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Forecasting Nigerian Stock Market Returns using ARIMA and Artificial Neural Network Models

¹Godknows M. Isenah and Olusanya E. Olubusoye

The study reports empirical evidence that artificial neural network based models are applicable to forecasting of stock market returns. The Nigerian stock market logarithmic returns time series was tested for the presence of memory using the Hurst coefficient before the models were trained. The test showed that the logarithmic returns process is not a random walk and that the Nigerian stock market is not efficient. Two artificial neural network based models were developed in the study. These networks are TECH (4 – 3 – 1) and TECH (3 – 3 – 1) whose out-of-sample forecast performance was compared with a baseline ARIMA (3, 0, 1) model. The results obtained in the study showed that artificial neural network based models are capable of mimicking closely the log-returns as compared to the ARIMA based model. The out-of-sample evaluations of the trained models were based on the RMSE, MAE, NMSE and the directional change metric D_{stat} respectively. Based on these metrics, it was found that the artificial neural network based models outperformed the ARIMA based model in forecasting future developments of the returns process. Another result of the study shows that instead of using extensive market data, simple technical indicators can be used as predictors for forecasting future values of the stock market returns given that the returns has memory of its past.

Keywords: Artificial neural networks, Long memory, Random walk, Forecasting, Training, Stock Market Returns, Technical analysis indicator, ARIMA.

JEL Classification: E44, G17

1.0 Introduction

Artificial neural networks are one of the most popular tools for forecasting financial and economic time series. They are universal and highly flexible function approximators for pattern recognition and classification, [Beresteau (2003); Chan *et al.* (2009)]. An artificial neural network based model requires

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no prior assumptions on the behaviour and functional form of the related variables, but can still capture the underlying dynamics and nonlinear relationships that exist amongst the variables. This paper proposes artificial neural network based models for forecasting the *Nigerian Stock Exchange All-Share-Index* logarithmic returns, and comparing the out-of-sample forecast performance of the networks with a baseline *ARIMA* (p, d, q) model.

In stock market predictions, many methods for technical analysis and forecasting have been developed and are being used, [see Pring (1985)]. In technical forecasting, technical indices (*in the form of rolling means, rolling standard deviations/or variances, lagged values etc.*) are usually computed from a time series and are used to forecast future changes in the levels of the series. Several artificial neural network based models have been developed for stock market forecasting. Some of these models are applied to forecasting the future rates of changes of stock prices, [see Kimoto *et al* (1990)], and some are applied to recognizing certain patterns in stock prices that are characteristics of the future price changes, [Kamojo and Tanigawa (1990)]. The performance of artificial neural networks has been extensively compared to that of various parametric statistical methods within the areas of prediction and classification [Ripley (1996)]. In particular, some literature on time series forecasting using artificial neural networks has been generated, though, with mixed results. Some of the articles reviewed on the performance of artificial neural networks at the time of this study are Lepedes and Farber (1987), Tang *et al.* (1991), Shada(1994) and Stern (1996). These articles show that neural network models outperform conventional parametric models especially for time series with little or no stochastic component. An interesting result by Tang *et al.* (1991) is that the relative performance of an artificial neural network model is influenced by the memory of the time series when compared with the Box-Jenkins ARIMA models.

In Nigeria, Akinwale *et al.* (2009) used regression neural network with back-propagation algorithm to analyze and predict *translated* and *un-translated* Nigerian stock market prices (NSMP). Their study compared forecast performance of the neural networks with translated and un-translated NSMP as inputs, and this revealed that the network with translated NSMP inputs outperformed the network with un-translated NSMP inputs. In terms of prediction accuracy measures, the translated NSMP network predicted

accurately 11.3% of the stock prices as compared to 2.7% prediction accuracy of the un-translated NSMP network model.

Similarly, from the ARIMA scheme's perspective of forecasting the Nigerian stock market returns, Ojo and Olatayo (2009) studied the estimation and performance of subset autoregressive integrated moving average (ARIMA) models. They estimated parameters for ARIMA and *subset* ARIMA processes using numerical iterative schemes of Newton-Raphson and the Marquardt-Levenberg algorithms. The performance of the models and their residual variance were examined using AIC and BIC. The result of their study showed that the SARIMA model outperformed the ARIMA model with smaller residual variance. On the other hand, Emenike (2010) studied the NSE market returns series using monthly data of the All-Share-Index for the period January 1985 through December 2008. In his study, an ARIMA (1,1,1) model was selected as a tentative model for predicting index points and growth rates. The results revealed that the global meltdown destroyed the correlation structure existing between the NSE All-Share-Index and its past values. Agwuegbo *et al.* (2010) also studied the daily returns process of the Nigerian Stock Market using *Discrete Time Markov Chains (DTMC)*, and *martingales*. Their study provided evidence that the daily stock returns process follows a random walk, but that the stock market itself is not efficient even in weak form.

Several other studies that have used ARIMA schemes for analysis and forecasting of stock market prices/or returns in Africa include Simons and Laryea (2004), Rahman and Hossain (2006), and Al-Shiab (2006) among others. These studies did not test whether or not the stock price/or returns processes are fractal in nature. This we intend to determine for the Nigerian stock market before we proceed with further analysis.

For our study, we will apply the *Feed-forward multilayer perceptron (MLP) neural network models* with a single hidden layer. The architecture of the log-returns prediction system for the Nigerian stock market consists of a pre-processing unit, a MLP neural network and a post-processing unit. The pre-processing unit scales each of the inputs (*the predictors*) to have zero mean and standard deviation of 1, before they are passed into the network for processing. In a similar fashion, the response variable (*log-return*) is scaled to fall within the interval of the activation functions of the neural network. The output/or signal produced by the neural network is then passed to the post-

processing unit which converts the networks output/or signal to the predicted stock market returns.

The Box and Jenkins (1976) ARIMA method of forecasting is different from most optimization based methods. This technique does not assume any particular pattern in the historical data of the time series to be forecasted. It uses iterative procedures to identify a tentative model from a general class of models. The chosen model is then checked for adequacy and if found to be inadequate, the modeling process is repeated all over again until a satisfactory model is found.

The rest of the study is as follows: Section 2 discusses the Methodology, Random Walk and Efficient Market Hypothesis, Tools for detection of memory in time series, Statistical concepts and Training of artificial neural networks. Section 3 discusses the proposed models and data analysis. Section 4 gives results and discussions, while Section 5 ends with summary and conclusion.

2.0 Methodology

2.1 The random walk and efficient market hypotheses

A school of thought in the theory of financial econometrics that is widely accepted by financial economists is the *Efficient Market Hypothesis(EMH)*. They believe generally that financial markets are very efficient in reflecting information about individual securities traded in the markets and about the market as a whole. The *EMH* states, according to Ongorn (2009) that prices of securities traded, for example: stocks, bonds, or properties reflects all known information and therefore are unbiased in the sense that they reflect the collective beliefs of all investors about the future prospects. Under the *EMH*, information is quickly and efficiently incorporated into asset prices at any point in time, so that the price history cannot be used to predict future price movements of the assets. In general, under the *EMH*, an asset price, say stocks, denoted by S_t already incorporates all relevant information, and the only reason for the prices to change between time t and time $t + 1$ will be due to shocks. The *EMH* therefore postulates that the assets price process follow a *random walk*. The random walk model without drift parameter is expressed as:

$$S_t = S_{t-1} + \varepsilon_t, \quad t = 1, 2, \dots, n \quad (1)$$

where $\varepsilon_t \sim iid(0, \sigma_\varepsilon^2)$ is a white noise process. When ε_t is not a white noise process, the price series is said to have memory which violates the *EMH*, [Shiriaeve, (1999)]. According to Fama (1965; 1995), a stock market where successive price changes in individual securities are independent, is by definition a random walk. Stock prices following a random walk imply that the price changes are independent of one another as the gains and losses [Kendal, (1953)]. The independence of the random walk or the *EMH* is valid as long as the time series of the price changes of the securities does not have memory. In this study, our objective is to forecast the monthly logarithmic returns of the *NSE* using artificial neural network based models with technical analysis indicators of the returns as inputs. This objective can only be achieved if the log-returns process has memory. And to test for the presence of memory in the returns series, we employed the fractional difference parameter (d) of a fractal time series; the Hurst (1951) coefficient (H); and the sample autocorrelation and partial autocorrelation functions (*ACF*) and (*PACF*) respectively.

2.2 Tools for detection of memory in stock market returns time series

The Hurst coefficient (H), is a measure of the bias in fractionally integrated time series. This coefficient could be used to test financial time series for the presence of memory. The presence of memory in a time series indicates the possibility of predicting the future values using its history. The rescaled range, (R/S) analysis which was proposed by Hurst (1951), and later refined by Mandelbrot and Ness (1968) and Mandelbrot (1975; 1982), is able to distinguish a random series from a fractionally integrated series, irrespective of the distribution of the underlying process. The R/S statistic is the range of partial sums of deviations of a time series from its mean, rescaled by its standard deviation. Specifically, let X_t denote a stationary time series, then the R/S statistic is defined as:

$$R/S = \frac{1}{S_N} \left[\max_{1 \leq k \leq N} \sum_{t=1}^k (X_t - \bar{X}) - \min_{1 \leq k \leq N} \sum_{t=1}^k (X_t - \bar{X}) \right] \quad (2)$$

where $\bar{X} = \frac{1}{N} \sum_{t=1}^N X_t$ is the sample mean and $S_N = \left[\frac{\sum_{t=1}^N (X_t - \bar{X})^2}{N} \right]^{1/2}$ is the sample standard deviation. When there is absence of long memory in a

stationary time series, the R/S statistic converges to a random variable $N^{-1/2}$, where N denotes the length of the time series. However, when the stationary time series X_t has long memory, Mandelbrot (1975) showed that the R/S statistic converges to a random variable at N^H , where H is the Hurst coefficient, [see also Zivot and Wang (2003) for more details].

The Hurst coefficient is computed using the expression:

$$H = \frac{\log(R/S)}{\log(N)} \quad (3)$$

It describes three distinct categories of time series. These categories are:(i) $H = 1/2$ describe uncorrelated noise processes, whether they are Gaussian or not; (ii) $0 \leq H < 1/2$ describe ergodic processes with frequent reversals and high volatility, and (iii) $1/2 \leq H < 1$ describe reinforcing processes that are characterized by long memory. The Hurst coefficient H is related to the *fractional differencing* parameter d , of a fractionally integrated time series. The relationship is given by:

$$d = H - \frac{1}{2} \quad (4)$$

According to Hosking (1981; 1996) and Mills (2007), for values of $d \in (0, \frac{1}{2})$, the series is stationary and has long memory. For values of $d \in (-\frac{1}{2}, 0)$, the time series is anti-persistent, while for values of $d \in (-\frac{1}{2}, \frac{1}{2})$, the series is stationary and ergodic. Therefore, the Hurst coefficient and the fractional difference parameter, d can be used interchangeably for testing for the presence of long memory in a stationary time series.

The monthly NSE All-Share-Index logarithmic returns are defined as:

$$r_t = \ln \left[\frac{NSE\ INDEX_t}{NSE\ INDEX_{t-1}} \right] = \Delta \ln [NSE\ INDEX_t] \quad (5)$$

The application of the memory tests just discussed on the log-returns series give the results reported in Table 1. From these results, we conclude that the monthly log-returns do not follow a random walk and neither is the Nigerian Stock market efficient; this confirming one of the results provided by

Agwuegbo *et al* (2010). Figures 1 through 3 (see Appendix) show the time plots of the monthly NSE All-Share-Index and the monthly logarithmic returns; sample *ACF* and *PACF*; the histogram and quantile-quantile plot of the log-returns. The graphs show that the returns process is stationary, but its distribution is leptokurtic and skewed to the left with long tails. While the plots of sample *ACF* and *PACF* further confirm the results of the memory test above by showing small but significant spikes in the correlograms.

Table 1: Sample descriptive statistics of NSE log returns and memory test results

Series length (N)	Mean of log returns (\bar{r})	Variance of log returns ($S_{r_t}^2$)	Standard deviation of log returns (S_{r_t})	Rescaled of range statistic (R/S)	Hurst coefficient (H)	Fractional difference parameter (d)
311	0.01738	0.00383	0.0686	2.05104	0.609996	0.109996

2.3 Statistical concepts

The MultiLayer Perceptron (*MLP*) neural networks describe mapping of input variables $\mathbf{X} \in \mathbb{R}^p$ onto the output variable $\mathbf{y} \in \mathbb{R}^q$. For the feed-forward multilayer perceptron neural network with a single hidden layer and one output variable, ($q = 1$), $\mathbf{y} \in \mathbb{R}$ is a function of the vector of input variables \mathbf{X} . This relationship can be expressed using an MLP neural network model of the form:

$$y_{nn} = \gamma_0 + \sum_{h=1}^H \gamma_h \psi \left(\omega_{0,h} + \sum_{j=1}^p \omega_{j,h} x_j \right) = g_h(\mathbf{v}_h^T \mathbf{N}) \quad (6i)$$

where we define

$$N_h = \psi \left(\omega_{0,h} + \sum_{j=1}^p \omega_{j,h} x_j \right) = \psi(\boldsymbol{\omega}_{0,h} + \boldsymbol{\omega}_h^T \mathbf{X}) \quad (6ii)$$

$\mathbf{N} = (N_1, N_2, \dots, N_H)$ is the vector of hidden layer nodes of the network; $g_h(\cdot)$ is a function of the hidden layer nodes; H denotes the number of nodes in the hidden layer; $\psi(\cdot)$ is an activation function, and T denotes the transpose of a matrix. The parameter vector:

$\boldsymbol{\Omega} = (\boldsymbol{\omega}, \boldsymbol{\gamma}) = (\omega_{0,1}, \dots, \omega_{p,1}, \omega_{0,2}, \dots, \omega_{p,h}; \gamma_0, \dots, \gamma_H)^T \in \mathbb{R}^{H(p+1)+H+1}$
contains all the weights of the neural network.

Artificial neural networks are known to possess the properties of *universal approximators*, hence, it is possible to construct nonparametric estimators for regression functions, [see Hornik *et al* (1989), Beresteanu (2003) and Franke *et al.*(2004) for more details]. Given the regression time series model:

$$y_t = f(\mathbf{X}_t; \boldsymbol{\Omega}) + \varepsilon_t \quad (7)$$

The response function, $f(\mathbf{X}_t; \boldsymbol{\Omega})$ can be approximated by fitting a neural network model to the predictor variables: $X_{1t}, X_{2t}, \dots, X_{pt}$ and the response variable y_t . The parameters of the network can be estimated using the nonlinear least squares estimator $\hat{\boldsymbol{\Omega}}$ obtained by minimizing:

$$Q_n(\boldsymbol{\Omega}) = \sum_{t=1}^n (y_t - y_{nn,t})^2 = \sum_{t=1}^n \sum_{h=1}^H (y_t - g_h(\hat{\mathbf{Y}}_h^T \mathbf{N}_t))^2 \quad (8)$$

where $y_{nn,t} = g_h(\hat{\mathbf{Y}}_h^T \mathbf{N}_t)$ denotes the fitted neural network model.

2.4 Estimation/or training of neural networks

The least squares criterion given by Equation (8) is obviously a nonlinear function of $\boldsymbol{\Omega}$. In this study, the *Quasi – Newton* iterative scheme will be applied for the minimization of $Q(\boldsymbol{\Omega})$. The iterative scheme is a *local gradient-based search*, in which the first and second order derivatives of $Q(\boldsymbol{\Omega})$ with respect to the weight vector $\boldsymbol{\Omega}$, and continuous updating of the initial conditions of $\boldsymbol{\Omega}$, by the derivatives until some stopping criteria are met. Given the initial weight vector $\boldsymbol{\Omega}_0$, we obtain a second-order Taylor series expansion of $Q(\boldsymbol{\Omega})$, given as:

$$Q(\boldsymbol{\Omega}) \approx Q(\boldsymbol{\Omega}_0) + \nabla'(\boldsymbol{\Omega} - \boldsymbol{\Omega}_0) + \frac{1}{2}(\boldsymbol{\Omega} - \boldsymbol{\Omega}_0)' \boldsymbol{\delta}_0 (\boldsymbol{\Omega} - \boldsymbol{\Omega}_0) \quad (9)$$

where $\nabla = \frac{\partial Q}{\partial \boldsymbol{\Omega}}$ is the gradient of $Q(\boldsymbol{\Omega})$ evaluated at $\boldsymbol{\Omega}_0$ and $\boldsymbol{\delta}_0 = \frac{\partial^2 Q}{\partial \boldsymbol{\Omega} \partial \boldsymbol{\Omega}'}$ is the Hessian of $Q(\boldsymbol{\Omega})$ evaluated at $\boldsymbol{\Omega}_0$. The approximating sum of squares function $Q(\boldsymbol{\Omega})$ will have a stationary point when its gradient is zero, that is:

$$\nabla + \delta_0(\Omega - \Omega_0) = \mathbf{0}$$

and this stationary point will be a minimum if δ_0 is positive definite. If δ_0 is positive definite, then the Newton-Raphson step is:

$$\Omega - \Omega_0 = -\delta_0^{-1}\nabla \tag{10}$$

The generic approach to the minimization of $Q(\Omega)$ is the *back-propagation*. The back-propagation algorithm is a two-pass filter, [Friedman *et al.* (2008)]. This can be computed by a forward and backward sweep over the network, keeping track of only quantities local to each unit of the network. To create the filter, the partial derivatives of (8) with respect to γ_h and ω_j are calculated, which are respectively given by:

$$\frac{\partial Q(\Omega)}{\partial \gamma_h} = -2[y_t - g_h(\hat{\gamma}_h^T N_t)]g'_h(\hat{\gamma}_h^T N_t)N_{h,t} \tag{11}$$

And

$$\frac{\partial Q(\Omega)}{\partial \omega_j} = -2 \sum_{h=1}^H [y_t - g_h(\hat{\gamma}_h^T N_t)] g'_h(\hat{\gamma}_h^T N_t) \gamma_h \psi'(\omega_h^T X_t) X_{j,t} \tag{12}$$

The gradient descent update at the $(r + 1)^{st}$ iteration using these derivatives has the form:

$$\gamma_h^{(r+1)} = \gamma_h^r - \varphi_r \sum_{t=1}^n \frac{\partial Q(\Omega)}{\partial \gamma_h^{(r)}}$$

and

$$\omega_j^{(r+1)} = \omega_j^{(r)} - \varphi_r \sum_{t=1}^n \frac{\partial Q(\Omega)}{\partial \omega_j^{(r)}}$$

where φ_r is the learning rate. Rewriting (13) and (14) as:

$$\frac{\partial Q(\Omega)}{\partial \gamma_h} = \theta_h N_{h,t}$$

and

$$\frac{\partial Q(\Omega)}{\partial \omega_j} = \phi_j X_{j,t}$$

The quantities θ_h and ϕ_j are errors from the current model at the output and hidden layer units respectively. These errors satisfy $\phi_j = N_{h,t} \sum_{h=1}^H \gamma_h \theta_h$, which is known as *back-propagation*, [Friedman *et al.*(2008)].

3.0 Proposed artificial neural network based models and data analysis

3.1 The proposed models

The proposed artificial neural network based models to be trained in the study are the multilayer perceptron (*MLP*) feed-forward neural networks with one hidden and one output layers and without *skip* connections. The neural network's architecture is of the form:

And inputs nodes function:

$$n_{h,j} = \hat{\omega}_{h,0} + \sum_{j=1}^p \hat{\omega}_{h,j} X_{jt} \quad (13)$$

Activation or hidden nodes function:

$$N_{h,t} = \psi(n_{h,t}) = \frac{1}{1 + e^{-n_{h,t}}} \quad (14)$$

Output node function:

$$\hat{r}_{t.scaled} = g(N_{h,t}, \hat{\gamma}) = \hat{\gamma}_0 + \sum_{h=1}^H \hat{\gamma}_h N_{h,t} \quad (15)$$

Following the approach of Yao and Tan (2000) and Erik (2002), the neural network's architecture is denoted as: $I - H - O$, where I denotes the input layer size, H the hidden layer size and O the output layer size respectively.

3.2 Data segmentation, input selection and processing

The log-returns time series is segmented into *training* and *test* data sets respectively. The training data set comprises of data points from January 1985

through December 2009, while the test data set comprises of data points from January, 2010 through December, 2010.

The inputs selected for the networks are technical indices. These indices are:(i) Rolling means denoted as: *One-month (ma1)*, *three-month (ma3)*, *six-month (ma6)*and *twelve-month (ma12) moving averages*.(ii) Lagged values of the log-returns denoted as: *one-period lagged values*(r_{t-1}), *two-period lagged values*(r_{t-2})and *three-period lagged values*(r_{t-3}).

Since the activation function chosen (i.e. the *logistic function*) has its output values in the interval [0, 1], the output variable was first scaled to have values in this interval using the transformation:

$$r_{t.scaled} = \frac{r_t - \min(r_t)}{\max(r_t) - \min(r_t)}$$

The de-scaled log-returns fitted by the network are then obtained using the expression:

$$\hat{r}_t = [\max(r_t) - \min(r_t)] * \hat{r}_{t.scaled} + \min(r_t).$$

Similarly, the input variables (*technical indices*) were normalized to have mean zero and standard deviation of one using:

$$z_t = \frac{r_t - \bar{r}}{\hat{\sigma}_{r_t}}$$

3.3 Evaluation of neural networks

In- sample-evaluations criteria

The structures of the fitted neural networks at the training stages are compared using the following order determination criteria to decide the best networks.

- Akaike information criterion (*AIC*) defined by:

$$AIC = \ln \left[\frac{1}{N} \sum_{t=1}^N (r_t - \hat{r}_t)^2 \right] + \frac{2k}{N}$$

- Hannan-Quinn information criterion (*HQIF*) defined by:

$$HQIF = \ln \left[\frac{1}{N} \sum_{t=1}^N (r_t - \hat{r}_t)^2 \right] + \frac{k}{N} \ln[\ln(N)]$$

- Bayesian information criterion (*BIC*) defined by:

$$BIC = \ln \left[\frac{1}{N} \sum_{t=1}^N (r_t - \hat{r}_t)^2 \right] + \frac{k}{N} \ln(N)$$

where k is the number of estimated parameters.

Out-sample-evaluations criteria

Comparisons of the predictive powers of the trained models are determined by the use of the following metrics.

Root mean square error defined by:

$$RMSE = \frac{1}{\tau^*} \left[\sum_{\tau=1}^{\tau^*} (r_{\tau} - \hat{r}_{\tau})^2 \right]^{1/2}$$

Mean absolute error defined by:

$$MAE = \frac{1}{\tau^*} \sum_{\tau=1}^{\tau^*} |r_{\tau} - \hat{r}_{\tau}|$$

Normalized mean square error defined by:

$$NMSE = \frac{\sum_{\tau=1}^{\tau^*} (r_{\tau} - \hat{r}_{\tau})^2}{\sum_{\tau=1}^{\tau^*} (r_{\tau} - \bar{r})^2} = \frac{1}{N\sigma_{\tau^*}^2} \sum_{\tau=1}^{\tau^*} (r_{\tau} - \hat{r}_{\tau})^2$$

Directional change statistic defined by:

$$D_{stat} = \frac{1}{N} \sum_{\tau=1}^{\tau^*} b_{\tau}$$

where $b_{\tau} = \begin{cases} 1, & \text{if } (r_{\tau+1} - r_{\tau})(\hat{r}_{\tau+1} - \hat{r}_{\tau}) \geq 0 \\ 0, & \text{otherwise} \end{cases}$ and τ^* is the number of observations in the test data set and $\{\hat{r}_t\}$.

4.0 Results and Discussions

This section presents discussions and the results obtained in the process of analyzing the data using S-PLUS 6.1 Professional Edition. The following parameters were held constant at their respective values throughout the

training process. Maximum number of iteration per fitted neural network: 200, Tours: 300, Range (random range from uniform distribution for weight vector selection):[-0.7, +0.7], Absolute tolerance: 10^{-4} , Relative tolerance: 10^{-8} , and Output type: *Linear*. The *penalty* parameters were varied at the values 0.001, 0.01, 0.05 and 0.10 for each trained neural network model.

4.1 Technical Analysis and Forecasting using Rolling Means as Inputs to the Networks

The hidden layer size was varied from 2 through 6 neurons, and a total of 1500 neural network models were trained for a given value of the penalty parameter, λ . Table 2 shows a summary of the best fitted network models for each value of λ . Based on the reports of the in-sample information criteria, the neural network model *TECH* (4 – 3 – 1) with $\lambda = 0.001$ was chosen as a tentative model. The eigen-values of the Hessian matrix of this neural network are all positive, indicating that the iterations converged to a global minimum. The out-of-sample evaluations reports of the estimated neural network are given in Table 3. The reported *RMSE*, *MAE* and the *NMSE* values are quite small, they show that the network performed well in the held-out sample. Similarly, the directional statistic D_{stat} shows that the network was able to predict 45% of positive directional change of the log-returns in the held-out sample.

Table 2: Summary of best trained networks with MA inputs for the different values of the decay, λ .

Best fitted network	Decay (λ)	Size of hidden node	Number of estimated weights	Final sum of squared residuals	R^2	AIC	HQIF	BIC
TECH (4-3-1)	0.001	3	19	0.69583	0.71324	-5.898	-5.915	-5.657
TECH (4-2-1)	0.01	2	13	0.86795	0.64231	-5.718	-5.73	-5.553
TECH (4-2-1)	0.05	2	13	0.99498	0.58996	-5.582	-5.593	-5.417
TECH (4-2-1)	0.1	2	13	1.0618	0.56243	-5.517	-5.528	-5.352

Table 3: Out-of-sample evaluations of trained *TECH* (4-3-1) neural network model.

Model	RMSE	MAE	NMSE	D_{stat}
TECH (4-3-1) with $\lambda=0.001$	0.01497	0.05685	0.03584	45.455

4.2 Technical analysis and Forecasting using Autoregressive inputs to the Networks

The order of the autoregressive inputs to the nonlinear autoregression, $NLAR(p)$ neural networks were determined using $ARIMA$ maximum likelihood estimation with AIC . The best order of the autoregressive inputs to the network is 3 [see Table 4]. Again, the size of the hidden layer of the network was varied between 2 and 6 inclusive for the given values of the decay parameter. The summary of the results obtained in the training process are presented in Tables 5. From this table, network model $TECH(3-3-1)$ with $\lambda=0.001$, was chosen as a tentative model. The Hessian of this network is positive definite, hence the search for optimal weight vector leads to a global minimum. In Table 6, the out-of-sample evaluations reports are presented. The trained $TECH(3-3-1)$ neural network was able to predict 45% of positive directional change in the log-returns as reported by the D_{stat} statistic.

Table 4: Determining the order of autoregressive inputs for $TECH(3-3-1)$ neural network.

$ARMA(p,q)$	$nAIC$	$ARMA(p,q)$	$nAIC$	$ARMA(p,q)$	$nAIC$
ARMA (4,0)	1914.579	ARMA (3,1)	1911.789	ARMA (2,0)	1934.155
ARMA (3,3)	1914.125	ARMA (3,0)	1922.474	ARMA (1,2)	1934.15
ARMA (3,2)	1911.993	ARMA (2,1)	1928.581	ARMA (1,1)	1932.321

Table 5: Summary of Best Fitted 3-3-1 Network Models using autoregressive inputs

Best fitted model	Number of tours per fit	Decay parameter (λ)	Maximum number of iterations	Number of hidden nodes	Number of estimated weights	AIC	HQIF	BIC
TECH (3-3-1)	300	0.001	200	3	16	-5.077	-5.091	-4.878
TECH (3-3-1)	300	0.01	200	3	16	-5.011	-5.025	-4.812
TECH (3-2-1)	300	0.05	200	2	11	-4.928	-4.938	-4.792
TECH (3-2-1)	300	0.1	200	2	11	-4.911	-4.921	-4.775

Table 6: Out-of-sample evaluation of the $TECH(3-3-1)$ network with autoregressive inputs

Model	RMSE	MAE	NMSE	D_{stat}
TECH (3-3-1) model with $\lambda=0.001$	0.10546	0.09087	1.77797	45.455

4.3 ARIMA time series modeling of the percentage stock market returns

The orders p and q of the *ARMA* model for the log-returns were determined using the sample *ACF* and *PACF* with some experimentation. Figure 2 (see Appendix) displays the sample *ACF* and *PACF* of the log-returns. The *AIC* for combinations of the orders p and q are those shown in Table 4 above. Based on the *AIC* values, we chose *ARMA*(3,1) as a tentative model for predicting the log-returns. The diagnostics of the residuals show that autocorrelations and partial autocorrelations of the residuals are within the 95% confidence limits, [Figures not shown]. By reason of this diagnostics, we conclude that our tentative *ARIMA* model is adequate. Table 7 presents the out-of-sample evaluations report. It shows that the *ARMA*(3,1) model performs poorly in the held-out sample as compared to the neural network models.

Table 7: Out-Sample Evaluation of *ARIMA* Fitted Model

Model fitted	RMSE	MAE	NMSE	D_{stat}
<i>ARMA</i> (3,1)	5.07262	3.68315	0.86545	27.273

4.4 The fitted forecast models

The forecast models were derived by re-estimating the *TECH* (4-3-1), *TECH* (3-3-1), and *ARIMA* (3,0,1) models using data points from January 1985 through December 2010. The re-estimated *TECH* (4 – 3 – 1) forecast neural network model is:

$$\hat{N}_{1t} = \frac{\exp(-0.06 + 0.2ma1 - 0.01ma3 + 0.01ma6 - 0.03ma12)}{1 + \exp(-0.06 + 0.2ma1 - 0.01ma3 + 0.01ma6 - 0.03ma12)} \quad (16)$$

$$\hat{N}_{2t} = \frac{\exp(0.10 + 0.5ma1 + 0.07ma3 - 0.02ma6 - 0.08ma12)}{1 + \exp(0.10 + 0.5ma1 + 0.07ma3 - 0.02ma6 - 0.08ma12)} \quad (17)$$

$$\hat{N}_{3t} = \frac{\exp(0.18 + 0.19ma1 + 0.03ma3 - 0.01ma6 + 0.02ma12)}{1 + \exp(0.18 + 0.19ma1 + 0.03ma3 - 0.01ma6 + 0.02ma12)} \quad (18)$$

and

$$\hat{r}_{t \text{ scaled } TECH \ 431} = -0.32 + 0.92N_{1t} - 0.18N_{2t} + 0.93N_{3t} \quad (19)$$

The time series of the actual log-returns, in-sample forecasts and the residuals of this neural network are presented in Figure 5 at the Appendix.

The re-estimated *TECH* (3 – 3 – 1) forecast neural network model is:

$$\hat{N}_{1t} = \frac{\exp(-5.73 + 0.41r_{t-1} - 0.16r_{t-2} - 0.26r_{t-3})}{1 + \exp(-5.73 + 0.41r_{t-1} - 0.16r_{t-2} - 0.26r_{t-3})} \quad (20)$$

$$\hat{N}_{2t} = \frac{\exp(1.95 - 0.22r_{t-1} + 0.27r_{t-2} + 0.05r_{t-3})}{1 + \exp(1.95 - 0.22r_{t-1} + 0.27r_{t-2} + 0.05r_{t-3})} \quad (21)$$

$$\hat{N}_{3t} = \frac{\exp(-2.53 + 0.21r_{t-1} - 0.16r_{t-2} - 0.07r_{t-3})}{1 + \exp(-2.53 + 0.21r_{t-1} - 0.16r_{t-2} - 0.07r_{t-3})} \quad (22)$$

and

$$\hat{r}_{t \text{ scaled } TEC \ 331} = -0.25 - 0.96N_{1t} + 0.78N_{2t} + 1.65N_{3t} \quad (23)$$

The time plots of the actual log-returns, in-sample forecasts as well as the residuals of this neural network are presented in Figure 5 at the Appendix.

While the re-estimated *ARIMA* (3,0,1) forecast model for the demeaned log-returns is given by:

$$\hat{w}_t = -0.506w_{t-1} + 0.289w_{t-2} + 0.334w_{t-3} + 0.677\hat{\varepsilon}_{t-1} \quad (24)$$

where $w_t = r_t - 0.01738$. The t-values of this model are -4.1257, 4.5826, 6.2159 and 5.4044 respectively, and they are highly significant at conventional test levels. The diagnostics of this *ARIMA* model presented in Figure 6 show that the ACF and PACF of the residuals fall within the 95% confidence limits. Hence, it can be concluded that the model is adequate. The time plots of the actual and predicted log-returns series are shown in Figure 7

at the Appendix. Table 8 reports the summary of forecast results of the models measured in terms of the out-sample performance metrics over a period of 11 months.

Table 8: Summary of out-of- sample forecast evaluations of the fitted models.

Model Type	RMSE	MAE	NMSE	D_{stat}
TECH (4-3-1)	0.01497	0.05685	0.03584	45.455
TECH (3-3-1)	0.10546	0.09087	1.77797	45.455
ARIMA (3,0,1)	5.07263	3.68315	0.86545	27.273

6.0 Summary and conclusion

The results from Table 8 show that the neural network models performed better than the ARIMA model, indicating their suitability for financial time series forecasting. In terms of the *RMSE*, *MAE*, *NMSE*, the two neural networks performed better than the ARIMA model since their out-of-sample performance metric values are respectively smaller than those of the ARIMA model. In a similar manner, the directional change statistic, D_{stat} , values of the neural networks are greater than that of the ARIMA model.

From the results obtained in the research, we found that the NSE is not efficient; this confirmed one of the results by Agwuegbo *et al.* (2010). The monthly NSE log-returns series is fractal with long memory, thus it was possible for us to forecast the stock market returns using simple technical analysis indicators rather than using extensive market data. The artificial neural network models were able to predict approximately 45% of the log-returns as reported by the directional change metric as compared to the 27% predicted by the ARIMA model. Though, the hit rates as reported by the D_{stat} statistic for the neural networks are less than 50%; the reason for this may be attributed to the small size of the test data set. For the forecast models developed in the study, particularly, the TECH (4-3-1) proves to be the best in predicting the log-returns, as it was able to mimic the log-returns process precisely and accurately with negligible errors.

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Appendix

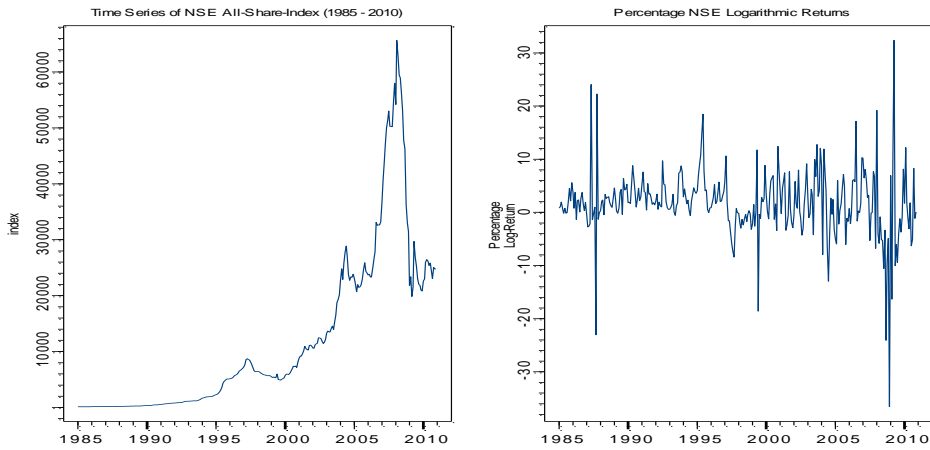


Figure 1: *Time series plots of the NSE All-Share-Index and the Percentage logarithmic returns.*

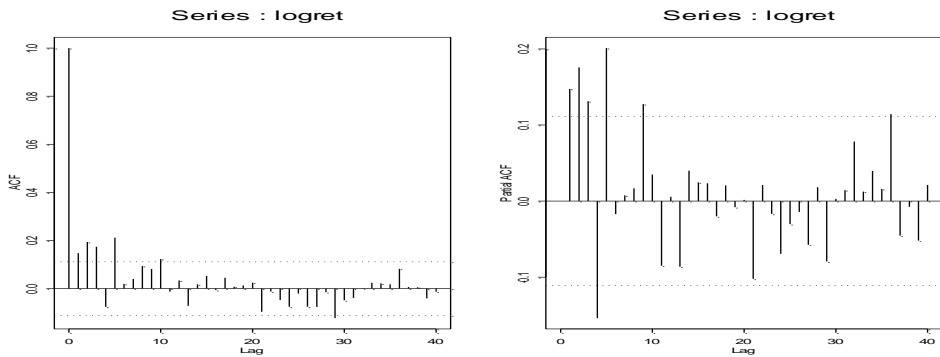


Figure 2: *Sample ACF and PACF of the monthly NSE log-returns*

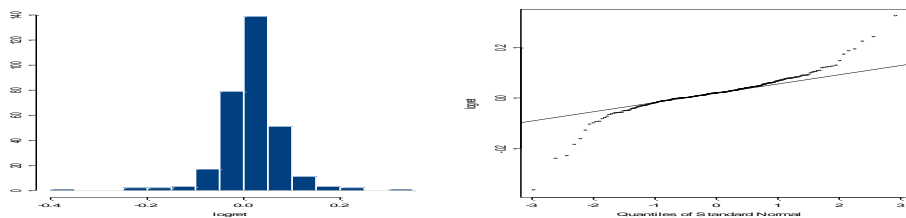


Figure 3: *Histogram and the quantile-quantile normal plot of the log-returns.*

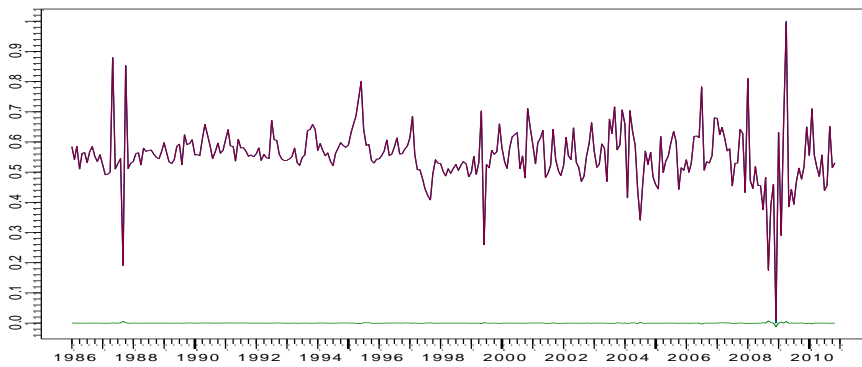


Figure 4: *Time plots of the fitted (red), actual scaled log-returns (blue) and the residuals (green) of re-estimated TECH (4 – 3 – 1) neural network.*

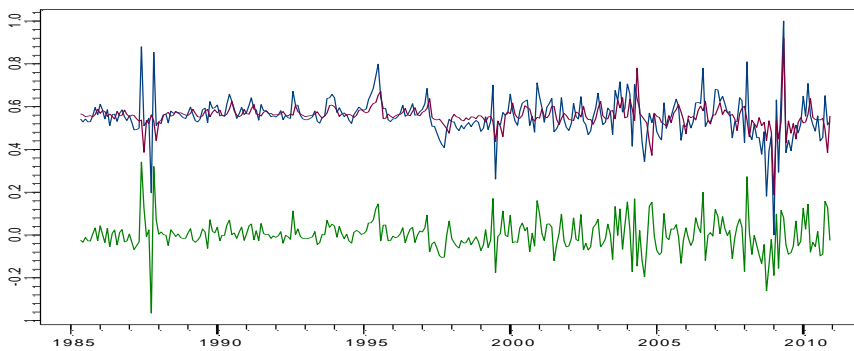


Figure 5: *Time plots of the fitted (red), actual scaled log-returns (blue) and the residuals (green) of re-estimated TECH (3 – 3 – 1) neural network.*

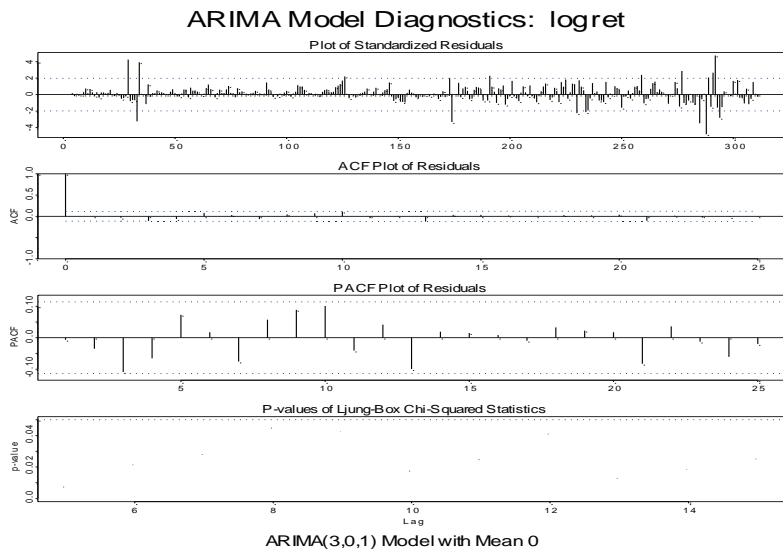


Figure 6: Diagnostic plots of the re-estimated ARIMA(3,0,1) model.

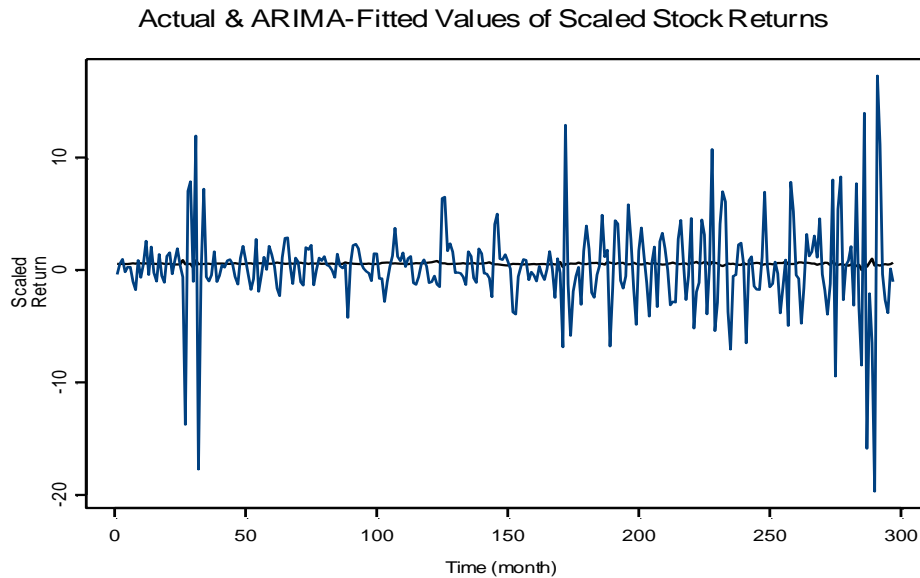


Figure 7: Time plots of actual (in blue) and predicted (in black) log-returns from the ARIMA (3,0,1) model.