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Article

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An optimal quantity tax path in a dynamic setting

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Abstract. Following Ramsey, the existing literature on optimal quantity taxation only compares the pre and the post-tax market equilibriums in order to account for the efficiency losses. However, when the government imposes a quantity tax on the consumer, the buyer's price jumps to the pre-tax equilibrium price plus the amount of the tax, and the supply and the demand of the taxed commodity then adjust over time to bring the new post-tax market equilibrium. The existing literature does not take into account the efficiency losses during the adjustment process while computing the optimal quantity taxes. This paper derives an optimal quantity tax path in a dynamic setting minimizing the efficiency losses (output and/ or consumption lost) during the dynamic adjustment process as well as the post-tax market equilibrium.

Keywords. Quantity tax; Dynamic efficiency; Adjustment Path; Equilibrium

JEL classification. H20; H21; H22

1. Introduction

Optimal taxation in theory is the design of a tax that minimizes inefficiency and distortion due to deviation from the pre-tax efficient market equilibrium under given economic constraints. Ramsey (1927) was the first to make a significant contribution to the theory of optimal taxation from an economic standpoint. He developed a theory for optimal commodity taxes and proposed a theoretical solution that consumption tax on each good should be "proportional to the sum of the reciprocals of its supply and demand elasticities". Diamond and Mirrlees (1971) consider commodity taxation along with the other kinds of taxes. Mirrless (1975) modified the standard problem by considering simultaneously excise taxes and a poll tax. Diamond (1975) examines the Ramsey rule for a many-person economy with excise taxes and a poll tax. Atkinson and Stiglitz (1976) show that with an optimal nonlinear income tax, discriminatory commodity taxes are only necessary to the extent that individual commodities are not weakly separable from leisure. In Deaton (1981), rules for optimal differential commodity taxes have been derived for the three different cases usually studied in the literature: the one consumer economy, the unidimensional continuum of consumers economy, and the finite number of discrete consumers economy. Lucas and Stokey (1983) derive a time consistent optimal fiscal policy in an economy without capital

maximizing the consumer welfare subject to the condition that a competitive equilibrium holds in each time period.

In Judd (1985), the government taxes capital income net of depreciation at a proportional rate, which is assumed to be constant. Chamley (1986) analyzes the optimal tax on capital income in general equilibrium models of the second best. Deaton and Stern (1986) show that optimal commodity taxes for an economy with many households should be at a uniform proportional rate under certain conditions. Cremer and Gahvari (1993) incorporate tax evasion into Ramsey's optimal taxation problem. Cremer and Gahvari (1995) prove that optimal taxation requires a mix of differential commodity taxes and a uniform lump-sum tax. Naito (1999) shows that imposing a non-uniform commodity tax can Pareto-improve welfare even under nonlinear income taxation if the production side of an economy is taken into the consideration. Saez (2002) shows that a small tax on a given commodity is desirable if high-income earners have a relatively higher taste for this commodity or if consumption of this commodity increases with leisure.

The quantity taxes are currently more popular in the environmental economics literature, e.g. Nordhaus (1993) proposes an optimal carbon tax (tax per ton of carbon). Chari, Christiano and Kehoe (1994) deal with the labor and capital income taxes instead of a quantity tax as in our model. Ekins (1996) takes into account the secondary benefits of Carbon dioxide abatement for an optimal carbon tax. Coleman (2000) derives the optimal dynamic taxation of consumption, income from labor, and income from capital, and estimates the welfare gain that the US could attain by switching from its current income tax policy to an optimal dynamic tax policy. Pizer (2002) explores the possibility of a hybrid permit system and a dynamic optimal policy path in order to accommodate growth and not because of the adjustment over time to equalize the marginal benefit and cost. It is implicitly assumed that the marginal cost equals the marginal benefit in each time-period.

Following Ramsey, the existing literature on optimal quantity taxation only compares the pre and the post-tax market equilibriums in order to account for the efficiency losses. However, when the government imposes a quantity tax on the consumer, the buyer's price jumps to the pre-tax equilibrium price plus the amount of the tax, and the supply and the demand of the taxed commodity then adjust over time to bring the new post-tax market equilibrium. The existing literature does not take into account the efficiency losses during the adjustment process while computing the optimal quantity taxes. This paper derives an optimal quantity tax path in a dynamic setting minimizing the efficiency losses (output and/ or consumption lost) during the dynamic adjustment process as well as the post-tax market equilibrium.

The remainder of this paper is organized as follows: Section 2 explains how the individual components of the market system are joined together to form a dynamic market model. Section 3 provides the solution of the model with a quantity tax imposed. Section 4 derives an optimal commodity tax path minimizing the efficiency losses subject to a tax revenue target in a specific time-period. Section 5 summarizes the findings and concludes. The appendix presents mathematical details.

2. The model

Let's assume that there is a perfectly competitive market of a single homogeneous commodity in equilibrium (so our starting point is when the market is already in equilibrium). There are four types of infinitely-lived agents: a representative -or a unit mass of- producer (that produces a good, and demand labor and capital), a middleman (who buys the good from firms to sell to consumers, and possibly accumulating inventories), a representative -or a unit mass of- consumer (who buys the good, accumulates capital by investing and supplies labor inelastically), and a government. The role of middleman is motivated by the real world scenario where the producer and the consumer seldom directly meet for a transaction to take place. The existence of retailers, wholesalers, financial institutions, educational institutions and the hospitals reflect the presence of middlemen between producers and consumers in most of the economic activity going on. The producer produces the goods and supplies those to the middleman, who keeps an inventory of the goods and sells those to the consumer at the market price. In the model, the middleman plays a key role, as she sets the selling price p by maximizing the difference between the revenue for selling goods to consumers and the costs of inventories. The buying price paid to the producer is αp with $\alpha < 1$, and the producer is a price taker.

The price adjustment mechanism is based on the fact that when a shock leads the market out of equilibrium, the buyers' and sellers' decisions are not coordinated at the current prices. An example can illustrate the working of this market. Consider that the market is initially in equilibrium. The middleman has an equilibrium stock of inventory. Then, an exogenous demand contraction will increase the stock of inventory, due to firms' output could not match with the -now lower- units demanded by the consumer at the current price. This excess of supply is accumulated in inventory held by the middleman. The middleman will decrease the price so that the producer will find optimal to produce a lower level of output. A new equilibrium with a lower price and a lower level of output is then reached. The equilibrium is defined as follows:

(i) The producer and the middleman maximize their profits and the consumer maximizes her utility subject to the constraints they face (mentioned in their individual dynamic optimization problems in Section 2).

(ii) The quantity supplied by the producer equals the quantity consumed by the consumer (and hence the inventory does not change when the market is in equilibrium).

The conditions for the existence of the equilibrium (Routh-Hurwitz stability criterion, which provides a necessary and sufficient condition for the stability of a linear dynamical system) have been mentioned in Section 3.

As the set-up is for a perfectly competitive market, therefore, the middleman who sells the goods to the consumer at the market price is a price taker when the market is in equilibrium. When the market is out of equilibrium, the middleman can change the price along the dynamic adjustment path until the new equilibrium arrives, where again the middleman becomes a price taker. The government announces and imposes a commodity tax at the same time (the expectations of the agents will be taken into account in a future research project when the dates

of announcement and implementation of the tax are different). When a commodity/ quantity tax is imposed, the market does not suddenly jump to the post-tax market equilibrium, rather the price adjusts over time to bring the new equilibrium. This adjustment process involves endogenous decision making (in their own interest) by all the agents in the market, i.e. consumer, producer and the middleman as follows: Suppose there is a producer in a market who produces a perishable good and sells it to a middleman who further sells it to a consumer living in a community. The producer and the middleman sell a quantity exactly equal to the quantity the producer produces in each time period, and the market stays in equilibrium. If the government announces and imposes a commodity tax on the buyer, which decreases the demand of this product, some of the production sold to the middleman will remain unsold to the consumer and be wasted by the end of the time period in which the tax was imposed. Assuming that the producer and the middleman can change the production and the price respectively, immediately, had they known the exact pattern of new demand, they would immediately pick the quantity (by the producer) and the price (by the middleman) to maximize their profits and clear the market without wasting the production. However, they lack this information, so the middleman decreases the price based on her best guess about the new demand (based on the quantity of the unsold production), driving the market close to the new equilibrium. At the lower price, the producer produces a lower quantity than before. If in the following time period, his production sold to the middleman is fully sold out to the consumer, he will know that the new equilibrium has arrived, however, if a part of his production still remains unsold, the middleman will reduce the price further (and the producer, the production accordingly) to bring the market closer to the new equilibrium. The market will eventually settle at the new equilibrium after some efficiency loss. The resources wasted by the imposition of the tax are those that went into the unsold production in each time-period during the adjustment process. A new equilibrium with a deadweight loss due to commodity taxation is finally arrived at. The total efficiency loss because of commodity taxation is the loss during the adjustment process plus the loss in the final equilibrium.

For the mathematical treatment, the objective of each of the three market agents is maximized through the first order conditions of their objective functions and to capture the collective result of their individual actions, the equations representing their individual actions are solved simultaneously. For simplification, we assume that after the imposition of the quantity tax, the new equilibrium is not too far from the initial equilibrium. This assumption makes the linearization of supply and demand curves quite reasonable; see Figure 1 (the time axis is not shown). Linearization seems to be a good approximation when we move from point *a* to *b*, whereas it is not a good approximation when we move from point *a* to *c*. For modeling the movement of the market from point *a* to *c*, we need to model a non-linear dynamical system (which is not covered under the scope of this paper).

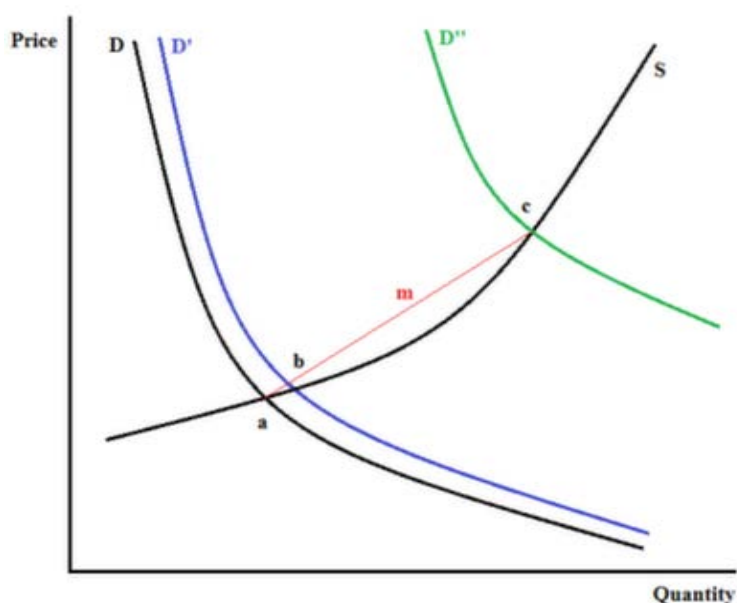


Figure 1: When is Linearity a Reasonable Assumption?

2.1 Middleman

The middleman purchases goods from the producer and sells those to the consumer for profit. As happens in the real world, the middleman does not buy and sell exactly the same quantity at all points in time, thus he holds an inventory of the goods purchased to be sold subsequently. Inventory is an intermediary stage between supply and demand which reflects the quantum of difference between supply and demand of the goods in the market. If the inventory remains the same, it implies that demand and supply rates are the same. An increase or decrease in inventory implies a change in supply, demand or both at different rates.

Figure 2 helps to understand the link between inventory, supply, demand and prices. When the supply curve shifts to the right (while demand remains the same), the inventory in the market increases at the initial price, and the new equilibrium brings the price down. Similarly, when the demand curve shifts to the right (while supply remains constant), the inventory depletes from the market at the previous price and the new equilibrium brings the price up. This shows that there is an inverse relationship between an inventory change and a price change (all else the same). If both the supply and demand curves shift by the same magnitude such that the inventory does not change, then price will also remain the same. Inventory unifies the supply and demand shocks in the sense that they are both affecting the same factor, i.e. inventory and are basically the faces of the same coin. Therefore each kind of shock is in fact just an inventory shock. From the above mentioned discussion, we have seen that there is an inverse relationship between an inventory change and a price change.

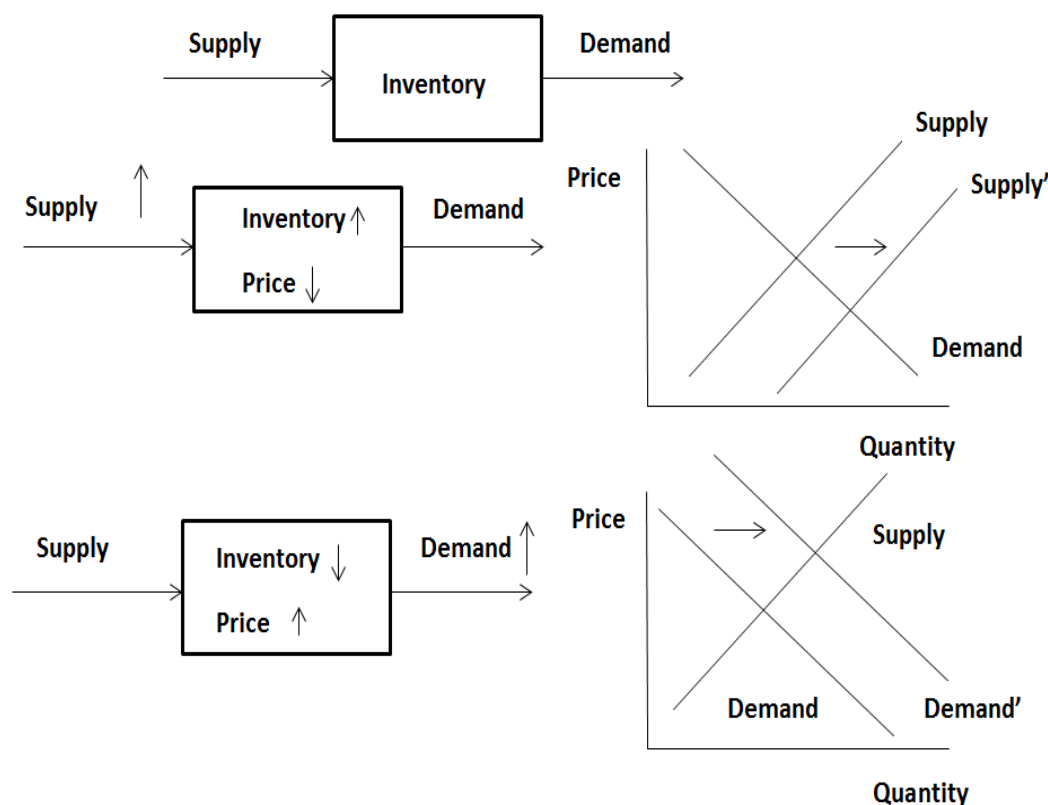


Figure 2: Movement of Price with Inventory.

Now let's discuss the mechanism which brings about such a change. Consider a market of homogeneous goods where the middlemen, such as whole sellers, retailers, etc. hold inventories, incur some cost for holding those, and sell products to the consumers to make profits. The cost is a positive function of the size of an inventory, i.e. a larger inventory costs more to hold as compared to a smaller inventory. In the absence of an exogenous shock, if the supply and demand rates are equal then the system is in equilibrium and the price does not vary with time. Suppose that a technological advancement decreases the marginal cost of production and increases the supply rate, whereas the demand rate remains the same. As the demand and supply rates are no longer equal, therefore the difference will appear somewhere in the economy in the form of piled up inventories. As the production flows from the producer to the consumer through the middleman, therefore it is reasonable to assume that the middleman will be holding the net difference (Explanation: The piled up inventories can also be in the form of producers' inventories of finished goods, which does not change the key point that a difference of supply and demand rates directly affect the inventories in the economy). The economy will not be able to sustain this situation indefinitely, and the middlemen will have to think of some means of getting rid of piled up inventories. The only resort they have is to decrease the price which brings the demand up along the demand curve.

In a perfectly competitive market, the price will eventually come down to equalize the new marginal cost, however the adjustment path depends on how the middlemen react to the change in their inventories. Notice that the marginal cost of production has decreased but the marginal cost of holding an extra unit of inventory for the middleman has increased. This is an intuitive explanation which is theoretically consistent with the demand, supply, utility and profit maximization by a consumer and a producer respectively. In the real world, we see examples of this behavior of middlemen, e.g. as consumers, we enjoy the *end of year sales*, offers such as *buy one get one free*, *gift offers* if you buy above a certain quantity threshold, etc. For a mathematical treatment, we need to consider the profit maximization problem of the *middleman* as follows.

2.1.1 Short-run problem

Let's first consider the short-run problem of the middleman as follows (the middleman's objective is myopic rather than doing dynamic optimization. In a discrete analog, this is a one period analysis, which is presented for an intuitive purpose as an anticipation of the -more complicated- dynamic problem in section 2.1.2).

$$\Pi = pq(p) - \zeta(m(p, e)), \quad [1]$$

where

Π = profit,

p = market price,

$q(p)$ = quantity sold at price p ,

m = inventory (total number of goods held by the *middleman*),

e = other factors which influence inventory other than the market price including the middleman's purchase price from the producer,

$\zeta(m(p, e))$ = cost as a function of inventory (increasing in inventory).

The first order condition (with respect to price) is as follows:

$$p q'(p) + q(p) - \zeta'(m(p, e)) m_1(p, e) = 0, \quad [2]$$

The middleman has an incentive to change the price only during the adjustment process and will incur losses by deviating from the price (equal to the marginal cost) when the market is in equilibrium. During the adjustment process, the demand does not equal the supply and the market drifts toward the new equilibrium (however, the price cannot move automatically and it is reasonable to assume that some economic agent moves the price in her own benefit), therefore a price change by the middleman in the direction of bringing the new equilibrium is not against the market forces, so he does not lose business by changing price on the adjustment path unlike when the market is in equilibrium and where the middleman faces an infinitely elastic demand as

follows:

$$p \dot{q}(p) + q(p) = \zeta(m(p, e)) \dot{m}_1(p, e),$$

$$p \left[1 + \frac{1}{\text{demandelasticity}} \right] = \zeta(m(p, e)) \frac{\dot{m}_1(p, e)}{\dot{q}(p)},$$

$$\text{demandelasticity} = p \frac{\dot{q}(p)}{\dot{q}(p)}.$$

The right hand side of the above expression is the marginal cost which equals the price when the middleman faces an infinitely elastic demand. Suppose that as a result of a supply shock, the marginal cost of production decreases, and the supply curve shifts downwards. Now the competitive market is out of equilibrium as the demand does not equal the supply at the previous equilibrium price. The price must eventually decrease to bring the new equilibrium, however, the price will not jump to equalize the demand and supply, and rather the middleman will continue charging a price higher than the new marginal cost until the market forces make him realize that the supply has increased and he needs to lower the price to satisfy the profit maximizing condition. The similar is the case of a reverse supply shock, where the price must eventually increase to bring the new equilibrium. In this case, the middleman will continue charging a price lower than the marginal cost until the market forces make him increase the price, in which case it is the consumer who is the short term beneficiary. Again, the consumer will be paying a price less than the marginal cost only during the adjustment process and only until the middleman increases the price. The equilibrium price is equal to the marginal cost of production plus the marginal cost of storage (i.e. the total marginal cost) in the absence of any kind of a tax, so neither does the middleman earn any economic rent, nor does the consumer benefit by paying a price less than the marginal cost when the competitive market is in equilibrium.

For the mathematical treatment, suppose that as a result of a supply shock (while demand remains the same) such as a technological advancement which reduces the marginal cost of production and increases the supply by the producers, if the middleman wants to hold an extra

unit of inventory, his marginal cost of holding an extra unit, i.e. $\zeta(m(p, e)) \frac{\dot{m}_1(p, e)}{\dot{q}(p)}$, is higher at

the previous price, because the term $\zeta(m(p, e))$ is higher at the previous price. This might be on account of higher storage charges because of increased demand of warehouses, godowns,

etc. after increased supply in the market. The second term, i.e. $\frac{\dot{m}_1(p, e)}{\dot{q}(p)}$ is a function of price,

and is the same as before as the price has not changed yet (we are assuming that the middleman's purchase price is the same as before as the producer is a price taker during the

adjustment process as well and always charges a fixed fraction of the market price to the middleman). A discrete analog of this scenario is that the middleman maximizes profits in each time period without considering the future time periods, and in each time period he takes the purchase price from the producer as given and only chooses the sale price. This implies that on the previous price, now the middleman faces

$$\frac{\partial \Pi}{\partial p} = p q(p) + q(p) - \zeta(m(p, e)) m_1(p, e) < 0, \quad [3]$$

which means that the middleman must decrease the price to hold an extra unit of inventory to satisfy the profit maximizing condition after the supply shock. Please notice that in this static scenario, the short term gains accrued from the decreased marginal cost of production will be reaped by the producer, as his marginal cost has decreased but he charges the same price to the middleman until the middleman changes the price. If we plot together various profit maximizing combinations of inventories and the respective prices chosen by a middleman, we will get a downward sloping *inventory curve* with the price on the y -axis and the inventory on the x -axis. This is analogous to the concept of *supply* and *demand curves* for the profit maximizing producers and the utility maximizing consumers respectively.

2.1.2 Dynamic problem

Now let's consider the dynamic problem of the middleman. In a dynamic setting, the middleman maximizes the present discounted value of the future stream of profits, and his present value at time zero is as follows:

$$V(0) = \int_0^{\infty} [pq(p) - \zeta(m(p, e))] e^{-rt} dt, \quad [4]$$

where r denotes the discount rate, $p(t)$ is the *control variable* and $m(t)$ the *state variable*. The maximization problem can be written as

$$\text{Max}_{\{p(t)\}} V(0) = \int_0^{\infty} [pq(p) - \zeta(m(p, e))] e^{-rt} dt,$$

subject to the constraints

$$\dot{m}(t) = \dot{m}_1(p(t), e(p(t), z)) p(t) + \dot{m}_2(p(t), e(p(t), z)) e_1(p(t), z) p(t) \quad (\text{state equation,}$$

describing how the state variable changes with time; z are exogenous factors),

$$m(0) = m_s \quad (\text{initial condition}),$$

$$m(t) \geq 0 \quad (\text{non-negativity constraint on state variable}),$$

$$m(\infty) \text{ free} \quad (\text{terminal condition}).$$

The current-value Hamiltonian for this case is

$$\tilde{H} = p(t)q(p(t)) - \zeta(m(p(t), e(p(t), z))) + \mu(t) p(t) \left[\frac{\dot{m}_1(p(t), e(p(t), z)) + \dot{m}_2(p(t), e(p(t), z))}{\dot{e}_1(p(t), z)} \right]^* \quad [5]$$

The maximizing conditions are as follows:

- (i) $p^*(t)$ maximizes \tilde{H} for all t : $\frac{\partial \tilde{H}}{\partial p} = 0$,
- (ii) $\dot{\mu} - r\mu = -\frac{\partial \tilde{H}}{\partial m}$,
- (iii) $\dot{m}^* = \frac{\partial \tilde{H}}{\partial \mu}$ (this just gives back the state equation),
- (iv) $\lim_{t \rightarrow \infty} \mu(t)m(t)e^{-rt} = 0$ (the transversality condition).

The first two conditions are as follows:

$$\frac{\partial \tilde{H}}{\partial p} = 0, \quad [6]$$

and

$$\dot{\mu} - r\mu = -\frac{\partial \tilde{H}}{\partial m} = \dot{\zeta}(m(p(t), e(p(t), z))). \quad [7]$$

When the market is in equilibrium, $\dot{p}(t) = 0$, and the expression $\frac{\partial \tilde{H}}{\partial p}$ boils down to the following (see appendix):

$$p(t) \left[1 + \frac{1}{\text{demand elasticity}} \right] = \dot{\zeta}(m(p(t), e(p(t), z))) \left\{ \frac{\dot{m}_1(p(t), e(p(t), z))}{\dot{q}(p(t))} + \frac{\dot{m}_2(p(t), e(p(t), z)) \dot{e}_1(p(t), z)}{\dot{q}(p(t))} \right\},$$

which suggests that the price equals the marginal cost (the right hand side of the above expression is the marginal cost in a dynamic setting, which is different from that in a static problem on account of the fact that in a dynamic setting the middleman also takes into account the impact of price chosen on his purchase price from the producer) when the demand is infinitely elastic. Now suppose that as a result of a supply shock, if the middleman wants to hold an extra unit of inventory, then the marginal cost of holding an extra unit is higher because the term $\dot{\zeta}(m(p(t), e(p(t), z)))$ is higher at the previous price at that point in time. The term in

parentheses in the expression of the marginal cost, i.e.

$$\frac{\dot{m}_1(p(t), e(p(t), z))}{\dot{q}(p(t))} + \frac{\dot{m}_2(p(t), e(p(t), z)) \dot{e}_1(p(t), z)}{\dot{q}(p(t))}$$

is a function of price and is the same at

the previous price. This implies that on the previous price, now the middleman faces

$$\frac{\partial \tilde{H}}{\partial p} < 0.$$

Therefore, in order to satisfy the condition of dynamic optimization, the middleman must decrease the price for an increase in inventory. This implies a negative relationship between price and inventory. The concept of inventory unifies the market supply and demand. If the supply and demand rates are equal, the market is in a steady state equilibrium. If a difference of finite magnitude is created between the supply and demand rates and the consumer and the producer do not react to a price change induced by a difference in the supply and demand rates, the price will continue changing until the system saturates. This behavior can be depicted by the following formulation:

Price change \propto change in market inventory.

P = price change.

$M = m - m_s$ = change in inventory in the market,

m = inventory at time t ,

m_s = inventory in steady state.

$$\text{Input} - \text{output} = \frac{dm}{dt} = \frac{d(m - m_s)}{dt} = \frac{dM}{dt},$$

$$\text{or } M = \int (\text{input} - \text{output}) dt.$$

Price change $\propto \int (\text{supply rate} - \text{demand rate}) dt$, or

$$P = -K_m \int (\text{supply rate} - \text{demand rate}) dt,$$

where K_m is the proportionality constant; *supply* and *demand rate* is the supply and demand per unit time respectively. A negative sign indicates that when (supply rate – demand rate) is positive, then P is negative (i.e. price decreases). The above equation can be re-arranged as follows:

$$\int (\text{supply rate} - \text{demand rate}) dt = -\frac{P}{K_m}, \text{ or}$$

$$\int (w_i - w_0) dt = -\frac{P}{K_m}, \quad [8]$$

w_i = supply rate,

w_0 = demand rate,

K_m = dimensional constant.

Let at time $t = 0$, *supply rate = demand rate* (market is in a steady state equilibrium), then eq. [8] can be written as

$$\int (w_{is} - w_{0s}) dt = 0. \quad [9]$$

The subscript s indicates the steady state equilibrium and $P = 0$ in steady state. Subtracting eq. [9] from eq. [8], we obtain

$$\int (w_i - w_{is}) dt - \int (w_0 - w_{0s}) dt = -\frac{P}{K_m}, \text{ or}$$

$$\int (W_i - W_0) dt = -\frac{P}{K_m}, \quad [10]$$

where $w_i - w_{is} = W_i$ = change in supply rate, $w_0 - w_{0s} = W_0$ = change in demand rate.

P , W_i and W_0 are deviation variables, which indicate deviation from the steady state equilibrium.

The initial values of the deviation variables are zero. Eq. (10) may also be written as follows:

$$P = -K_m \int W dt = -K_m M, \quad [11]$$

where $W = W_i - W_0$. If P gets a jump as a result of some factor other than an inventory change, such as imposition of a tax on consumer, that is considered as a separate input and can be added to eq. (11) as follows:

$$P = -K_m \int W dt + J = -K_m M + J. \quad [11a]$$

Similarly, there can be an exogenous shock in inventory other than the price feedback.

2.2 Producer

The producer maximizes the present discounted value of the future stream of profits, and his present value at time zero is as follows:

$$V(0) = \int_0^{\infty} [\alpha p(t)F(K(t), L(t)) - w(t)L(t) - \Re(t)I(t)] e^{-rt} dt, \quad [12]$$

α is the fraction of the market price the producer charges to the middleman. r denotes the discount rate. $L(t)$ (labor) and $I(t)$ (level of investment) are the *control variables* and $K(t)$ the *state variable*. The maximization problem can be written as

$$\underset{\{L(t), I(t)\}}{\text{Max}} V(0) = \int_0^{\infty} [\alpha p(t)F(K(t), L(t)) - w(t)L(t) - \Re(t)I(t)] e^{-rt} dt,$$

subject to

$$\dot{K}(t) = I(t) - \delta K(t) \text{ (state equation, describing how the state variable changes with time),}$$

$$K(0) = K_0 \text{ (initial condition),}$$

$$K(t) \geq 0 \text{ (non-negativity constraint on state variable),}$$

$$K(\infty) \text{ free (terminal condition).}$$

The current-value Hamiltonian for this case is

$$\tilde{H} = \alpha p(t)F(K(t), L(t)) - w(t)L(t) - \Re(t)I(t) + \mu(t)[I(t) - \delta K(t)] \quad [13]$$

Now the maximizing conditions are as follows:

$$(i) \ L^*(t) \text{ and } I^*(t) \text{ maximize } \tilde{H} \text{ for all } t: \frac{\partial \tilde{H}}{\partial L} = 0 \text{ and } \frac{\partial \tilde{H}}{\partial I} = 0,$$

$$(ii) \ \dot{\mu} - r\mu = -\frac{\partial \tilde{H}}{\partial K},$$

$$(iii) \ \dot{K}^* = \frac{\partial \tilde{H}}{\partial \mu} \text{ (this just gives back the state equation),}$$

$$(iv) \ \lim_{t \rightarrow \infty} \mu(t)K(t)e^{-rt} = 0 \text{ (the transversality condition).}$$

The first two conditions are as follows:

$$\frac{\partial \tilde{H}}{\partial L} = 0, \quad [14]$$

$$\frac{\partial \tilde{H}}{\partial I} = 0, \quad [15]$$

and

$$\dot{\mu} - r\mu = -\frac{\partial \tilde{H}}{\partial K}. \quad [16]$$

In order to satisfy the condition of dynamic optimization after the price increase, the producer must increase the production level (see appendix). Let p = market price, c = a reference price (such as the retail price which includes the production cost, profit of producer and profit of the middleman). c is a parameter which may vary with time or be kept fixed for a limited time period, e.g. the cost of a product may vary over time or can also remain constant for a while. It is the reference point with respect to which the variation in p is considered by the producer for decision making.

W_m = Change in production due to change in price,

$(p - c)$ acts as an incentive for the producer to produce more. Therefore,

$$W_m \propto \alpha(p - c), \text{ or}$$

$$W_m = K_s(p - c). \quad [17]$$

When the market is in equilibrium, then $W_m = 0$, or

$$0 = K_s(p_s - c_s). \quad [18]$$

K_s is the proportionality constant. p_s and c_s are the steady state equilibrium values. Subtracting eq. [18] from eq. [17],

$$W_m = K_s[(p - p_s) - (c - c_s)] = -K_s(C - P) = -K_s\epsilon, \quad [19]$$

where W_m , C and P are deviation variables.

2.3 Consumer

The consumer maximizes the present discounted value of the future stream of utilities, and his present value at time zero is as follows:

$$V(0) = \int_0^{\infty} U(x(t))e^{-\rho t} dt, \quad [20]$$

where ρ denotes the discount rate and $x(t)$ is the *control variable*. The maximization problem can be written as

$$\text{Max}_{\{x(t)\}} V(0) = \int_0^{\infty} U(x(t))e^{-\rho t} dt,$$

subject to

$\dot{a}(t) = R(t)a(t) + w(t) - p(t)x(t)$ (state equation, describing how the state variable changes with time). $a(t)$ is asset holdings (a *state variable*) and $w(t)$ and $R(t)$ are exogenous time path of wages and return on assets.

$a(0) = a_s$ (initial condition),

$a(t) \geq 0$ (non-negativity constraint on state variable),

$a(\infty)$ free (terminal condition).

The current-value Hamiltonian for this case is

$$\tilde{H} = U(x(t)) + \mu(t)[R(t)a(t) + w(t) - p(t)x(t)] \quad [21]$$

Now the maximizing conditions are as follows:

$$(i) \ x^*(t) \text{ maximizes } \tilde{H} \text{ for all } t: \frac{\partial \tilde{H}}{\partial x} = 0,$$

$$(ii) \ \dot{\mu} - \rho\mu = -\frac{\partial \tilde{H}}{\partial a},$$

$$(iii) \ \dot{a}^* = \frac{\partial \tilde{H}}{\partial \mu} \text{ (this just gives back the state equation),}$$

$$(iv) \ \lim_{t \rightarrow \infty} \mu(t)a(t)e^{-\rho t} = 0 \text{ (the transversality condition).}$$

The first two conditions are as follows:

$$\frac{\partial \tilde{H}}{\partial x} = \dot{U}(x(t)) - \mu(t)p(t) = 0, \quad [22]$$

and

$$\dot{\mu} - \rho\mu = -\frac{\partial \tilde{H}}{\partial a} = -\mu(t)R(t). \quad [23]$$

If the price of good x increases, the consumer faces (at the previous level of consumption)

$$\frac{\partial \tilde{H}}{\partial x} = \dot{U}(x(t)) - \mu(t)p(t) < 0.$$

Therefore in order to satisfy the condition of dynamic optimization after the price increase, the consumer must decrease the consumption of good x . Let the change in demand be proportional to the change in price, i.e. P . Then we can write:

Change in demand $\propto P$, or

$$W_d = -K_d P. \quad [24]$$

W_d is the change in demand due to P ; when P is positive W_d is negative.

3. Solution of the model with a quantity tax

The solution of the model can be written as

$$\frac{dP(t)}{dt} + K_m(K_s + K_d)P(t) = K_m K_s C(t). \quad [25]$$

If $C(t) = T$, i.e. the government imposes a per unit tax on producer at $t = 0$, then the above differential equation becomes as follows:

$$\frac{dP(t)}{dt} + K_m(K_s + K_d)P(t) = K_m K_s T. \quad [26]$$

The Routh–Hurwitz stability criterion (which provides a necessary and sufficient condition for stability of a linear dynamical system) for the stability of the above differential equation is $K_m(K_s + K_d) > 0$, which holds as K_m , K_s and K_d are all defined to be positive. This ensures that, away from a given initial equilibrium, every adjustment mechanism will lead to another equilibrium. Now let's look at the dynamics of the price if the quantity tax is imposed on the buyer

instead. The market price is the buyer's price as before, however, the producer will be taking into account the price before tax for his/ her production decisions. Therefore,

$$\varepsilon(t) = T - P(t). \quad [27]$$

This implies that

$$\frac{dP(t)}{dt} + K_m(K_s + K_d)P(t) = K_m K_s T,$$

which is the same as eq. [26]. The solution of the above differential equation with initial conditions of a buyer's tax is as follows: The solution has the form

$$P(t) = C_1 + C_2 e^{-[K_m(K_s + K_d)]t}. \quad [28]$$

Substituting the values of C_1 and C_2 in eq. [28] we obtain

$$P(t) = \frac{K_s T}{K_s + K_d} + \frac{K_d T}{K_s + K_d} e^{-[K_m(K_s + K_d)]t}. \quad [29]$$

When $t = 0$, $P(0) = T$ (the initial condition), and when $t = \infty$, $P(\infty) = \frac{K_s T}{K_s + K_d}$ (the final steady state equilibrium value). In the final equilibrium, the quantity demanded must equal the quantity supplied, which holds (see appendix).

4. An optimal quantity tax path

The efficiency loss as a result of a tax, generally mentioned in the economics literature is the dead weight loss as a result of comparisons of the pre and post tax market equilibriums. However, the dynamic picture shows that there is some efficiency loss on the dynamic adjustment path to the new equilibrium as well after the tax. After the imposition of the tax, the price jumps to a price equal to the previous equilibrium price plus the tax. The price then adjusts over time to bring the new equilibrium price which is higher than the previous equilibrium price and less than the price at the time the tax was imposed depending on the elasticity of demand and supply schedules. A pile up of inventory indicates a higher supply than demand, and a depletion of inventory occurs when demand is higher than the supply in a given time period. When the demand and supply are the same, there is no efficiency loss. If the demand and supply are different, the output and/ or consumption is being lost at that point in time. Therefore if we sum up the inventory change at all points in time, we get the total efficiency loss, which is as follows:

$$EL = \int_0^{\infty} M(t) dt. \quad [30]$$

Eq. [30] can be written as

$$EL = -\frac{1}{K_m} \int_0^{\infty} [P(t) - T - K_d K_m T] dt. \quad [30a]$$

In Figure 3, the inventory difference jumps to $K_d T$, i.e. the decrease in demand because of tax at $t = 0$. The demand does not equal the supply any longer, and the market forces come into play. The inventory along with the price adjusts over time and arrives at the new equilibrium, i.e. $M(\infty)$. The shaded area is the efficiency loss (the amount of output and/ or consumption lost) during the adjustment process. The area between the lines $M(t) = 0$, and $M(t) = M(\infty)$ is the efficiency loss resulting from a difference in pre and post tax market equilibriums. The expression for the tax revenue is as follows:

$$TR = T[w_{id}(0) - K_d P(t)]. \quad [31]$$

If we want to minimize the efficiency loss subject to the constraint that tax revenue generated is greater than or equal to G in a given time period, our problem is as follows:

$$\min_T EL \text{ s.t. } TR \geq G.$$

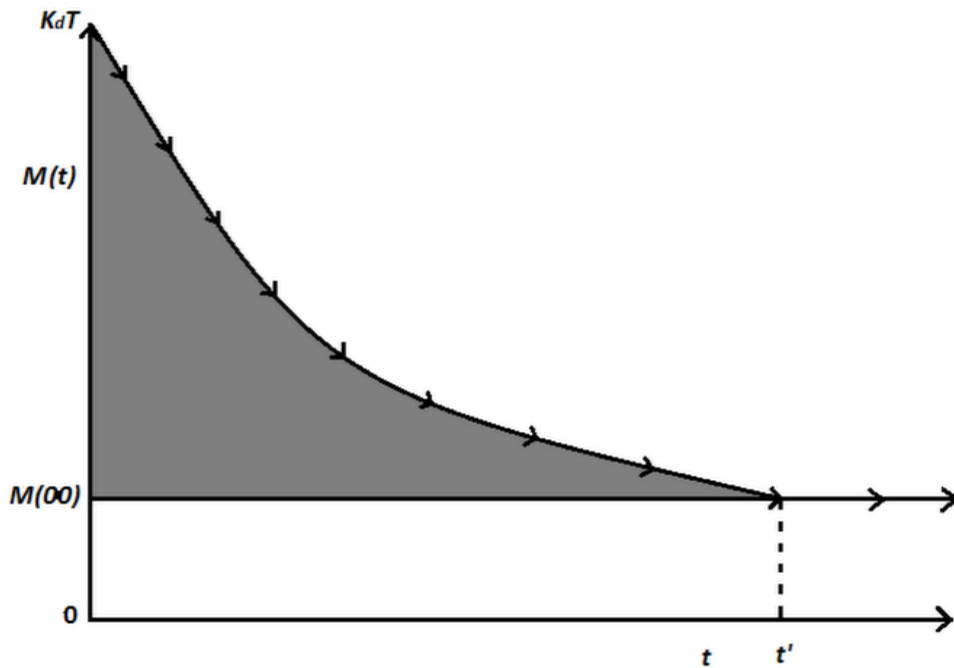


Figure 3. Dynamic efficiency loss because of a quantity tax

The choice variable is the tax rate, and the constraint is binding. The Lagrangian for the above problem is as follows:

$$\begin{aligned} \mathcal{L} &= -\frac{1}{K_m} \int_0^{\infty} [P(t) - T - K_m K_d T] dt + \lambda [G - T[w_{id}(0) - K_d P(t)]] \\ &= \int_0^{\infty} \left[\frac{-K_s T}{K_m(K_s + K_d)} - \frac{K_d T}{K_m(K_s + K_d)} e^{-[K_m(K_s + K_d)]t} + \frac{T}{K_m} + K_d T \right] dt \\ &\quad + \lambda \left[G - T \left[w_{id}(0) - K_d \left\{ \frac{K_s T}{K_s + K_d} + \frac{K_d T}{K_s + K_d} e^{-[K_m(K_s + K_d)]t} \right\} \right] \right]. \end{aligned}$$

Taking the first order condition with respect to T , we get:

$$T = \frac{\lambda w_{id}(0) - \int_0^{\infty} \left[K_d + \frac{1}{K_m} - \frac{K_s}{K_m(K_s + K_d)} - \frac{K_d}{K_m(K_s + K_d)} e^{-[K_m(K_s + K_d)]t} \right] dt}{2\lambda K_d \left[\frac{K_s}{K_s + K_d} + \frac{K_d}{K_s + K_d} e^{-[K_m(K_s + K_d)]t} \right]}. \quad [32]$$

Taking the first order condition with respect to λ , we get:

$$G - T \left[w_{id}(0) - K_d \left\{ \frac{K_s T}{K_s + K_d} + \frac{K_d T}{K_s + K_d} e^{-[K_m(K_s + K_d)]t} \right\} \right] = 0. \quad [33]$$

Eq. [32] can also be written as

$$T = \frac{\lambda w_{id}(0) - J}{2\lambda Q}. \quad [34]$$

Substituting the value of λ into eq. [34], we obtain

$$T(t) = \frac{w_{id}(0) - \sqrt{w_{id}^2(0) - 4QG}}{2Q}. \quad [35]$$

A negative optimal tax is an optimal subsidy. The second order condition for minimization has been checked (see appendix). Suppose that the government wants to generate a revenue of \$1000 by imposing tax on a certain good. The initial equilibrium quantity of that good is 100, and the value of each one of K_m , K_s and K_d is equal to one. Substituting these values in eq. [35] yields

$$T(0) = \frac{100 - \sqrt{10000 - 4000}}{2} = 11.27,$$

where $Q = 0.5 + 0.5e^{-2t}$, and at $t = 0$, $Q = 1$. The tax revenue generated is

$TR = T[w_{id}(0) - QT] = 1000$. Now when $t = \infty$, $Q = 0.5$. This implies that

$$T(\infty) = \frac{100 - \sqrt{10000 - 2000}}{1} = 10.56.$$

The tax revenue is again 1000 as desired. Therefore the optimal quantity taxation is that the government should impose a tax rate of \$11.27 per unit quantity initially and then gradually decrease the tax rate over time up to a final tax rate of \$10.56 per unit quantity of the same good.

5. Conclusions

When a government imposes a quantity/ commodity tax on the consumer, the price jumps to the pre tax equilibrium price plus the amount of the tax. The demand and supply adjust over time to bring the new post tax equilibrium. As a result of a tax, there are efficiency losses during the adjustment process as well as the new post tax equilibrium as compared to the pre-tax efficient equilibrium. It is important to take into consideration the efficiency losses during the adjustment process as well while deriving an optimal tax schedule. Eq. (35) gives an optimal quantity tax path over time which generates the same desired revenue at any given point in time considering the adjustment of demand and supply over time. The expression is a function of the slopes of the demand, supply and the inventory curves, and the initial pre-tax equilibrium quantity. The expression is much more complex as compared to the optimal tax expression of Ramsey, where he takes into account the efficiency losses just in the final equilibrium.

Regarding further research, a complete dynamic welfare analysis against various governmental policies, such as value added tax, income tax, toll tax, corporate tax, environmental tax, etc. can be carried out and the optimal governmental policy instruments can be derived following the methodology developed in this paper.

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Appendix

Dynamic problem of the Middleman

In a dynamic setting, the middleman maximizes the present discounted value of the future stream of profits, and his present value at time zero is as follows:

$$V(0) = \int_0^{\infty} [pq(p) - \zeta(m(p, e))] e^{-rt} dt, \quad [36]$$

where r denotes the discount rate, $p(t)$ is the *control variable* and $m(t)$ the *state variable*. The maximization problem can be written as

$$\text{Max}_{\{p(t)\}} V(0) = \int_0^{\infty} [pq(p) - \zeta(m(p, e))] e^{-rt} dt,$$

subject to the constraints that

$$\dot{m}(t) = \dot{m}_1(p(t), e(p(t), z)) \dot{p}(t) + \dot{m}_2(p(t), e(p(t), z)) \dot{e}_1(p(t), z) \dot{p}(t) \quad (\text{state equation,}$$

describing how the state variable changes with time; z are exogenous factors),

$$m(0) = m_s \quad (\text{initial condition}),$$

$$m(t) \geq 0 \quad (\text{non-negativity constraint on state variable}),$$

$$m(\infty) \text{ free (terminal condition).}$$

The current-value Hamiltonian for this case is

$$\tilde{H} = p(t)q(p(t)) - \zeta(m(p(t), e(p(t), z))) + \mu(t) \dot{p}(t) \begin{bmatrix} \dot{m}_1(p(t), e(p(t), z)) + \dot{m}_2(p(t), e(p(t), z)) * \\ \dot{e}_1(p(t), z) \end{bmatrix} \quad [37]$$

the maximizing conditions are as follows:

$$(i) \quad p^*(t) \text{ maximizes } \tilde{H} \text{ for all } t: \frac{\partial \tilde{H}}{\partial p} = 0,$$

$$(ii) \quad \dot{\mu} - r\mu = -\frac{\partial \tilde{H}}{\partial m},$$

$$(iii) \quad \dot{m}^* = \frac{\partial \tilde{H}}{\partial \mu} \quad (\text{this just gives back the state equation}),$$

$$(iv) \quad \lim_{t \rightarrow \infty} \mu(t)m(t)e^{-rt} = 0 \quad (\text{the transversality condition}).$$

The first two conditions are

$$\begin{aligned} \frac{\partial \tilde{H}}{\partial p} = & q(p(t)) + p(t) \dot{q}(p(t)) - \dot{\zeta}(m(p(t), e(p(t), z))) \left\{ \frac{\dot{m}_1(p(t), e(p(t), z)) + \dot{m}_2(p(t), e(p(t), z)) *}{\dot{e}_1(p(t), z)} \right\} \\ & + \mu(t) p(t) * \left[\frac{\ddot{m}_{11}(p(t), e(p(t), z)) + \dot{m}_{12}(p(t), e(p(t), z)) \dot{e}_1(p(t), z) +}{m_{21}(p(t), e(p(t), z)) \dot{e}_1(p(t), z) + m_{22}(p(t), e(p(t), z)) \dot{e}_1(p(t), z)} \right] = 0 \end{aligned} \quad [38]$$

and

$$\dot{\mu} - r\mu = - \frac{\partial \tilde{H}}{\partial m} = \dot{\zeta}(m(p(t), e(p(t), z))). \quad [39]$$

When the market is in equilibrium, $\dot{p}(t) = 0$, and the expression $\frac{\partial \tilde{H}}{\partial p}$ boils down to the following:

$$\begin{aligned} q(p(t)) + p(t) \dot{q}(p(t)) - \dot{\zeta}(m(p(t), e(p(t), z))) \left\{ \frac{\dot{m}_1(p(t), e(p(t), z)) + \dot{m}_2(p(t), e(p(t), z)) *}{\dot{e}_1(p(t), z)} \right\} &= 0, \\ p(t) \dot{q}(p(t)) + q(p(t)) = \dot{\zeta}(m(p(t), e(p(t), z))) \left\{ \frac{\dot{m}_1(p(t), e(p(t), z)) + \dot{m}_2(p(t), e(p(t), z)) *}{\dot{e}_1(p(t), z)} \right\}, \\ p(t) \left[1 + \frac{1}{\text{demand elasticity}} \right] = \dot{\zeta}(m(p(t), e(p(t), z))) \left\{ \frac{\dot{m}_1(p(t), e(p(t), z))}{\dot{q}(p(t))} + \frac{\dot{m}_2(p(t), e(p(t), z)) \dot{e}_1(p(t), z)}{\dot{q}(p(t))} \right\}, \end{aligned}$$

suggesting that the price equals the marginal cost (the right hand side of the above expression is the marginal cost in a dynamic setting, which is different from that in a static problem on account of the fact that in a dynamic setting the middleman also takes into account the impact of price chosen on his purchase price from the producer) when the demand is infinitely elastic. Now suppose that as a result of a supply shock, if the middleman wants to hold an extra unit of inventory, then the marginal cost of holding an extra unit is higher because the term $\dot{\zeta}(m(p(t), e(p(t), z)))$ is higher at the previous price at that point in time. The term in parentheses in the expression of the marginal cost, i.e.

$$\frac{\dot{m}_1(p(t), e(p(t), z))}{\dot{q}(p(t))} + \frac{\dot{m}_2(p(t), e(p(t), z)) \dot{e}_1(p(t), z)}{\dot{q}(p(t))}$$

is a function of price and is the same at the previous price. This implies that on the previous price, now the middleman faces

$$\frac{\partial \tilde{H}}{\partial p} = q(p(t)) + p(t) \dot{q}(p(t)) - \zeta(m(p(t), e(p(t), z))) \left\{ \begin{matrix} \dot{m}_1(p(t), e(p(t), z)) + \dot{m}_2(p(t), e(p(t), z)) * \\ e_1(p(t), z) \end{matrix} \right\} \\ + \mu(t) \dot{p}(t) * \left[\begin{matrix} \ddot{m}_{11}(p(t), e(p(t), z)) + \dot{m}_{12}(p(t), e(p(t), z)) \dot{e}_1(p(t), z) + \\ \dot{m}_{21}(p(t), e(p(t), z)) \dot{e}_1(p(t), z) + \dot{m}_{22}(p(t), e(p(t), z)) \dot{e}_1(p(t), z) \end{matrix} \right] < 0.$$

Therefore in order to satisfy the condition of dynamic optimization, the middleman must decrease the price for an increase in inventory. This implies a negative relationship between price and inventory. The concept of inventory unifies the market supply and demand. If the supply and demand rates are equal, the market is in a steady state equilibrium. If a difference of finite magnitude is created between the supply and demand rates and the consumer and the producer do not react to a price change induced by a difference in the supply and demand rates, the price will continue changing until the system saturates. This behavior can be depicted by the following formulation:

Price change \propto change in market inventory.

P = price change.

$M = m - m_s$ = change in inventory in the market,

m = inventory at time t ,

m_s = inventory in steady state.

$$\text{Input} - \text{output} = \frac{dm}{dt} = \frac{d(m - m_s)}{dt} = \frac{dM}{dt},$$

$$\text{or } M = \int (\text{input} - \text{output}) dt.$$

Price change $\propto \int (\text{supply rate} - \text{demand rate}) dt$, or

$$P = -K_m \int (\text{supply rate} - \text{demand rate}) dt,$$

where K_m is the proportionality constant. A negative sign indicates that when $(\text{supply rate} - \text{demand rate})$ is positive, then P is negative (i.e. price decreases). The above equation can be re-arranged as follows:

$$\int (\text{supply rate} - \text{demand rate}) dt = -\frac{P}{K_m}, \text{ or}$$

$$\int (w_i - w_0) dt = -\frac{P}{K_m}, \quad [40]$$

w_i = supply rate,

w_0 = demand rate,

K_m = dimensional constant.

Let at time $t = 0$, *supply rate = demand rate* (market is in a steady state equilibrium), then eq. (40) can be written as

$$\int (w_{is} - w_{0s}) dt = 0. \quad [41]$$

The subscript s indicates the steady state equilibrium and $P = 0$ in steady state. Subtracting eq. (41) from eq. (40), we get:

$$\int (w_i - w_{is}) dt - \int (w_0 - w_{0s}) dt = -\frac{P}{K_m}, \text{ or}$$

$$\int (W_i - W_0) dt = -\frac{P}{K_m}, \quad [42]$$

where $w_i - w_{is} = W_i$ = change in supply rate, $w_0 - w_{0s} = W_0$ = change in demand rate.

P , W_i and W_0 are deviation variables, which indicate deviation from the steady state equilibrium.

The initial values of the deviation variables are zero. Eq. (42) may also be written as follows:

$$P = -K_m \int W dt = -K_m M, \quad [43]$$

where $W = W_i - W_0$. If P gets a jump as a result of some factor other than an inventory change, such as imposition of a tax on consumer, that is considered as a separate input and can be added to eq. (43) as follows:

$$P = -K_m \int W dt + J = -K_m M + J. \quad [43a]$$

Similarly, there can be an exogenous shock in inventory other than the price feedback.

Producer

The producer maximizes the present discounted value of the future stream of profits, and his present value at time zero is as follows:

$$V(0) = \int_0^{\infty} [\alpha p(t)F(K(t), L(t)) - w(t)L(t) - \Re(t)I(t)] e^{-rt} dt, \quad [44]$$

where α is the fraction of the market price the producer charges to the middleman. r denotes the discount rate. $L(t)$ (labor) and $I(t)$ (level of investment) are the *control variables* and $K(t)$ the *state variable*. The maximization problem can be written as

$$\underset{\{L(t), I(t)\}}{\text{Max}} V(0) = \int_0^{\infty} [\alpha p(t)F(K(t), L(t)) - w(t)L(t) - \Re(t)I(t)] e^{-rt} dt,$$

subject to the constraints

$$\dot{K}(t) = I(t) - \delta K(t) \text{ (state equation, describing how the state variable changes with time),}$$

$$K(0) = K_0 \text{ (initial condition),}$$

$$K(t) \geq 0 \text{ (non-negativity constraint on state variable),}$$

$$K(\infty) \text{ free (terminal condition).}$$

The current-value Hamiltonian for this case is

$$\tilde{H} = \alpha p(t)F(K(t), L(t)) - w(t)L(t) - \Re(t)I(t) + \mu(t)[I(t) - \delta K(t)] \quad [45]$$

Now the maximizing conditions are as follows:

$$(i) \ L^*(t) \text{ and } I^*(t) \text{ maximize } \tilde{H} \text{ for all } t: \frac{\partial \tilde{H}}{\partial L} = 0 \text{ and } \frac{\partial \tilde{H}}{\partial I} = 0,$$

$$(ii) \ \dot{\mu} - r\mu = -\frac{\partial \tilde{H}}{\partial K},$$

$$(iii) \ \dot{K}^* = \frac{\partial \tilde{H}}{\partial \mu} \text{ (this just gives back the state equation),}$$

$$(iv) \ \lim_{t \rightarrow \infty} \mu(t)K(t)e^{-rt} = 0 \text{ (the transversality condition).}$$

The first two conditions are as follows:

$$\frac{\partial \tilde{H}}{\partial L} = \alpha p(t)F_2(K(t), L(t)) - w(t) = 0, \quad [46]$$

$$\frac{\partial \tilde{H}}{\partial I} = -\Re(t) + \mu(t) = 0, \quad [47]$$

and

$$\dot{\mu} - r\mu = -\frac{\partial \tilde{H}}{\partial K} = -\left[\alpha p(t) \dot{F}_1(K(t), L(t)) - \delta \mu(t)\right]. \quad [48]$$

Substituting the value of $\dot{\mu}$ and μ from eq. (47) into eq. (48) yields

$$\alpha p(t) \dot{F}_1(K(t), L(t)) - (r + \delta)\mathfrak{R}(t) + \dot{\mathfrak{R}}(t) = 0.$$

If the price, i.e. $p(t)$ goes up, (at the previous level of investment and labor) the producer faces

$$\alpha p(t) \dot{F}_2(K(t), L(t)) - w(t) > 0,$$

$$\alpha p(t) \dot{F}_1(K(t), L(t)) - (r + \delta)\mathfrak{R}(t) + \dot{\mathfrak{R}}(t) > 0.$$

Therefore, in order to satisfy the condition of dynamic optimization after the price increase, the producer must increase the production level. Let p = market price, c = a reference price (such as the retail price which includes the production cost, profit of producer and profit of the middleman). c is a parameter which may vary with time or be kept fixed for a limited time period, e.g. the cost of a product may vary over time or can also remain constant for a while. It is the reference point with respect to which the variation in p is considered by the producer for decision making.

W_m = Change in production due to change in price,

where $(p - c)$ acts as an incentive for the producer to produce more. Therefore,

$$W_m \propto \alpha(p - c), \text{ or}$$

$$W_m = K_s(p - c). \quad [49]$$

When the market is in equilibrium, then $W_m = 0$, or

$$0 = K_s(p_s - c_s). \quad [50]$$

where K_s is the proportionality constant. p_s and c_s are the steady state equilibrium values.

Subtracting eq. (50) from eq. (49), we get:

$$W_m = K_s[(p - p_s) - (c - c_s)] = -K_s(C - P) = -K_s\mathcal{E}, \quad [51]$$

where W_m , C and P are deviation variables.

Consumer

The consumer maximizes the present discounted value of the future stream of utilities, and his present value at time zero is as follows:

$$V(0) = \int_0^{\infty} U(x(t))e^{-\rho t} dt, \quad [52]$$

where ρ denotes the discount rate and $x(t)$ is the *control variable*. The maximization problem can be written as

$$\text{Max}_{\{x(t)\}} V(0) = \int_0^{\infty} U(x(t))e^{-\rho t} dt,$$

subject to

$\dot{a}(t) = R(t)a(t) + w(t) - p(t)x(t)$ (state equation, describing how the state variable changes with time). $a(t)$ is asset holdings (a *state variable*) and $w(t)$ and $R(t)$ are exogenous time path of wages and return on assets.

$a(0) = a_s$ (initial condition),

$a(t) \geq 0$ (non-negativity constraint on state variable),

$a(\infty)$ free (terminal condition).

The current-value Hamiltonian for this case is

$$\tilde{H} = U(x(t)) + \mu(t)[R(t)a(t) + w(t) - p(t)x(t)]. \quad [53]$$

The maximizing conditions are as follows:

- (i) $x^*(t)$ maximizes \tilde{H} for all t : $\frac{\partial \tilde{H}}{\partial x} = 0$,
- (ii) $\dot{\mu} - \rho\mu = -\frac{\partial \tilde{H}}{\partial a}$,
- (iii) $\dot{a}^* = \frac{\partial \tilde{H}}{\partial \mu}$ (this just gives back the state equation),
- (iv) $\lim_{t \rightarrow \infty} \mu(t)a(t)e^{-\rho t} = 0$ (the transversality condition).

The first two conditions are as follows:

$$\frac{\partial \tilde{H}}{\partial x} = U'(x(t)) - \mu(t)p(t) = 0, \quad [54]$$

and

$$\dot{\mu} - \rho\mu = -\frac{\partial \tilde{H}}{\partial a} = -\mu(t)R(t). \quad [55]$$

If the price of good x goes up, the consumer faces (at the previous level of consumption)

$$\frac{\partial \tilde{H}}{\partial x} = \dot{U}(x(t)) - \mu(t)p(t) < 0.$$

Therefore, in order to satisfy the condition of dynamic optimization after the price increase, the consumer must decrease the consumption of good x . Let the change in demand be proportional to the change in price, i.e. P . Then we can write:

Change in demand $\propto P$, or

$$W_d = -K_d P. \quad [56]$$

where W_d is the change in demand due to P ; when P is positive W_d is negative.

Solution of the model with a quantity tax

From eqs. (11a), (19) and (24) we have the following expressions:

$$\frac{dP(t)}{dt} = -K_m W(t),$$

$$W_m(t) = -K_s \varepsilon(t),$$

$$\varepsilon(t) = C(t) - P(t),$$

$$W_d(t) = -K_d P(t),$$

and

$$W(t) = W_m(t) - W_d(t),$$

if there is no exogenous change in supply and demand. From the above equations, we obtain

$$\begin{aligned} \frac{dP(t)}{dt} &= -K_m [W_m(t) - W_d(t)] \\ &= -K_m [-K_s \varepsilon(t) + K_d P(t)] \\ &= -K_m [-K_s C(t) + (K_s + K_d)P(t)] \end{aligned}$$

The above expression can be rearranged as follows:

$$\frac{dP(t)}{dt} + K_m (K_s + K_d) P(t) = K_m K_s C(t). \quad [57]$$

If $C(t) = T$, i.e. the government imposes a per unit tax on producer at $t = 0$, then the above differential equation becomes as follows:

$$\frac{dP(t)}{dt} + K_m(K_s + K_d)P(t) = K_m K_s T. \quad [58]$$

Now let's look at the dynamics of the price if the quantity tax is imposed on the buyer instead. We start from the same expressions as we did for a producer's tax, i.e.

$$\frac{dP(t)}{dt} = -K_m[W_m(t) - W_d(t)],$$

$$W_m(t) = -K_s \varepsilon(t),$$

$$W_d(t) = -K_d P(t).$$

The market price is the buyer's price as before, however, the producer will be taking into account the price before tax for his/her production decisions. Therefore,

$$\varepsilon(t) = T - P(t). \quad [59]$$

This implies that

$$\frac{dP(t)}{dt} = -K_m[K_s\{P(t) - T\} + K_d P(t)],$$

$$\frac{dP(t)}{dt} + K_m(K_s + K_d)P(t) = K_m K_s T,$$

which is the same as eq. [58]. In order to solve the above differential equation with initial conditions of a buyer's tax, we proceed as follows.

The characteristic function of the differential equation is

$$x + K_m(K_s + K_d) = 0.$$

The characteristic function has a single root given by

$$x = -K_m(K_s + K_d).$$

Thus, the complementary solution is

$$P_c(t) = C_2 e^{-[K_m(K_s + K_d)]t}.$$

The particular solution has the form

$$P_p(t) = C_1.$$

Thus, the solution has the form

$$P(t) = C_1 + C_2 e^{-[K_m(K_s + K_d)]t}. \quad [60]$$

The constant C_1 is determined by substitution into the differential equation:

$$-K_m(K_s + K_d)C_2 e^{-[K_m(K_s + K_d)]t} + K_m(K_s + K_d)C_1 + K_m(K_s + K_d)C_2 e^{-[K_m(K_s + K_d)]t} = K_m K_s T,$$

$$C_1 = \frac{K_s T}{K_s + K_d}.$$

C_2 is determined by the initial condition by

$$P(0) = \frac{K_s T}{K_s + K_d} + C_2 = T,$$

$$\begin{aligned} C_2 &= T - \frac{K_s T}{K_s + K_d} \\ &= \frac{K_s T + K_d T - K_s T}{K_s + K_d} \\ &= \frac{K_d T}{K_s + K_d}. \end{aligned}$$

Substituting the values of C_1 and C_2 in eq. (60), we obtain

$$P(t) = \frac{K_s T}{K_s + K_d} + \frac{K_d T}{K_s + K_d} e^{-[K_m(K_s + K_d)]t}. \quad [61]$$

When $t = 0$, $P(0) = T$ (the initial condition), and when $t = \infty$, $P(\infty) = \frac{K_s T}{K_s + K_d}$ (the final steady state equilibrium value). In the final equilibrium, the quantity demanded must equal the quantity supplied. In order to verify that this holds, we proceed as follows: From eq. [56], the change in demand due to a change in price after the tax is as follows:

$$\begin{aligned} W_d(t) &= -K_d P(t), \\ \text{or } w_{nd}(t) - w_{id}(0) &= -K_d P(t), \end{aligned}$$

where $w_{id}(0)$ is the initial demand and $w_{nd}(t)$ is the new demand after tax, because $W_d(t)$ is a deviation variable, i.e. deviation from the initial equilibrium value. Similarly from eq. [51], for the supply

$$\begin{aligned} W_m(t) &= -K_s \varepsilon(t), \\ w_{nm}(t) - w_{im}(0) &= -K_s [T - P(t)] \end{aligned}$$

In the final equilibrium

$$\begin{aligned} w_{nm}(\infty) &= w_{nd}(\infty), \text{ or} \\ w_{im}(0) - K_s [T - P(\infty)] &= w_{id}(0) - K_d P(\infty), \end{aligned}$$

which holds as in the initial equilibrium, the quantity demanded equals the quantity supplied, i.e.

$$w_{im}(0) = w_{id}(0).$$

An optimal quantity tax path

The efficiency loss as a result of a tax, generally mentioned in the economics literature is the dead weight loss as a result of comparisons of the pre and post tax market equilibriums. However, the dynamic picture shows that there is some efficiency loss on the dynamic adjustment path to the new equilibrium as well after the tax. After the imposition of the tax, the price jumps to a price equal to the previous equilibrium price plus the tax. The price then adjusts over time to bring the new equilibrium price which is higher than the previous equilibrium price and less than the price at the time the tax was imposed depending on the elasticity of demand and supply schedules. A pile up of inventory indicates a higher supply than demand, and a depletion of inventory occurs when demand is higher than the supply in a given time period. When the demand and supply are the same, there is no efficiency loss. If the demand and supply are different, the output and/ or consumption is being lost at that point in time. Therefore if we sum up the inventory change at all points in time, we get the total efficiency loss, which is as follows:

$$EL = \int_0^{\infty} M(t) dt. \quad [62]$$

From eq. [43a], we have

$$P(t) = -K_m M(t) + J.$$

The value of J can be found by imposing the initial conditions, i.e. $P(0) = T$, and $M(0) = K_d T$ (the decrease in demand because of tax at $t = 0$ from eq. (56)), therefore $J = T + K_m K_d T$. Substituting the value of J in eq. (43a), we get

$$P(t) = -K_m M(t) + T + K_m K_d T,$$

and eq. [62] can be written as

$$EL = -\frac{1}{K_m} \int_0^{\infty} [P(t) - T - K_m K_d T] dt. \quad [62.a]$$

In Figure 3, the inventory difference jumps to $K_d T$, i.e. the decrease in demand because of tax at $t = 0$. The demand does not equal the supply any longer, and the market forces come into play. The inventory along with the price adjusts over time and arrives at the new equilibrium, i.e. $M(\infty)$. The shaded area is the efficiency loss (the amount of output and/ or consumption lost)

during the adjustment process. The area between the lines $M(t) = 0$, and $M(t) = M(\infty)$ is the efficiency loss resulting from a difference in pre and post tax market equilibriums. From eq. [56], the change in demand due to a change in price after the tax is as follows:

$$W_d(t) = -K_d P(t),$$

$$\text{or } w_{nd}(t) - w_{id}(0) = -K_d P(t),$$

where $w_{id}(0)$ is the initial demand and $w_{nd}(t)$ is the new demand after tax, because $W_d(t)$ is a deviation variable, i.e. deviation from the initial equilibrium value. Therefore the expression for the tax revenue is as follows:

$$TR = T[w_{id}(0) - K_d P(t)] \quad [63]$$

If we want to minimize the efficiency loss subject to the constraint that tax revenue generated is greater than or equal to G in a given time period, our problem is as follows:

$$\min_T EL \text{ s.t. } TR \geq G.$$

The choice variable is the tax rate, and the constraint is binding. The Lagrangian for the above problem is as follows:

$$\begin{aligned} L &= -\frac{1}{K_m} \int_0^\infty [P(t) - T - K_m K_d T] dt + \lambda [G - T[w_{id}(0) - K_d P(t)]] \\ &= \int_0^\infty \left[\frac{-K_s T}{K_m (K_s + K_d)} - \frac{K_d T}{K_m (K_s + K_d)} e^{-[K_m (K_s + K_d)]t} + \frac{T}{K_m} + K_d T \right] dt \\ &\quad + \lambda \left[G - T \left[w_{id}(0) - K_d \left\{ \frac{K_s T}{K_s + K_d} + \frac{K_d T}{K_s + K_d} e^{-[K_m (K_s + K_d)]t} \right\} \right] \right]. \end{aligned}$$

Taking the first order condition with respect to T , we get:

$$\begin{aligned} &\int_0^\infty \left[\frac{-K_s}{K_m (K_s + K_d)} - \frac{K_d}{K_m (K_s + K_d)} e^{-[K_m (K_s + K_d)]t} + \frac{1}{K_m} + K_d \right] dt \\ &- \lambda \left[w_{id}(0) - TK_d \left\{ \frac{K_s}{K_s + K_d} + \frac{K_d}{K_s + K_d} e^{-[K_m (K_s + K_d)]t} \right\} \right] \\ &\quad + \lambda TK_d \left[\frac{K_s}{K_s + K_d} + \frac{K_d}{K_s + K_d} e^{-[K_m (K_s + K_d)]t} \right] = 0. \end{aligned}$$

This implies

$$\int_0^{\infty} \left[K_d + \frac{1}{K_m} - \frac{K_s}{K_m(K_s + K_d)} - \frac{K_d}{K_m(K_s + K_d)} e^{-[K_m(K_s + K_d)]t} \right] dt$$

$$+ 2\lambda TK_d \left[\frac{K_s}{K_s + K_d} + \frac{K_d}{K_s + K_d} e^{-[K_m(K_s + K_d)]t} \right]$$

$$= \lambda w_{id}(0),$$

or

$$T = \frac{\lambda w_{id}(0) - \int_0^{\infty} \left[K_d + \frac{1}{K_m} - \frac{K_s}{K_m(K_s + K_d)} - \frac{K_d}{K_m(K_s + K_d)} e^{-[K_m(K_s + K_d)]t} \right] dt}{2\lambda K_d \left[\frac{K_s}{K_s + K_d} + \frac{K_d}{K_s + K_d} e^{-[K_m(K_s + K_d)]t} \right]}. \quad [64]$$

Taking the first order condition with respect to λ , we get:

$$G - T \left[w_{id}(0) - K_d \left\{ \frac{K_s T}{K_s + K_d} + \frac{K_d T}{K_s + K_d} e^{-[K_m(K_s + K_d)]t} \right\} \right] = 0. \quad [65]$$

Substituting the value of T from eq. [64] into [65],

$$G = w_{id}(0) \cdot \frac{\lambda w_{id}(0) - \int_0^{\infty} \left[K_d + \frac{1}{K_m} - \frac{K_s}{K_m(K_s + K_d)} - \frac{K_d}{K_m(K_s + K_d)} e^{-[K_m(K_s + K_d)]t} \right] dt}{2\lambda K_d \left[\frac{K_s}{K_s + K_d} + \frac{K_d}{K_s + K_d} e^{-[K_m(K_s + K_d)]t} \right]}$$

$$- K_d \left\{ \frac{K_s}{K_s + K_d} + \frac{K_d}{K_s + K_d} e^{-[K_m(K_s + K_d)]t} \right\}$$

$$* \left[\frac{\lambda w_{id}(0) - \int_0^{\infty} \left[K_d + \frac{1}{K_m} - \frac{K_s}{K_m(K_s + K_d)} - \frac{K_d}{K_m(K_s + K_d)} e^{-[K_m(K_s + K_d)]t} \right] dt}{2\lambda K_d \left[\frac{K_s}{K_s + K_d} + \frac{K_d}{K_s + K_d} e^{-[K_m(K_s + K_d)]t} \right]} \right]^2,$$

$$\text{or } 4\lambda^2 QG = 2\lambda^2 w_{id}^2(0) - 2\lambda w_{id}(0)J - \lambda^2 w_{id}^2(0) - J^2 + 2\lambda w_{id}(0)J,$$

$$\text{where } Q = K_d \left\{ \frac{K_s}{K_s + K_d} + \frac{K_d}{K_s + K_d} e^{-[K_m(K_s + K_d)]t} \right\},$$

$$J = \int_0^{\infty} \left[K_d + \frac{1}{K_m} - \frac{K_s}{K_m(K_s + K_d)} - \frac{K_d}{K_m(K_s + K_d)} e^{-[K_m(K_s + K_d)]t} \right] dt.$$

This implies that

$$\{w_{id}^2(0) - 4QG\}\lambda^2 - J^2 = 0.$$

$$\lambda = \frac{J}{\sqrt{w_{id}^2(0) - 4QG}}.$$

Eq. [64] can also be written as

$$T = \frac{\lambda w_{id}(0) - J}{2\lambda Q}. \quad [66]$$

Substituting the value of λ into eq. [66], we get:

$$T(t) = \frac{\frac{w_{id}(0)J}{\sqrt{w_{id}^2(0) - 4QG}} - J}{2QJ},$$

$$T(t) = \frac{w_{id}(0) - \sqrt{w_{id}^2(0) - 4QG}}{2Q}. \quad [67]$$

A negative optimal tax is an optimal subsidy. In order to check the second order condition for minimization, we proceed as follows: The Lagrangian can be written as

$$L = JT + \lambda[G - T(w_{id}(0) - QT)]$$

The Bordered Hessian matrix of the Lagrange function is as follows:

$$BH = \begin{bmatrix} 0 & w_{id}(0) - 2QT \\ w_{id}(0) - 2QT & \frac{2QJ}{\sqrt{w_{id}^2(0) - 4QG}} \end{bmatrix},$$

the determinant of which is negative as $-(w_{id}(0) - 2QT)^2 < 0$, which implies that the efficiency loss is minimized.