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# Horvitz-Thompson estimator based on theauxiliary variable J. Al-Jararha ${ }^{1}$, Mazen Sulaiman ${ }^{2}$ 


#### Abstract

In this paper, the Horvitz and Thompson (1952) estimator will be modified; so that, the modified estimators will use the availability of the auxiliary variable. Furthermore, the modified estimators are extended to be used in stratified sampling designs. Empirical studies are given for comparison purposes.


Key words: Horvitz-Thompson Estimator, Stratified Sampling Designs, Dual Calibration, GREG Type Estimator.

## 1. Introduction

Consider the finite population $U$ of $N$ units indexed by the set $\{1,2, \cdots, N\}$. For the $i$ th unit, let $y_{i}$ be the value of the interest variable $Y$, and $x_{i}$ be the value of the auxiliary variable $X$. The values of $X$ are known for all the units in the population and correlated with the study variable $Y$. Without loss of generality, we can assume that $x_{i}>0$ for $i=1,2, \ldots, N$. Based on a probability sampling design $p($.$) , draw a random sample s$ from $U$. The first order inclusion probability $\pi_{i}$ is defined by $\pi_{i}=\sum_{s \ni i} p(s)$, and the second inclusion probability $\pi_{i j}$ is defined by $\pi_{i j}=\sum_{s \ni i, j} p(s)$, for $i \neq j$, and $\pi_{i j}=\pi_{i}$ when $i=j$. The probability sampling design $p($.$) is assumed to be a measurable design. The population total for the$ auxiliary variable $X$ is $t_{x}=\sum_{i \in U} x_{i}$.

Horvitz and Thompson (1952) proposed the following estimator

$$
\begin{align*}
\hat{t}_{y \pi} & =\sum_{i \in U} \frac{y_{i}}{\pi_{i}} I_{\{i \in s\}} \\
& =\sum_{i \in s} d_{i} y_{i} \tag{1}
\end{align*}
$$

to estimate the finite population total $t_{y}=\sum_{i \in U} y_{i}$, where $d_{i}=1 / \pi_{i}$ are the sampling design weights and $I_{\{i \in s\}}$ is one if $i \in s$ and zero otherwise. The $\hat{t}_{y \pi}$ is exactly an unbiased estimator for $t_{y}$.

Remark 1.1 The availability and the calibration on the auxiliary variables can be used to increase the precision of estimators. However, the Horvitz and Thompson (1952) estimator does not use the availability of the auxiliary variables. Therefore, the Horvitz and Thompson (1952) estimator will be modified, so that the modified estimators will use the availability of the auxiliary variable.

[^1]Deville and Särndal proposed the following estimator

$$
\begin{equation*}
\hat{t}_{y . d s}=\sum_{i \in U} w_{i} y_{i} I_{\{i \in s\}}=\sum_{i \in s} w_{i} y_{i}, \tag{2}
\end{equation*}
$$

for estimating $t_{y}$, where $w_{i}, i \in s$, are the new sampling design weights that calibrated the sampling design weights $d_{i}$ defined by Eq.(1) based on the calibration on the known population total for the auxiliary variable $X$ and the chi-square distance. The calibrated weights $w_{i}$ are obtained by minimizing the chi-square distance, subject to the side condition. As a result of this, the calibrated weights $w_{i}$ are given by

$$
\begin{equation*}
w_{i}=d_{i}+\frac{t_{x}-\hat{t}_{x \pi}}{\sum_{i \in s} d_{i} q_{i} x_{i}^{2}} d_{i} q_{i} x_{i}, \tag{3}
\end{equation*}
$$

Therefore, Eq. (2) is reduced to

$$
\begin{equation*}
\hat{t}_{y . d s}=\hat{t}_{y \pi}+\hat{\beta}_{d s}\left(t_{x}-\hat{t}_{x \pi}\right) \tag{4}
\end{equation*}
$$

which is a GREG type estimator, where $q_{i}$ 's are known positive weights unrelated to $d_{i}$, $\hat{\beta}_{d s}=\frac{\sum_{i \in s} d_{i} q_{i} x_{i} y_{i}}{\sum_{i \in s} d_{i} q_{i} i_{i}^{2}}$, and $\hat{t}_{x \pi}$ is the Horvitz and Thompson (1952) estimator of $t_{x}$.

Stearns and Singh (2008) summarized the developments by several researchers on the GREG estimators and used the calibration idea to propose three new estimators of the variance of the GREG estimators.

Singh (2013) estimated $t_{y}$ based on the dual calibration approach and his approach is summarized by the following.

Let

$$
\begin{equation*}
\hat{t}_{s i n}=\sum_{i \in s} \omega_{i} x_{i} \tag{5}
\end{equation*}
$$

subject to

$$
\begin{equation*}
\sum_{i \in s} d_{i}=\sum_{i \in s} \omega_{i} \tag{6}
\end{equation*}
$$

and a new constraint $\alpha$ defined by

$$
\begin{equation*}
\alpha=\frac{1}{2} \sum_{i \in s} \frac{\left(\omega_{i}-d_{i}\right)^{2}}{d_{i} q_{i}} \tag{7}
\end{equation*}
$$

As a result of this, the proposed estimator is

$$
\begin{equation*}
\hat{t}_{y . \sin }=\hat{t}_{y \pi}+\hat{\beta}_{\sin }\left(t_{x}-\hat{t}_{x \pi}\right) \tag{8}
\end{equation*}
$$

to estimate the finite population total $t_{y} ; \hat{t}_{y . s i n}$ is a GREG type estimator, where

$$
\begin{equation*}
\hat{\beta}_{s i n}=\frac{S_{x y}}{S_{x x}} \tag{9}
\end{equation*}
$$

where

$$
\begin{equation*}
S_{x y}=\sum_{i \in s} d_{i} q_{i}\left(y_{i}-\frac{\sum_{i \in s} d_{i} q_{i} y_{i}}{\sum_{i \in s} d_{i} q_{i}}\right)\left(x_{i}-\frac{\sum_{i \in s} d_{i} q_{i} x_{i}}{\sum_{i \in s} d_{i} q_{i}}\right) \tag{10}
\end{equation*}
$$

and

$$
\begin{equation*}
S_{x x}=\sum_{i \in s} d_{i} q_{i}\left(x_{i}-\sum_{i \in s} d_{i} q_{i} x_{i} / \sum_{i \in s} d_{i} q_{i}\right)^{2} \tag{11}
\end{equation*}
$$

Two concerns about Eq.(8) are raised by Singh (2013), Remark 1 and Remark 2. Al-Yaseen (2014) showed that the estimator given by Eq.(8) can be obtained theoretically, which clarifies the first concern mentioned in Remark 1. Al-Jararha (2015) made an attempt to suggest a way to use the dual calibration of the design weights in the case of multi-auxiliary variables; in other words, an attempt to give an answer to the second concern in Remark 2.

Sugden and Smith (2002) defined the term strictly linear estimator and proposed two exactly unbiased estimators for the general linear estimates. The possibility of construction an exactly unbiased estimator from a general linear estimator, the constructed unbiased estimator is called a strictly linear estimate. Consider the general linear estimates of $t_{y}$, defined by Godambe (1955), to be of the form

$$
\begin{equation*}
\hat{t}_{y}=\sum_{i \in s} b_{s i} y_{i} \tag{12}
\end{equation*}
$$

The exactly unbiased estimators, based on the Sugden and Smith (2002) approach, from $\hat{t}_{y}$ are defined by

$$
\begin{equation*}
\hat{t}_{y(1)}=\hat{t}_{y}-\sum_{i \in s}\left(B_{i}-1\right) y_{i} / \pi_{i} \tag{13}
\end{equation*}
$$

and

$$
\begin{equation*}
\hat{t}_{y(2)}=\sum_{i \in s} b_{s i} y_{i} / B_{i} \tag{14}
\end{equation*}
$$

for estimating the finite population total $t_{y}$, where

$$
\begin{equation*}
B_{i}=\sum_{s \ni i} p(s) b_{s i} . \tag{15}
\end{equation*}
$$

Recently, different authors have adopted the calibration technique to modify the original weights in stratified sampling designs. In the case of stratified sampling designs, Nidhi, Sisodia, Singh and Singh (2017) proposed a class of calibration estimators for estimating
the population mean. Based on the availability of two auxiliary variables in the study and in the case of stratified sampling designs, Ozgul (2018) proposed a calibration estimator for estimating the population mean.

The Horvitz and Thompson (1952) estimator is well known in survey sampling for estimating the finite population total $t_{y}$. However, this estimator does not use the availability of the auxiliary variable. In order to improve the precision of this estimator, an attempt to generalize this estimator will be given, so that the modified Horvitz and Thompson (1952) estimators will use the availability of the auxiliary variable. Furthermore, our approach can be applied in the case of stratified sampling designs.

## 2. Proposed Approach

Based on the dual calibration approach, the estimator

$$
\begin{equation*}
\hat{t}_{y \cdot n e w}=\sum_{i \in S} \omega_{i} y_{i} \tag{16}
\end{equation*}
$$

is proposed to estimate the finite population total $t_{y}$, by modifying the constraint $\alpha$ of the Singh (2013) approach. In other words, redefine $\alpha$ as

$$
\begin{equation*}
\alpha=\frac{1}{2} \sum_{i \in s} \frac{\left(\omega_{i}-d_{i}\right)^{2}}{d_{i} q_{i}}+\frac{1}{2} \phi^{2} \sum_{i \in s} \frac{\omega_{i}^{2}}{d_{i} q_{i}}, \tag{17}
\end{equation*}
$$

where $\phi$ is a positive quantity.
The problem now is to minimize

$$
\begin{equation*}
\hat{t}_{x}=\sum_{i \in s} \omega_{i} x_{i} \tag{18}
\end{equation*}
$$

with respect to $\omega_{i}$ subject to

$$
\begin{equation*}
\sum_{i \in s} \omega_{i}=\sum_{i \in s} d_{i} \tag{19}
\end{equation*}
$$

and a new constraint $\alpha$ defined by Eq.(17).
The Lagrange function is defined by

$$
\begin{equation*}
l=\sum_{i \in s} \omega_{i} x_{i}-\lambda_{1}\left(\sum_{i \in s} \omega_{i}-\sum_{i \in s} d_{i}\right)-\lambda_{2}\left(\frac{1}{2} \sum_{i \in s} \frac{\left(\omega_{i}-d_{i}\right)^{2}}{d_{i} q_{i}}+\frac{1}{2} \phi^{2} \sum_{i \in s} \frac{\omega_{i}^{2}}{d_{i} q_{i}}-\alpha\right) \tag{20}
\end{equation*}
$$

where $\lambda_{1}$ and $\lambda_{2}$ are the Lagrange multipliers.
Differentiating the right hand side of Eq.(20) with respect to $\omega_{i}$, equate to zero, and
solving for $\omega_{i}$, we have

$$
\begin{equation*}
\omega_{i}=\frac{1}{1+\phi^{2}}\left(d_{i}+\frac{d_{i} q_{i}}{\lambda_{2}}\left(x_{i}-\lambda_{1}\right)\right) \tag{21}
\end{equation*}
$$

Summing both sides of Eq.(21) over all possible sampled values and using Eq.(19), we have

$$
\begin{equation*}
\lambda_{1}=\frac{1}{\sum_{i \in s} d_{i} q_{i}}\left(\sum_{i \in s} d_{i} q_{i} x_{i}-\phi^{2} \lambda_{2} \sum_{i \in s} d i\right) \tag{22}
\end{equation*}
$$

Now, substituting Eq.(21) into Eq.(17), we have

$$
\begin{equation*}
2 \alpha\left(1+\phi^{2}\right) \lambda_{2}^{2}=\phi^{2} \lambda_{2}^{2} \sum_{i \in s} \frac{d_{i}}{q_{i}}+\sum_{i \in s} d_{i} q_{i} x_{i}^{2}-2 \lambda_{1} \sum_{i \in s} d_{i} q_{i} x_{i}+\lambda_{1}^{2} \sum_{i \in s} d_{i} q_{i} \tag{23}
\end{equation*}
$$

Substituting Eq.(22) into Eq.(23), we have

$$
\begin{equation*}
\lambda_{2}= \pm \frac{1}{c} \sqrt{\sum_{i \in s} d_{i} q_{i}\left(x_{i}-\sum_{i \in s} d_{i} q_{i} x_{i} / \sum_{i \in s} d_{i} q_{i}\right)^{2}} \tag{24}
\end{equation*}
$$

where

$$
\begin{equation*}
c=\sqrt{2 \alpha\left(1+\phi^{2}\right)-\phi^{2} \sum_{i \in s} d_{i} / q_{i}-\phi^{4}\left(\sum_{i \in s} d_{i}\right)^{2} / \sum_{i \in s} d_{i} q_{i}} . \tag{25}
\end{equation*}
$$

Ignore the negative sign, where the sign is to be determined by the choice of the sign of $c$. Substituting Eq.(24) into Eq.(22) and using the result in Eq.(21), multiplying $\omega_{i}$ by $y_{i}$ and summing over $i \in s$ we have

$$
\begin{equation*}
\hat{t}_{y . n e w}=\frac{1}{1+\phi^{2}}\left(\sum_{i \in s} d_{i} y_{i}+\phi^{2}\left(\sum_{i \in s} d_{i} / \sum_{i \in s} d_{i} q_{i}\right) \sum_{i \in s} d_{i} q_{i} y_{i}+\delta c\right) \tag{26}
\end{equation*}
$$

where

$$
\begin{equation*}
\delta=S_{x y} / \sqrt{S_{x x}}, \tag{27}
\end{equation*}
$$

where $c, S_{x y}$, and $S_{x y}$ are given by Eq.(25), Eq.(10), and Eq.(11) respectively. With the same reasons adopted by Singh (2013), the best choice of $c$ is

$$
c=\frac{t_{x}-\hat{t}_{x \pi}}{\sqrt{S_{x x}}} \sim N(0,1) ;
$$

therefore,

$$
\begin{equation*}
\hat{t}_{y . n e w}=\lambda \hat{t}_{y . s i n}+(1-\lambda) \widetilde{t}_{y \pi}, \tag{28}
\end{equation*}
$$

where $\lambda=1 /\left(1+\phi^{2}\right), \hat{y}_{\text {y.sin }}$ is defined by Eq.(8), and

$$
\begin{equation*}
\widetilde{t}_{y \pi}=\frac{\hat{t}_{1 \pi}}{\hat{t}_{q \pi}} \hat{t}_{q y \pi} \tag{29}
\end{equation*}
$$

Furthermore, $\hat{t}_{1 \pi}=\sum_{i \in s}\left(1 / \pi_{i}\right), \quad \hat{t}_{q \pi}=\sum_{i \in s}\left(q_{i} / \pi_{i}\right)$, and $\hat{t}_{q y \pi}=\sum_{i \in s}\left(q_{i} y_{i} / \pi_{i}\right)$ be the Horvitz and Thompson (1952) estimators for $N, t_{q}$, and $t_{q y}$, respectively.

Remark 2.1 Since $\lambda \in(0,1)$, Eq. $(28)$ is a convex transformation between $\hat{y}_{y . s i n}$ and $\widetilde{t}_{y \pi}$, defined by Eq.(8) and Eq.(29) respectively. At the same time, as $\phi^{2} \rightarrow \infty \Rightarrow \lambda \rightarrow 0 \Rightarrow$ $\hat{t}_{y . n e w} \rightarrow \widetilde{t}_{y \pi}$; moreover, as $\phi^{2} \rightarrow 0 \Rightarrow \lambda \rightarrow 1 \Rightarrow \hat{t}_{y . n e w} \rightarrow \hat{t}_{y . s i n}$.

The performance of $\hat{t}_{y . n e w}$ will be discussed through simulations from real data set. We will compare $\hat{t}_{y . n e w}, \hat{t}_{y . s i n}$, and $\widetilde{t}_{y \pi}$. Consider the FEV data set which was used by Singh (2013) and downloaded from http://www.amstat.org/publications/jse/datasets/fev.dat.txt. Let $Y$ be the Forced expiratory volume, $t_{y}=1724$; and the auxiliary variable $X$ be the Children height in inches, $t_{x}=39988$. Our aim is to estimate $t_{y}$ by using $\hat{t}_{y . n e w}, \hat{t}_{y . s i n}$, and $\widetilde{t}_{y \pi}$. To achieve our aim, simulate $v=3000$ independent random samples from the FEV data set by using procedure surveyselect of SAS Institute, under SRSWR design. For $q_{i}=x_{i}$ and based on the random samples, estimate $t_{y}$ by $\hat{t}_{y . n e w}, \hat{t}_{y . s i n}$, and $\tilde{t}_{y \pi}$. Furthermore, compute the empirical mean (Em.Mean), relative bias (RB), and empirical relative mean squares error (REMSE) of the estimators $\hat{t}_{y . n e w}, \hat{t}_{y . s i n}$, and $\widetilde{t}_{y \pi}$; where

$$
\begin{align*}
\operatorname{EM.Mean}\left(\hat{t}_{y}^{*}\right) & =\frac{1}{v} \sum_{i=1}^{v}\left(\hat{t}_{y}^{*}\right)_{i}  \tag{30}\\
\operatorname{RB}\left(\hat{t}_{y}^{*}\right) & =\frac{\operatorname{EM.Mean}\left(\hat{t}_{y}^{*}\right)-t_{y}}{t_{y}} \times 100 \%  \tag{31}\\
\operatorname{REMSE}\left(\hat{t}_{y}^{*}\right) & =\frac{\sum_{i=1}^{v}\left(\hat{t}_{y}^{*}-t_{y}\right)^{2}}{\sum_{i=1}^{v}\left(\hat{t}_{y . n e w}-t_{y}\right)^{2}}, \tag{32}
\end{align*}
$$

where EM.Mean $\left(\hat{t}_{y}^{*}\right), \operatorname{RB}\left(\hat{t}_{y}^{*}\right)$, and $\operatorname{REMSE}\left(\hat{t}_{y}^{*}\right)$ are the empirical mean, relative bias, and relative mean squares error of the estimator $\hat{t}_{y}^{*}$. For $n=25,35,45,55,65$, and 75 . The results are summarized in Table (1).

From Table (1), in the sense of REMSE, the estimator $\hat{y}_{y . s i n}$ performs better than $\hat{t}_{y . n e w}$ and $\widetilde{t}_{y \pi}$ for all values of $n$ and for the different values of $\lambda=0,0.25,0.5,0.75$, and 1 . However, $\operatorname{REMSE}\left(\tilde{y}_{y \pi}\right)$ varies from 1 to 6.74 ; at the same time, $\operatorname{REMSE}\left(\widetilde{t}_{y \pi}\right)=6.74$ is attainable for large $n=75$. From this point, concentrations will be focused on the performance of $\widetilde{f}_{y \pi}$ in order to improve the performance of $\hat{t}_{y . n e w}$. The remaining of this article will be focused on the improvement of $\widetilde{t}_{y \pi}$.

Remark 2.2 The Horvitz and Thompson (1952) estimator defined by Eq.(1) is a special case from Eq.(29), namely when $q_{i}=1$ (or a positive constant). Hence, $\tilde{t}_{y \pi}$ is modified $\hat{y}_{y \pi}$ for estimating the finite population total $t_{y}$. Further, $\tilde{t}_{y \pi}$ uses the availability of the auxiliary variable through $q_{i}$ 's.

To the first order and by using Taylor expansion, expanding the right hand side of Eq.(29), we have

$$
\begin{equation*}
\tilde{t}_{y \pi} \simeq \frac{t_{1}}{t_{q}} t_{q y}+\frac{t_{q y}}{t_{q}}\left(\hat{t}_{1 \pi}-t_{1}\right)+\frac{t_{1}}{t_{q}}\left(\hat{t}_{q y \pi}-t_{q y}\right)-\frac{t_{1} t_{q y}}{t_{q}^{2}}\left(\hat{t}_{q \pi}-t_{q}\right) \tag{33}
\end{equation*}
$$

Therefore, the bias of $\widetilde{t}_{y \pi}$ is given by

$$
\begin{equation*}
\operatorname{Bias}\left(\widetilde{t}_{y \pi}\right)=t_{y}-\frac{t_{1}}{t_{q}} t_{q y} . \tag{34}
\end{equation*}
$$

Remark 2.3 It is clear from Eq.(34) that $\tilde{t}_{y \pi}$ is a biased estimator for estimating the finite population total $t_{y}$. However, $\tilde{t}_{y \pi}$ is a strictly linear estimator; therefore, we can deduce two exactly unbiased estimators from $\tilde{y}_{y \pi}$ based on Sugden and Smith (2002).

From Eq.(29), rewrite $\tilde{t}_{y \pi}$ as

$$
\begin{equation*}
\tilde{t}_{y \pi}=\sum_{i \in s} b_{s i} y_{i} \tag{35}
\end{equation*}
$$

where

$$
\begin{equation*}
b_{s i}=\frac{q_{i} / \pi_{i}}{\sum_{i \in s}\left(q_{i} / \pi_{i}\right) / \sum_{i \in s}\left(1 / \pi_{i}\right)} . \tag{36}
\end{equation*}
$$

From Eq.(15), recall the definition of $B_{i}$,

$$
\begin{align*}
B_{i} & =\sum_{s \ni i} p(s) b_{s i} \\
& =\frac{q_{i}}{\pi_{i}} \sum_{s \ni i}\left[p(s) \frac{\sum_{i \in s}\left(1 / \pi_{i}\right)}{\sum_{i \in s}\left(q_{i} / \pi_{i}\right)}\right] \tag{37}
\end{align*}
$$

Based on Sugden and Smith (2002) approach, the two exactly unbiased estimators deduced from $\tilde{t}_{y \pi}$ for $t_{y}$ are

$$
\begin{equation*}
\tilde{t}_{y \pi(1)}=\tilde{t}_{y \pi}-\sum_{i \in s}\left(B_{i}-1\right) y_{i} / \pi_{i} \tag{38}
\end{equation*}
$$

and

$$
\begin{equation*}
\tilde{t}_{y \pi(2)}=\sum_{i \in s} \frac{b_{s i}}{B_{i}} y_{i} \tag{39}
\end{equation*}
$$

where $b_{s i}$ and $B_{i}$ are defined by Eq.(36) and Eq.(37) respectively.

Remark 2.4 Eq.(35) shows that $\widetilde{t}_{y \pi}$ is a general linear estimator of $t_{y}$. Furthermore, $\widetilde{t}_{y \pi(1)}$ and $\tilde{t}_{y \pi(2)}$ are two exactly unbiased estimators for $t_{y}$ deduced from $\tilde{t}_{y \pi}$; therefore, $\tilde{t}_{y \pi}$ is a strictly linear estimator based on the Sugden and Smith (2002) definition. Hence, the estimators $\widetilde{t}_{y \pi(1)}$ and $\widetilde{t}_{y \pi(2)}$ are generalization of the Horvitz and Thompson (1952) estimator and use the availability of the auxiliary variable.

Since $\tilde{t}_{y \pi(1)}$ and $\widetilde{t}_{y \pi(2)}$ are exactly unbiased estimators for $t_{y}$, the infinite number of exactly unbiased estimators is defined by

$$
\begin{equation*}
\tilde{t}_{y \pi}=\omega \tilde{t}_{y \pi(1)}+(1-\omega) \tilde{t}_{y \pi(2)}, \quad \text { for } \quad 0 \leq \omega \leq 1 . \tag{40}
\end{equation*}
$$

Remark 2.5 The estimator $\tilde{t}_{y \pi}$ is a convex transformation and an unbiased estimator for estimating the population total $t_{y}$.

### 2.1. Modified Horvitz-Thompson and Stratified Sampling Designs

The finite population $U$ of size $N$ is divided into $L$ non-overlapping strata $U_{1}, U_{2}, \ldots, U_{L}$; $U=\bigcup_{h=1}^{L} U_{h}$. The population total for the $h^{t h}$ stratum is $t_{y h}=\sum_{i \in U_{h}} y_{i}$. Furthermore, the $h^{t h}$ stratum is of size $N_{h}$ and $N=\sum_{h=1}^{L} N_{h}$. The population total $t_{y}$ is redefined as

$$
\begin{equation*}
t_{y}=\sum_{h=1}^{L} t_{y h} \tag{41}
\end{equation*}
$$

For the $h^{t h}$ stratum and based on a measurable sampling design $p_{h}$ (.), draw a random sample $s_{h}$ of size $n_{h}$ from $U_{h}$. Assume $\bar{x}_{h}=\sum_{i \in U_{h}} x_{i} / N_{h}$ is known for $h=1,2, \ldots, L$. Apply $\widetilde{t}_{y \pi(1)}$ and $\widetilde{t}_{y \pi(2)}$ to the $h^{t h}$ stratum. In other words, estimate $t_{y h}$ by

$$
\begin{equation*}
\tilde{t}_{y \pi(1) . h}=\tilde{t}_{y \pi . s t}-\sum_{i \in s_{h}}\left(B_{i}-1\right) y_{i} / \pi_{i}, \tag{42}
\end{equation*}
$$

or by

$$
\begin{equation*}
\tilde{t}_{y \pi(2) \cdot h}=\sum_{i \in s_{h}} \frac{b_{s_{h i}}}{B_{i}} y_{i} . \tag{43}
\end{equation*}
$$

In this case, $\tilde{t}_{y \pi(1) . h}$ and $\widetilde{t}_{y \pi(2) . h}$ are exactly two unbiased estimators for $t_{y h}$, where

$$
\begin{equation*}
\widetilde{t}_{y \pi . s t}=\sum_{h=1}^{L} \frac{\hat{t}_{1 \pi . h}}{\hat{t}_{q \pi . h}} \hat{t}_{q y \pi . h} ; \tag{44}
\end{equation*}
$$

$\hat{t}_{1 \pi . h}=\sum_{i \in s_{h}}\left(1 / \pi_{i}\right), \quad \hat{t}_{q \pi . h}=\sum_{i \in s_{h}}\left(q_{i} / \pi_{i}\right)$, and $\hat{t}_{q y \pi . h}=\sum_{i \in s_{h}}\left(q_{i} y_{i} / \pi_{i}\right)$ be the Horvitz and Thompson (1952) estimators for $N_{h}, t_{q . h}$, and $t_{q y . h}$, respectively.

From Eq.(41), estimate $t_{y}$ by

$$
\begin{equation*}
\tilde{t}_{y \pi(1) \cdot s t}=\sum_{h=1}^{L} \tilde{t}_{y \pi(1) \cdot h}, \tag{45}
\end{equation*}
$$

or by

$$
\begin{equation*}
\tilde{t}_{y h \pi(2) \cdot s t}=\sum_{h=1}^{L} \tilde{t}_{y \pi(2) \cdot h} \tag{46}
\end{equation*}
$$

where $\tilde{t}_{y \pi(1) . h}$ and $\widetilde{t}_{y \pi(2) . h}$ are defined in Eq.(42) and Eq.(43), respectively.
Remark 2.6 The two estimators $\tilde{t}_{y \pi(1) . h}$ and $\tilde{t}_{y \pi(2) . h}$ are two exactly unbiased estimators for $t_{y h}$. Based on this idea, the two estimators $\widetilde{t}_{y \pi(1) . s t}$ and $\widetilde{t}_{y \pi(2) . s t}$ are exactly unbiased estimators for $t_{y}$; therefore, the accumulation of bias across strata is avoided.

### 2.2. Special Cases

The exactly unbiased estimators $\widetilde{t}_{y \pi(1)}$ and $\widetilde{t}_{y \pi(2)}$ are given by Eq.(38) and Eq.(39) respectively, deduced from the modified HT estimator $\widetilde{t}_{y \pi}$, depending on the weight $q_{i}$. Therefore, $\widetilde{t}_{y \pi(1)}$ and $\widetilde{t}_{y \pi(2)}$ can use the availability of the auxiliary variables through $q_{i}$. In this section, different special cases are considered.

As we mentioned earlier, $\tilde{t}_{y \pi}$ reduces to $\hat{y}_{y \pi}$, the ordinary Horvitz and Thompson (1952) estimator, when $q_{i}$ 's are one or positive constant. Furthermore, from Eq.(36), $b_{s i}=1 / \pi_{i}$ and from Eq.(37), $B_{i}=1$. Therefore,

$$
\begin{equation*}
\tilde{t}_{y \pi(1)}=\tilde{t}_{y \pi(2)}=\hat{t}_{y \pi}, \tag{47}
\end{equation*}
$$

i.e. $\widetilde{t}_{y \pi(1)}$ and $\widetilde{t}_{y \pi(2)}$ are identical; in other words, $\widetilde{t}_{y \pi}$ is exactly an unbiased estimator for $t_{y}$. In this case, the Sugden and Smith (2002) approach gives exactly one unbiased estimator for estimating $t_{y}$.

Draw a random sample $s$ of size $n$ from the population $U$ of size $N$ by using the simple random sample without replacement (SRSWR) design. Under SRSWR design, $p(s)=1 /\binom{N}{n}$ and $\pi_{i}=n / N$. Consider the following two cases:
a. $q_{i}=\pi_{i}$.

In this case, $b_{s i}=\frac{N}{n}$ and $B_{i}=1$. Therefore,

$$
\begin{equation*}
\hat{t}_{y \pi}=\widetilde{t}_{y \pi(1)}=\widetilde{t}_{y \pi(2)}=N \bar{y}_{s}, \tag{48}
\end{equation*}
$$

which is well-known estimator for estimating $t_{y}$, where $\bar{y}_{s}=\sum_{i=1}^{n} y_{i} / n$. In this case, the two exactly unbiased estimators based on Sugden and Smith (2002) are reduced to one unbiased estimator, i.e. the Sugden and Smith (2002) approach produces exactly only one unbiased estimator.
b. $q_{i}=x_{i}, x_{i}>0$.

In this case, $b_{s i}=N x_{i} / \sum_{j \in s} x_{j}$ and $B_{i}=N x_{i} p(s) \sum_{s \ni i}\left(\sum_{j \in s} x_{j}\right)^{-1}$. Therefore,

$$
\begin{equation*}
\tilde{t}_{y \pi(1)}=N\left[\frac{\sum_{i \in s} x_{i} y_{i}}{\sum_{i \in s} x_{i}}+\bar{y}_{s}-\frac{1}{\binom{N-1}{n-1}} \sum_{i \in s}\left\{\sum_{s \ni i}\left(\sum_{j \in s} x_{j}\right)^{-1}\right\} x_{i} y_{i}\right], \tag{49}
\end{equation*}
$$

and

$$
\begin{align*}
\tilde{t}_{y \pi(2)} & =\binom{N}{n} \sum_{i \in s}\left[\frac{y_{i}}{\sum_{s \ni i}\left(\sum_{j \in s} x_{j}\right)^{-1}}\right] / \sum_{j \in s} x_{j}  \tag{50}\\
& =\hat{T}_{R(2)} \tag{51}
\end{align*}
$$

where $\hat{T}_{R(2)}$ is an estimate of $t_{y}$ defined by Sugden and Smith (2002), Eq.(4.5).

## 3. Empirical Studies

Sugden and Smith (2002) considered the ratio estimator

$$
\begin{equation*}
\hat{T}_{R}=t_{x} \frac{\hat{t}_{y \pi}}{\hat{t}_{x \pi}} \tag{52}
\end{equation*}
$$

as a general linear estimator for the population total $t_{y} . \hat{T}_{R}$ is asymptotically an unbiased estimator of $t_{y}$. Since $\hat{T}_{R}$ produces two exactly unbiased estimators of $t_{y}, \hat{T}_{R}$ is a strictly linear estimator for $t_{y}$. Under SRSWR, $B_{R i}=t_{x} \sum_{s \ni i}\left(\sum_{j \in s} x_{j}\right)^{-1} /\binom{N}{n}$. In this case, the exactly unbiased estimators are

$$
\begin{equation*}
\hat{T}_{R(1)}=\hat{T}_{R}-\frac{N}{n} \sum_{i \in s}\left(B_{R i}-1\right) y_{i}, \tag{53}
\end{equation*}
$$

and $\widetilde{T}_{R(2)}$, defined by Eq.(51).
Assume all the values of the auxiliary variable are available in the study; under SRSWR design, the estimators $\hat{t}_{y \pi}, \tilde{t}_{y \pi(1)}, \tilde{t}_{y \pi(2)}, \hat{T}_{R(2)}, \hat{T}_{R}$, and $\hat{T}_{R(1)}$ defined by Eq.(48), (49), (50), (51), (52), (53) respectively, will be used in the empirical studies.

Consider the data set given by Example(4.9), Page 139, Lohr (2010). In this example, $X$ is the photo counts of dead trees and $Y$ is the field counts of dead trees; $N=25, t_{x}=$ 265 , and $t_{y}=289$. From this data set, under SRSWR, draw all random samples of sizes $n=2,3,4$. The computations are implemented by using a SAS program written under the iml procedure. The number of all random samples is $m=300,2300,12650$ for $n=2,3,4$ respectively. The relative efficiency of the ratio family is defined by $\operatorname{MSE}\left(\hat{T}_{R(i)}\right) / \operatorname{MSE}\left(\hat{T}_{R}\right)$ and relative efficiency of the Horvitz and Thompson (1952) family is defined by $\operatorname{MSE}\left(\widetilde{t}_{y \pi(i)}\right) / \operatorname{MSE}\left(\hat{t}_{y \pi}\right)$ for $i=1,2$. The results are given in Table(2).

In the case of a stratification, consider the data set cars93 from Scheaffer, Menden-
hall and Ott (2006). The data set cars93 consists of different variables; for our study, let $X:=M P G C I T Y, Y:=M P G H I G H$, and the stratifications based on the variable "typecode". The cars93 data set is summarized by the following table.

| $h^{\text {th }}$ stratum | 1 | 2 | 3 | 4 | 5 | 6 | total |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $N_{h}$ | 20 | 16 | 22 | 11 | 14 | 9 | $N=92$ |
| $t_{x h}$ | 598 | 363 | 430 | 202 | 305 | 153 | $t_{x}=2051$ |
| $t_{y h}$ | 712 | 478 | 588 | 294 | 403 | 197 | $t_{y}=2672$ |

For the $h^{\text {th }}$ stratum, $h=1, \ldots, 6$, the results are given in Tables (3),...,(8) respectively. Based on the stratified sampling design, the population total $t_{y}$ is estimated by using the estimators $\hat{t}_{y \pi}, \widetilde{t}_{y \pi(1)}, \widetilde{t}_{y \pi(2)}, \hat{T}_{R(2)}, \hat{T}_{R}$, and $\hat{T}_{R(1)}$; for $n=12,18,24$. The results are given in Table (9). At the same time, Table (9) is computed from Tables (3),...,(8).

## 4. Concluding Remarks

In this paper, the Horvitz and Thompson (1952) estimator is modified so that the modified estimators can use the availability of the auxiliary variable in the study. Based on the Sugden and Smith (2002) approach, two exactly unbiased estimators for estimating the population total $t_{y}$ are deduced from the modified estimator. Furthermore, the exactly two unbiased estimators can be used in stratified sampling designs.

From Table(2), the deduced estimators $\tilde{t}_{y \pi(1)}$ and $\widetilde{t}_{y \pi(2)}$ are exactly unbiased estimators for estimating $t_{y}$ and perform better than the original Horvitz and Thompson (1952) estimator $\hat{t}_{y \pi}$, in the sense of relative efficiency. Moreover, Table(2) supports the same conclusion mentioned by Sugden and Smith (2002), i.e. the estimators $\hat{T}_{R(1)}$ and $\hat{T}_{R(2)}$ are exactly unbiased estimators and perform better than the original ratio estimator $\hat{T}_{R}$, in the sense of relative efficiency.

Based on the Sugden and Smith (2002) approach, the two exactly unbiased estimators based on their families for estimating $t_{y}$ perform better than the original estimators even if the original estimators are asymptotically unbiased or unbiased estimators. Furthermore, the estimators deduced from Horvitz and Thompson (1952) perform better than the deduced estimators from the ratio estimator. Small sample sizes are usually selected in the case of stratified sampling design; moreover, the deduced estimators can be applied to every stratum and aggregated together to estimate the population total.

For $h=1, \ldots, 6$ the results are given by Tables (3),...,(8), respectively. Table (9) is computed from Tables (3),..,(8), and shows that $\widetilde{t}_{y \pi(1)}, \widetilde{t}_{y \pi(2)}, \hat{T}_{R(1)}$, and $\hat{T}_{R(2)}$ are exactly unbiased estimators for $t_{y}$. Furthermore, the bias of the ratio estimator $\hat{T}_{R}$, is negligible (asymptotically unbiased) and performs better than $\hat{t}_{y \pi}$ (exactly unbiased) in the sense of relative efficiency. $\hat{T}_{R(1)}$ and $\hat{T}_{R(2)}$ estimators perform better than the ratio estimator $\hat{T}_{R}$ for all $n=12,18,24$. At the same time, the relative efficiency of $\hat{T}_{R(1)}$ and $\hat{T}_{R(2)}$ are approximately the same for $n=12,18,24$. In the case of the Horvtiz-Thompson family, the deduced estimators $\widetilde{t}_{y \pi(1)}$ and $\widetilde{t}_{y \pi(2)}$ perform significantly better than the original estimator $\hat{t}_{y \pi}$, in the sense of relative efficiency. Furthermore, the estimators $\widetilde{t}_{y \pi(1)}$ and $\widetilde{t}_{y \pi(2)}$ deliver approximately the same performance, for all $n=12,18,24$.

From Eq.(51), we have $\tilde{t}_{y \pi(2)}=\hat{T}_{R(2)}$; therefore, the ratio family and the Horvitz-Thompson family can be compared. Tables (2), (3),..., (9) show that

$$
\frac{\operatorname{MSE}\left(\tilde{t}_{y \pi(1)}\right)}{\operatorname{MSE}\left(\tilde{t}_{y \pi(2)}\right)} \cong \frac{\operatorname{MSE}\left(\hat{T}_{R(1)}\right)}{\operatorname{MSE}\left(\hat{T}_{R(2)}\right)},
$$

for all values of $n$. Therefore, the deduced estimators $\tilde{t}_{y \pi(1)}$ and $\tilde{t}_{y \pi(2)}$ from the HorvitzThompson family and $\hat{T}_{R(1)}$ and $\hat{T}_{R(2)}$ from the ratio family perform better than the original families even though the original families are unbiased or asymptotically unbiased estimators.

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|  |  | $\hat{t}_{y . \sin }$ | $\tilde{t}_{y} \pi$ | $\hat{t}_{\text {y.new }}$ |  |  | $\hat{t}_{y . \sin }$ | $\widehat{t}_{y} \pi$ | $\hat{t}_{\text {y.new }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & n=25 \\ & \lambda \rightarrow 0 \end{aligned}$ | Em.Mean | 1720.34 | 1770.59 | 1770.59 | $n=55$ | Em.Mean | 1722.70 | 1768.77 | 1768.77 |
|  | RB | -0.24 | 2.68 | 2.68 | $\lambda \rightarrow 0$ | RB | -0.10 | 2.57 | 2.57 |
|  | REMSE | 0.21 | 1.00 | 1.00 |  | REMSE | 0.17 | 1.00 | 1.00 |
| $\begin{gathered} n=25 \\ \lambda=0.25 \end{gathered}$ | Em.Mean | 1720.34 | 1770.59 | 1758.03 | $n=55$ | Em.Mean | 1722.70 | 1768.77 | 1757.25 |
|  | RB | -0.24 | 2.68 | 1.95 | $\lambda=0.25$ | RB | -0.10 | 2.57 | 1.90 |
|  | REMSE | 0.32 | 1.54 | 1.00 |  | REMSE | 0.27 | 1.58 | 1.00 |
| $\begin{gathered} n=25 \\ \lambda=0.50 \end{gathered}$ | Em.Mean | 1720.34 | 1770.59 | 1745.47 | $n=55$ | Em.Mean | 1722.70 | 1768.77 | 1745.73 |
|  | RB | -0.24 | 2.68 | 1.22 | $\lambda=0.50$ | RB | -0.10 | 2.57 | 1.23 |
|  | REMSE | 0.52 | 2.51 | 1.00 |  | REMSE | 0.45 | 2.68 | 1.00 |
| $\begin{gathered} \hline n=25 \\ \lambda=0.75 \end{gathered}$ | Em.Mean | 1720.34 | 1770.59 | 1732.90 | $n=55$ | Em.Mean | 1722.70 | 1768.77 | 1734.21 |
|  | RB | -0.24 | 2.68 | 0.49 | $\lambda=0.75$ | RB | -0.10 | 2.57 | 0.57 |
|  | REMSE | 0.83 | 3.98 | 1.00 |  | REMSE | 0.78 | 4.58 | 1.00 |
| $\begin{aligned} & n=25 \\ & \lambda \rightarrow 1 \end{aligned}$ | Em.Mean | 1720.34 | 1770.59 | 1720.34 | $n=55$ | Em.Mean | 1722.70 | 1768.77 | 1722.70 |
|  | RB | -0.24 | 2.68 | -0.24 | $\lambda \rightarrow 1$ | RB | -0.10 | 2.57 | -0.10 |
|  | REMSE | 1.00 | 4.81 | 1.00 |  | REMSE | 1.00 | 5.89 | 1.00 |
| $\begin{aligned} & n=35 \\ & \lambda \rightarrow 0 \end{aligned}$ | Em.Mean | 1722.08 | 1770.28 | 1770.28 | $n=65$ | Em.Mean | 1722.93 | 1768.89 | 1768.89 |
|  | RB | -0.14 | 2.66 | 2.66 | $\lambda \rightarrow 0$ | RB | -0.09 | 2.58 | 2.58 |
|  | REMSE | 0.19 | 1.00 | 1.00 |  | REMSE | 0.16 | 1.00 | 1.00 |
| $\begin{gathered} n=35 \\ \lambda=0.25 \end{gathered}$ | Em.Mean | 1722.08 | 1770.28 | 1758.23 | $n=65$ | Em.Mean | 1722.93 | 1768.89 | 1757.40 |
|  | RB | -0.14 | 2.66 | 1.96 | $\lambda=0.25$ | RB | -0.09 | 2.58 | 1.91 |
|  | REMSE | 0.30 | 1.55 | 1.00 |  | REMSE | 0.26 | 1.57 | 1.00 |
| $\begin{gathered} n=35 \\ \lambda=0.50 \end{gathered}$ | Em.Mean | 1722.08 | 1770.28 | 1746.18 | $n=65$ | Em.Mean | 1722.93 | 1768.89 | 1745.91 |
|  | RB | -0.14 | 2.66 | 1.26 | $\lambda=0.50$ | RB | -0.09 | 2.58 | 1.24 |
|  | REMSE | 0.49 | 2.56 | 1.00 |  | REMSE | 0.44 | 2.67 | 1.00 |
| $\begin{gathered} n=35 \\ \lambda=0.75 \end{gathered}$ | Em.Mean | 1722.08 | 1770.28 | 1734.13 | $n=65$ | Em.Mean | 1722.93 | 1768.89 | 1734.42 |
|  | RB | -0.14 | 2.66 | 0.56 | $\lambda=0.75$ | RB | -0.09 | 2.58 | 0.58 |
|  | REMSE | 0.80 | 4.17 | 1.00 |  | REMSE | 0.76 | 4.59 | 1.00 |
| $\begin{aligned} & n=35 \\ & \lambda \rightarrow 1 \end{aligned}$ | Em.Mean | 1722.08 | 1770.28 | 1722.08 | $n=65$ | Em.Mean | 1722.93 | 1768.89 | 1722.93 |
|  | RB | -0.14 | 2.66 | -0.14 | $\lambda \rightarrow 1$ | RB | -0.09 | 2.58 | -0.09 |
|  | REMSE | 1.00 | 5.20 | 1.00 |  | REMSE | 1.00 | 6.07 | 1.00 |
| $\begin{aligned} & n=45 \\ & \lambda \rightarrow 0 \end{aligned}$ | Em.Mean | 1721.84 | 1769.24 | 1769.24 | $n=75$ | Em.Mean | 1723.25 | 1770.39 | 1770.39 |
|  | RB | -0.15 | 2.60 | 2.60 | $\lambda \rightarrow 0$ | RB | -0.07 | 2.66 | 2.66 |
|  | REMSE | 0.19 | 1.00 | 1.00 |  | REMSE | 0.15 | 1.00 | 1.00 |
| $\begin{gathered} \begin{array}{c} n=45 \\ \lambda=0.25 \end{array} \end{gathered}$ | Em.Mean | 1721.84 | 1769.24 | 1757.39 | $n=75$ | Em.Mean | 1723.25 | 1770.39 | 1758.61 |
|  | RB | -0.15 | 2.60 | 1.91 | $\lambda=0.25$ | RB | -0.07 | 2.66 | 1.98 |
|  | REMSE | 0.29 | 1.55 | 1.00 |  | REMSE | 0.25 | 1.59 | 1.00 |
| $\begin{gathered} n=45 \\ \lambda=0.50 \end{gathered}$ | Em.Mean | 1721.84 | 1769.24 | 1745.54 | $n=75$ | Em.Mean | 1723.25 | 1770.39 | 1746.82 |
|  | RB | -0.15 | 2.60 | 1.22 | $\lambda=0.50$ | RB | -0.07 | 2.66 | 1.30 |
|  | REMSE | 0.48 | 2.57 | 1.00 |  | REMSE | 0.42 | 2.73 | 1.00 |
| $\begin{gathered} n=45 \\ \lambda=0.75 \end{gathered}$ | Em.Mean | 1721.84 | 1769.24 | 1733.69 | $n=75$ | Em.Mean | 1723.25 | 1770.39 | 1735.04 |
|  | RB | -0.15 | 2.60 | 0.54 | $\lambda=0.75$ | RB | -0.07 | 2.66 | 0.61 |
|  | REMSE | 0.78 | 4.22 | 1.00 |  | REMSE | 0.74 | 4.81 | 1.00 |
| $\begin{aligned} & n=45 \\ & \lambda \rightarrow 1 \end{aligned}$ | Em.Mean | 1721.84 | 1769.24 | 1721.84 | $n=75$ | Em.Mean | 1723.25 | 1770.39 | 1723.25 |
|  | RB | -0.15 | 2.60 | -0.15 | $\lambda \rightarrow 1$ | RB | -0.07 | 2.66 | -0.07 |
|  | REMSE | 1.00 | 5.39 | 1.00 |  | REMSE | 1.00 | 6.47 | 1.00 |

Table 1: Computations are based on Eq.(28). The REMSE's are computed by using Eq. (32) for $\hat{t}_{y}^{*}=\hat{t}_{y . \sin }, \widetilde{t}_{y \pi}$, and $\hat{t}_{y . n e w}$.

| Estimator | $n=2$ |  | $n=3$ |  | $n=4$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | ty | $S_{y}^{2}$ | ty | $S_{y}^{2}$ | ty | $S_{y}^{2}$ |
| $\hat{T}_{R}$ | 294.3058 | $\begin{array}{r} 2545.752 \\ (\mathbf{2 5 7 3 . 9 0 4}) \end{array}$ | 292.291 | $\begin{array}{r} 1549.1841 \\ (\mathbf{1 5 6 0 . 0 2 1 3}) \end{array}$ | $\begin{aligned} & 291.322 \\ & (2.322) \end{aligned}$ | $\begin{array}{r} 1081.5572 \\ (\mathbf{1 0 8 6 . 9 4 8 8}) \end{array}$ |
| $\hat{T}_{R(1)}$ | 289 | 1684.9349 | 289 | 1111.1305 | 289 | 834.9348 |
| $\hat{T}_{R(2)}$ | 289 | 1650.5674 | 289 | 1087.7975 | 289 | 821.8695 |
| $\hat{t}_{y} \pi$ | 289 | 2613.375 | 289 | 1666.5 | 289 | 1193.0625 |
| ${ }^{t_{y}} \pi$ (1) | $289$ | 1689.2317 | 289 | 1115.3438 | 289 | 845.6788 |
| ${ }^{t} y \pi(2)$ | 289 | 1650.5674 | 289 | 1087.7975 | 289 | 821.8695 |
| $\hat{T}_{R}$ Family | MSE <br> MSE <br> MSE <br> MSE <br> MSE <br> MSE | $=0.6546$ <br> $=0.6413$ <br> $=1.0208$ | MSE <br> MS <br> MSE <br> MS <br> MSE <br> MSE | $\begin{aligned} & =0.7123 \\ & =0.6973 \\ & =1.0215 \end{aligned}$ | MSE <br> MSE <br> MSE <br> MSE <br> MSE <br> MSE | $\begin{aligned} & =0.7682 \\ & =0.7561 \\ & =1.0159 \end{aligned}$ |
| Horvtiz-Thopson family | $M S E($ <br> $M S E$ <br> $M S E($ <br> $M S E$ <br> $M S E($ | $\begin{aligned} & =0.6464 \\ & =0.6316 \\ & =1.0234 \end{aligned}$ | $\begin{gathered} M S E \\ \hline M S t \\ M S E \\ \hline M S E \\ M S E \\ \hline M S E \end{gathered}$ | $\begin{aligned} & =0.6693 \\ & =0.6527 \\ & =1.0253 \end{aligned}$ | MSE <br> $M S E$ <br> $M S E$ <br> $M S E$ <br> $M S E$ <br> $M S E$ | $\begin{aligned} & =0.7088 \\ & =0.6889 \\ & =1.029 \end{aligned}$ |

Table 2: Empirical results based on real data set. For the estimator $\hat{T}_{R}$ : the number between brackets under the mean is the bias and the bold one under the variance is the MSE of $\hat{T}_{R}$.

| Estimator | $n_{h}=2$ |  | $n_{h}=3$ |  | $n_{h}=4$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $t_{\text {yh }}$ | $S_{\text {yh }}^{2}$ | $t_{y h}$ | $S_{\text {yh }}^{2}$ | $t_{y h}$ | $S_{\text {yh }}^{2}$ |
| $\hat{T}_{R}$ | 715.7886 | 1533.6014 | 714.4398 | 975.7520 | 713.7416 | 691.1576 |
|  | (3.7886) | (1547.9549) | (2.4398) | ( 981.7046 ) | ( 1.741556 ) | (694.1906 ) |
| $\hat{T}_{R(1)}$ | 712 | 1363.2611 | 712 | 522.6314 | 712 | 358.48553 |
| $\hat{T}_{R(2)}$ | 712 | 1405.6602 | 712 | 523.4136 | 712 | 353.7434 |
| $\hat{t}_{y \pi}$ <br> $\tilde{t}_{y \pi(1)}$ <br> $t_{y \pi(2)}$ | 712 | 5900.2105 | 712 | 3714.9474 | 712 | 2622.3158 |
|  | 712 | 1483.1003 | 712 | 578.5657 | 712 | 391.3314 |
|  | 712 | 1405.6602 | 712 | 523.4136 | 712 | 353.7434 |
| $\hat{T}_{R}$ Family | $\frac{M S E\left(\hat{T}_{R(1)}\right)}{M S\left(T_{R}\right)}=0.8807$$\frac{M S E\left(T_{R(2)}\right)}{M S E\left(\hat{I}_{R}\right)}=0.9081$$\frac{M S E\left(\hat{T}_{R(1)}\right)}{M S E\left(\hat{T}_{R(2)}\right)}=0.9698$ |  | $\begin{aligned} & \hline \frac{\operatorname{MSE}\left(\hat{T}_{R(1)}\right)}{M S\left(T_{R}\right)}=0.5324 \\ & \frac{M S E\left(T_{R(2)}\right)}{M S E\left(\hat{T}_{R}\right)}=0.5332 \\ & \frac{M S E\left(T_{R(1)}\right)}{M S E\left(\hat{T}_{R(2)}\right)}=0.9985 \end{aligned}$ |  | $\begin{aligned} & \hline \hline \frac{M S E\left(\hat{T}_{R(1)}\right)}{M S E}=0.5164 \\ & \frac{M S E\left(\bar{T}_{R}\right)}{}=15\left(\hat{T}_{2}\right) \\ & M S E=0.5096 \\ & \frac{M S E\left(T_{R(1)}\right)}{M S E\left(\hat{T}_{R(2)}\right)}=1.0134 \end{aligned}$ |  |
| Hort-Thom <br> family | $\frac{M S E\left(t_{y n}\right.}{M S\left(t_{1}\right.}$ $\frac{M S E\left(t_{y}\right.}{M S E\left(t_{1}\right)}$ $\frac{M S E}{M S E\left(t_{y}\right)}$ | $\begin{aligned} & \text { ) }=0.2514 \\ & =0.2382 \\ & )=1.0551 \end{aligned}$ | $\begin{aligned} & \frac{M S E\left(t_{y \pi(1)}\right)}{M S E\left(t_{1}\right)} \\ & \frac{M S E\left(t_{y \pi \pi}\right)}{M S E(t))} \\ & \left.\frac{M S E\left(t_{y \pi \pi}\right)}{M S E\left(t_{y \pi(1)}\right)}\right) \end{aligned}$ | $\left\{\begin{array}{l} =0.1557 \\ =0.1409 \\ =1.10537 \end{array}\right.$ |  | $\begin{aligned} & =0.1492 \\ & =0.1349 \\ & =1.1063 \end{aligned}$ |

Table 3: Empirical results from cars93 for Stratum (1): When typecode=1

| Estimator | $n_{h}=2$ | $n_{h}=3$ | $n_{h}=4$ |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $t_{y h} \quad S_{y h}^{2}$ | $t_{y h} \quad S_{y h}^{2}$ | $t_{y h}$ | $S_{y h}^{2}$ |
| $\hat{T}_{R}$ | $478.0681 \quad 306.3392$ | 478.0383188 .7059 | 478.0252 | 130.3291 |
|  | (0.0681) (306.3439) | (0.0383) ( 188.7074 ) | (0.0252 ) | (130.3297) |
| $\hat{T}_{R(1)}$ | 478 443.4048 | $478 \quad 219.6018$ | 478 | 139.9649 |
| $\hat{T}_{R(2)}$ | 478 444.9974 | 478 220.1128 | 478 | 140.1862 |
| $\hat{t}_{y \pi}$ | $478 \quad 968.8000$ | $478 \quad 599.7333$ | 478 | 415.2000 |
| $\widetilde{t}_{y}{ }_{\text {d }}(1)$ | $478 \quad 446.9986$ | $478 \quad 221.5335$ | 478 | 141.1973 |
| $\widetilde{t}_{y \pi(2)}$ | $478 \quad 444.9974$ | 478 220.1128 | 478 | 140.1862 |
| $\hat{T}_{R}$ Family | $\begin{aligned} & \frac{\operatorname{MSE}\left(\hat{T}_{R(1)}\right)}{M S\left(T_{R}\right)}=1.4474 \\ & \frac{M S E\left(T_{R(2)}\right)}{M S E\left(\hat{T}_{R}\right)}=1.4526 \\ & \frac{M S E\left(T_{R(1)}\right)}{M S E\left(\hat{T}_{R(2)}\right)}=0.9964 \end{aligned}$ | $\begin{aligned} & \frac{\operatorname{MSE}\left(\hat{T}_{R(1)}\right)}{M S\left(T_{R}\right)}=1.1637 \\ & \frac{M S E\left(T_{R(2)}\right)}{M S E\left(T_{R}\right)}=1.1664 \\ & \frac{M S E\left(T_{R(1)}\right)}{M S E\left(\hat{T}_{R(2)}\right)}=0.9977 \end{aligned}$ | $\frac{M S E\left(\hat{T}_{R(1)}\right)}{M S E\left(T_{R}\right)}$ $\frac{M S E\left(\hat{T}_{R(2)}\right)}{M S E\left(\hat{T}_{R}\right)}$ $\frac{M S E\left(\hat{T}_{R(1)}\right)}{M S E\left(\hat{T}_{R(2)}\right)}$ | $\begin{aligned} & =1.0739 \\ & =1.0756 \\ & =0.9984 \end{aligned}$ |
| Hort-Thom <br> family | $\begin{aligned} & \frac{M S E\left(t_{y \pi(1)}\right)}{M S\left(\hat{t}_{\pi \pi}\right)}=0.4614 \\ & \frac{M S E\left(t_{y \pi(2)}\right)}{M S E E\left(t_{y \pi \pi}\right)}=0.4593 \\ & \frac{M S E\left(t_{y \pi(1)}\right)}{M S E\left(t_{y \pi(2)}\right)}=1.0045 \end{aligned}$ | $\begin{aligned} & \frac{M S E\left(t_{y \pi(1)}\right)}{M S E}=0.3694 \\ & \frac{M S E\left(t_{y \pi \tau}\right)}{M S E(2))} \\ & =0.3671 \\ & \frac{M S E\left(t_{y \pi \pi}\right)}{M S E\left(t_{y \pi(1)}\right)} \end{aligned}=1.0065$ |  | $\begin{aligned} & =0.3401 \\ & =0.3376 \\ & =1.0072 \end{aligned}$ |

Table 4: Empirical results from cars93 for Stratum (2): When typecode=2

| Estimator | $n_{h}=2$ |  | $n_{h}=3$ |  | $n_{h}=4$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $t_{y h}$ | $S_{y h}^{2}$ | ${ }^{\text {t }}$ yh | $S_{y h}^{2}$ | ${ }^{\text {y }}$ y | $S_{y h}^{2}$ |
| $\hat{T}_{R}$ | 588.4592 | 449.2140 | 588.2849 | 277.1965 | 588.2004 | 194.4815 |
|  | (0.4592) | (449.4248) | (0.2849) | (277.2777) | (0.2004) | (194.5216) |
| $\hat{T}_{R(1)}$ | 588 | 525.4486 | 588 | 260.7300 | 588 | 174.2959 |
| $\hat{T}_{R(2)}$ | 588 | 527.9447 | 588 | 261.3186 | 588 | 174.4998 |
| $\begin{aligned} & \hline \hat{t}_{y \pi} \\ & \tilde{t}_{y \pi(1)} \\ & \tilde{t}_{y \pi(2)} \\ & \hline \end{aligned}$ | 588 | 1386.6667 | 588 | 878.2222 | 588 | 624.0000 |
|  | 588 | 532.0924 | 588 | 264.2138 | 588 | 176.5988 |
|  | 588 | 527.9447 | 588 | 261.3186 | 588 | 174.4998 |
| $\hat{T}_{R}$ Family | $\operatorname{MSE}\left(\hat{T}_{R(1)}\right)$ | $\frac{\operatorname{MSE}\left(\hat{T}_{R}\right)}{}=1.1692$ | $\operatorname{MSE}\left(\hat{T}_{R(1)}\right)$ |  | $\operatorname{MSE}\left(\hat{T}_{R(1)}\right)=0.8960$ |  |
|  | $\operatorname{MSE}\left(\hat{T}_{R(2)}\right)$ | $=1.1747$ | $\frac{M S E( }{M S E}$ | $=0.9424$ | $\operatorname{MSE}\left(\hat{T}_{R(2)}\right)$ |  |
|  | $\operatorname{MSE}\left(\hat{T}_{R(1)}\right)$ |  | $\begin{array}{r} \text { MSE } \\ \text { MSE } \\ \hline \end{array}$ | $=0.9978$ | $\operatorname{MSE}\left(\hat{T}_{R(1)}\right)$ |  |
|  | $\frac{K(1))}{\operatorname{MSE}\left(\hat{T}_{R(2)}\right)}=0.9953$ |  | $\operatorname{MSE}\left(\hat{T}_{R(2)}\right)$ |  | $\operatorname{MSE}\left(\hat{T}_{R(2)}\right)$ |  |
| Hort-Thom | $\operatorname{MSE}\left(\tilde{t}_{y \pi}(1)\right)$ |  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(1)}\right)$ |  | $\operatorname{MSE}\left(\tilde{t}_{y \pi}(1)\right)$ |  |
| family | $\frac{\operatorname{MDL}\left({ }^{l} y \pi(2)\right)}{\operatorname{MSE}\left(\hat{t}_{y} \pi\right)}=0.3807$ |  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(2)}\right)$ |  | $\frac{(y \pi(2))}{\operatorname{MSE}\left(\hat{t}_{y \pi}\right)}=0.2797$ |  |
|  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(1)}\right)$ |  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(1)}\right)$ |  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(1)}\right)$ | $=1.0120$ |
|  | $\frac{\operatorname{MSE}\left(\tilde{t}_{y \pi(2)}\right)}{}=1.0079$ |  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(2)}\right)$ |  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(2)}\right)=1.0$ |  |

Table 5: Empirical results from cars93 for Stratum (3): When typecode=3

| Estimator | $n_{h}=2$ |  | $n_{h}=3$ |  | $n_{h}=4$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $t_{y h}$ | $S_{y h}^{2}$ | $t_{y h}$ | $S_{y h}^{2}$ | ${ }^{t}{ }_{y h}$ | $S_{y h}^{2}$ |
| $\hat{T}_{R}$ | 294.4412 | 99.6516 |  | 58.9851 | 294.1697 | 38.6799 |
|  | (0.4412 ) | (99.8463 ) | (0.2596 ) | (59.0524) | (0.1697) | (38.7087) |
| $\hat{T}_{R(1)}$ | 294 | 32.2542 | 294 | 28.9585 | 294 | 24.42012 |
| $\hat{T}_{R(2)}$ | 294 | 31.9504 | 294 | 28.8365 | 294 | 24.3733 |
| $\begin{aligned} & \hat{t}_{y} \pi \\ & t_{y \pi(1)} \\ & \tilde{t}_{y \pi(2)} \\ & \hline \end{aligned}$ | 294 | 80.1000 | 294 | 47.4667 | 294 | 31.1500 |
|  | 294 | 32.0873 | 294 | 29.0126 | 294 | 24.5711 |
|  | 294 | 31.9504 | 294 | 28.8365 | 294 | 24.3733 |
| $\hat{T}_{R}$ Family | $\frac{1}{\operatorname{MSE}\left(\hat{T}_{R}\right)}=0.3230$ | $0.3230$ | $\frac{M S E( }{M S E}$ | $=0.4904$ | $\operatorname{MSE}\left(\hat{T}_{R(1)}\right)$ |  |
|  | $\begin{array}{r} M S E \\ M S E( \\ \hline M S E \end{array}$ | $=0.3199$ | $\begin{array}{r} \text { MSE } \\ M S E( \\ \hline M S E \end{array}$ | $=0.4883$ | $\begin{array}{r} \hline M S E \\ M S E(\hat{T} \\ \hline M S E \end{array}$ | $=0.6297$ |
|  | $\operatorname{MSE}\left(\hat{T}_{R(1)}\right)$ |  | $\operatorname{MSE}\left(\hat{T}_{R(1)}\right)$ |  | $\operatorname{MSE}\left(\hat{T}_{R(1)}\right)$ |  |
|  | $\operatorname{MSE}\left(\hat{T}_{R(2)}\right)$ |  | $\operatorname{MSE}\left(\hat{T}_{R(2)}\right)$ |  | $\overline{\operatorname{MSE}\left(\hat{T}_{R(2)}\right)}$ |  |
| Hort-Thom | $\operatorname{MSE}\left(\tilde{t}_{y \pi(1)}\right)$ |  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(1)}\right)$ |  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(1)}\right)$ |  |
| family | $\operatorname{MSE}\left(\tilde{t}_{y \pi(2)}\right)$ |  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(2)}\right)$ |  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(2)}\right)$ |  |
|  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(1)}\right)$ |  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(1)}\right)$ |  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(1)}\right)$ |  |
|  | $\overline{\operatorname{MSE}\left(\tilde{t}_{y \pi(2)}\right)}=1.0043$ |  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(2)}\right)$ |  | $\operatorname{MSE}\left(\tilde{t}_{y \pi(2)}\right)$ |  |

Table 6: Empirical results from cars93 for Stratum (4): When typecode=4

| Estimator | $n_{h}=2$ |  | $n_{h}=3$ |  | $n_{h}=4$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $t_{y h}$ | $S_{y h}^{2}$ | $t_{y h}$ | $S_{y h}^{2}$ | $t_{y h}$ | $S_{y h}^{2}$ |
| $\hat{T}_{R}$ | 404.9682 | $\begin{gathered} 464.2094 \\ (\mathbf{4 6 8 . 0 8 3 3}) \end{gathered}$ | $\begin{aligned} & 404.2003 \\ & (1.2003) \end{aligned}$ | $\begin{array}{r} 279.8831 \\ (\mathbf{2 8 1 . 3 2 3 8}) \end{array}$ | $\begin{gathered} 403.8170 \\ (0.8170) \end{gathered}$ | 189.1534 $(\mathbf{1 8 9 . 8 2 0 9})$ |
| $\hat{T}_{R(1)}$ | 403 | 219.7774 | 403 | 117.0185 | 403 | 96.4114 |
| $\hat{T}_{R(2)}$ | 403 | 221.1506 | 403 | 114.8667 | 403 | 94.8695 |
| $\hat{t}_{y} \boldsymbol{r}$ | 403 | 1113.6923 | 403 | 680.5897 | 403 | 464.0385 |
| ${ }^{t_{y}} \boldsymbol{y}$ (1) | 403 | 234.9529 | 403 | 123.6658 | 403 | 100.9741 |
| $\tilde{t}_{y \pi}(2)$ | 403 | 221.1506 | 403 | 114.8667 | 403 | 94.8695 |
| $\hat{T}_{R}$ Family | $\begin{aligned} & \frac{\operatorname{MSE}\left(\hat{T}_{R(1)}\right)}{\operatorname{MSE}\left(\hat{T}_{R}\right)}=0.4695 \\ & \frac{\operatorname{MSE}\left(\hat{T}_{R(2)}\right)}{\operatorname{MSE}\left(\hat{T}_{R}\right)}=0.4725 \\ & \frac{\operatorname{MSE}\left(\hat{T}_{R(1)}\right)}{\operatorname{MSE}\left(\hat{T}_{R(2)}\right)}=0.9938 \end{aligned}$ |  | $\begin{aligned} & \frac{\operatorname{MSE}\left(\hat{T}_{R(1)}\right)}{\operatorname{MSE}\left(\hat{T}_{R}\right)}=0.4160 \\ & \frac{\operatorname{MSE}\left(\hat{T}_{R(2)}\right)}{\operatorname{MSE}\left(\hat{T}_{R}\right)}=0.4083 \\ & \frac{\operatorname{MSE}\left(\hat{T}_{R(1)}\right)}{\operatorname{MSE}\left(\hat{T}_{R(2)}\right)}=1.0187 \end{aligned}$ |  | $\begin{aligned} & \frac{\operatorname{MSE}\left(\hat{T}_{R(1)}\right)}{\operatorname{MSE}\left(\hat{T}_{R}\right)}=0.5079 \\ & \frac{\operatorname{MSE}\left(\hat{T}_{R(2)}\right)}{\operatorname{MSE}\left(\hat{T}_{R}\right)}=0.4998 \\ & \frac{\operatorname{MSE}\left(\hat{T}_{R(1)}\right)}{\operatorname{MSE}\left(\hat{T}_{R(2)}\right)}=1.0163 \end{aligned}$ |  |
| Hort-Thom family | MSE <br> MSE <br> MSE <br> $M S E$ <br> $M S E$ <br> $M S E$ | $\begin{aligned} & =0.2110 \\ & =0.1986 \\ & =1.0624 \end{aligned}$ | $\begin{array}{r} \text { MSE } \\ \hline M S E \\ M S E( \\ \hline M S E \\ M S E( \\ \hline M S E( \end{array}$ | $\begin{aligned} & =0.1817 \\ & =0.1688 \\ & =1.0766 \end{aligned}$ | MSE <br> $M S E$ <br> $M S E($ <br> $M S E$ <br> $M S E($ | $=0.2176$ $=0.2044$ $=1.0644$ |

Table 7: Empirical results from cars93 for Stratum (5): When typecode=5

| Estimator | $n_{h}=2$ | $n_{h}=3$ | $n_{h}=4$ |
| :---: | :---: | :---: | :---: |
|  | $t_{y h} \quad S_{y h}^{2}$ | $t_{y h} \quad S_{y h}^{2}$ | $t_{y h} \quad S_{y h}^{2}$ |
| $\hat{T}_{R}$ | 197.091923 .2645 | $197.0515 \quad 13.2744$ | 197.03198 .2891 |
|  | (0.0919) ( 23.2730 ) | (0.0515 ) (13.2770) | (0.0319) (8.2901) |
| $\hat{T}_{R(1)}$ | $197 \quad 22.6543$ | 19711.1726 | $197 \quad 7.1120$ |
| $\hat{T}_{R(2)}$ | 197 22.6484 | $197 \quad 11.1820$ | $197 \quad 7.1201$ |
| $\hat{t}_{y \pi}$ | $197 \quad 66.5000$ | $197 \quad 38.0000$ | $197 \quad 23.75$ |
| $\tilde{t}_{y}{ }_{\sim}(1)$ | 197 22.6953 | $197 \quad 11.2614$ | $197 \quad 7.2046$ |
| $\tilde{t}_{y \pi(2)}$ | $197 \quad 22.6484$ | $197 \quad 11.1820$ | $197 \quad 7.1201$ |
| $\hat{T}_{R}$ Family | $\frac{M S E\left(\hat{T}_{R(1)}\right)}{M S E\left(\hat{T}_{R}\right)}=0.9734$ $\frac{M S E\left(\hat{T}_{R(2)}\right)}{M S E\left(\hat{T}_{R}\right)}=0.9732$ $\frac{M S E\left(\hat{T}_{R(1)}\right)}{M S E\left(T_{R(2)}\right)}=1.0003$ | $\frac{\operatorname{MSE}\left(\hat{T}_{R(1)}\right)}{M S E\left(T_{T}\right)}=0.8415$ $\frac{M S E\left(\hat{T}_{R(2)}\right)}{M S E\left(\hat{T}_{R}\right)}=0.8422$ $\frac{M S E\left(\hat{T}_{R(1)}\right)}{M S E\left(T_{R(2)}\right)}=0.9992$ | $\begin{aligned} & \frac{\operatorname{MSE}\left(\hat{T}_{R(1)}\right)}{M S\left(T_{R}\right)}=0.8579 \\ & \frac{M S E\left(T_{R(2)}\right)}{M S E\left(T_{R}\right)}=0.8589 \\ & \frac{M S E\left(T_{R(1)}\right)}{M S E\left(\hat{T}_{R(2)}\right)}=0.9989 \end{aligned}$ |
| Hort-Thom family |  |  |  |

Table 8: Empirical results from cars93 for Stratum (6): When typecode=6


Table 9: Empirical results from cars93 based on stratified sampling designs

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