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DISCUSSION PAPER NO. 272

Linear Functionals of Convex Sets with Applications to Economics, Game-Theory and Social Choice*

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Linear Functional of Convex Sets with Applications to Economics, Game-Theory and Social Choice

Ehud Kalai and Roger B. Myerson

1. Introduction

Let $\mathcal C$ denote the set of all compact convex subsets of the n-dimensional Euclidean space, R^n . $\mathcal C$ is a convex cone $(A,B\in\mathcal C)$ imply $A+B=\{a+b:a\in A,b\in B\}\in\mathcal C$ and $rA=\{ra:a\in A\}\in\mathcal C$ for every $r\geq 0$). The main purpose of this paper is to characterize all the uniformly continuous (relative to the Hausdorff metric on $\mathcal C$) real valued linear functions (F(A+B)=F(A)+F(B)) and F(rA)=rF(A) for $r\geq 0$) on $\mathcal C$. In section 2 we give examples to show that these functions are common in Economics and Game-Theory. Section 3 is devoted to the proof of an extended version of Theorem 1 below. Section 4 exhibits a method of recovering the measures associated with our characterization and presents an open problem.

For $C\in\mathcal{C}$ and $p\in R^n$ let $V_C(p)$ denote the support of C in the direction p, i.e. $V_C(p) = \sup_{c\in C} c\cdot p$. Let S denote the boundary of the unit ball in R^n .

Theorem 1: F is a uniformly continuous, real valued linear function on $\mathcal C$ if and only if there exist non-negative real numbers a and b and probability measures μ and η on S such that for every $C\in\mathcal C$

$$F(C) = aE_{\mu}V_{C} - bE_{\eta}V_{C}$$

where E $_{\mu}$ denotes the expected value relative to the measure $\mu\text{.}$

2. Examples

References to show the frequency of occurrence of linear functionals in Economics are too numerous to list (e.g. Debreu [1959] and Gale [1960]). We give the following examples in order to show four specific cases where the function F of Section 1 is natural.

Example 1: Decomposition of Production

We think of each of the coordinates of a point in ${\ensuremath{\mathtt{R}}}^n$ as representing output level of a certain good. Thus a point $x \in R^n$ represents output x^1 of good 1, x^2 of good 2 and so on. A set CEC represents the feasible output levels for a producer. Given such a set C, let F(C) be the profit (or cost) associated with the producer's choice in C. If a set A represents the feasible production levels in one location and B representes the feasible production levels in another location then A + B represents the feasible production levels from the two loca-F(A+B) = F(A) + F(B) means that as far as profit is concerned the problem is decomposable and the decision can be made jointly or separately. Similar considerations will justify the requirement that F(kC) = kF(C) for every positive integer k, F(rC) = rF(C) for every positive rational number r, and continuity argument will result in F(tC) = tF(C) for every non-negative real number t. Of course the quantity F(C) could represent many other concepts for which decomposition is desired.

Notice that $E_{\mu} V_C$ is the expected worth of the feasible production set C when prices have the distribution μ . Thus, by Theorem 1, it

follows that every uniformly continuous function which is decomposable can be viewed as the difference of the expected worth of the set C according to two different fixed probability distributions on potential prices.

Linear, real valued functions arise in cooperative game theory when we consider the von-Neumann Morgenstern utility that an individual has for the options of participating in various cooperative games. For simplicity we illustrate this point on a class of very simple games of this type (see Aumann-Peleg [1960] for the general case and Nash [1950] for the special case that we consider here). In addi-

tion linear functions of convex sets arise naturally when we consider

of cooperative games without sidepayments (Kalai-Myerson [1977]).

possible extensions of the Shapley Value (Shapley [1953]) to the family

Example 2: The Utility of Participating in a Cooperative Game

We consider two fixed individuals with fixed von-Neumann Morgenstern utility functions. A two-person game of these two individuals is represented by a pair $(a,C)\in R^2$ $_x$ $_c$. $a=(a^1,a^2)$ represents the V-M utility levels resulting to the two of them when they do not cooperate. C represents the utility levels available to them when they do cooperate. Thus $c=(c^1,c^2)\in C$ if and only if there is a joint strategy yielding utility levels c^1 and c^2 to the two players respectively. We are interested in the V-M utility that player 1 may have for participating in the various games that he may encounter with 2. (See Roth [1976] for a treatment of the sidepayments case as a generalization

of the Shapley Value.) Consider three games, (a,A) (b,B) and the game resulting from the following lottery. With probability α they will play (a,A) and with probability $1-\alpha$ (b,B). If we consider the ex-ante feasible V-M utility level associated with the third game (c,C) we obtain

$$(c,C) = (\alpha a + (1-\alpha)b, \alpha A + (1-\alpha)B).$$

Thus it follows from the V-M theory that player 1's utility for the games must satisfy

$$u(\alpha a + (1-\alpha)b, \alpha A + (1-\alpha)B) = \alpha u(a,A) + (1-\alpha)u(b,B).$$

By considering all the games with a fixed non-cooperation point, or by choosing a non-cooperation point that varies linearly with the choice of the feasible set we obtain that u must induce a linear, real valued function on \mathcal{C} .

Example 3: Decentralization of Social Choice Decisions

We let a set C denote the feasible production levels of n-public goods. F(C) represents society's utility from the choice made out of C. The linearity of F means that if C is decomposed into sets that add up to C then making the choice on every one of the component sets will not effect society's utility of the final outcome.

Example 4: Utilitarian Social Welfare Functions

We consider a society of n individuals each having a von-Neumann Morgenstern utility function $u_{\bf i} (1 \le {\bf i} \le n)$. A set $C \subseteq R^n$ represents (as in Example 2) feasible utility levels of the n individuals in a certain situation. Thus if society's options in a certain situation are given by a set A then $C = \{(u_1(a), u_2(a), \dots, u_n(a)) : a \in A\}$. C must be convex if we assume that the society has the option to randomize over alternatives in A. We let F(C) denote the V-M utility of the society when it makes the choice from C. The argument given in Example 2 holds also in this case and implies that F must be linear on C.

Notice that if society's utility of a choice set C is given by the function $V_C(p)$ (= sup c·p) for some $p \in \mathbb{R}^n$ then society has a utilication social welfare function with the interpersonal weights given by $p = (p_1, p_2, \ldots, p_n)$. (See Harsanyi [1955] for an aximatization of this Social Welfare Function.) If society has a utility function of the form $u(C) = E_\mu V_C$ where μ is a probability distribution on the boundary of the unit ball in \mathbb{R}^n then it is basically a utilitarian society which has a probability distribution μ over the interpersonal weights. Thus Theorem 1 tells us that every uniformly continuous V-M utility function for the society can be viewed as the difference of two utilitarian functions with two different probability distributions over the interpersonal weights.

3. Main Results

Let X denote a convex cone of closed convex sets in R^n with a common recession cone $T \neq R^n$. Thus we assume that X satisfies the following conditions.

- 1. Every element of ${\mathcal K}$ is closed and convex.
- 2. A,B \in % imply that A+B \in % (+ denotes set addition)
- A € X and t > 0 imply that tA € K.
- 4. There exists a closed convex cone in Rⁿ, T(≠ Rⁿ), such that for every A€X the recession cone of A is T.
 Recall that the recession cone is the set of directions to which A is unbounded, i.e.

 $T = \{v \in \mathbb{R}^n : A + \{v\} \subseteq A\}$ (see Rockafellar [1970]).

Notice that when $T = \{0\}$ then $\mathcal{K} = \mathcal{C}$.

The cases where T = $-R_+^n$ are very common in Game-Theory and Economics (free disposal). We let W denote the polar cone of T (= $\{w \in R^n : w \cdot r \leq 0 \text{ for every } r \in T\}$) and for every AeX we let V_A denote the support function of A then the effective domain of V_A is W. V_A is continuous, convex, and homogeneous of degree 1 on W. And there is a 1-1 correspondence between convex sets with T as a recession cone and functions on W which satisfy these conditions. We let \overline{W} denote the intersection of W with the boundary of the unit ball in R^n , \overline{W} = $\{v \in W : ||v|| = 1\}$ where $||\cdot||$ denotes the Euclidean norm.

For A,B% the Hausdorff distance between A and B is defined as usual to be the supremum of radei of Euclidean balls which are centered around a point of one of the two sets A, B, without intersecting the other set. We discuss continuity of functions on % relative to this Hausdorff metric.

A real valued function F on \mathcal{K} is linear if for every A,B \in X and every r > 0, F(A+B) = F(A) + F(B) and F(rA) = rF(A).

Theorem 2: F is a real valued uniformly continuous linear function on X if and only if there is some signed regular Borel measure M on \overline{W} such that for every $C \in X$

$$F(C) = \int_{\overline{W}} V_C(\tilde{p}) dM(p).$$

Let X be a normed linear space over the real numbers, let Y denote a convex cone in X, and let f be a real valued linear function on Y. We define $|| f ||_Y = \sup \{ \frac{|f(y)-f(z)|}{||y-z||} : y,z\in Y \}$ and we say that f is bounded on Y if $||f||_Y < \infty$.

<u>Lemma 1</u>: A real valued bounded linear function f defined on a convex cone Y can be extended to a bounded linear function \overline{f} on the entire space X with $||\overline{f}|| = ||f||_{Y}$.

Proof of Lemma 1: We let Z = Y - Y then Z is a subspace of X.
We extend f to f defined on Z by

$$f(y_2 - y_2) = f(y_2) - f(y_2).$$

By the linearity of f it follows that f is well defined, linear, and $\| f \|_Z = \| f \|_Y$. The Hahn-Banach Theorem completes the proof of the lemma.

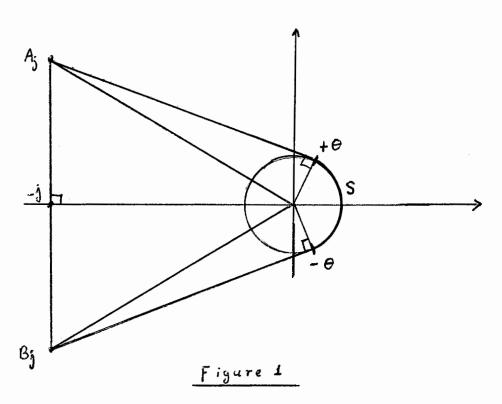
<u>Proof of Theorem 2</u>: Let \overline{W}^* denote the set of all real valued functions defined on \overline{W} which are the restrictions to \overline{W} of some support function V_A with effective domain W. Every element in \overline{W}^* can be associated uniquely with some V_A for some unique convex set $A \in \mathcal{K}$. We let \overline{V}_A denote the restriction of V_A to \overline{W} . Thus we can definine F^* on \overline{W} by $F^*(\overline{V}_A) = F(A)$. So F^* is a well defined, linear, real valued function on \overline{W}^* . Also F^* is uniformly continuous (with the sup norm) because F is (see Artstein [1970] or Kalai [1975]). To show that F^* is bounded on \overline{W}^* we assume to the contrary that there exists a sequence of functions $\overline{V}_A(i)$ and $\overline{V}_B(i)$ on \overline{W}^* such that

 $R(A(\mathbf{i}),B(\mathbf{i})) = \frac{|F^*(\overline{V}_{A(\mathbf{i})})-F^*(\overline{V}_{B(\mathbf{i})})|}{||\overline{V}_{A(\mathbf{i})}-\overline{V}_{B(\mathbf{i})}||} \to \infty \text{ as } \mathbf{i} \to \infty. \text{ By the uniform}$ continuity of F^* there exists a $\delta > 0$ such that if $||\overline{V}_{A(\mathbf{i})}-\overline{V}_{B(\mathbf{i})}|| \leq \delta$ then $||F^*(\overline{V}_{A(\mathbf{i})})-F^*(\overline{V}_{B(\mathbf{i})})|| \leq 1$. If we consider the sequence $(A_{(\mathbf{i})}^1,B_{(\mathbf{i})}^1) \leq \frac{1}{\delta} \text{ for all } \mathbf{i} \text{ but also } R(A_{(\mathbf{i})}^1,B_{(\mathbf{i})}^1) \to \infty \text{ as } \mathbf{i} \to \infty, \text{ a contradiction.}$ Thus F^* is a real valued, linear, bounded function on \overline{W}^* . Since \overline{W}^* is a convex cone in the space $C_o(\overline{W})$ consisting of all continuous functions on \overline{W} we can extend, by Lemma 1, F^* to be a linear bounded real valued function on $C_o(\overline{W})$. Now Riesz Representation Theorem completes the proof of the theorem.

Corollary: Theorem 1 follows immediately from Theorem 2 by the Hahn Decomposition Theorem for signed measures. Notice also that if M is determined uniquely for a given F then Hahn's theorem implies that a,b, μ and η of Theorem 1 are determined uniquely after the obvious normalization.

4. Uniqueness, Recovering the Measure, and an Open Question

We give an example in \mathbb{R}^2 to show how to recover the measure M underlying a given uniformly continuous linear F defined on \mathcal{C} . We believe that this method can be applied to the general case. In particular this would show that the measure M described by Theorem 2 is unique.



We let S be the interval described in Figure 1. S_j is the convexhull of S and the points A_j and B_j . T_j is the convexhull of A_j , B_j and (0,0). We claim that $M(S) = \lim_{j \to \infty} [F(S_j) - F(T_j)]$. To justify this claim, consider the support functions of S_j and T_j

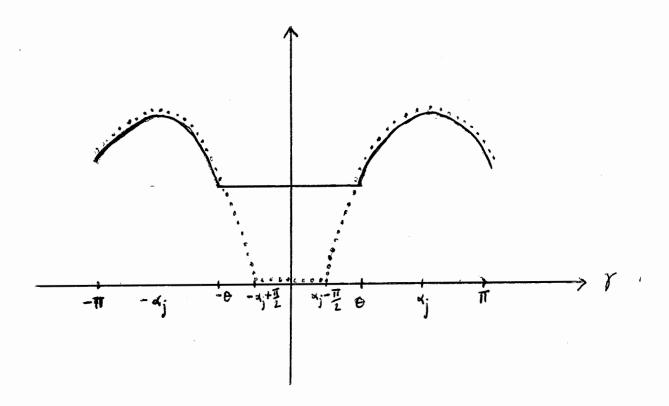


Figure 2.

 $V_{T_{\hat{j}}}(\gamma) = \max (0, |A_{j}|\cos(\gamma+\alpha_{j}), |A_{j}|\cos(\gamma-\alpha_{j}))$, the dotted line in Figure 2.

 $V_{S_{j}}(\gamma) = \max (1, |A_{j}|\cos(\gamma+\alpha_{j}), |A_{j}|\cos(\gamma-\alpha_{j}))$, the solid line in Figure 2.

Since $-\alpha_{j} + \frac{\Pi}{2} \rightarrow -\theta$ and $\alpha_{j} - \frac{\Pi}{2} \rightarrow \theta$ as $j \rightarrow \infty$ it follows that $\int_{\mathbf{j}} V_{\mathbf{S}_{j}}(\gamma) - V_{\mathbf{T}_{j}}(\gamma) dM(\gamma) \rightarrow \int_{\mathbf{S}} 1 dM(\gamma) = M(\mathbf{S}) \text{ as } j \rightarrow \infty.$

Let $F = (F_1, F_2, \dots, F_n)$ consist of n uniformly continuous linear real valued functions on \mathcal{K} . Let M_1, M_2, \dots, M_n be the corresponding

measures. A question that arises naturally from the examples given in Section 2 is whether $F(C) \in C$ for every $C \in \mathcal{K}$. This would enable us to consider the actual choice that the decision maker makes out of the alternative in C. Necessary and sufficient conditions on the M_i 's that will induce this feasibility property would be of great interest. The condition that F(C) be on the boundary of C for every $C \in \mathcal{K}$ (or Pareto Optimality) is also desirable but unfortunately it is inconsistent with continuity (see Kalai-Myerson [1977]).

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