(x|a - \varepsilon)} \cong 1 + \varepsilon l(x|a).$$

So l is steep around x if and only if changes in the outcome around x provide significantly different information about a versus $a - \varepsilon$. Take $x'' > x'$. Then, since $(\log f)_{ax} = l_x$, the condition $(\log f)_{ax} \text{ lsm}$ is equivalent to the condition that as a increases, l becomes relatively steeper at x'' versus x' . That is, as a goes up, changes in the outcome near x'' become more informative about a versus $a - \varepsilon$ relative to changes in the outcome near x' .

This is intuitive. If a is low, then *any* high outcome may be largely a matter of (good) luck, with the relative probability of these outcomes not depending much on small differences in effort. This leads to a relatively flat l at high outcomes. Conversely, when a is high, it is low outcomes that are largely a matter of (bad) luck, leading to a relatively flat l at low outcomes.

Finally, we connect NUC to TP_3 , a condition explored by [Jewitt \(1988, p. 1182\)](#).

LEMMA 1. *Assume MLRP and let F be \mathcal{C}^5 . Then*

$$f^2(\log f)_{ax} \text{ strictly lsm} \implies \text{TP}_3 \implies f^2(\log f)_{ax} \text{ lsm}.$$

Hence, by [Proposition 2](#), NUC is considerably more permissive than TP_3 . See [Appendix A.3](#).

¹⁴Because f is strictly lsm, each of the relevant objects is strictly positive on (\underline{x}, \bar{x}) .

¹⁵We are very grateful to a referee who helped us toward a simpler proof of the second implication.

4. NUC, THRESHOLD TESTS, AND COMPARATIVE STATICS

In this section, we provide a first application of NUC. This application is economically relevant in its own right and also illuminates an intuitive foundation for NUC. We begin with a simplified setting and show that an intuitive comparative static holds *if and only if* NUC is in force. We then consider a more elaborate and economically realistic version of the problem, and show that strict NUC remains the right condition to imply the desired comparative static. Together, these results substantially strengthen our belief that NUC is a natural condition to impose.

A university department that has junior faculty of ability $\theta \in \{\ell, h\}$, where the probability of type ℓ is p and the probability of type h is $1 - p$. The department can offer research support $\delta \in \{0, 1\}$ to its junior faculty. Research output with ability θ and support δ is distributed according to $F(\cdot | \alpha(\theta, \delta))$, where $\alpha(\theta, 0) < \alpha(\theta, 1)$ for $\theta \in \{\ell, h\}$ and $\alpha(\ell, \delta) < \alpha(h, \delta)$ for $\delta \in \{0, 1\}$. That is, output is stochastically increased both by ability and by the level of research support. Tenure is granted if and only if output exceeds a threshold t . The department gets utility -1 from tenuring type ℓ , utility 1 from tenuring type h , and utility 0 from not tenuring, for an expected payoff of

$$\pi(t, \delta) = -p(1 - F(t | \alpha(\ell, \delta))) + (1 - p)(1 - F(t | \alpha(h, \delta))). \quad (2)$$

Say that preferences are *monotone* if for all pairs (p, α) , the function $\pi(t, 1) - \pi(t, 0)$ never crosses zero from above at some interior t . That is, the department never wants to support faculty facing an easy tenure hurdle, but not to support them when they face a harder hurdle. As discussed in the Introduction, we find monotonicity quite intuitive.

PROPOSITION 3. *Preferences are monotone if and only if F satisfies NUC.*

PROOF. Using (2) at $\delta = 0$ and $\delta = 1$, and rearranging, at any interior t ,

$$\pi(t, 1) - \pi(t, 0) = -\frac{p}{1 - p} + \frac{F(t | \alpha(h, 1)) - F(t | \alpha(h, 0))}{F(t | \alpha(\ell, 1)) - F(t | \alpha(\ell, 0))}, \quad (3)$$

using FOSD. The result follows from the definition of NUC, since the range of $\frac{p}{1-p}$ is $[0, \infty)$. \square

REMARK 2. This setting is equivalent to one in which an observer is trying to guess a state based only on the information of whether output exceeds threshold t , and is choosing which of two information environments ($\delta = 0$ or $\delta = 1$) she prefers for any given t . This is similar to a setting considered by [Jewitt et al. \(2008\)](#). In this interpretation, it is intuitive to let the observer also guess according to her prior, simply ignoring whether or not the threshold was exceeded. In [Appendix A.4](#), we show that if F is \mathcal{C}^2 and satisfies a log-concavity condition, then any failure of NUC allows one to choose α and p such that (a) the observer uses her information (and so optimally guesses state h if and only if the threshold is exceeded) and (b) a failure of monotonicity occurs.

REMARK 3. This sort of situation is ubiquitous in any setting where what is reported to the decision maker is a coarsening of a raw “score.” For example, in many areas restaurant goers can only see whether a given restaurant earned an A or a B placard, corporate lenders can only see which of a small number of possible ratings a borrowing firm received, a professional school may provide only a coarse report of student performance, and Amazon provides customers only some of the information it uses to certify the vendors using its platform. Our condition corresponds to a situation where if the threshold score for a high rating goes up, the users of the information do not switch their preferences from an easier inspection/grading/certification system to a harsher one.

To see that NUC is really the “right” condition for this sort of problem, let us elaborate our base setting. Let θ have arbitrary distribution Γ (atomic or otherwise), let $\delta \in [0, 1]$, and let $v(\theta)$ be the value to the department of tenuring a faculty member of ability θ , where we assume v single-crosses zero from below (we do not need the natural but stronger condition that v is increasing). Let output for the faculty member be distributed as $F(\cdot|\alpha(\theta, \delta))$, where α_θ and α_δ are strictly positive. For given t and δ , the payoff to the department is thus

$$\pi(t, \delta) = \int v(\theta)(1 - F(t|\alpha(\theta, \delta))) d\Gamma(\theta).$$

This problem embeds the problem originally considered, and so NUC remains necessary for monotonicity. In its strict form, it also remains sufficient.

PROPOSITION 4. Fix (p, α) , and assume that F is \mathcal{C}^2 and satisfies NUC strictly (i.e., that $-F_a$ is strictly lsm). Then, for every pair $\delta_\ell < \delta_h$, $\pi(\cdot, \delta_h) - \pi(\cdot, \delta_\ell)$ has the strict single-crossing property and, hence, the optimal choice of δ is increasing in t .¹⁶

PROOF. It is enough to show that if $\pi(t, \delta_h) - \pi(t, \delta_\ell)$ is 0, then $(\pi(t, \delta_h) - \pi(t, \delta_\ell))_t > 0$. But

$$\pi(t, \delta_h) - \pi(t, \delta_\ell) = \int y(\theta, t) d\Gamma(\theta),$$

where $y(\theta, t) = v(\theta)(F(t|\alpha(\theta, \delta_\ell)) - F(t|\alpha(\theta, \delta_h)))$, and, hence,

$$(\pi(t, \delta_h) - \pi(t, \delta_\ell))_t = \int y_t(\theta, t) d\Gamma(\theta) = \int \frac{y_t(\theta, t)}{y(\theta, t)} y(\theta, t) d\Gamma(\theta).$$

Since v single-crosses 0 from below and since $F(t|\alpha(\cdot, \delta_\ell)) - F(t|\alpha(\cdot, \delta_h)) > 0$, it follows that $y(\cdot, t)$ is first strictly negative and then strictly positive. Hence, since $\int y(\theta, t) d\Gamma(\theta) = 0$, it is enough, using an inequality in Beesack (1957), to show that $y_t(\cdot, t)/y(\cdot, t)$ is strictly increasing.¹⁷ This is established in Appendix A.5, where the proof hinges on the fact that

$$\frac{y_t(\theta, t)}{y(\theta, t)} = \frac{f(t|\alpha(\theta, \delta_\ell)) - f(t|\alpha(\theta, \delta_h))}{F(t|\alpha(\theta, \delta_\ell)) - F(t|\alpha(\theta, \delta_h))},$$

¹⁶In particular, if $t_h > t_\ell$, then the smallest optimal δ at t_h is larger than the largest optimal δ at t_ℓ .

¹⁷The version of Beesack's inequality we use states that if G is a measure, h is a function that strictly single-crosses 0 from below, and q is a strictly increasing function, then $\int h dG = 0 \implies \int qh dG > 0$.

which can be expressed as an expectation of $f_a(t|\cdot)/F_a(t|\cdot)$ with respect to the density ξ on a , where we recall that $\xi(a) = -F_a(t|a)/\int -F_a(t|s) ds$ and where we condition on $a \in [\alpha(\theta, \delta_l), \alpha(\theta, \delta_h)]$. Since α is increasing in θ , the result follows since the conditional expectations of an increasing function over an interval increase in the endpoints of that interval. But, by [Proposition 1](#), $f_a(\cdot|a)/F_a(\cdot|a)$ is strictly increasing since F satisfies NUC strictly. \square

5. NUC AND QUASI-CONCAVE EXPECTATIONS

NUC is of particular use when one is considering maximizing the expectation of a function with respect to a parameterized distribution. To be concrete, let an agent have ability $\theta \in \Theta \subseteq \mathbb{R}$ that she views as coming from prior Γ , let the relationship between effort, ability, and output be given by $F(\cdot|a, \theta)$, and let the payoff to the agent of output x and ability θ be $v(x, \theta)$. Let the cost of effort a to the agent be $c(a)$, with c strictly increasing and c^2 . Then the agent maximizes

$$U(a) = \int_{\Theta} \left(\int_X v(x, \theta) f(x|a, \theta) dx \right) d\Gamma(\theta) - c(a).$$

If Γ is degenerate and v is independent of θ , then this is the problem faced by an agent in a standard moral-hazard problem with contract v (in utils), a topic on which we have more to say in [Section 7](#). If Γ is nondegenerate, then this is a key building block for a career-concerns model, where v , which does not depend on θ , is the market's estimate of the value of the agent given output x and the market's conjectured effort level by the agent.¹⁸

In any such application, analysis of the problem via the first-order condition is very convenient. But to do so, one needs to know that the first-order condition characterizes the global optimum. In the following proposition, we use NUC to provide such a result.

PROPOSITION 5. *Assume that, for each θ , $F(\cdot|\cdot, \theta)$ satisfies NUC, where $F(\cdot|\cdot, \theta)$ has a C^2 density $f(\cdot|\cdot, \theta)$, and assume that there is a differentiable function q of x and θ that is strictly increasing in x and such that, for each θ , v_x/q_x is decreasing in x and*

$$\frac{(\mathbb{E}[q|a])_{aa}}{(\mathbb{E}[q|a])_a} < \frac{c_{aa}(a)}{c_a(a)}. \quad (4)$$

Then U is strictly quasi-concave and, hence, the first-order condition characterizes the optimal choice of a .

PROOF. We have

$$U_a(a) = \int_{\Theta} \int_X v(x, \theta) f_a(x|a, \theta) dx d\Gamma(\theta) - c_a(a)$$

and

$$U_{aa}(a) = \int_{\Theta} \int_X v(x, \theta) f_{aa}(x|a, \theta) dx d\Gamma(\theta) - c_{aa}(a).$$

¹⁸See [Dewatripont et al. \(1999\)](#) for details on the two-period career-concerns model.

When $U_a = 0$,

$$c_{aa}(a) = \frac{c_{aa}(a)}{c_a(a)} c_a(a) = \int_{\Theta} \int_X \frac{c_{aa}(a)}{c_a(a)} v(x, \theta) f_a(x|a, \theta) dx d\Gamma(\theta),$$

and so, substituting and rearranging, we have

$$U_{aa}(a) = \int_{\Theta} \int_X v(x, \theta) \left(f_{aa}(x|a, \theta) - \frac{c_{aa}(a)}{c_a(a)} f_a(x|a, \theta) \right) dx d\Gamma(\theta).$$

It is thus enough that the inner integral is negative for each θ . Integrating the inner integral by parts, it suffices that for each θ ,

$$\begin{aligned} 0 &< \int_X v_x(x, \theta) \left(F_{aa}(x|a, \theta) - \frac{c_{aa}(a)}{c_a(a)} F_a(x|a, \theta) \right) dx \\ &= \int_X \frac{v_x(x, \theta)}{q_x(x, \theta)} q_x(x, \theta) \left(F_{aa}(x|a, \theta) - \frac{c_{aa}(a)}{c_a(a)} F_a(x|a, \theta) \right) dx. \end{aligned}$$

Since $q_x(\cdot, \theta) > 0$ for all θ , it follows by NUC that $q_x(F_{aa} - (c_{aa}/c_a)F_a)$ is never first strictly negative and then strictly positive. Hence, since v_x/q_x is positive and decreasing in x by assumption, we can apply another inequality of Beesack (1957).¹⁹ It is in particular sufficient that for each θ ,

$$\int_X q_x(x, \theta) \left(F_{aa}(x|a, \theta) - \frac{c_{aa}(a)}{c_a(a)} F_a(x|a, \theta) \right) dx > 0 \quad (5)$$

or, equivalently (integrating by parts and rearranging), that

$$\frac{(\mathbb{E}[q|a])_{aa}}{(\mathbb{E}[q|a])_a} < \frac{c_{aa}(a)}{c_a(a)}$$

for all θ , and we are done. \square

In decision problems under uncertainty, where, for example, v is the utility function for income, it is commonly assumed that v is concave in x and then $q(x, \theta) = x$ suffices. Then (4) asks simply that for each type of the agent, c is at least as convex as the expected value of the outcome.²⁰ This holds if expected outcome is concave and costs are convex (with one strictly so), but can also easily hold in applications where expected outcome is not concave or costs are not convex. An attractive feature of Proposition 5 is that both NUC and (4) have clean interpretations.

As we will see below (see in particular Corollary 2), the generality offered by q is very useful in applications. To see where q comes from, note that it may be that either v is not concave in x or expected output is insufficiently concave. But it may also be that

¹⁹This version of Beesack's inequality states that if G is a measure, h is a function that strictly single-crosses 0 from below (above), and r is an increasing (decreasing) positive function, then $\int h dG > 0 \implies \int r h dG > 0$.

²⁰In the two-period career-concerns model, v is a composition of functions whose curvature is much more difficult to pin down. When v will be concave in this case is well beyond the scope of this paper.

by a change of variables, the requisite properties hold. This is the role of q , which, for any given θ , corresponds to simply stretching the x axis according to $z = q(x, \theta)$. Denote the inverse of q with respect to x by φ . If under this relabelling, $\hat{v}(z, \theta) = v(\varphi(z, \theta), \theta)$ is concave in z for each θ , while the expectation of $z = q(x, \theta)$ is more concave than c for each θ , then we are done as well.²¹

6. WHEN DOES NUC FAIL?

In this section, we explore settings where NUC fails. We begin with a continuous distribution and then provide a discrete example that exposes intuition.

For an example where NUC fails but strict MLRP holds, let $a \in [0, 0.48]$, $x \in [0, 1]$, and

$$f(x|a) = \left(\frac{1}{6} - 2 \left(\frac{1}{2} - x \right)^2 \right) \frac{a^2}{2} + 4 \left(x - \frac{1}{2} \right) a + 1,$$

which is quadratic in a with coefficients that depend on x . It can be checked that f satisfies strict MLRP. But f_{aa} has sign pattern $-/+/-$, and so $F_{aa} = \int_0^x f_{aa}$ will be first strictly negative and then strictly positive. In fact, this example contains a recipe for constructing examples where NUC fails: the key step is to appropriately craft the coefficient of a^2 .

To see a discrete example, consider a student who chooses an effort level in $\{0, 1, 2\}$, with probability and cumulative distributions over grades given effort given by

$$f = \begin{array}{c|ccc} & \text{A} & \text{B} & \text{C} \\ \hline 0 & 0 & 1-x & x \\ 1 & 1-y & y-w & w \\ 2 & 1/2 & 1/2 & 0 \end{array} \quad \text{and} \quad F = \begin{array}{c|ccc} & \text{A} & \text{B} & \text{C} \\ \hline 0 & 1 & 1 & x \\ 1 & 1 & y & w \\ 2 & 1 & 1/2 & 0 \end{array},$$

where rows indicate effort and columns indicate grades. Then strict MLRP is equivalent to $(1/2)/(1/2) > (1-y)/(y-w)$ and $(y-w)/w > (1-x)/x$ or, equivalently, $w < 2y-1$ and $w < yx$, and, thus, requires $y > 1/2$. Similarly, NUC holds if $(1/2-y)/(-w) > (y-1)/(w-x)$ or, equivalently, using that by strict FOSD, $w-x < 0$, $w < (2y-1)x$. Thus, strict MLRP holds but NUC fails when

$$x \in (0, 1), \quad y \in (1/2, 1), \quad \text{and} \quad w \in ((2y-1)x, yx) \cap [0, 2y-1).$$

In Figure 2, y is fixed in $(1/2, 1)$, with the shaded areas representing pairs (x, w) where MLRP holds and the lighter area representing pairs where NUC also holds.²²

²¹If v is independent of θ , then the decision maker's expected utility can be written as $\int v(x) (\int f(x|a, \theta) d\Gamma(\theta)) dx$, and so one might hope to work simply with the density $\int f(x|a, \theta) d\Gamma(\theta)$. But as the next section illustrates, NUC need not be inherited by a mixture of distributions that satisfy NUC, and so it may be convenient to retain the θ structure here as well.

²²In this example, NUC implies MLRP. An example that satisfies NUC and FOSD, but fails MLRP is

$$f = \begin{array}{c|ccc} & \text{A} & \text{B} & \text{C} \\ \hline 0 & 0 & 1/2 & 1/2 \\ 1 & 1/4 & 1/2 & 1/4 \\ 2 & 3/4 & 1/8 & 1/8 \end{array} \quad \text{and} \quad F = \begin{array}{c|ccc} & \text{A} & \text{B} & \text{C} \\ \hline 0 & 1 & 1 & 1/2 \\ 1 & 1 & 3/4 & 1/4 \\ 2 & 1 & 1/4 & 1/8 \end{array},$$

where MLRP fails because $f(B|2)/f(C|2) < f(B|1)/f(C|1)$.

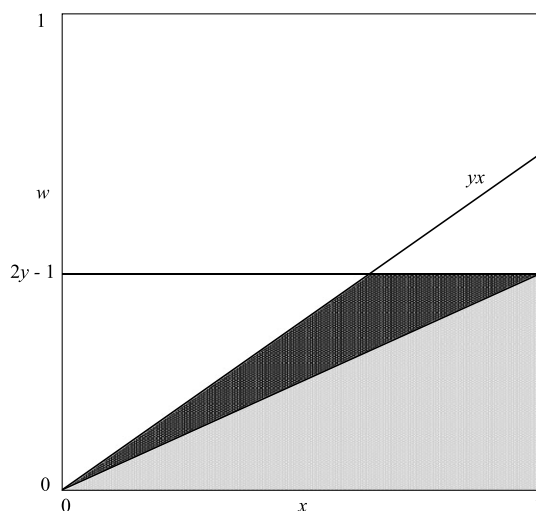


FIGURE 2. Failure of NUC.

In these examples, increasing effort from 0 to 1 moves substantial weight from B to A, while increasing effort from 1 to 2 moves relatively more weight from C to B. More generally, NUC fails when, starting from a low effort level, incremental effort has an effect more on high outcomes, while starting from a high effort level, incremental effort has an effect more on low outcomes.²³

If $x = 1/2$, $y = 3/4$, and $w = 3/8$, then

$$f = \begin{matrix} & \begin{matrix} A & B & C \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \end{matrix} & \begin{bmatrix} 0 & 1/2 & 1/2 \\ 1/4 & 3/8 & 3/8 \\ 1/2 & 1/2 & 0 \end{bmatrix} \end{matrix} \quad \text{and} \quad F = \begin{matrix} & \begin{matrix} A & B & C \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \end{matrix} & \begin{bmatrix} 1 & 1 & 1/2 \\ 1 & 3/4 & 3/8 \\ 1 & 1/2 & 0 \end{bmatrix} \end{matrix}.$$

For a professor with known grading standards, this situation is quite odd: turning in some work should primarily turn Cs into Bs, while turning in all the work instead of some of the work should be relatively more important in turning Bs into As.

To see how such a failure of NUC might still occur, imagine f reflects a professor with unknown type, which can be soft (S) or harsh (H), with $\mathbb{P}[S]/\mathbb{P}[H] = 3$ and with

$$f_S = \begin{matrix} & \begin{matrix} A & B & C \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \end{matrix} & \begin{bmatrix} 0 & 2/3 & 1/3 \\ 1/3 & 1/2 & 1/6 \\ 2/3 & 1/3 & 0 \end{bmatrix} \end{matrix} \quad \text{and} \quad f_H = \begin{matrix} & \begin{matrix} A & B & C \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \end{matrix} & \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \end{matrix},$$

with associated F_S and F_H . Each distribution (weakly) satisfies MLRP and NUC, but as we saw above, the mixture of f_S and f_H , given by f , fails NUC. Indeed, changes in effort

²³If (x, y, w) is uniform on $[0, 1]^3$, then the probability of NUC given MLRP is 87%, where we had to explore several low-dimensional parameterizations of this 3 by 3 example before we found one where NUC ever failed while MLRP held.

from 0 to 1 affect only the grade given by the soft professor, who is quite likely to change a B to an A in response. In contrast, the change in effort from 1 to 2, because it affects the grade given by the harsh professor, has a relatively larger effect on B versus C, leading NUC to fail.²⁴

7. NUC AND THE FIRST-ORDER APPROACH

An important context in which NUC is very helpful is in verifying the validity of the first-order approach in the standard moral-hazard problem. In this section, we remind the reader of the basic issue, and then see how NUC and [Proposition 5](#) simplify the analysis.

A risk-neutral principal hires a strictly risk-averse agent whose effort $a \in A$ is unobservable to the principal. The principal sees a signal $x \in X$ that is distributed according to $F(\cdot|a)$, where f is strictly lsm (strict MLRP). The agent's utility for income is u , his cost of effort is c , both of which are assumed to be C^2 , and his wage is a function of output w . For any contract w and effort a , the agent's expected utility is $\int u(w(x))f(x|a)dx - c(a)$, while the principal's expected profit is $\int (x - w(x))f(x|a)dx$. The agent has an outside option that yields utility u_0 . The principal's problem is to choose a contract w and recommend an effort a to maximize expected profits subject to incentive compatibility and participation. Formally, the principal's problem is

$$\begin{aligned} \max_{w,a} \quad & \int (x - w(x))f(x|a)dx \\ \text{s.t.} \quad & \int u(w(x))f(x|a)dx - c(a) \geq u_0 \\ & a \in \arg \max_{a' \in A} \int u(w(x))f(x|a')dx - c(a'). \end{aligned} \tag{6}$$

As is standard ([Hölmstrom 1979](#), [Mirrlees 1999](#)), the FOA begins by considering the relaxed problem in which (6) is replaced by the agent's first-order condition

$$\int u(w(x))f_a(x|a)dx = c_a(a), \tag{7}$$

for which an optimal solution is of the form (recall that $l \equiv f_a/f$)

$$\frac{1}{u'(w(x))} = \lambda + \mu l(x|a), \tag{8}$$

where $\lambda > 0$ is the Lagrange multiplier associated with the participation constraint, and $\mu > 0$ is the one associated with (7) (see [Jewitt 1988](#) for the proof that μ is strictly positive). The question the FOA addresses is when can we conclude that the solution to this relaxed problem satisfies (6) as well. But this is true as long as $\int u(w(x))f(x|a)dx - c(a)$ is quasi-concave in a .²⁵ Hence, from [Proposition 5](#), the key question is to understand

²⁴This is mathematically the same point as the fact that the convex combination of two distributions each satisfying MLRP need not satisfy MLRP.

²⁵As in [Proposition 5](#), we derive conditions for strict quasi-concavity, but there are versions of all the results in this section where the appropriate inequality is weak.

the behavior of $u(w(\cdot))$, where one can exploit the structure inherent in (8) to put structure on $u(w(\cdot))$.

As in Jewitt (1988), let ρ carry $1/u'$ to u .²⁶ Then, from (8), if the action being implemented is \hat{a} , then $u(w(x)) = \rho(\lambda + \mu l(x|\hat{a}))$ and so

$$(u(w(x)))_x = \rho'(\lambda + \mu l(x|\hat{a}))\mu l_x(x|\hat{a}), \quad (9)$$

which is strictly positive since $l_x > 0$ by strict MLRP. We can, thus, use Proposition 5 in one of two ways. The first is a direct variation of Theorem 1 in Jewitt (1988).

COROLLARY 1. *Assume f is C^2 , F satisfies NUC and MLRP, ρ is concave, l is concave in x for each a , and*

$$\frac{(\mathbb{E}[x|a])_{aa}}{(\mathbb{E}[x|a])_a} < \frac{c_{aa}(a)}{c_a(a)}. \quad (10)$$

Then the FOA is valid.

The proof is immediate from Proposition 5, taking q to be the identity function and noting that v , given by $v(x) = u(w(x))$, is concave under the stated conditions on ρ and l .

Jewitt (1988, Corollary 1) observes that for exponential families (defined in Section 8) with $l(\cdot|a)$ concave, it is enough to check that expected output is concave in effort. The force of our result is that under NUC, this basic insight of exponential families holds *regardless* of the distribution. Under NUC, there is only *one* integral to check (recall that (10) is equivalent to (5) with $q_x = 1$), instead of a continuum of such expectations as in Jewitt (1988). In addition, the relevant integral has a simple economic interpretation.

Proposition 5 also yields the following corollary, which, modulo the use of the disutility of effort, is similar to a result in Jung and Kim (2015a) (see their Proposition 7 and Lemma 2).

COROLLARY 2. *Assume f is C^2 , F satisfies NUC and MLRP, ρ is concave, and that for all a and \hat{a} ,*

$$\frac{(\mathbb{E}[\hat{l}|a])_{aa}}{(\mathbb{E}[\hat{l}|a])_a} < \frac{c_{aa}(a)}{c_a(a)}, \quad (11)$$

where $\hat{l} = l(\cdot|\hat{a})$. Then the FOA is valid.

The proof is immediate from Proposition 5 and from (9), taking $q = l(\cdot|\hat{a})$ and $v(x) = u(w(x))$, and noting that $v'/l_x(\cdot|\hat{a}) = \mu\rho'$ is decreasing, since ρ is concave by assumption.

As mentioned in the Introduction, we stress that both corollaries follow effortlessly from Proposition 5, which in turn follows easily from a *single* integration by parts plus the application of an integral inequality to sign a *single* integral.

We see in the next section that for exponential families, (11) is easy to check. Also, removing the concavity condition on $l(\cdot|\hat{a})$ is especially useful for some exponential families, where $\mathbb{E}[l(\cdot|\hat{a})|a]$ is quite tractable; see Section 8, Example 1.

²⁶That is, define $\rho(\cdot)$ by $\rho(z) = u([u']^{-1}(1/z))$.

REMARK 4. If $l(\cdot|a)$ is concave in x for each a and if NUC holds, then (11) is weaker than (10).

See Appendix A.6 for a direct proof of this remark and see Jung and Kim (2015a, Proposition 8) for an alternative argument. Thus, Corollary 2 generalizes Theorem 1 in Jewitt (1988) in three directions. First, it incorporates the curvature of c . Second, it allows for examples in which l is not concave. Third, even when l is concave, the integral condition typically becomes strictly weaker, as shown by the remark above. For examples where l is convex but the integral condition holds, and where l is concave but the distinction between (10) and (11) has real bite, see Section 8.

So far we have explored the implications of Proposition 5 for the moral-hazard problem, but there is also an interesting implication of the condition $(\log(\log f)_{ax})_{ax} \geq 0$, which, as Proposition 2 shows, under strict MLRP is a sufficient condition for NUC. Pick (a, λ, μ) and $(\hat{a}, \hat{\lambda}, \hat{\mu})$ with $\hat{a} > a$. Let $\phi(x) = \lambda + \mu l(x|a)$ and $\hat{\phi}(x) = \hat{\lambda} + \hat{\mu} l(x|\hat{a})$ be the corresponding contracts considered as functions from x to $1/u'$. Since ρ is strictly increasing, the associated monetary contracts $w = \rho(\phi)$ and $\hat{w} = \rho(\hat{\phi})$ have the same crossing properties as ϕ and $\hat{\phi}$. Now $\hat{\phi}'(x)/\phi'(x) = \hat{\mu} l_x(x|\hat{a})/\mu l_x(x|a)$ and, thus,

$$\left(\frac{\hat{\phi}'(x)}{\phi'(x)} \right)_x =_s \left(\frac{l_{xx}(x|\hat{a})}{l_x(x|\hat{a})} - \frac{l_{xx}(x|a)}{l_x(x|a)} \right) =_s \left(\frac{l_{xx}}{l_x} \right)_a = (\log(\log f)_{ax})_{ax},$$

where we remind the reader that “ $=_s$ ” means “has strictly the same sign as” and where we note that by the last equality and the premise, $(l_{xx}/l_x)_a$ is everywhere positive. So $(\log(\log f)_{ax})_{ax} \geq 0$ holds if and only if the ratio of the slope of the higher effort contract to the slope of the lower effort contract increases in x , so that the higher effort contract is more convex than the lower effort contract. An implication is that (except if they are the same contract) $\hat{\phi}$ can cross ϕ at most twice, and if it does so, it does so first from above and then from below.²⁷ For the exponential families, $(\log(\log f)_{ax})_{ax} = 0$ and, hence, contracts either coincide everywhere, cross exactly once, or do not cross at all, something that is potentially useful to the modeler.

We have followed the standard method to study the validity of the FOA, which imposes conditions on the conditional distribution of the outcome x (and also on u and c). The central point of Jung and Kim (2015a), however, is that one can instead focus on the distribution of the likelihood ratio l , which leads to conditions for the validity of the FOA that do not require strict MLRP on l and that apply also to the multidimensional-signal case.

For completeness, let us see how Proposition 5 implies a key part of their analysis. To do so, fix \hat{a} and for each $\zeta \in \mathbb{R}$, define $X(\zeta, \hat{a}) = \{x | l(x|\hat{a}) \leq \zeta\}$. Let

$$G(\zeta|a, \hat{a}) \equiv \int_{X(\zeta, \hat{a})} f(s|a) ds$$

²⁷If $(\log(\log f)_{ax})_{ax} < 0$, then $\hat{\phi}$ and ϕ cross at most twice, with $\hat{\phi}$ crossing ϕ first from below and then from above.

be the probability, given effort a , that output satisfies $l(x|\hat{a}) \leq \zeta$, and let $g(\cdot|a, \hat{a})$ be the associated density. Let $r(\zeta) \equiv \rho(\lambda + \mu\zeta)$ for each ζ and write the agent's expected utility given effort a as $\int r(\zeta)g(\zeta|a, \hat{a})d\zeta - c(a)$. We then have the following variation on Proposition 7 and Lemma 2 of Jung and Kim (2015a), which unlike Corollary 2 does not assume that l is increasing in x .

PROPOSITION 6. *Assume that $G(\cdot|a, \hat{a})$ satisfies FOSD in a for each \hat{a} , and that $G(\cdot|a, \hat{a})$ is \mathcal{C}^2 and satisfies NUC for each \hat{a} . Assume also that ρ is concave and that for all a and \hat{a} ,*

$$\frac{(\mathbb{E}_{G(\cdot|a, \hat{a})}[\zeta|a])_{aa}}{(\mathbb{E}_{G(\cdot|a, \hat{a})}[\zeta|a])_a} < \frac{c_{aa}(a)}{c_a(a)}.$$

Then the FOA is valid.

The proof is immediate from Proposition 5, with ζ taking the role of x , $G(\cdot|a, \hat{a})$ taking the role of F , and r taking the role of v , taking q as the identity, and noting that $r' = \mu\rho'$ is decreasing, since ρ is concave by assumption.

The degree to which this result is useful depends on the degree to which one can check that $G(x|\cdot, \hat{a})$ satisfies FOSD in a for each x and \hat{a} , and that $G(\cdot|a, \hat{a})$ satisfies NUC for each \hat{a} . Note in particular that once one has abandoned MLRP, the sets $X(\zeta, \hat{a})$ are in principle arbitrary, and so it is not clear what primitives on F are required even for FOSD, let alone NUC. See Jung and Kim (2015a, Section 4.3) for some positive examples.

As an alternative, one could tackle the multidimensional-signal case directly, as in Jewitt (1988) and as in the general analysis in Conlon (2009). The difficulty in extending our results to the multidimensional case is to come up with the analog of the crossing condition that characterizes NUC in the one-dimensional case. One case in which NUC remains useful is the two-signal case when signals are independent (this case was also analyzed by Jewitt (1988)). In this case, it is easy to use strict MLRP, ρ concave, and NUC on the distribution of each signal to justify the FOA. To see this, let y be a second signal with support on an interval with infimum \underline{y} and supremum \bar{y} , and with parameterized distribution P and density p . Assume that F and P are \mathcal{C}^2 and that f and p satisfy strict MLRP. Denote by ℓ the likelihood ratio of y , that is, $\ell \equiv p_a/p$, and for any \hat{a} the principal wants to implement, let $\hat{\ell} \equiv \ell(\cdot|\hat{a})$. Then we have the following result, whose proof is given in Appendix A.7:

PROPOSITION 7. *Assume that x and y are independent signals with \mathcal{C}^2 densities f and p that satisfy strict MLRP, and with distributions F and P that satisfy NUC. Assume also that ρ is concave, and that for all a and \hat{a} , $\hat{\ell}$ and ℓ satisfy (11). Then the FOA is valid.*

Here again, NUC simplifies the analysis and leads to interpretable sufficient conditions.

8. THE EXPONENTIAL FAMILIES

In this section, we explore the exponential families. As mentioned, the exponential, Poisson, gamma, normal, and beta distributions, and their truncations are exponential families. Such truncations are important when applying some of the results in this

section to the FOA, since they bound the likelihood ratio and, thus, rule out a standard nonexistence issue. Motivated by our previous results, we focus on the behavior of $\mathbb{E}[x|a]$ and $\mathbb{E}[l(\cdot|\hat{a})|a]$.

Recall that a family of densities $\{f(\cdot|a)\}_{a \in A}$ is a (one-parameter) exponential family if it can be expressed as

$$f(x|a) = m(a)n(x)e^{H(a)j(x)}, \quad (12)$$

where $n \geq 0$ and $m(a) = 1/\int n(x)e^{H(a)j(x)} dx$.²⁸ Let H be analytic, set $h \equiv H'$, and assume that $h > 0$. Note that

$$l(x|a) = h(a)j(x) + \frac{m'(a)}{m(a)} \quad (13)$$

and so $l_x(x|a) = h(a)j'(x)$. Hence, f satisfies MLRP if and only if j is increasing, as we henceforth assume. Finally, note that $l_{ax}(x|a) = h'(a)j'(x)$ and so

$$(\log(\log f)_{ax})_{ax} = \left(\frac{l_{ax}}{l_x}\right)_x = \left(\frac{h'}{h}\right)_x = 0,$$

as claimed following [Proposition 2](#).

With this in hand, let us return to the moral-hazard problem and, in particular, to the question of when the relevant integral condition holds for exponential families. Then, by (13), the inequality (11) reduces simply to

$$\frac{(\mathbb{E}[j|a])_{aa}}{(\mathbb{E}[j|a])_a} < \frac{c_{aa}(a)}{c_a(a)}, \quad (14)$$

where the problem is more tractable because we can throw away the multiplicatively separable factor $h(\hat{a}) > 0$. By [Corollary 1](#), if j is concave, then it also suffices to check

$$\frac{(\mathbb{E}[x|a])_{aa}}{(\mathbb{E}[x|a])_a} < \frac{c_{aa}(a)}{c_a(a)},$$

as observed by [Jewitt \(1988\)](#), which may be simpler in some settings. Examples include the exponential and Poisson distributions.

There are two reasons to want to go further. First, once j is non-concave, it is not enough to check concavity of output. Second, even when j is concave, concavity of output is more than we need, and may unnecessarily exclude cases of interest. In the following example, j is concave, but it is both easier to check concavity of $\mathbb{E}[j|x]$ than $\mathbb{E}[x|a]$ and critical to do so.

EXAMPLE 1. Consider

$$f(x|a) = a^b x^{a^b-1} = a^b e^{(a^b-1)\log x}$$

²⁸It is implicit in this definition that n , H , and j are chosen such that $n(x)e^{H(a)j(x)}$ is integrable for all a in (\underline{a}, \bar{a}) . It follows (e.g., [Lehmann and Romano 2005](#), Theorem 2.7.1) that if H is analytic on (\underline{a}, \bar{a}) , then so is m , and that f has finite moments of all orders.

for $x \in [0, 1]$, $a > 0$, and $b > 0$. As an exponential family, NUC holds. It is then a matter of simple calculation that, since $j = \log x$, $\mathbb{E}[j|a] = -1/a^b$, which is concave in a for any $b > 0$, while $\mathbb{E}[x|a] = a^b/(a^b + 1)$, which fails to be concave for any $b > 1$.²⁹ \diamond

Our next result illuminates what is needed to satisfy (14). To simplify notation, write σ for the standard deviation of j and write $\gamma = \mathbb{E}[(j(x) - \bar{j})^3|a]/\sigma^3$ for the skewness of j .

PROPOSITION 8. *Let F be an exponential family. Then for each a , (14) holds if and only if*

$$\frac{h'(a)}{h(a)} + h(a)\sigma\gamma < \frac{c_{aa}(a)}{c_a(a)}. \quad (15)$$

This holds if c is strictly relatively more convex than H (since $h'/h = H''/H'$) and j is negatively skewed. Sufficient for j to be negatively skewed is that H is positive and j'/n is decreasing.

The proof is provided in [Appendix A.8](#) and its main step shows that $(\mathbb{E}[j])_{aa}/(\mathbb{E}[j])_a = (h'(a)/h(a)) + h(a)\sigma\gamma$. The result implies that, for exponential families, the FOA is valid if c is strictly relatively more convex than H , $H \geq 0$ and j'/n is decreasing in x . Given [Proposition 8](#), to construct simple examples where j need not be concave but where the integral condition holds, let j be an arbitrary increasing and differentiable function, and take $n = j'$ and H positive and concave.

REMARK 5. The exponential families satisfy $(\log f)_{ax}$ lsm weakly. We can, however, modify this family and construct tractable F for which $(\log f)_{ax}$ lsm is strict. Say that F is a *blended exponential family* if it can be written in the form $f(x|a) = m(a)n(x)e^{j(x)H(a)+\hat{j}(x)\hat{H}(a)}$, where j , \hat{j} , H , and \hat{H} are increasing. Then $l(x|a) = j(x)h(a) + \hat{j}(x)\hat{h}(a) + \frac{m'(a)}{m(a)}$ and $(\log f)_{ax}(x|a) = l_x(x|a) = j'(x)h(a) + \hat{j}'(x)\hat{h}(a) > 0$, and so MLRP is satisfied. Further,

$$(\log(\log f)_{ax})_a(x|a) = \frac{j'(x)h'(a) + \hat{j}'(x)\hat{h}'(a)}{j'(x)h(a) + \hat{j}'(x)\hat{h}(a)}$$

and it is now possible to construct distributions with a rich set of behaviors for $(\log(\log f)_{ax})_{ax}$.³⁰ Indeed, take $H(a) = a^2/2$ and $\hat{H}(a) = -(1-a)^2/2$. Then $h(a) = a$, $\hat{h}(a) = 1-a$, $l_x(x|a) = j'(x)a + \hat{j}'(x)(1-a)$, and $(\log(\log f)_{ax})_a(x|a) = (j'(x) - \hat{j}'(x))/aj'(x) + (1-a)\hat{j}'(x)$. By suitable choice of $\hat{j}(x)$ and $j(x)$, we can make $(\log(\log f)_{ax})_{ax}$ strictly positive. For example, if $j''/j' > \hat{j}''/\hat{j}'$, then $(\log(\log f)_{ax})_{ax} > 0$ and, thus, NUC holds.

²⁹In this example, the likelihood ratio is unbounded below. This is easy to modify by assuming that $x \in [\eta, 1 + \eta]$ with $\eta > 0$, so that $f(x|a) = (a^b x^{a^b-1})/((1+\eta)^{a^b} - \eta^{a^b})$. One can verify that for each $b > 1$, if one takes η sufficiently small, the expectation of $j(x)$ is concave in a , but the expectation of x is not.

³⁰One can actually go further by letting $f(x|a) = m(a)n(x)e^{\int j(x,s)H(a,s)dK(s)}$ for some distribution K and running through the same derivation.

9. CONCLUDING REMARKS

We have introduced, motivated, and illustrated the economic relevance of a log-supermodularity condition, which we call NUC, on a parameterized family of distributions. We provided a characterization for NUC under differentiability assumptions as well as several sufficient conditions that are easier to check in some settings. We showed that NUC has a strong intuitive foundation in terms of a natural monotonicity property in a statistical decision problem.

We showed that NUC is useful in the analysis of some interesting economic problems. It is especially relevant when characterizing a global optimum using first-order conditions in some problems under uncertainty. Two such problems are the principal-agent problem with moral hazard, where a technical hurdle is to justify the FOA, and the career-concerns problem, where the agent's first-order condition becomes an equilibrium condition under rational expectations.

We also explored the limitations of NUC and provided examples where NUC fails. Although NUC can fail, we contend that the instances where this happens are somewhat artificial, lending further credibility to NUC as a natural condition.

In the last part of the paper, we provided a thorough analysis of the validity of the FOA in the moral-hazard problem using NUC and we related the results to those in the analysis in [Jewitt \(1988\)](#) and [Jung and Kim \(2015a\)](#). In particular, we explored the usefulness of NUC in the case of exponential families and illustrated its tractability in commonly used examples of this class. It is our hope on a forward-going basis that, as for MLRP, NUC turns out to simplify and clarify analysis in a broad set of problems.

APPENDIX: OMITTED PROOFS

A.1 Proof of [Proposition 1](#)

LEMMA 2. *Let $\chi : \mathbb{R}^2 \rightarrow \mathbb{R}$ be strictly positive and \mathcal{C}^2 . Then χ is lsm if and only if for each $\tau \in \mathbb{R}$ and each a , $-\chi_a(\cdot, a) + \tau\chi(\cdot, a)$ is never first strictly negative and then strictly positive.*

PROOF. Sufficiency follows since

$$-\chi_a(x, a) + \tau\chi(x, a) = \tau - \frac{\chi_a(x, a)}{\chi(x, a)}.$$

Since χ is lsm, χ_a/χ is increasing in x , so once $-\chi_a(x, a) + \tau\chi(x, a)$ is negative, it remains so.

For necessity, assume χ is not lsm. Then there are $x', x'' \in (\underline{x}, \bar{x})$ with $x'' > x'$ such that

$$\frac{\chi_a}{\chi}(x'', a) < \frac{\chi_a}{\chi}(x', a),$$

and so for any $\tau \in (\frac{\chi_a}{\chi}(x'', a), \frac{\chi_a}{\chi}(x', a))$, $-\chi_a(x', a) + \tau\chi(x', a) < 0 < -\chi_a(x'', a) + \tau\chi(x'', a)$, contradicting the premise. \square

PROOF OF **PROPOSITION 1**. That (ii) is equivalent to (iii) is immediate by applying **Lemma 2** to $\chi(x, a) = -F_a(x|a)$, which is positive under our maintained assumption of FOSD.

To see that (i) and (ii) are equivalent, let

$$R(x) \equiv \frac{F(x|a'_h) - F(x|a_h)}{F(x|a'_l) - F(x|a_l)} = \frac{-\int_{a_h}^{a'_h} F_a(x|s) ds}{-\int_{a_l}^{a'_l} F_a(x|s) ds}$$

and so

$$\begin{aligned} R'(x) &= {}_s(\log R)_x \\ &= \frac{\int_{a_h}^{a'_h} f_a(x|s) ds}{\int_{a_h}^{a'_h} F_a(x|s) ds} - \frac{\int_{a_l}^{a'_l} f_a(x|s) ds}{\int_{a_l}^{a'_l} F_a(x|s) ds} \\ &= \int_{a_h}^{a'_h} \frac{f_a}{F_a}(x|s) \frac{-F_a(x|s)}{\int_{a_h}^{a'_h} (-F_a(x|s)) ds} ds - \int_{a_l}^{a'_l} \frac{f_a}{F_a}(x|s) \frac{-F_a(x|s)}{\int_{a_l}^{a'_l} (-F_a(x|s)) ds} ds \\ &= \mathbb{E}_\xi \left(\frac{f_a}{F_a}(x|a) \middle| a \in [a_h, a'_h] \right) - \mathbb{E}_\xi \left(\frac{f_a}{F_a}(x|a) \middle| a \in [a_l, a'_l] \right). \end{aligned} \quad (16)$$

Assume that $-F_a$ is lsm in (x, a) . Then f_a/F_a increases in a and (16) implies that $R' \geq 0$, since the expectation of an increasing function increases in either bound of the conditioning set.

Assume that $R' \geq 0$. Then, for any interior x , any $a'' > a'$, and for each $\varepsilon > 0$, it follows from (16) that

$$\mathbb{E}_\xi \left(\frac{f_a(x|a)}{F_a(x|a)} \middle| a \in [a'', a'' + \varepsilon] \right) - \mathbb{E}_\xi \left(\frac{f_a(x|a)}{F_a(x|a)} \middle| a \in [a', a' + \varepsilon] \right) \geq 0 \quad (17)$$

and so, taking $\varepsilon \rightarrow 0$,

$$\frac{f_a(x|a'')}{F_a(x|a'')} \geq \frac{f_a(x|a')}{F_a(x|a')}.$$

Hence, $-F_a$ is lsm in (x, a) . □

A.2 Proof of Proposition 2

The first implication is trivial since f is lsm and the product of lsm functions is lsm.

Let us prove that $f^2(\log f)_{ax} \text{ lsm} \implies F^2(\log F)_{ax} \text{ lsm}$. Note that $F^2(\log F)_{ax} = f_a F - F_a f$. Now

$$\frac{(f_a F - F_a f)_a}{f_a F - F_a f} = \frac{f_{aa} F + f_a F_a - F_{aa} f - F_a f_a}{f_a F - F_a f} = \frac{\frac{f_{aa}}{f} - \frac{F_{aa}}{F}}{\frac{f_a}{f} - \frac{F_a}{F}} \equiv \eta(x|a)$$

and so, to establish that $f_a F - F_a f$ is lsm, we need to show that $\eta_x \geq 0$. But

$$\begin{aligned} \frac{f_{aa}}{f}(x|a) - \frac{F_{aa}}{F}(x|a) &= \int_{\underline{x}}^x \left(\frac{f_{aa}}{f}(x|a) - \frac{f_{aa}}{f}(z|a) \right) \frac{f(z|a)}{F(x|a)} dz \\ &= \int_{\underline{x}}^x \int_z^x \left(\frac{f_{aa}}{f}(s|a) \right)_x ds \frac{f(z|a)}{F(x|a)} dz \\ &= \int_{\underline{x}}^x \left(\frac{f_{aa}}{f}(s|a) \right)_x \left(\int_{\underline{x}}^s \frac{f(z|a)}{F(x|a)} dz \right) ds \\ &= \int_{\underline{x}}^x \left(\frac{f_{aa}}{f}(s|a) \right)_x \frac{F(s|a)}{F(x|a)} ds, \end{aligned}$$

where the second equality uses the Fundamental Theorem of Calculus and the third equality exchanges the order of integration over the domain $\underline{x} \leq z \leq s \leq x$. Similarly,

$$\frac{f_a}{f}(x|a) - \frac{F_a}{F}(x|a) = \int_{\underline{x}}^x \left(\frac{f_a}{f}(s|a) \right)_x \frac{F(s|a)}{F(x|a)} ds$$

and so

$$\begin{aligned} \eta &= \frac{\int_{\underline{x}}^x \left(\frac{f_{aa}}{f}(s|a) \right)_x F(s|a) ds}{\int_{\underline{x}}^x \left(\frac{f_a}{f}(s|a) \right)_x F(s|a) ds} \\ &= \int_{\underline{x}}^x \frac{\left(\frac{f_{aa}}{f}(s|a) \right)_x \left(\frac{f_a}{f}(s|a) \right)_x F(s|a)}{\left(\frac{f_a}{f}(s|a) \right)_x \int_{\underline{x}}^x \left(\frac{f_a}{f}(\tau|a) \right)_x F(\tau|a) d\tau} ds \\ &= \int_{\underline{x}}^x \beta(s) \frac{\psi(s)}{\Psi(x)} ds, \end{aligned}$$

where

$$\beta(s) = \frac{\left(\frac{f_{aa}}{f}(s|a) \right)_x}{\left(\frac{f_a}{f}(s|a) \right)_x}, \quad \psi(s) = \frac{\left(\frac{f_a}{f}(s|a) \right)_x F(s|a)}{\int \left(\frac{f_a}{f}(\tau|a) \right)_x F(\tau|a) d\tau}$$

and Ψ is the cumulative distribution function of ψ .

We would then be done if β is increasing, since the conditional expectation of an increasing function over an interval increases in the endpoints of that interval. But

$$\beta = \frac{\left(\frac{f_{aa}}{f}\right)_x}{\left(\frac{f_a}{f}\right)_x} = \frac{f_{aax}f - f_{aa}f_x}{f_{ax}f - f_af_x} = \frac{(f_{ax}f - f_af_x)_a}{f_{ax}f - f_af_x},$$

which is increasing in x , since $f_{ax}f - f_af_x = f^2(\log f)_{ax}$ is lsm by assumption.

Finally, we prove that $F^2(\log F)_{ax}$ lsm \implies NUC. Fix a and at any $x \in (\underline{x}, \bar{x}]$, differentiate the identity $F_a = FF_a/F$ by a to get

$$F_{aa} = F_a \frac{F_a}{F} + F \left(\frac{F_a}{F} \right)_a$$

and so

$$\nu \equiv F_{aa} - \tau F_a = F \left(\left(\frac{F_a}{F} \right)^2 + \left(\frac{F_a}{F} \right)_a - \tau \frac{F_a}{F} \right),$$

where we think of ν as a function purely of x . Thus,

$$\nu' = f \left(\left(\frac{F_a}{F} \right)^2 + \left(\frac{F_a}{F} \right)_a - \tau \frac{F_a}{F} \right) + F \left(2 \left(\frac{F_a}{F} \right) \left(\frac{F_a}{F} \right)_x + \left(\frac{F_a}{F} \right)_{ax} - \tau \left(\frac{F_a}{F} \right)_x \right)$$

or

$$\nu'(x) = \frac{f}{F} \nu(x) + F \left(\frac{F_a}{F} \right)_x (x|a)(r(x) - \tau), \quad (18)$$

where

$$r = 2 \left(\frac{F_a}{F} \right) + \frac{\left(\frac{F_a}{F} \right)_{ax}}{\left(\frac{F_a}{F} \right)_x}$$

and where it is standard that lsm is preserved by integration, so f is lsm implies that F is lsm and, thus, $(F_a/F)_x > 0$. Note also that

$$r = \left(\log \left(F^2 \left(\frac{F_a}{F} \right)_x \right) \right)_a = (\log(F_{ax}F - F_aF_x))_a$$

and, hence, r is increasing in x if and only if $(F_{ax}F - F_aF_x) = F^2(\log F)_{ax}$ is lsm.

Assume that F fails NUC, so that there is $x' < x''$ such that $\nu(x') < 0 < \nu(x'')$. Then there must be $\tilde{x} \in (x', x'')$ such that $\nu(\tilde{x}) = 0$ and $\nu'(\tilde{x}) \geq 0$, and so from (18), $r(\tilde{x}) \geq \tau$. Since r is increasing, it also follows from (18) that for all $x \in (\tilde{x}, \bar{x})$, if $\nu > 0$, then $\nu' > 0$. Thus, since $\nu(x'') > 0$, ν is strictly increasing after x'' and so $\nu(\tilde{x}) > \nu(x'') > 0$. But $\nu(\tilde{x}) = F_{aa}(\tilde{x}) - \tau F_a(\tilde{x}) = 0$, contradicting that F fails NUC.

A.3 Proof of [Lemma 1](#)

Let

$$d = \begin{vmatrix} f & f_a & f_{a^2} \\ f_x & f_{ax} & f_{a^2x} \\ f_{x^2} & f_{ax^2} & f_{a^2x^2} \end{vmatrix}.$$

Given MLRP, [Karlin \(1957, Theorem 2\)](#) shows that necessary for TP_3 is that $d \geq 0$ for each x and a , and sufficient is that $d > 0$ for each x and a (see [Karlin 1957](#), pp. 289–290 for a discussion of the case $d = 0$). [Lemma 1](#) then follows from the observation that

$$\begin{aligned} & (\log(f^2(\log f)_{ax}))_{ax} \\ &= (\log(f_{ax}f - f_af_x))_{ax} = \left(\frac{(f_{ax}f - f_af_x)_a}{f_{ax}f - f_af_x} \right)_x = \left(\frac{f_{a^2x}f - f_{a^2}f_x}{f_{ax}f - f_af_x} \right)_x \\ &= {}_s(f_{a^2x^2}f - f_{a^2}f_{x^2})(f_{ax}f - f_af_x) - (f_{a^2x}f - f_{a^2}f_x)(f_{ax^2}f - f_af_{x^2}) \\ &= f(-f_af_xf_{a^2x^2} + f_xf_{a^2}f_{ax^2} + f_af_{x^2}f_{a^2x} - f_{ax}f_{a^2}f_{x^2} + ff_{a^2x^2}f_{ax} - ff_{ax^2}f_{a^2x}) \\ &= {}_s f(f_{ax}f_{a^2x^2} - f_{a^2x}f_{ax^2}) - f_a(f_xf_{a^2x^2} - f_{x^2}f_{a^2x}) + f_{a^2}(f_xf_{ax^2} - f_{x^2}f_{ax}) \\ &= d. \end{aligned}$$

A.4 Proof of [Remark 2](#)

Let us now formalize and prove [Remark 2](#).

PROPOSITION 9. Assume that A is an interval, that F is \mathcal{C}^2 , and that $F(t|\cdot)$ and $1 - F(t|\cdot)$ are strictly log-concave for all t interior. Then if F fails NUC, then there exists α , p , and \hat{t} such that $\pi(\cdot, 1) - \pi(\cdot, 0)$ crosses 0 from above at \hat{t} and such that on a neighborhood of \hat{t} , $\max\{\pi(\cdot, 1), \pi(\cdot, 0)\} > \max\{0, 1 - 2p\}$.

Noting that $\max\{0, 1 - 2p\}$ is the observer's payoff from guessing using her prior, this means that near \hat{t} , the observer is strictly better off to use the results of the test rather than act according to the prior, where just to the left of \hat{t} , the observer strictly prefers $\delta = 1$, while just to the right of \hat{t} , the observer strictly prefers $\delta = 0$.

PROOF. If NUC fails, then by [Proposition 1 \(ii\)](#), there exist \hat{t} , a_l , and $a_h > a_l$ such that

$$\frac{f_a}{F_a}(\hat{t}|a_l) > \frac{f_a}{F_a}(\hat{t}|a_h)$$

and so there is $\delta > 0$ such that

$$\mathbb{E}_\xi \left(\frac{f_a(\hat{t}|a)}{F_a(\hat{t}|a)} \middle| a \in [a_l, a_l + \delta] \right) - \mathbb{E}_\xi \left(\frac{f_a(\hat{t}|a)}{F_a(\hat{t}|a)} \middle| a \in [a_h, a_h + \delta] \right) > 0.$$

Take $\alpha(l, 0) = a_l$, $\alpha(l, 1) = a_l + \delta$, $\alpha(h, 0) = a_h$, and $\alpha(h, 1) = a_h + \delta$, and choose p such that

$$\frac{p}{1-p} = \frac{F(\hat{t}|a_h + \delta) - F(\hat{t}|a_h)}{F(\hat{t}|a_l + \delta) - F(\hat{t}|a_l)}.$$

Then, by (3) and (16), $\pi(t, 1) - \pi(t, 0)$ strictly crosses 0 from above at \hat{t} . It remains to show that $\pi(\hat{t}, 1) = \pi(\hat{t}, 0) > \max\{0, 1 - 2p\}$.

Let us show first that $\pi(\hat{t}, 0) > 1 - 2p$ or, equivalently, that

$$-p(1 - F(\hat{t}|a_l)) + (1 - p)(1 - F(\hat{t}|a_h)) > 1 - 2p.$$

This is equivalent to

$$\frac{F(\hat{t}|a_h)}{F(\hat{t}|a_l)} < \frac{p}{1 - p} = \frac{F(\hat{t}|a_h + \delta) - F(\hat{t}|a_h)}{F(\hat{t}|a_l + \delta) - F(\hat{t}|a_l)},$$

where the equality uses our choice of p . Rearranging the end expressions (recalling that the denominator on the right-hand side is negative), we arrive at

$$\frac{F(\hat{t}|a_h)}{F(\hat{t}|a_l)} > \frac{F(\hat{t}|a_h + \delta)}{F(\hat{t}|a_l + \delta)},$$

which holds for all $a_h > a_l$ and $\delta > 0$ since

$$\frac{F(\hat{t}|a_h + \tau)}{F(\hat{t}|a_l + \tau)} = \exp \int_{a_l}^{a_h} \left(\frac{\partial}{\partial a} \log F(\hat{t}|a + \tau) \right) da,$$

which is strictly decreasing in τ since $F(\hat{t}|\cdot)$ is strictly log-concave. The proof that $\pi(\hat{t}, 1) > 0$ is analogous, using that $1 - F(\hat{t}|\cdot)$ is strictly log-concave. \square

A.5 Proof that $y_t(\cdot, t)/y(\cdot, t)$ is increasing

Since $y(\theta, t) = v(\theta)(F(t|\alpha(\theta, \delta_l)) - F(t|\alpha(\theta, \delta_h)))$, we have that

$$\begin{aligned} \frac{y_t(\theta, t)}{y(\theta, t)} &= \frac{f(t|\alpha(\theta, \delta_l)) - f(t|\alpha(\theta, \delta_h))}{F(t|\alpha(\theta, \delta_l)) - F(t|\alpha(\theta, \delta_h))} \\ &= \frac{1}{F(t|\alpha(\theta, \delta_l)) - F(t|\alpha(\theta, \delta_h))} \int_{\alpha(\theta, \delta_l)}^{\alpha(\theta, \delta_h)} (-f_a(t|a)) da \\ &= \frac{1}{F(t|\alpha(\theta, \delta_l)) - F(t|\alpha(\theta, \delta_h))} \int_{\alpha(\theta, \delta_l)}^{\alpha(\theta, \delta_h)} \frac{f_a(t|a)}{F_a(t|a)} (-F_a(t|a)) da \\ &= \frac{\int -F_a(t|s) ds}{F(t|\alpha(\theta, \delta_l)) - F(t|\alpha(\theta, \delta_h))} \int_{\alpha(\theta, \delta_l)}^{\alpha(\theta, \delta_h)} \frac{f_a(t|a)}{F_a(t|a)} \frac{-F_a(t|a)}{\int -F_a(t|s) ds} da \\ &= \mathbb{E}_\xi \left(\frac{f_a(t|a)}{F_a(t|a)} \middle| a \in [\alpha(\theta, \delta_l), \alpha(\theta, \delta_h)] \right). \end{aligned}$$

Since $f_a(t|\cdot)/F_a(t|\cdot)$ is increasing and since α is increasing in θ , the result follows.

A.6 Proof of Remark 4

It is enough to show that when $l(\cdot|a)$ is concave, then $(\mathbb{E}[\hat{l}|a])_{aa}/(\mathbb{E}[\hat{l}|a])_a \leq (\mathbb{E}[x|a])_{aa}/(\mathbb{E}[x|a])_a$ for all a . Consider the densities $F_a \hat{l}_x / \int F_a \hat{l}_x dx$ and $F_a / \int F_a dx$, and note that since $\hat{l}(\cdot|a)$ is concave, the first density is likelihood ratio dominated by the second (i.e., the ratio of the first density to the second is decreasing in x). Thus,

$$\frac{(\mathbb{E}[\hat{l}|a])_{aa}}{(\mathbb{E}[\hat{l}|a])_a} = \frac{-\int \hat{l}_x F_{aa} dx}{-\int \hat{l}_x F_a dx} = \int \frac{F_{aa}}{F_a} \frac{-F_a \hat{l}_x}{-\int F_a \hat{l}_x dx} dx \leq \int \frac{F_{aa}}{F_a} \frac{-F_a}{-\int F_a dx} dx = \frac{(\mathbb{E}[x|a])_{aa}}{(\mathbb{E}[x|a])_a},$$

where the first and last equalities follow by integration by parts, and the inequality follows because F_{aa}/F_a is increasing in x by NUC (see Proposition 1(ii)) and by likelihood ratio dominance.³¹

A.7 Proof of Proposition 7

Let $v(x, y) \equiv u(w(x, y))$ for all (x, y) , where w is the contract conditioned on the realization of the two signals. The agent's problem is

$$\max_a \int \int v(x, y) f(x|a) p(y|a) dx dy - c(a).$$

The first-order condition is

$$\int \left(\int v(x, y) f_a(x|a) dx \right) p(y|a) dy + \int \left(\int v(x, y) p_a(y|a) dy \right) f(x|a) dx - c_a(a) = 0,$$

which is equal to (by integration by parts)

$$\begin{aligned} & \int \left(\int v_x(x, y) (-F_a(x|a)) dx \right) p(y|a) dy \\ & + \int \left(\int v_y(x, y) (-P_a(y|a)) dy \right) f(x|a) dx - c_a(a) = 0. \end{aligned}$$

The second derivative can be written as

$$\begin{aligned} & \int \left(\int v_x(x, y) (-F_{aa}(x|a)) dx \right) p(y|a) dy + \int \left(\int v_y(x, y) (-P_{aa}(y|a)) dy \right) f(x|a) dx \\ & + 2 \int \int v_{xy}(x, y) F_a(x|a) P_a(y|a) dx dy - c_{aa}(a), \end{aligned}$$

where the last integral follows by integrating two terms by parts.

Using the first-order condition, we obtain

$$- \int \left(\int v_x(x, y) \left(F_{aa} - \frac{c_{aa}(a)}{c_a(a)} F_a(x|a) \right) dx \right) p(y|a) dy$$

³¹Note that if F_{aa}/F_a is not a constant (which can only happen in the trivial case $F_{aa} \equiv 0$) and if \hat{l} is strictly concave, then this inequality is strict.

$$\begin{aligned}
& - \int \left(\int v_y(x, y) \left(P_{aa}(y|a) - \frac{c_{aa}(a)}{c_a(a)} P_a(y|a) \right) dy \right) f(x|a) dx \\
& + 2 \int \int v_{xy}(x, y) F_a(x|a) P_a(y|a) dx dy.
\end{aligned}$$

We show that this expression is strictly negative under the premises. In particular, note that by [Hölmstrom \(1979\)](#), $v(x, y) = \rho(\lambda + \mu\hat{l} + \mu\hat{\ell})$. Thus, $v_x = \rho'\mu\hat{l}_x$ and $v_y = \rho'\mu\hat{\ell}_y$, which are both strictly positive under strict MLRP. Also, $v_{xy} = \rho''\mu^2\hat{l}_x\hat{\ell}_y$, which is negative if ρ is concave. It follows that the last term is negative by FOSD. Regarding the first term, it is strictly negative since $\rho' > 0$, $\mu > 0$, and

$$\frac{(\mathbb{E}[\hat{l}|a])_{aa}}{(\mathbb{E}[\hat{l}|a])_a} < \frac{c_{aa}(a)}{c_a(a)},$$

and similarly for the second term. Hence, the FOA is valid and we are done.

A.8 Proof of [Proposition 8](#)

We begin with two lemmas. To simplify notation, we set $k \equiv n(x)e^{j(x)H(a)}$.

LEMMA 3. *If F is an exponential family, then*

$$\lim_{x \rightarrow \bar{x}} F_a(x|a)j(x) = \lim_{x \rightarrow \underline{x}} F_a(x|a)j(x) = 0.$$

PROOF. Consider first the case $x \rightarrow \bar{x}$. Note that

$$F = 1 - m(a) \int_x^{\bar{x}} k ds$$

and so

$$F_a = -m(a) \left(h(a) \int_x^{\bar{x}} j(s)k ds + \frac{m'(a)}{m(a)} \int_x^{\bar{x}} k ds \right).$$

But since $m(a) = 1 / \int k dx$,

$$\frac{m'(a)}{m(a)} = - \frac{h(a) \int jk ds}{\int k ds} = -h(a)\bar{j}, \quad (19)$$

where $\bar{j} = \mathbb{E}[j(x)|a]$ and, hence,

$$F_a = -h(a)m(a) \int_x^{\bar{x}} (j(s) - \bar{j})k ds$$

and

$$j(x)F_a = -h(a)m(a) \int_x^{\bar{x}} j(x)(j(s) - \bar{j})k ds.$$

But by MLRP, for x sufficiently large, $j(s) - \bar{j} > 0$ for all $s > x$, and so for x sufficiently large,

$$|j(x)F_a(x|a)| \leq |h(a)m(a)| \left| \int_x^{\bar{x}} j(s)(j(s) - \bar{j})k ds \right|.$$

But since $\sigma^2 = m(a) \int j(s)(j(s) - \bar{j})k ds$ is finite (see [footnote 28](#)), it must be that

$$\lim_{x \rightarrow \bar{x}} \int_x^{\bar{x}} j(s)(j(s) - \bar{j})k ds = 0$$

and so, since $|h(a)m(a)|$ is a constant independent of x , we have $\lim_{x \rightarrow \bar{x}} j(x)F_a(x|a) = 0$. The case $x \rightarrow \underline{x}$ is similar. \square

LEMMA 4. *Let F be an exponential family. Then $(\sigma^2)_a = h(a)\sigma^3\gamma$.*

PROOF. We have

$$\sigma^2 = \frac{\int j^2 k dx}{\int k dx} - \frac{\left(\int j k dx \right)^2}{\left(\int k dx \right)^2}$$

and, hence,

$$\begin{aligned} (\sigma^2)_a &= \left(\frac{\int j^2 k dx}{\int k dx} - \frac{\left(\int j k dx \right)^2}{\left(\int k dx \right)^2} \right)_a \\ &= h(a) \left(\frac{\int j^3 k dx}{\int k dx} - \frac{\int j^2 k dx \int j k dx}{\left(\int k dx \right)^2} - 2 \frac{\int j k dx}{\int k dx} \left(\frac{\int j^2 k dx}{\int k dx} - \frac{\left(\int j k dx \right)^2}{\left(\int k dx \right)^2} \right) \right) \\ &= h(a) (\mathbb{E}[j^3|a] - 3\bar{j}\mathbb{E}[j^2|a] + 2\bar{j}^3) \\ &= h(a) \mathbb{E}[(j - \bar{j})^3|a] \\ &= h(a)\sigma^3\gamma, \end{aligned}$$

where the fourth equality is standard from the third central moment of a distribution. \square

This in hand, note that

$$(\mathbb{E}[jl])_a = \int j f_a dx = \int j \frac{f'_a}{f} dx = \int j \left(h j + \frac{m'}{m} \right) f dx = h(a) \int j(j - \bar{j}) f dx = h(a)\sigma^2,$$

where the third equality uses (13) and the fourth equality uses (19).

Differentiating again and using [Lemma 4](#), we obtain

$$(\mathbb{E}[j])_{aa} = h'(a)\sigma^2 + h(a)(\sigma^2)_a = h'(a)\sigma^2 + h^2(a)\sigma^3\gamma.$$

Hence, $(\mathbb{E}[j])_{aa}/(\mathbb{E}[j])_a = (h'(a)/h(a)) + h(a)\sigma\gamma$ and, thus, [\(14\)](#) holds if and only if [\(15\)](#) holds.

To prove the final assertion, note that we desire that

$$-\gamma =_s -\mathbb{E}[(j - \bar{j})^3|a] = -\int (j^2 - 2\bar{j}j)(j - \bar{j})f \, dx \geq 0.$$

Integrating by parts yields

$$\begin{aligned} -\gamma &=_s -(j^2 - 2\bar{j}j) \int_{\underline{x}}^x (j(s) - \bar{j})f(s) \, ds \Big|_{\underline{x}}^{\bar{x}} + 2 \int (j - \bar{j})j' \int_{\underline{x}}^x (j(s) - \bar{j})f(s) \, ds \, dx \\ &= 2 \int (j - \bar{j})j' \int_{\underline{x}}^x (j(s) - \bar{j})f(s) \, ds \, dx, \end{aligned}$$

where the integrand in the last expression has sign pattern $+/-$ since $\int_{\underline{x}}^x (j(s) - \bar{j})f(s) \, ds \leq 0$ and since $j' > 0$. By a standard integral inequality (see [Beesack 1957](#)), it would thus be enough that j'/f is decreasing and

$$\int (j - \bar{j})f \int_{\underline{x}}^x (j(s) - \bar{j})f(s) \, ds \, dx \geq 0. \quad (20)$$

To see that [\(20\)](#) holds, note that since

$$(j(x) - \bar{j})f(x) = \frac{\partial}{\partial x} \int_{\underline{x}}^x (j(s) - \bar{j})f(s) \, ds,$$

the left-hand side of [\(20\)](#) is equal to

$$\frac{1}{2} \left(\int_{\underline{x}}^x (j(s) - \bar{j})f(s) \, ds \right)^2 \Big|_{\underline{x}}^{\bar{x}} = 0.$$

To see that j'/f is decreasing, note that

$$\left(\frac{j'}{f} \right)_x =_s \frac{j''}{j'} - \frac{f_x}{f} = \frac{j''}{j'} - \frac{n'}{n} - j'(x)H(a) \leq \left(\log \frac{j'}{n} \right)_x =_s \left(\frac{j'}{n} \right)_x \leq 0,$$

where the two sign equalities use $j' > 0$, the second equality uses [\(12\)](#), the first inequality follows since $H(a) \geq 0$, and the second inequality follows by assumption.

REFERENCES

Beesack, Paul R. (1957), “A note on an integral inequality.” *Proceedings of the Americal Mathematical Society*, 8, 875–879. [455, 457, 475]

Brown, Murray, Shin Hwan Chiang, Satyajit Ghosh, and Elmar Wolfstetter (1986), “A new class of sufficient conditions for the first-order approach to the principal-agent problem.” *Economics Letters*, 21, 1–6. [449]

Chade, Hector and Jeroen Swinkels (2019), “Disentangling moral hazard and adverse selection.” Working Paper, Arizona State University. [450]

Conlon, John R. (2009), “Two new conditions supporting the first-order approach to multisignal principal-agent problems.” *Econometrica*, 77, 249–278. [463]

Dewatripont, Mathias, Ian Jewitt, and Jean Tirole (1999), “The economics of career concerns, part I: Comparing information structures.” *Review of Economic Studies*, 66, 183–198. [449, 456]

Hölmstrom, Bengt (1979), “Moral hazard and observability.” *Bell Journal of Economics*, 10, 74–91. [448, 460, 473]

Jewitt, Ian (1988), “Justifying the first-order approach to principal-agent problems.” *Econometrica*, 56, 1177–1190. [446, 449, 450, 453, 460, 461, 462, 463, 464, 466]

Jewitt, Ian, Ohad Kadan, and Jeroen M. Swinkels (2008), “Moral hazard with bounded payments.” *Journal of Economic Theory*, 143, 59–82. [447, 454]

Jung, Jin Yong and Son Ku Kim (2015a), “Information space conditions for the first-order approach in agency problems.” *Journal of Economic Theory*, 160, 243–279. [446, 449, 450, 461, 462, 463, 466]

Jung, Jin Yong and Son Ku Kim (2015b), “Justifying the first-order approach to the principal-agent problem without concavity.” Unpublished Paper, Seoul National University. [449]

Karlin, Samuel (1957), “Pólya type distributions, II.” *Annals of Mathematical Statistics*, 28, 281–308. [470]

Lehmann, Erich and Joseph Romano (2005), *Testing Statistical Hypothesis*, third edition. Springer-Verlag, New York. [464]

Mirrlees, James (1999), “Moral hazard and the theory of unobservable behavior: Part I.” *Review of Economic Studies*, 66, 3–21. [448, 460]

Rogerson, William (1985), “The first-order approach to principal-agents problems.” *Econometrica*, 53, 1357–1367. [448, 450]

Co-editor Thomas Mariotti handled this manuscript.

Manuscript received 1 July, 2017; final version accepted 18 September, 2019; available online 20 September, 2019.