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Working Paper

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Working Paper, No. 142

Provided in Cooperation with:

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Suggested Citation: König, Michael D.; Liu, Xiaodong; Zenou, Yves (2014) : R&D networks: Theory, empirics and policy implications, Working Paper, No. 142, University of Zurich, Department of Economics, Zurich,
<https://doi.org/10.5167/uzh-93904>

This Version is available at:

<https://hdl.handle.net/10419/111199>

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**University of
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University of Zurich
Department of Economics

Working Paper Series
ISSN 1664-7041 (print)
ISSN 1664-705X (online)

Working Paper No. 142

R&D Networks: Theory, Empirics and Policy Implications

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March 2014

R&D Networks: Theory, Empirics and Policy Implications[☆]

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Abstract

We study a structural model of R&D alliance networks in which firms jointly form R&D collaborations to lower their production costs while competing on the product market. We derive the Nash equilibrium of this game, provide a welfare analysis and determine the optimal R&D subsidy program that maximizes total welfare. We also identify the key firms, i.e. the firms whose exit would reduce welfare the most. We then structurally estimate our model using a panel dataset of R&D collaborations and annual company reports. We use our estimates to identify the key firms and analyze the impact of R&D subsidy programs. Moreover, we analyze temporal changes in the rankings of key firms and how these changes affect the optimal R&D policy.

Key words: R&D networks, key firms, optimal subsidies

JEL: D85, L24, O33

1. Introduction

R&D partnerships have become a widespread phenomenon characterizing technological dynamics especially in industries with rapid technological development such as, for instance, the pharmaceutical, chemical and computer industries [cf. [Ahuja, 2000](#); [Hagedoorn, 2002](#); [Powell et al., 2005](#); [Riccaboni and Pammolli, 2002](#); [Roijakkers and Hagedoorn, 2006](#)]. In those industries, firms have become more specialized in specific domains of a technology and they tend to combine their knowledge with the knowledge of other firms that are specialized in different technological domains [[Powell et al., 1996](#); [Weitzman, 1998](#)]. The increasing importance of R&D collaborations has spurred research for theoretical models studying these relationships, and for empirical tests of these models.

In this paper, we consider a general model of competition à la Cournot, where firms choose

[☆]We would like to thank Christian Helmers, Coralio Ballester, Matt Jackson, Michelle Sovinsky, Art Owen, Hang Hong, Marcel Fafchamps, Adam Szeidl, Sanjeev Goyal, Bastian Westbrock and seminar participants at the University of Zurich, Utrecht University, Stanford University and the IZA Workshop on Social Networks in Bonn for their helpful comments. Michael D. König acknowledges financial support from Swiss National Science Foundation through research grants PBEZP1-131169 and 100018.140266, and thanks SIEPR and the department of economics at Stanford University for their hospitality during 2010-2012. Yves Zenou acknowledges financial support from the Swedish Research Council (Vetenskapsrådet) through research grant 421-2010-1310.

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both R&D expenditures and output levels. Firms can reduce their costs of production by investing into R&D as well as by establishing R&D collaborations with other firms. An important – and realistic – innovation of our framework is to study the equilibrium outcomes in which firms can establish R&D collaborations with both, competing firms in their own sector, as well as firms in other sectors. In this model, R&D collaborations can be represented by a network. This allows us to write the profit function of each firm as a function of two matrices, \mathbf{A} and \mathbf{B} , where \mathbf{A} is the adjacency matrix of the network capturing all the direct R&D collaborations, while \mathbf{B} is a competition matrix that keeps track of which firm is in competition with which other firm in the same product market. Because of these two matrices, and thus of these two opposing effects of technology spillovers and competition, indirectly all firms interact with all other firms. To illustrate this point, consider for example the car manufacturing sector. The price of a car is determined by the demand for cars and the competition between other car producing firms. However, when these firms have R&D collaborations not only with other car manufacturing firms but also with firms from other sectors, the price of cars will also be indirectly influenced by the firms from other industries.

We characterize the Nash equilibrium of our model for any type of R&D collaboration network (i.e. any matrix \mathbf{A}) as well as for any type of competition structure between firms (i.e. any matrix \mathbf{B}). We show that there exists a key trade off faced by firms between the *technology (or knowledge) spillover effect* of R&D and the *product rivalry effect* of competition. The former effect captures the *positive* impact of R&D collaborations on output and profits (through the matrix \mathbf{A}) while the latter captures the *negative* impact of competition and market stealing effects (through the matrix \mathbf{B}).

We show that the Nash equilibrium can be characterized by the fact that firms produce their goods proportionally to their Katz-Bonacich centrality, a well-known measure in the sociology literature that determines how central each firm is in the network, and also the degree of competition in the product market. In particular, a very central firm in the network will not always produce the highest output because the optimal output choice will also depend on the competition intensity the firm faces in the product market.

We also provide a welfare analysis with an explicit expression for total welfare as a function of the fundamental parameters of the model. We further provide a lower and an upper bound on the welfare function with bounds that depend on the parameters as well as the topology of the network. Moreover, we study the problem of optimal *network design* where we show which network is the most efficient one (i.e. the one that maximizes welfare determined by producer and consumer surplus among all possible networks). We then study two important policies. First, our equilibrium characterization allows us to define the *key firms*, i.e. the firms whose exit would reduce welfare the most. These are the systemically relevant firms for industry productivity and performance. Second, we study subsidy policies where the planner can subsidize the R&D effort of each firm. In both cases, we are able to derive an exact formula for any type of network and competition structure that determines who the key firm is and the amount of subsidy that should be given to each of them.

We then bring the model to the data by using a panel of R&D collaborations and annual company reports over different sectors and years. We estimate the first-order conditions of the model by testing the trade-off for firms between the *technology (or knowledge) spillover effect* of R&D and the *product rivalry effect* of competition mentioned above. In terms of identification strategy, we use firm and time fixed effects (as we have a panel of firms), an IV strategy and an estimation of a network formation model. As predicted by the theoretical model, we find that the spillover effect has a *positive* and significant impact on output and profit while, the competition effect has a *negative* and significant impact. We also show that the net effect from collaboration is positive.

Following our theoretical results, we empirically rank the key firms in terms of their contribution to welfare across different sectors and countries. In particular, in our analysis of the key firms we quantify theoretically and empirically the highest welfare loss incurred due to the exit of a firm. Our results could thus help to guide policy makers in evaluating how much it would be worth bailing out a particular firm. We also perform the same analysis for R&D subsidies. We further analyze the temporal changes of the rankings of key firms and the subsidized firms. We show, in particular, that the key firms are not always the most central ones by any conventional measure. In other words, the key firms are not always the ones that have the largest number of R&D collaborations, nor the highest eigenvector, betweenness or closeness centrality. More importantly, we also show that the key firms are not the ones that have the highest market share in their industry. For example, we find that *General Motors* is a key firm but it does not have the highest market share in its sector since it detains “only” 12.14 % of market share while, for example, *Hitachi*, *Altria* or *Pepsico* have a much higher share (up to 50 %) but are not the top key firms. This means that it is not straightforward to determine which firm should be “targeted” in the network by only observing its market share, size or even its position in the network. We believe that our analysis can be used to guide R&D policies that aim at fostering the innovativeness of an economy, and we show how these policies need to be dynamically adjusted to changes in the economy.

The rest of the paper is organized as follows. In the next section, we compare our contribution to the existing literature. In Section 3, we develop a model of firms competing in the product market with technology sharing R&D collaborations that allow them to reduce their production costs. We characterize the Nash equilibrium of this game and show under which conditions it exists, is unique and interior. Section 4 determines welfare and investigates the optimal network structure of R&D collaborations. Section 5 introduces the definition and computation of the key firms while Section 6 discusses optimal R&D subsidies. Section 7 describes the data. Section 8 is divided in two parts. In Section 8.1, we define the econometric specification of our model while, in Section 8.2, we highlight our identification strategy. The empirical results are given in Section 9. The policy results of our empirical analysis are given in Section 10 where the key player analysis can be found in Section 10.1 while that of the subsidy analysis is in Section 10.2. Finally, Section 11 concludes. The network definitions and characterizations used throughout the paper are given in Appendix A, an analysis in terms of Bertrand compe-

tition is performed in Appendix B and some additional results for welfare are in Appendix C. In Appendix D, we provide a theoretical model of intra and interindustry collaborations. All proofs can be found in Appendix E.

2. Related Literature

Our paper lies at the intersection of different strands of the literature. We would like to expose them in order to highlight our contribution.

Network Theory Our theoretical model analyzes a game with strategic complementarities where firms decide about output and R&D effort by taking the network as given. It thus belongs to the class of games known as *games on networks* [cf. Jackson and Zenou, 2014].¹ Compared to this literature, where a prominent paper is the one of Ballester et al. [2006], we re-interpret their model in terms of R&D networks and extend their framework to account for competition between firms not only within the same product market but also between different product markets (see our Proposition 1). This yields very general results that can encompass any possible network of collaborations and any possible interaction structure of competition between firms. We also provide an explicit welfare characterization, provide lower and upper bounds and determine which network maximizes total welfare (see Propositions 2, 3 and 4). To the best of our knowledge, this is one of the first papers that provides such an analysis.² We also provide two policy analyses. The first one consists of subsidizing firms' R&D efforts. We are able to determine the optimal subsidy level both when it is homogenous (Proposition 6) and when it is targeted to firms (Proposition 7). We are not aware of other studies of subsidy policies in the context of networks.³ Finally, we extend the key player analysis proposed by Ballester et al. [2006]. In their paper, they define a key player in the context of crime where the removal of the key player generates the highest reduction of crime in the network. In our context of R&D networks, we define a key firm as the one that would reduce total welfare the most if it were removed. It is a different notion since the key firms are the ones whose disappearance from the market would result in a dramatic in total welfare loss. By doing so, we generalize the inter-centrality formula proposed in Ballester et al. [2006] by having both network and competition effects defining the key player (see Proposition 5).

Theoretical Studies of R&D Collaboration Networks In the industrial organization literature, there is long tradition of models that analyze product and price competition with R&D

¹The economics of networks is a growing field. For overviews of the literature, see Vega-Redondo [2007], Goyal [2007], Jackson [2008], De Marti and Zenou [2011], Jackson and Zenou [2013, 2014], Zenou [2014].

²In a recent paper, Belhaj et al. [2013] study network design in a game on networks with strategic complements, but without competition effects.

³There are some papers that look at subsidies in industries with R&D collaborations but the network is not explicitly modeled. See e.g. Acemoglu et al. [2012]; Bagwell and Staiger [1994]; Bloom et al. [2002]; Hinloopen [2001]; Impullitti [2010]; Leahy and Neary [1997]; Qiu and Tao [1998]; Song and Vannetelbosch [2007]; Spencer and Brander [1983].

collaborations, first pioneered by [Arrow \[1962\]](#) and then pursued by [Spence \[1984\]](#). One of their main insights is that incentives to invest in R&D are reduced by the presence of such technology spillovers. This raised the interest for R&D cooperation as a means to internalize spillovers. More recently, the seminal works by [D’Aspremont and Jacquemin \[1988\]](#), [Suzumura \[1992\]](#), [Kamien et al. \[1992\]](#) focus on the direct links between firms in the R&D collaboration process.

In all this literature, however, there is no explicit network of R&D collaborations. The first paper that provides an explicit analysis of R&D networks is the one by [Goyal and Moraga-Gonzalez \[2001\]](#).⁴ The authors introduce a strategic Cournot oligopoly game in the presence of externalities induced by a network of R&D collaborations. Benefits arise in these collaborations from sharing knowledge about a cost-reducing technology. By forming collaborations, however, firms also change their own competitive position in the market as well as the overall market structure. Thus, there exists a two-way flow of influence from the market structure to the incentives to form R&D collaborations and, in turn, from the formation of collaborations to the market structure. [Westbrock \[2010\]](#) extends their framework to analyze welfare and inequality in R&D collaboration networks, but abstracts from R&D investment decisions.

However, these papers typically provide results only for a small number of firms or specific networks, such as regular networks (i.e. all firms have the same number of R&D collaborations), star-shaped or complete networks, networks that we typically do not observe in the real-world. Compared to these papers, we provide results for all possible networks with an arbitrary number of firms and a complete characterization of equilibrium output and R&D effort choices in multiple interdependent markets. We also determine policies related to network design, the identification of the key player and optimal R&D subsidies.

Econometrics of Networks The literature on identification and estimation of social network models has progressed significantly recently (see [Blume et al. \[2011\]](#), for a recent survey). In his seminal work, [Manski \[1993\]](#) introduces a linear-in-means social interaction model with endogenous effects, contextual effects, and correlated effects. Manski shows that the linear-in-means specification suffers from the “reflection problem” and the different social interaction effects cannot be separately identified. [Bramoullé et al. \[2009\]](#) generalize Manski’s linear-in-means model to a general local-average social network model, whereas the endogenous effect is represented by the average outcome of the peers. They provide some general conditions for the identification of the local-average model using an indirect connection’s characteristics as an instrument for the endogenous effect assuming that the network (and its adjacency matrix) is exogenous. However, if the adjacency matrix is endogenous, i.e., if there exists some unobservable factor that could affect both the link formation and the outcome, then the above identification strategy would fail. Here, as we have a panel data where the network changes over time (whereas in many applications, the network is observed at one point in time; [see e.g.

⁴See also [Dawid and Hellmann \[2012\]](#) and [Goyal and Joshi \[2003\]](#).

Bramoullé et al., 2009; Calvó-Armengol et al., 2009]), we adopt a similar identification strategy using instruments but with both firm and time fixed effects to attenuate the potential endogeneity of the adjacency matrix. We then go even further by considering instruments based on the predicted adjacency matrix. For that, in the first stage of the estimation, we run a regression of whether two firms i and j will have a link at time t (here an R&D collaboration) on some exogenous control variables (e.g., whether these two firms had an R&D collaboration in the past, whether they are in the same industry, and whether they are from the same country) to get a predicted adjacency matrix. Then, we carry out our instrumental variable (IV) estimation strategy described above with the *predicted adjacency matrix* and compare our results with the *actual adjacency matrix*.

Empirical Studies of R&D Collaboration Networks There is a large empirical literature on technology spillovers [see e.g. Bloom et al., 2013; Einiö, 2013; Griffith et al., 2006; Jones, 1998]. Besides, there is also a large number of empirical papers on R&D networks, which are mostly descriptive [see e.g. Fleming, 2007; Hanaki et al., 2010; Powell et al., 2005; Rosenkopf and Schilling, 2007]. Compared to these two literatures, we explicitly model the network of R&D collaborations, structurally estimate our model and derive policy implications.

To illustrate our contribution, let us consider a prominent paper within the first strand of literature, namely the one by Bloom et al. [2013]. This paper highlights the key trade-off faced by firms between the *technology (or knowledge) spillover effect* of R&D and the *product rivalry effect*. The former effect captures the *positive* impact of R&D collaborations on output and profit while the latter captures the *negative* impact of competition. The authors first provide different "distance" measures between firms to capture technology spillovers and then test the impact of these two effects on output and profits of firms. They show that the net effect of R&D is positive so that the former dominates the latter effect. Differently to Bloom et al. [2013] we can directly measure the technological spillovers between two firms through the presence of an R&D collaboration between them. We further provide a theoretical model of R&D collaboration networks that incorporates the trade off between the knowledge spillover effect and the product rivalry effect. We structurally estimate our theoretical model using the CATI alliance database and Compustat data and show that the net effect of R&D collaborations is positive. Using our estimates, we empirically apply our model to analyze subsidy and key player policies and provide a ranking of the top 25 firms. We believe that this is the first empirical paper that provides such a ranking based on these two types of R&D policies.

The Key-Player Problem The problem of identifying key players in a network has a long history, at least in the sociology literature. Indeed, one of the focuses of this literature is to propose different measures of network centrality and to assert the descriptive and/or prescriptive suitability of each of these measures to different situations [see, in particular Wasserman and Faust, 1994]. Borgatti [2003, 2006] was among the first to investigate the issue of identifying key players, which is based on explicitly measuring the contribution of a set of actors to the cohesion of a network. The basic strategy is to take any network property, such as density or maximum

flow, and derive a centrality measure by deleting nodes and measuring the change in the network property. Borgatti measures the amount of *reduction* in cohesiveness of the network that would occur if some nodes were not present.

Ballester et al. [2006, 2010] were the first to define the key-player problem in terms of the *behavior* of agents, and the total activity is measured as the sum of efforts of all agents at the Nash equilibrium. As stated above, from a theoretical viewpoint, we extend their intercentrality measure of the key player by looking at welfare loss instead of total activity (output) loss and by including both, the network spillover and the competition effect. In our context, a key firm can help to measure the fragility of the system, since, if it disappears from the economy, welfare reduction will be the highest among all other possible firms.

To the best of our knowledge, there are only two other papers that have empirically tested the key player policy. Liu et al. [2012] test the key player policy for juvenile crime in the United States, while Lindquist and Zenou [2013] identify key players for co-offending networks in Sweden. We are the first to test the key player policy for R&D networks and propose a ranking of firms according to their intercentrality measures. We also consider another policy which consists of subsidizing the R&D expenditures of firms so that total welfare is maximized. In the empirical section, we also compare the ranking of firms in terms of the key player and the subsidy policies.

3. The Model

We consider a general Cournot oligopoly game in which a set $\mathcal{N} = \{1, \dots, n\}$ of firms is partitioned in M heterogeneous product markets.⁵ We also allow for consumption goods to be imperfect substitutes (and thus differentiated products) by adopting the consumer utility maximization approach of Singh and Vives [1984]. We first consider the demand q_i for the good produced by firm i in market \mathcal{M}_m , $m = 1, \dots, M$. A representative consumer in market \mathcal{M}_m obtains the following gross utility from consumption of the goods $(q_i)_{i \in \mathcal{M}_m}$

$$\bar{U}_m((q_i)_{i \in \mathcal{M}_m}) = \alpha_m \sum_{i \in \mathcal{M}_m} q_i - \frac{1}{2} \sum_{i \in \mathcal{M}_m} q_i^2 - \rho \sum_{i \in \mathcal{M}_m} \sum_{j \in \mathcal{M}_m, j \neq i} q_i q_j.$$

In this formulation, the parameter α_m captures the market size or heterogeneity in products, whereas $\rho \in (0, 1]$ measures the degree of substitutability between products. In particular, $\rho = 1$ depicts a market of perfectly substitutable goods, while $\rho = 0$ represents the case of local monopolies.

The consumer maximizes net utility $U_m = \bar{U}_m - \sum_{i \in \mathcal{M}_m} p_i q_i$, where p_i is the price of good

⁵In the empirical analysis, we measure the market in which each firm operates by the Standard Industrial Classification (SIC), which classifies industries by a four-digit code. As a result, a market corresponds to a particular industry or sector.

i. This gives the inverse demand function for firm *i*

$$p_i = \bar{\alpha}_i - q_i - \rho \sum_{\substack{j \in \mathcal{M}_m, \\ j \neq i}} q_j, \quad (1)$$

where we have denoted by $\bar{\alpha}_i = \sum_{m=1}^M \alpha_m \mathbf{1}_{\{i \in \mathcal{M}_m\}}$. In the model, we will study both the general case in which $\rho > 0$ but also the special case when $\rho = 0$. The latter case is when firms are local monopolies so that the price of the good produced by each firm *i* is only determined by its quantity q_i (and the size of the market) and not by the quantities of other firms, i.e. $p_i = \bar{\alpha}_i - q_i$.

Firms can reduce their costs for production by investing in R&D as well as by establishing an R&D collaboration with another firm. The amount of this cost reduction depends on the R&D effort e_i of firm *i* and the R&D efforts of the firms that are collaborating with *i*, i.e., R&D collaboration partners.⁶ Given the effort level $e_i \in \mathbb{R}_+$, the marginal cost c_i of firm *i* is given by⁷

$$c_i = \bar{c}_i - e_i - \varphi \sum_{j=1}^n a_{ij} e_j, \quad (2)$$

The network *G* is captured by **A**, which is a symmetric $n \times n$ *adjacency matrix*. Its element $a_{ij} \in \{0, 1\}$ indicates if there exists a link between nodes *i* and *j* such that $a_{ij} = 1$ if there is a link (i, j) and zero otherwise.⁸ In the context of our model, $a_{ij} = 1$ if firms *i* and *j* set up an R&D collaboration (0 otherwise) and $a_{ii} = 0$. In Equation (2), the total cost reduction for firm *i* stems from its own research effort e_i and the research knowledge of other firms, i.e., *knowledge spillovers*, which is captured by the term $\sum_{j=1}^n a_{ij} e_j$, where $\varphi \geq 0$ is the marginal cost reduction due to neighbor's effort. We assume that R&D effort is costly. In particular, the cost of R&D effort is an increasing function, exhibits decreasing returns, and is given by $\frac{1}{2}e_i^2$. Firm *i*'s profit is then given by

$$\pi_i = (p_i - c_i)q_i - \frac{1}{2}e_i^2. \quad (3)$$

Inserting marginal cost from Equation (2) and inverse demand from Equation (1) into Equation (3) gives

$$\begin{aligned} \pi_i &= (\bar{\alpha}_i - q_i - \rho \sum_{j \in \mathcal{M}_m, j \neq i} q_j - \bar{c}_i + e_i + \varphi \sum_{j=1}^n a_{ij} e_j)q_i - \frac{1}{2}e_i^2 \\ &= (\bar{\alpha}_i - \bar{c}_i)q_i - q_i^2 - \rho \sum_{j=1}^n b_{ij} q_i q_j + q_i e_i + \varphi q_i \sum_{j=1}^n a_{ij} e_j - \frac{1}{2}e_i^2, \end{aligned} \quad (4)$$

where $b_{ij} \in \{0, 1\}$ indicates whether firms *i* and *j* operate in the same market or not, and let **B** be the $n \times n$ matrix whose *ij*-th element is b_{ij} . In Equation (4), we have that $\sum_{j \in \mathcal{M}_m, j \neq i} q_j =$

⁶See also Kamien et al. [1992] for a similar model in which firms unilaterally choose their R&D effort levels.

⁷This generalizes earlier studies such as the one by D'Aspremont and Jacquemin [1988] where spillovers are assumed to take place between all firms in the industry and no distinction between collaborating and non-collaborating firms is made.

⁸See Appendix A.1 for more definitions on networks.

$\sum_{j=1}^n b_{ij}q_j$ since $b_{ij} = 1$ if $i, j \in \mathcal{M}_m$ and $i \neq j$, and $b_{ij} = 0$ otherwise, i.e. if i and j do not belong to the same market. In other words, the matrix \mathbf{B} captures which firms operate in the same market and which firms don't. Take, for example, row i in matrix \mathbf{B} . If there are only zeros, then this means that firm i is alone in its market. If there is a 1 corresponding to column j , then this means that firms i and j operate in the same market (or sector).

In the following, we consider quantity competition among firms à la Cournot.⁹ The next proposition establishes the Nash equilibrium where each firm i simultaneously chooses *both* her quantities q_i and her R&D effort e_i in a given network of R&D collaborations.¹⁰

Proposition 1. *Consider the n -player simultaneous move game with payoffs given by Equation (4) and strategy space in $\mathbb{R}_+^n \times \mathbb{R}_+^n$. Denote by $\mu_i \equiv \bar{\alpha}_i - \bar{c}_i$ for all $i \in \mathcal{N}$, $\boldsymbol{\mu}$ the corresponding $n \times 1$ vector, $\phi \equiv \varphi/(1 - \rho)$, $|\mathcal{M}_m|$ the size of the largest market, \mathbf{I}_n the $n \times n$ identity matrix, \mathbf{u} the $(n \times 1)$ vector of 1 and $\lambda_{PF}(\mathbf{A})$ the largest eigenvalue of \mathbf{A} . Denote also by $\underline{\mu} = \max_i \{\mu_i \mid i \in \mathcal{N}\}$ and $\bar{\mu} = \max_i \{\mu_i \mid i \in \mathcal{N}\}$, with $0 < \underline{\mu} < \bar{\mu}$. We have:*

(i) If

$$\rho + \varphi < \left(\max \left\{ \lambda_{PF}(\mathbf{A}), \max_{m=1, \dots, M} \{(|\mathcal{M}_m| - 1)\} \right\} \right)^{-1} \quad (5)$$

and

$$\rho \max_{m=1, \dots, M} \{(|\mathcal{M}_m| - 1)\} < 1 - \varphi \lambda_{PF}(\mathbf{A}), \quad (6)$$

hold, then there exists a unique interior Nash equilibrium with output levels given by

$$\mathbf{q} = (\mathbf{I}_n + \rho \mathbf{B} - \varphi \mathbf{A})^{-1} \boldsymbol{\mu}. \quad (7)$$

(ii) Assume that there exists only a single market so that $M = 1$. Let the $\boldsymbol{\mu}$ -weighted Bonacich centrality be given by $\mathbf{b}_{\boldsymbol{\mu}}(G, \phi) \equiv (\mathbf{I}_n - \phi \mathbf{A})^{-1} \boldsymbol{\mu}$. If

$$\phi \lambda_{PF}(\mathbf{A}) + \frac{n\rho}{1 - \rho} \left(\frac{\bar{\mu}}{\underline{\mu}} - 1 \right) < 1, \quad (8)$$

holds, then there exists a unique interior Nash equilibrium with output levels given by

$$\mathbf{q} = \left(\frac{1}{1 - \rho} \right) \left[\mathbf{b}_{\boldsymbol{\mu}}(G, \phi) - \frac{\rho \|\mathbf{b}_{\boldsymbol{\mu}}(G, \phi)\|_1}{1 - \rho + \rho \|\mathbf{b}_{\mathbf{u}}(G, \phi)\|_1} \mathbf{b}_{\mathbf{u}}(G, \phi) \right]. \quad (9)$$

(iii) Assume a single market (i.e., $M = 1$) and that $\mu_i = \mu$ for all $i \in \mathcal{N}$. If $\phi \lambda_{PF}(\mathbf{A}) < 1$, then there exists a unique interior Nash equilibrium with output levels given by

$$\mathbf{q} = \frac{\mu}{1 - \rho + \rho \|\mathbf{b}_{\mathbf{u}}(G, \phi)\|_1} \mathbf{b}_{\mathbf{u}}(G, \phi). \quad (10)$$

⁹In Appendix B we show that the same functional forms for best response quantities and efforts can be obtained for price setting firms under Bertrand competition as we find them in the case of Cournot competition.

¹⁰See Appendix A.4 for a precise definition of the Bonacich centrality used in the proposition.

- (iv) Assume a single market (i.e., $M = 1$), $\mu_i = \mu$ for all $i \in \mathcal{N}$ and that goods are non-substitutable (i.e., $\rho = 0$). If $\varphi < \lambda_{PF}(\mathbf{A})^{-1}$, then the unique equilibrium quantities are given by $\mathbf{q} = \mu \mathbf{b}_u(G, \varphi)$.
- (v) Let \mathbf{q} be the unique Nash equilibrium quantities in any of the above cases (i) to (iv), then for all $i \in \mathcal{N} = \{1, \dots, n\}$ equilibrium profits are given by

$$\pi_i = \frac{1}{2} q_i^2, \quad (11)$$

and equilibrium efforts are given by

$$e_i = q_i. \quad (12)$$

This proposition gives the results of the Nash equilibrium starting from the most general case where firms can operate and have links in any market (case (i)) to the case when all firms operate in the same market (case (ii)) and when they have the same fixed cost of production and no product heterogeneity (case (iii)) and, finally, when, on top of that, goods are not substitutable (case (iv)). Indeed, it is easily verified (Appendix E, proof of Proposition 1) that the first-order condition with respect to R&D effort e_i is given by Equation (12)¹¹ while the first-order condition with respect to quantity q_i leads to:

$$q_i = \mu_i - \rho \sum_{j=1}^n b_{ij} q_j + \varphi \sum_{j=1}^n a_{ij} q_j. \quad (13)$$

or, in matrix form: $\mathbf{q} = \boldsymbol{\mu} - \rho \mathbf{B} \mathbf{q} + \varphi \mathbf{A} \mathbf{q}$. In terms of the literature on games on networks [Jackson and Zenou, 2014], this proposition generalizes the results of Ballester et al. [2006] and Calvó-Armengol et al. [2009] for the case of local competition in different markets and choices of both effort and quantity. This proposition provides a total characterization of an interior Nash equilibrium as well as its existence and uniqueness in a very general framework when different markets and different products are considered. If we consider case (i), the new conditions are Equations (5) and (6), which guarantee the existence, uniqueness and interiority of the Nash equilibrium solutions in the most general case. In case (ii) where all firms operate in the same market, in order to obtain a unique interior solution, only the condition in Equation (8) is required, which generalizes the usual condition $\phi \lambda_{PF}(\mathbf{A}) < 1$ given, for example, in Ballester et al. [2006]. In fact, the condition in Equation (8) imposes a more stringent requirement on $\rho, \varphi, \mathbf{A}$ as the left-hand side of the inequality is now augmented by $\frac{n\rho}{1-\rho} \left(\frac{\bar{\mu}}{\underline{\mu}} - 1 \right) \geq 0$. That is, everything else equal, the higher the discrepancy $\bar{\mu}/\underline{\mu}$ of marginal payoffs at the origin, the lower is the level of network complementarities $\phi \lambda_{PF}(\mathbf{A})$ compatible with a unique and interior Nash equilibrium.

More generally, the key insight of Proposition 1 is the interaction between the *network effect*,

¹¹The proportional relationship between R&D effort levels and output in Equation (12) has been confirmed in a number of empirical studies [see e.g. Cohen and Klepper, 1996,].

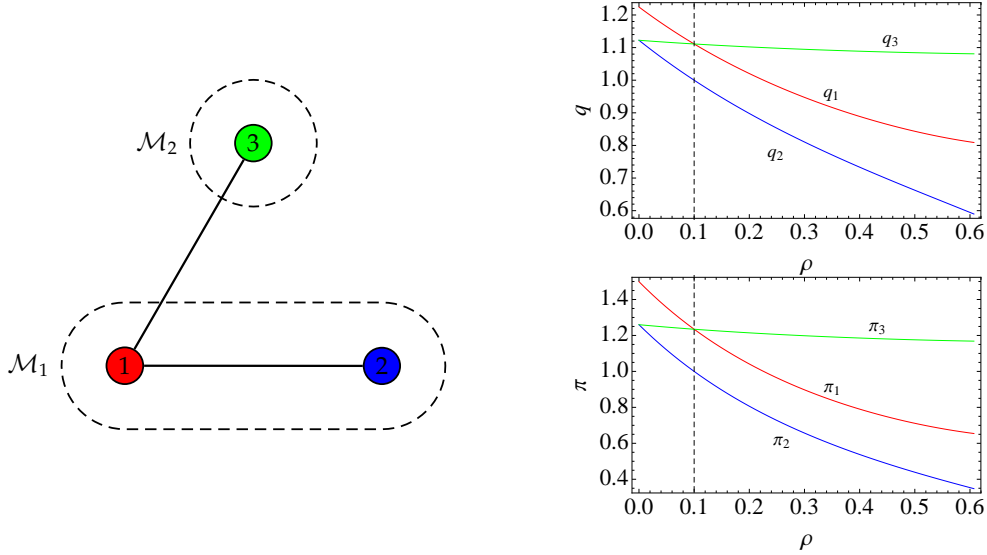


Figure 1: Equilibrium output from Equation (15) and profits for the three firms with varying values of the competition parameter $0 \leq \rho \leq \frac{1}{2}(\sqrt{2} - 2\varphi)$, $\mu = 1$ and $\varphi = 0.1$. Profits of firms 1 and 3 intersect at $\rho = \varphi$ (indicated with a dashed line).

through the adjacency matrix \mathbf{A} , and the *market effect*, through the competition matrix \mathbf{B} and that is why the first-order condition with respect to q_i given by Equation (13) takes into account both of them. To better understand this result, consider the following simple example of an industry composed of 3 firms and 2 sectors, \mathcal{M}_1 and \mathcal{M}_2 , where firm 1 and 2, as well as firm 1 and firm 3 have an R&D collaboration, while firms 1 and 2 operate in the same market \mathcal{M}_1 (see Figure 1).

Then the adjacency matrix \mathbf{A} and the competition matrix \mathbf{B} are given by

$$\mathbf{A} = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad \mathbf{B} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

Assume that firms are homogeneous such that $\mu_i = \mu$ for $i = 1, 2, 3$. Using Proposition 1, the equilibrium output is given by

$$\mathbf{q} = \mu(\mathbf{I} - \varphi\mathbf{A} + \rho\mathbf{B})^{-1}\mathbf{u} = \frac{\mu}{1 - 2\varphi^2 + 2\varphi\rho - \rho^2} \begin{pmatrix} 1 + 2\varphi - \rho \\ (\varphi + 1)(1 - \rho) \\ (1 + \rho)(1 + \varphi - \rho) \end{pmatrix}. \quad (14)$$

Profits are equal to $\pi_i = 1/2q_i^2$ for $i = 1, 2, 3$. The condition for an interior equilibrium is $\rho + \varphi < 1/\sqrt{2}$. Figure 1 shows an illustration of equilibrium outputs and profits for the three firms with varying values of the competition parameter $0 \leq \rho \leq \frac{1}{2}(\sqrt{2} - 2\varphi)$, $\mu = 1$ and $\varphi = 0.1$. We see that firm 1 has higher profits due to having the largest number of R&D collaborations when competition is weak (ρ is low compared to φ). However, when ρ increases,

its profits decrease and become smaller than the profit of firm 3 when $\rho > \varphi$. This result highlights the key trade off faced by firms between the *technology (or knowledge) spillover effect* and the *product rivalry effect* of R&D [cf. Bloom et al., 2013] since the former increases with φ , which captures the intensity of spillover effect while the latter increases with ρ , which indicates the degree of competition in the product market.

To better understand these two effects, consider the case of a single market, that is $M = 1$. It is easily verified that, in that case, $\mathbf{B} = (\mathbf{u}\mathbf{u}^\top - \mathbf{I}_n)$ where $\mathbf{u} = (1, \dots, 1)^\top$ is an n -dimensional vector of ones. In our example, if there is only one market, all three firms will compete with each other in the same market so that:

$$\mathbf{B} = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}.$$

If $\varphi/(1 - \rho) < 1/\sqrt{2}$, then the unique equilibrium output will given by:

$$\mathbf{q} = \frac{\mu}{1 - 2\varphi^2 + 4\varphi\rho + \rho - 2\rho^2} \begin{pmatrix} 1 + 2\varphi - \rho \\ 1 + \varphi - \rho \\ 1 + \varphi - \rho \end{pmatrix}. \quad (15)$$

Since there is only one market, the position in the network will determine which firm will produce the most and have the highest profit. Since firm 1 is the most central firm in the network and has the highest Bonacich centrality, it has the highest profit. In other words, when $M = 1$, only the *technology (or knowledge) spillover effect* matters and the position in the network is the only determinant of output and profit. We saw, however, that this was not the case in the previous example where there were two markets because, compared to firm 3, even if firm 1 had the highest Bonacich centrality, it was competing with firm 2 on the product market while firm 3 had no competitor in her market. In other words, there is now a trade off between the position in the network (*technology (or knowledge) spillover effect*) and the position in the product market (*product rivalry effect*). We have seen that, depending on the values of ρ and φ , firm 1 can have a higher or lower output and profit than firm 3.

4. Welfare

Let us now determine the welfare of this economy. We will consider different cases from general to more specific. Inserting the inverse demand from Equation (1) into net utility U_m of the consumer in market \mathcal{M}_m shows that

$$U_m = \frac{1}{2} \sum_{i \in \mathcal{M}_m} q_i^2 + \frac{\rho}{2} \sum_{i \in \mathcal{M}_m} \sum_{\substack{j \in \mathcal{M}_m, \\ j \neq i}} q_i q_j$$

In the special case of non-substitutable goods, when $\rho = 0$, we obtain

$$U_m = \frac{1}{2} \sum_{i \in \mathcal{M}_m} q_i^2,$$

while in the case of perfectly substitutable goods, when $\rho = 1$, we get

$$U_m = \frac{1}{2} \left(\sum_{i \in \mathcal{M}_m} q_i \right)^2.$$

The total consumer surplus is then given by $U = \sum_{m=1}^M U_m$. Producer surplus is given by aggregate profits $\Pi = \sum_{i=1}^n \pi_i$. As a result, the total welfare is equal to $W = U + \Pi$.

4.1. Non-Substitutable Goods

When products are not substitutable ($\rho = 0$), the total welfare is given by the producer and consumer surplus, which can then be written as

$$W(G) = \sum_{i=1}^n \left(\frac{q_i^2}{2} + \pi_i \right) = \sum_{i=1}^n q_i^2.$$

The following proposition provides upper and lower bounds on welfare for any given graph G , and determines the welfare maximizing graph.

Proposition 2. *Consider independent markets with $\rho = 0$ and let μ_i and φ be defined as in Proposition 1. Denote by $\mathcal{G}(n)$ the class of graphs with n nodes and the class of graphs with n nodes and m links by $\mathcal{H}(n, m) \subset \mathcal{G}(n)$.*

- (i) *Let the largest eigenvalue of the adjacency matrix \mathbf{A} be given by λ_{PF} and let \mathbf{v}_{PF} be the associated eigenvector. Then social welfare can be written as*

$$W(G) = \frac{(\boldsymbol{\mu}^\top \mathbf{v}_{PF})^2}{(1 - \varphi \lambda_{PF})^2} + o\left(\frac{1}{1 - \varphi \lambda_{PF}}\right),$$

and in the limit of large φ the efficient graph $G^ = \operatorname{argmax}_{G \in \mathcal{H}(n, m)} W(G)$ is a nested split graph in which the ordering of degrees $\{d_i\}_{i=1}^n$ follows the ordering of $\{\mu_i\}_{i=1}^n$.*

- (ii) *Assume that $\mu_i = \mu$ for all $i \in \mathcal{N}$. Then welfare in the efficient graph $G^* = \operatorname{argmax}_{G \in \mathcal{H}(n, m)} W(G)$ can be bounded from above and from below as*

$$\frac{\mu^2 n}{(1 - \varphi \bar{d})^2} \leq W(G^*) \leq \frac{\mu^2 n}{\left(1 - \varphi \sqrt{(n-1)\bar{d}}\right)^2},$$

where $\bar{d} = \frac{2m}{n}$ is the average degree in G .

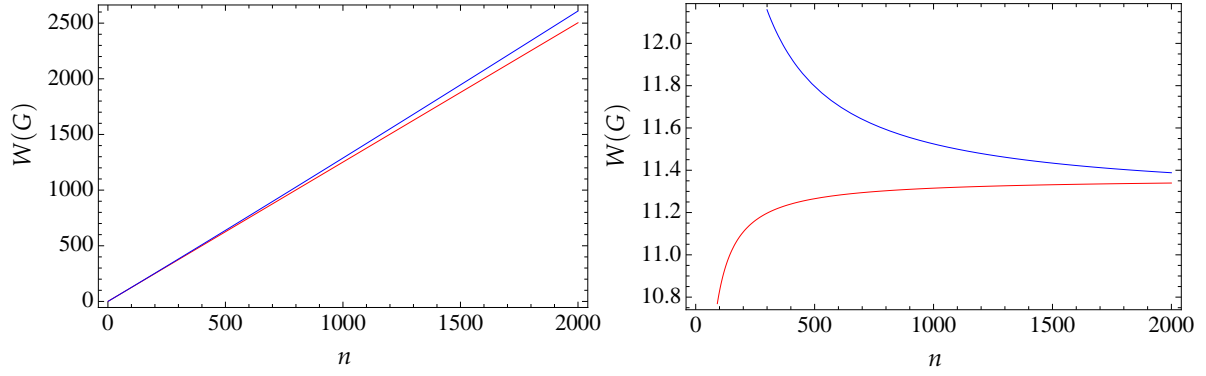


Figure 2: (Left panel) The two bounds from Proposition 2 for $\rho = 0.1$, $\varphi = 0.001$, $\mu = 1$, $m = n - 1$ for varying values of n . (Right panel) The two bounds from Proposition 4 for the same parameter values. Note that the comparison of welfare in the case of $\rho = 0$ and $\rho > 0$ in the above figures for increasing n is not meaningful as the first considers a growing number of products, while the latter a single product with an increasing number of firms producing it.

- (iii) The efficient graph $G^* = \operatorname{argmax}_{G \in \mathcal{G}(n)} W(G)$ is the one that maximizes the largest eigenvalue λ_{PF} , that is, the complete graph K_n .

This proposition provides several interesting results. First, when products are not substitutable ($\rho = 0$), we are able to write an explicit expression of the total welfare as a function of the fundamental parameters of the model and to provide a lower and an upper bound on this welfare function where the bounds depend on the parameters as well as the topology of the network (captured by the average degree in the network). Second, in terms of network design, when $\rho = 0$, there is no competition effect and thus only spillover effects through the network matter. As a result, it should not be surprising that the complete network is the efficient network because of positive complementarities between firms. We also show that, when φ is large (close to its maximum value in the limit), the nested split graph is the efficient network.^{12,13} Basically, in a nested-split graph the neighborhood of a node is contained in the neighborhoods of the nodes with higher degrees (see König et al. [2014] for a discussion of these graphs). If one looks at the leading term in the welfare function, then one can see that it depends on the product of μ and the Perron eigenvector \mathbf{v}_{PF} . In any nested split graph, the node with the highest degree also has the highest eigenvector. As a result, in order to maximize total welfare, one wants to have the node i with the highest μ_i to have the highest eigenvector component, which means that it should also have the highest degree. Note that similar results relating the largest eigenvalue to efficiency have been obtained in Corbo et al. [2006], König et al. [2011] and Belhaj et al. [2013]. The two bounds from Proposition 2 part (ii) are shown in Figure 2.

¹²The complete graph K_n is a particular (degenerate) case of a nested split graph.

¹³In Appendix A.3, we formally define nested-split graphs.

4.2. Imperfectly Substitutable Goods

In this section, we allow for products to be substitutable, i.e. $\rho > 0$. Then social welfare is given by

$$W(G) = \frac{1}{2} \left(\sum_{i=1}^n q_i^2 + \rho \sum_{i=1}^n \sum_{j \neq i}^n b_{ij} q_i q_j \right) + \sum_{i=1}^n \pi_i,$$

where equilibrium output and profit are given by Equations (9) and (11). Inserting profits as a function of output leads to:

$$W(G) = \sum_{i=1}^n q_i^2 + \frac{\rho}{2} \sum_{i=1}^n \sum_{j \neq i}^n b_{ij} q_i q_j = \mathbf{q}^\top \mathbf{q} + \frac{\rho}{2} \mathbf{q}^\top \mathbf{B} \mathbf{q},$$

We are now able to state a similar result as in part (i) of Proposition 2 for the case of (imperfectly) substitutable goods.

Proposition 3. Denote by $\mathbf{C} = \mathbf{A} - \frac{\rho}{\varphi} \mathbf{B}$, let $\{v_i\}_{i=1}^n$ be the eigenvalues of \mathbf{C} and $\{\mathbf{v}_i\}_{i=1}^n$ the associated eigenvectors. Then welfare can be written as

$$W(G) = \frac{2-\rho}{2} \frac{(\boldsymbol{\mu}^\top \mathbf{v}_1)^2}{(1-\varphi v_1)^2} \left(1 + \frac{\rho}{2-\rho} \mathbf{v}_1^\top \mathbf{B} \mathbf{v}_1 \right) + o \left(\frac{1}{1-\varphi v_1} \right)^2.$$

Proposition 3 shows that when spillover effects are strong such that the leading terms in $1/(1-\varphi v_1)$ dominate, then welfare is determined by the weighted sum of the eigenvector components $\boldsymbol{\mu}^\top \mathbf{v}_1 = \sum_{i=1}^n \mu_i v_{1,i}$ and the pairwise eigenvector complementarity effects in different markets $\mathbf{v}_1^\top \mathbf{B} \mathbf{v}_1 = \sum_{i=1}^n \sum_{j=1}^n v_{1,i} b_{ij} v_{1,j}$.

To gain further insights, we will assume in the following that there is only a single market (with $M = 1$, $b_{ij} = 1$ for $i \neq j$ and $b_{ii} = 0$ for all $i, j \in \mathcal{N}$) and make the homogeneity assumption that $\mu_i = \mu$ for all $i \in \mathcal{N}$. Then welfare can be written as follows

$$W(G) = \frac{2-\rho}{2} \|\mathbf{q}\|_2^2 + \frac{\rho}{2} \|\mathbf{q}\|_1^2,$$

where $\|\mathbf{q}\|_p \equiv (\sum_{i=1}^n q_i^p)^{\frac{1}{p}}$ is the ℓ^p -norm of \mathbf{q} and $\mathbf{u} = (1, \dots, 1)^\top$ is a vector of ones. Using the fact that $\|\mathbf{q}\|_2 \leq \|\mathbf{q}\|_1 \leq \sqrt{n} \|\mathbf{q}\|_2$, we obtain an upper bound on welfare given by

$$W(G) \leq \frac{2 + (n-1)\rho}{2} \|\mathbf{q}\|_2^2 = (2 + (n-1)\rho) \Pi,$$

where aggregate profits are given by $\Pi = \sum_{i=1}^n \pi_i$. Hence, welfare is upper bounded by a proportionality factor times the total profits generated in the economy.

We next consider the efficient network for small values of $\phi = \varphi/(1-\rho)$ (defined as in Proposition 1).

Proposition 4. Consider a large market with substitutable goods where $\rho > 0$. Further, assume that

$\mu_i = \mu$ for all $i = 1, \dots, n$, and let ρ , μ , ϕ and ϕ be defined as in Proposition 1. Denote by $\mathcal{G}(n)$ the class of graphs with n nodes and the class of graphs with n nodes and m links by $\mathcal{H}(n, m) \subset \mathcal{G}(n)$.

- (i) For small values of ϕ , such that terms of the order $O(\phi^3)$ can be neglected, welfare $W(G)$ is maximized in the graph $G \in \mathcal{H}(n, m)$ with the smallest degree variance σ_d^2 .
- (ii) For small values of ϕ such that terms of the order $O(\phi^4)$ can be neglected, welfare $W(G)$ for two graphs $G, G' \in \mathcal{H}(n, m)$ with the same degree variance σ_d^2 is higher for the one which is less degree assortative.
- (iii) Assume that $0 < \rho < 1$. The welfare in the efficient graph $G^* = \operatorname{argmax}_{G \in \mathcal{H}(n, m)} W(G)$ and can be bounded from above and from below as follows:

$$\frac{\mu^2}{2} \frac{n((n-1)\rho + 2)}{((n-1)(\rho - \phi) + 1)^2} \leq W(G^*) \leq \frac{2 - \rho}{2} \frac{\mu^2}{\rho^2} \left(\frac{\rho}{2 - \rho} + \frac{1 - \rho}{n(1 - \rho - \phi\sqrt{2m(n-1)/n})} \right).$$

- (iv) Assume that $0 < \rho < 1$. In the limit of weak spillovers and large population size the efficient graph in $\mathcal{G}(n)$ is the complete graph K_n , that is $\lim_{\phi \rightarrow 0} \lim_{n \rightarrow \infty} W(K_n) = W(G^*)$.

Proposition 4 case (i) contrasts to previous studies such as Westbrock [2010], where it is argued that welfare in R&D collaboration networks is increasing with the degree variance. Part (ii) of the proposition shows that, once we allow for stronger spillover effects, the assortativity of the network also matters for welfare.¹⁴ Part (iii) gives a general result when the competition effect is not too strong (i.e. when $0 < \rho < 1$). In that case, the welfare maximizing graph G^* can be bounded above and below. The two bounds from part (iii) of Proposition 4 are shown in Figure 2. The last result shows again that the complete network is the efficient one if spillover effects are not too strong.¹⁵

5. The Key Player Policy

As stated in the Introduction, the key-player problem has first been introduced in economics by Ballester et al. [2006, 2010]. In the context of crime, they have argued that concentrating efforts by targeting *key players*, i.e. criminals who once removed generate the highest possible reduction in aggregate crime level in a network, can have large effects on crime because of feedback effects or *social multipliers*. Based on a peer-effect model, Ballester et al. [2006, 2010] have proposed a centrality measure (the *intercentrality measure*) that determines the key player in each network. Because we are not dealing with crime but with R&D networks, we will

¹⁴The assortativity coefficient $\rho_d(G) \in [-1, 1]$ is essentially the Pearson correlation coefficient of degree between nodes that are connected. Positive values of $\rho_d(G)$ indicate that nodes with similar degrees tend to be connected, while negative values indicate that nodes with different degrees tend to be connected. See Newman [2002] and Pastor-Satorras et al. [2001] for further details.

¹⁵In Appendix C, we provide additional results on welfare where we focus on a particular class of networks, namely the ones with a large spectral gap.

redefine the key-player policy in the following way. First, as shown in Proposition 1, where only cases (iii) and (iv) correspond to the model of Ballester et al. [2006, 2010], we will consider a much more general model where both network and competition effects matter in a context of different markets (or sectors) and different types of goods. Second, we define the key player in a different way: it will be the firm which once removed from the network reduces *total welfare* the most (and not *total activity* or *total output* as in Ballester et al. [2006, 2010]). As it will turn out, the centrality that we obtain to define the key player (or key firm) will be quite different from the intercentrality measure proposed by Ballester et al. [2006, 2010].

Let G^{-i} be the network obtained from G by removing firm i . The key firm is the one whose removal from the network reduces welfare the most, i.e., the key firm $i^* \in \mathcal{N} = \{1, \dots, n\}$ and is defined by $i^* = \arg \max_{i \in \mathcal{N}} \{W(G) - W(G^{-i})\}$. The following proposition characterizes the key firm i^* both when $\rho = 0$ and when $\rho > 0$.

Proposition 5. *Let $\rho, \mu_i, i \in \mathcal{N}, \varphi$ and ϕ be defined as in Proposition 1.*

- (i) *Assume that goods are not substitutable, i.e. $\rho = 0$ and let $\varphi < 1/\lambda_{PF}$. Moreover, let $N_G(\varphi, i) = m_{ii}(G, \varphi)$ denote the generating function of the number of closed walks¹⁶ that start and terminate at node i and let $\mathbf{M}(G, \varphi) \equiv (\mathbf{I}_n - \varphi \mathbf{A})^{-1}$. Then the key firm is given by $i^* = \arg \max_{i \in \mathcal{N}} c_i(G, \varphi)$, where the intercentrality of firm i is given by*

$$c_i(G, \varphi) = \frac{b_{\mu,i}(G, \varphi)}{N_G(\varphi, i)} \left[(\mathbf{M}(G, \varphi) \mathbf{b}_{\mu}(G, \varphi))_i - \frac{1}{2} \frac{b_{\mu,i}(G, \varphi)}{N_G(\varphi, i)} (\mathbf{M}(G, \varphi)^2)_{ii} \right]. \quad (16)$$

- (ii) *Assume that goods are substitutable, i.e. $\rho > 0$, that the matrix $\mathbf{M}(G, \rho, \varphi) = (\mathbf{I}_n + \rho \mathbf{B} - \varphi \mathbf{A})^{-1}$ exists,¹⁷ and let $\mathbf{b}_{\mu}(G, \rho, \varphi) = \mathbf{M}(G, \rho, \varphi) \boldsymbol{\mu}$. Then the key firm is given by $i^* = \arg \max_{i \in \mathcal{N}} c_i(G, \rho, \varphi)$, where the intercentrality of firm i is given by*

$$c_i(G, \rho, \varphi) = \frac{b_{\mu,i}(G, \rho, \varphi)}{m_{ii}(G, \rho, \varphi)} \left((\mathbf{M}(G, \rho, \varphi) (2\mathbf{I}_n + \rho \mathbf{B}) \mathbf{b}_{\mu}(G, \rho, \varphi))_i - \frac{1}{2} \frac{b_{\mu,i}(G, \rho, \varphi)}{m_{ii}(G, \rho, \varphi)} (\mathbf{M}(G, \rho, \varphi) (2\mathbf{I}_n + \rho \mathbf{B}) \mathbf{M}(G, \rho, \varphi))_{ii} \right).$$

Let us start with case (i), which assumes that goods are not substitutable, i.e. $\rho = 0$. We propose a new intercentrality measure, which is an alternative to that of Ballester et al. [2006, 2010] defined as $\frac{b_{\mu,i}(G, \varphi)^2}{N_G(\varphi, i)}$. Our intercentrality measure is defined as $c_i = \frac{1}{2} \frac{d}{d\varphi} \left(\frac{\varphi b_{\mu,i}(G, \varphi)^2}{N_G(\varphi, i)} \right)$, which, after some calculations can be written as in Equation (16) (see the proof of Proposition 5). As for the case of crime, the key firm needs not necessarily be the one producing the highest output level or, equivalently, the one with the highest Bonacich centrality measure. This is because the removal of the key firm has both a *direct* and an *indirect* effect on the total welfare and thus

¹⁶See Appendix A.2 for a formal definition of walk generating functions of a graph and some results associated with them.

¹⁷See Proposition 1, item (i), for a sufficient condition that guarantees that this matrix is invertible.

the choice of the key firm results from a compromise between these two effects. Indeed, if the choice of the key firm was solely governed by the direct effect of firm removal on aggregate welfare, then the most productive firms would be the natural candidates. But the choice of the key firm needs also to take into account the indirect effect on aggregate welfare reduction induced by the network restructuring that follows from the removal of one firm from the original network. Our intercentrality measure defined in Equation (16) takes into account this trade off. Interestingly, in both intercentrality measures (ours and that of Ballester et al. [2006, 2010]), the two effects appear since they include both the Bonacich centrality of the key firm (direct effect) and the generating function of the number of closed walks that start and terminate at the key firm (indirect effect through self-loops).

If we now consider the more general case ($\rho > 0$) where both the network effect and the competition effect are taken into account, it can be seen that there is a difference in the weighted Bonacich centralities $\mathbf{b}_\mu(G, \cdot)$ between part (i) and part (ii) of Proposition 5. While the first is the standard weighted Bonacich centrality of the network G with firm specific weights μ_i (see Appendix A.4), in part (ii), the Bonacich centrality depends on both, the adjacency matrix \mathbf{A} of network G and the block diagonal matrix \mathbf{B} , which indicates which firm is competing with other firms. This is an important generalization of the intercentrality measure of the key player, which we believe is crucial when one deals with R&D networks (but also any network with both spillover and competition effects), since, as stated above, there is a key trade off faced by firms between the *technology (or knowledge) spillover effect* and the *product rivalry effect* of R&D that needs to be accounted for.

6. The R&D Subsidy Policy

In this section, we would like to consider an alternative policy to the key player one, that is R&D subsidies. Indeed, in order to foster innovative activities and economic growth, governments in numerous countries have introduced R&D support programs aimed at increasing R&D effort in the private sector.¹⁸ Also, national governments in a number of countries subsidize R&D activities of domestic firms, particularly in industries in which foreign and domestically owned firms are in competition for international markets. Such programs are, for example, the Eureka program in the European Union or the SPIR program in the United States.

To better understand this issue, we would now like to extend our framework by considering an optimal R&D subsidy program in the short run, i.e. taking the network G as given. For our analysis, we first assume that all firms obtain a homogeneous subsidy per unit of R&D effort spent. We then proceed by allowing the social planner to differentiate between firms and implement firm specific R&D subsidies.

¹⁸Public R&D grants covered about 7.5 % of private R&D in the OECD countries in 2004 (OECD [2012]). For an overview of R&D tax credits which are another commonly used fiscal incentive for R&D investment, see Bloom et al. [2002].

6.1. Homogeneous R&D Subsidies

Let us first consider the case of a single market, $M = 1$. An active government is introduced that can provide a subsidy, $s \geq 0$, per unit of R&D. It is assumed that each firm receives the same per unit R&D subsidy. The profit of firm i with R&D subsidy can then be written as:

$$\pi_i = (\bar{\alpha} - \bar{c}_i)q_i - q_i^2 - \rho q_i \sum_{j \neq i} b_{ij}q_j + q_i e_i + \varphi q_i \sum_{j=1}^n a_{ij}e_j - \frac{1}{2}e_i^2 + se_i. \quad (17)$$

This formulation is similar to that of [Spencer and Brander \[1983\]](#) where each firm i receives a fixed amount of money se_i proportional to firm i 's effort e_i . The government (or planner) is introduced here as an agent that can set subsidy rates on R&D effort in a period before the firms spend on R&D. The assumption that the government can pre-commit itself to such subsidies and thus can act in this leadership role is fairly natural. As a result, this subsidy will affect the levels of R&D committed by firms but not the resolution of the output game. In this context, the optimal R&D subsidy s^* determined by the planner is found by maximizing total welfare $W(G, s)$ less the cost of the subsidy $s \sum_{i=1}^n e_i$ taking into account the fact that firms choose output and effort for a given subsidy level by maximizing profits in Equation (17). If we define net welfare as $\bar{W}(G, s) \equiv W(G, s) - \sum_{i=1}^n e_i s_i$, then the social planner's problem is given by

$$s^* = \arg \max_{s \in \mathbb{R}_+} \bar{W}(G, s).$$

The following proposition derives the Nash equilibrium quantities and efforts, and the optimal subsidy level that solves the planner's problem.

Proposition 6. *Consider the n -player simultaneous move game with profits given by Equation (17) where firms choose quantities and efforts in the strategy space in $\mathbb{R}_+^n \times \mathbb{R}_+^n$. Further, let $\mu_i, i \in \mathcal{N}$ be defined as in Proposition 1.*

- (i) *If Equation (5) holds, then the matrix $\mathbf{M} = (\mathbf{I}_n + \rho \mathbf{B} - \varphi \mathbf{A})^{-1}$ exists, and the unique interior Nash equilibrium in quantities with subsidies (in the second stage) is given by*

$$\mathbf{q} = \bar{\mathbf{q}} + s\mathbf{r}, \quad (18)$$

where $\bar{\mathbf{q}} = \mathbf{M}\boldsymbol{\mu}$ and $\mathbf{r} = \varphi \mathbf{M} \left(\frac{1}{\varphi} \mathbf{u} + \mathbf{A}\mathbf{u} \right)$. The equilibrium profits are given by

$$\pi_i = \frac{q_i^2 + s^2}{2}, \quad (19)$$

- (ii) *Assume that goods are not substitutable, i.e. $\rho = 0$. Then if $\sum_{i=1}^n (r_i^2(1-3) + 2r_i + 1) \geq 0$, the optimal subsidy level (in the first stage) is given by*

$$s^* = \frac{\sum_{i=1}^n \bar{q}_i (1 - 2r_i)}{\sum_{i=1}^n (r_i (2r_i - 2) - 1)},$$

(iii) Assume that goods are substitutable, i.e. $\rho > 0$. Then if

$$\sum_{i=1}^n \left(r_i^2(1-3) + 2r_i + 1 - \rho \sum_{j=1}^n b_{ij}r_i r_j \right) \geq 0,$$

the optimal subsidy level (in the first stage) is given by

$$s^* = \frac{\sum_{i=1}^n \left(\bar{q}_i(2r_i - 1) + \frac{\rho}{2} \sum_{j=1}^n b_{ij}(\bar{q}_i r_j + \bar{q}_j r_i) \right)}{\sum_{i=1}^n \left(1 + r_i \left(2 - 2r_i - \rho \sum_{j=1}^n b_{ij}r_j \right) \right)},$$

In part (i) of Proposition 6, we solve the second stage of the game in which firms decide their output given the homogenous subsidy s . In parts (ii) and (iii) of the proposition, we solve the first stage when the planner optimally decide the subsidy per R&D effort when goods are not substitutable, i.e. $\rho = 0$, and when they are ($\rho > 0$). We are able to determine the exact value of the optimal subsidy to be given to each firm embedded in a network of R&D collaborations in both cases. Interestingly, the optimal subsidy depends on the vector $\mathbf{r} = \mathbf{M}\mathbf{u} + \varphi\mathbf{M}\mathbf{A}\mathbf{u}$ where the vector $\mathbf{A}\mathbf{u}$ determines the *degree* (i.e. number of links) of each firm.

6.2. Targeted R&D Subsidies

We now consider the case where the planner can discriminate between firms by offering different subsidies. In other words, we assume that each firm i , for all $i = 1, \dots, n$, obtains a subsidy $s_i \geq 0$ per unit of R&D effort. The profit of firm i can then be written as:

$$\pi_i = (\bar{\alpha} - \bar{c}_i)q_i - q_i^2 - \rho q_i \sum_{j \neq i} b_{ij}q_j + q_i e_i + \varphi q_i \sum_{j=1}^n a_{ij}e_j - \frac{1}{2}e_i^2 + s_i e_i. \quad (20)$$

As above, the optimal R&D subsidies \mathbf{s}^* are then found by maximizing welfare $W(G, \mathbf{s})$ less the cost of the subsidy $\sum_{i=1}^n s_i e_i$, when firms are choosing output and effort for a given subsidy level by maximizing profits in equation (20). If we define net welfare as $\bar{W}(G, \mathbf{s}) \equiv W(G, \mathbf{s}) - \sum_{i=1}^n e_i s_i$, then the social planner's problem is given by

$$\mathbf{s}^* = \arg \max_{\mathbf{s} \in \mathbb{R}_+^n} \bar{W}(G, \mathbf{s}).$$

The following proposition derives the Nash equilibrium quantities and efforts (second stage), and the optimal subsidy levels that solves the planner's problem (first stage).

Proposition 7. Consider the n -player simultaneous move game with profits given by Equation (17) where firms choose quantities and efforts in the strategy space in $\mathbb{R}_+^n \times \mathbb{R}_+^n$. Further, let $\mu_i, i \in \mathcal{N}$ be defined as in Proposition 1.

(i) If Equation (5) holds, then the matrix $\mathbf{M} = (\mathbf{I}_n + \rho\mathbf{B} - \varphi\mathbf{A})^{-1}$ exists, and the unique interior

Nash equilibrium in quantities with subsidies (in the second stage) is given by

$$\mathbf{q} = \bar{\mathbf{q}} + \mathbf{R}\mathbf{s}, \quad (21)$$

where $\mathbf{R} = \mathbf{M}(\mathbf{I}_n + \rho\mathbf{A})$, and equilibrium profits are given by

$$\pi_i = \frac{q_i^2 + s_i^2}{2}. \quad (22)$$

(ii) Assume that goods are not substitutable, i.e. $\rho = 0$. Then if the matrix $\mathbf{I}_n + 2\mathbf{R} - 2\mathbf{R}^2$ is positive definite, the optimal subsidy levels (in the first stage) are given by

$$\mathbf{s}^* = (\mathbf{I}_n + 2\mathbf{R} - 2\mathbf{R}^2)^{-1}(2\mathbf{R} - \mathbf{I}_n)\bar{\mathbf{q}}.$$

(iii) Assume that goods are substitutable, i.e. $\rho > 0$. Then if the matrix $\mathbf{I}_n - 2\mathbf{R}^\top \left(\frac{1}{2}(2\mathbf{I}_n + \rho\mathbf{B}) \mathbf{R} - \mathbf{I}_n \right)$ is positive definite, the optimal subsidy levels (in the first stage) are given by

$$\mathbf{s}^* = \left(\mathbf{I}_n - 2\mathbf{R}^\top \left(\frac{1}{2}(2\mathbf{I}_n + \rho\mathbf{B}) \mathbf{R} - \mathbf{I}_n \right) \right)^{-1} \left(\mathbf{R}^\top (2\mathbf{I}_n + \rho\mathbf{B}) - \mathbf{I}_n \right) \bar{\mathbf{q}}.$$

As in the previous proposition, in part (i) of Proposition 7, we solve for the second stage of the game in which firms decide their output given the *targeted* subsidy s_i . In parts (ii) and (iii), we solve the first stage of the model when the planner optimally decide the targeted subsidy per R&D effort when goods are substitutable, i.e. $\rho > 0$, and when they are not. We are able to determine the exact value of the optimal subsidy to be given to each firm embedded in a network of R&D collaborations in both cases. We will use the results of these two propositions below to empirically study R&D collaborations between firms in our dataset.

We would like now to test the different parts of the theoretical results. First, we will test Proposition 1 and will try to disentangle between the *technology (or knowledge) spillover effect* and the *product rivalry effect* of R&D. Second, once the parameters of the model have been estimated, we will determine who the key firms are in our dataset and compared to the ones that should be subsidized.

7. Data

We use data on interfirm R&D collaborations stemming from the MERIT-CATI database.¹⁹ Given its history and coverage, the MERIT-CATI database is one of the few databases that allows us to study patterns in R&D partnerships in several industries, both domestic and internationally, in different regions of the world over an extended period of several decades.

¹⁹We would like to thank Christian Helmers for providing access to the dataset.

This database contains information about strategic technology agreements, including any alliance that involves some arrangements for mutual transfer of technology or joint research, such as joint research pacts, joint development agreements, cross licensing, R&D contracts, joint ventures and research corporations [cf. [Hagedoorn, 2002](#)].²⁰ The database records only agreements for which a combined innovative activity or an exchange of technology is at least part of the agreement. Moreover, only agreements that have at least two industrial partners are included in the database, thus agreements involving only universities or government labs, or one company with a university or lab, are disregarded. From the MERIT-CATI database we then obtain a total of 13,040 companies. The systematic collection of inter-firm alliances started in 1987 and ends in 2006. However, information about alliances prior to 1987 are available in the database, and we use all the information available starting from the year 1950.²¹ We construct the R&D alliance network by assuming that an alliance lasts for 5 years [similar to e.g. [Rosenkopf and Padula, 2008](#)].²² In the robustness section below (Section 9.2.2), we will test our model for different durations of alliances.

Figure 3 shows the number of firms n participating in an alliance in the R&D network constructed in this way, the average degree \bar{d} , the degree variance σ_d^2 and the degree coefficient of variation, i.e. $c_v = \sigma_d / \bar{d}$, over the years 1990 to 2005. One can see that there are very large variations over the years of the number of firms having an R&D alliance with other firms. Starting from 1990, we observe a strong increase followed by a sudden drop to a low level. Since 1998 it is again increasing. Interestingly, the average number of alliances per firm (captured by the average degree \bar{d}), the degree variance σ_d^2 as well as the degree coefficient of variation c_v have decreased over the years, indicating lower inter-firm collaboration activity levels.

In Figure 4,^{23,24} exemplary plots of the largest connected component in the R&D network for the years 1990, 1995, 2000 and 2005 are shown. In 1990, the giant component had a core-periphery structure with many R&D interactions between firms from different sectors. If we look at the same picture in 2005, the core-periphery structure seems less obvious and two cores and a periphery seem to emerge, where in one of the cores there are only few interactions between firms of different sectors. This may indicate more specialization in R&D alliance partnerships.

²⁰[Schilling \[2009\]](#) compares different alliance databases, including MERIT-CATI, and finds that the different databases show similar patterns.

²¹As explained below, we do not have information available on firms' financial reports from Standard & Poor's Compustat database prior to 1950. Hence we choose this year as the first year of observation in our sample.

²²[Rosenkopf and Padula \[2008\]](#) use a five-year moving window assuming that alliances have a five-year life span, and state that the choice of a five-year window is consistent with extant alliance studies [e.g. [Gulati and Gargiulo, 1999](#); [Stuart, 2000](#)] and conforms to [Kogut \[1988\]](#) finding that the normal life span of most alliances is no more than five years. Moreover, [Harrigan \[1988\]](#) studies 895 alliances from 1924 to 1985 and concludes that the average life-span of the alliance is relatively short, 3.5 years, with a standard deviation of 5.8 years and 85 % of these alliances last less than 10 years. [Park and Russo \[1996\]](#) focus on 204 joint ventures among firms in the electronic industry for the period 1979–1988. They show that less than half of these firms remain active beyond a period of five years and for those that last less than 10 years (2/3 of the total), the average lifetime turns out to be 3.9 years.

²³See Appendix A.1 for the definition of a connected component.

²⁴Only firms for which we could obtain their industry classification are shown.

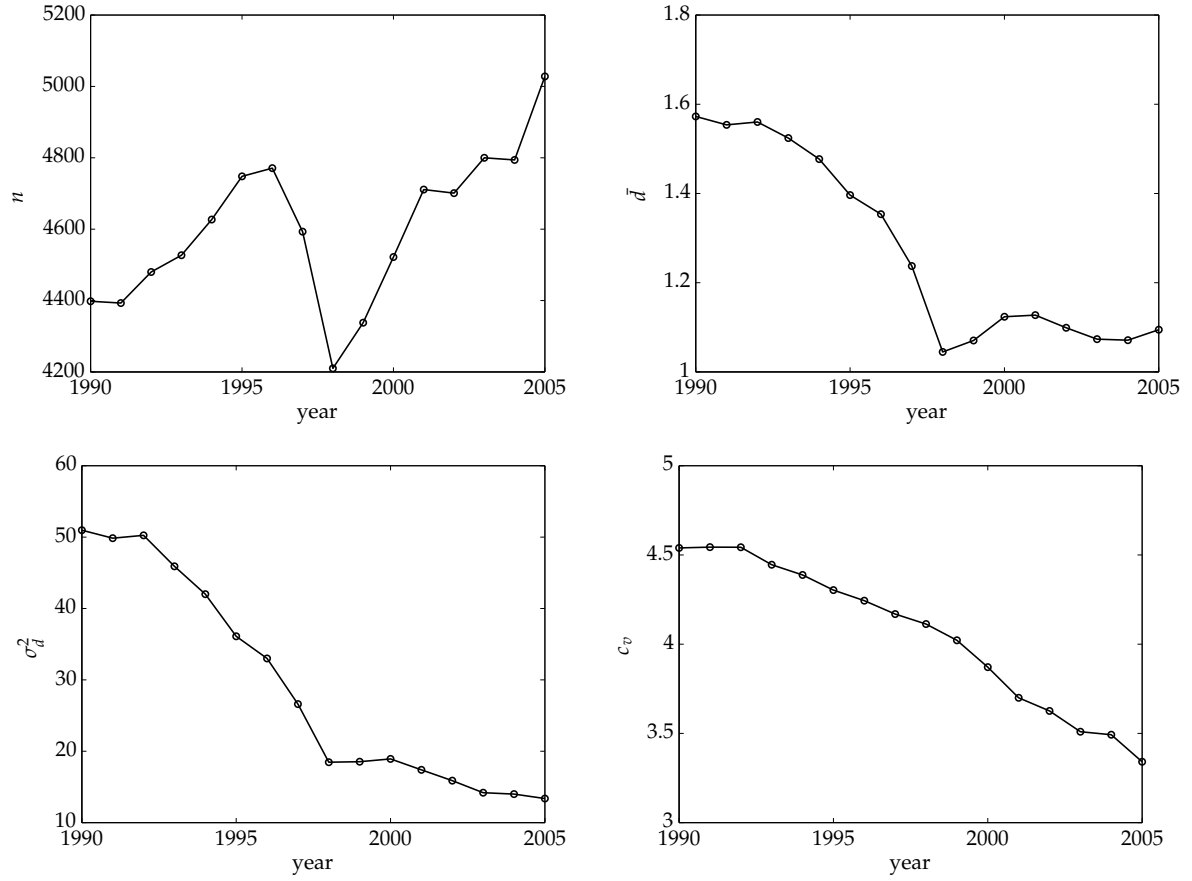
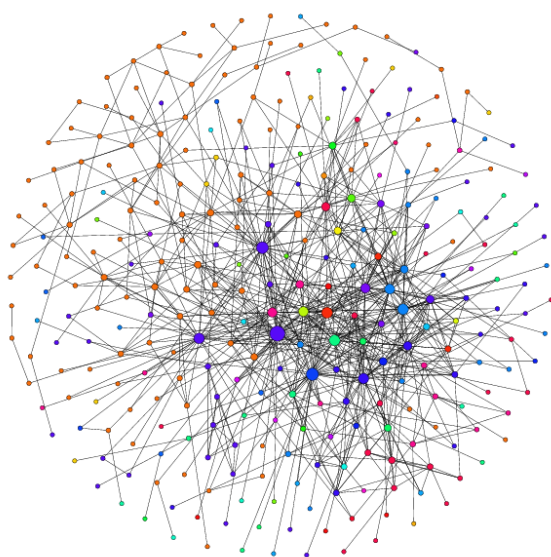
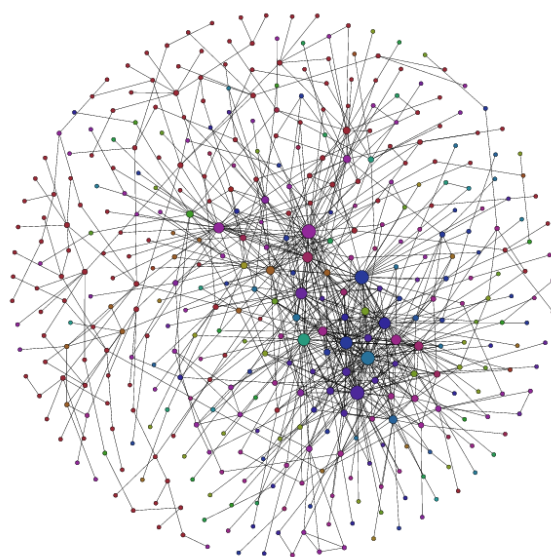


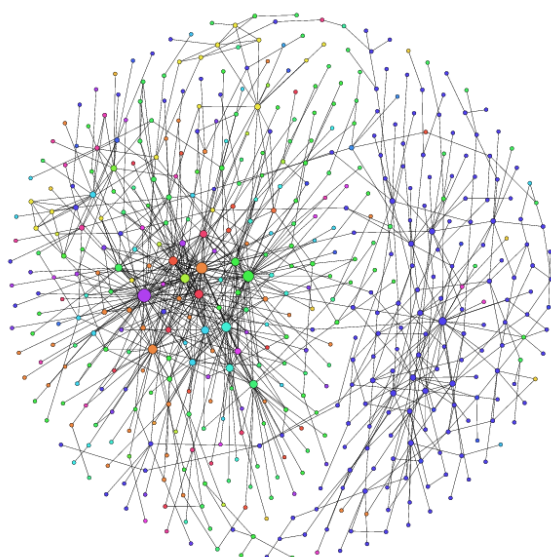
Figure 3: The number of firms n participating in an alliance, the average degree \bar{d} , the degree variance σ_d^2 and the degree coefficient of variation $c_v = \sigma_d / \bar{d}$.



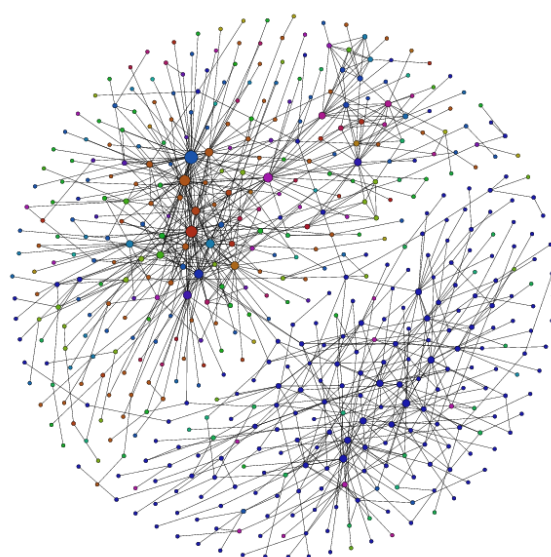
(a) 1990: $n = 303$, $m = 777$.



(b) 1995: $n = 405$, $m = 795$.



(c) 2000: $n = 497$, $m = 845$.



(d) 2005: $n = 513$, $m = 861$.

Figure 4: Network snapshots of the largest connected component for the years (a) 1990, (b) 1995, (c) 2000 and (d) 2005 with the number of firms n and the number of links m . Node colors represent different industry SIC codes at the 4-digit level. The nodes' sizes indicate their degree.

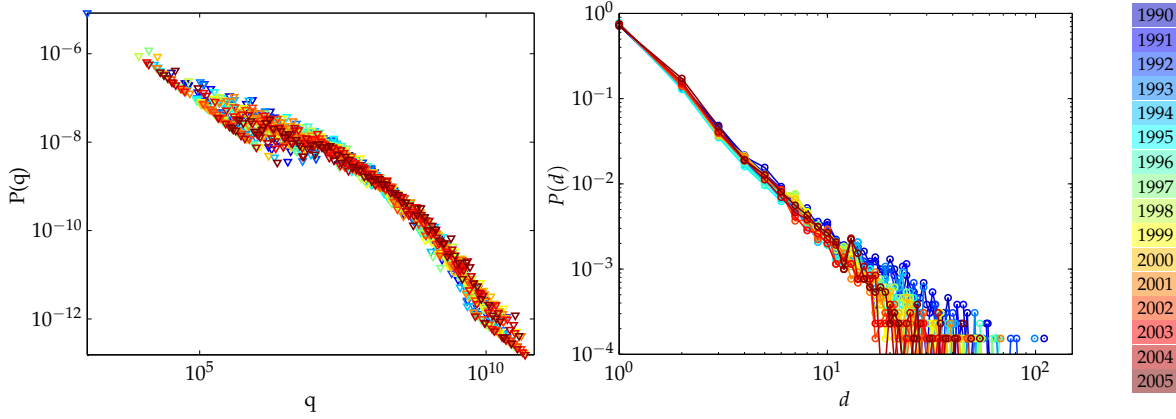


Figure 5: Empirical output distribution $P(q)$ and the distribution of degree $P(d)$ for the years 1975, ..., 2006. The data for output has been logarithmically binned and non-positive data entries have been discarded.

The CATI database provides the names for each firm in an alliance. We matched the firms' names in the CATI database with the firms' names in Standard & Poor's Compustat US and Global fundamentals databases, to obtain information about their balance sheets and income statements. For this purpose we adopted and extended the name matching algorithm developed as part of the NBER patent data project.²⁵ From our match between the firms' names in the CATI database and the firms' names in the Compustat database, we obtained a firm's gross profit, sales and research and development expenses. Moreover, we obtained information about a firm's number of employees and capital.

The empirical distributions for output $P(q)$ (using a logarithmic binning of the data with 100 bins) and the degree distribution $P(d)$ are shown in Figure 5. Both indicate a power-law distribution and a power law decay for large observations.

8. Econometric Analysis

8.1. Econometric Specification

In this section we introduce the econometric equivalent to the equilibrium quantity produced by each firm given in Equation (13). Our empirical counterpart of the marginal cost c_{it} of firm i from Equation (2) at period t has a fixed cost equal to $\bar{c}_{it} = \eta_i^* - \epsilon_{it} - \mathbf{x}_{it}^\top \boldsymbol{\beta}$, and thus we get

$$c_{it} = \eta_i^* - \epsilon_{it} - \mathbf{x}_{it}^\top \boldsymbol{\beta} - e_{it} - \varphi \sum_{j=1}^n a_{ij,t} e_{jt}, \quad (23)$$

where \mathbf{x}_{it} is a k -dimensional vector of observed exogenous characteristics of firm i , η_i^* captures the unobserved (to the econometrician) firm-specific fixed effect, and ϵ_{it} captures the remaining

²⁵See <https://sites.google.com/site/patentdatapoint/Home>.

unobserved (to the econometrician) characteristics of the firms. We use capital and labor to capture \mathbf{x}_{it} . Moreover, we assume that η_i^* and ε_{it} can be observed by other firms.

Similarly to Equation (1), the inverse demand function for firm i is given by:

$$p_{it} = \bar{\alpha}_m + \bar{\alpha}_t - q_{it} - \rho \sum_{j=1}^n b_{ij} q_{jt}, \quad (24)$$

where $b_{ij} = 1$ if i and j are in the same market and zero otherwise. In this equation, $\bar{\alpha}_m$ indicates the market-specific fixed effect and $\bar{\alpha}_t$ captures the time fixed effect due to exogenous demand shifters that affect consumer income, number of consumers (population), consumer taste and preferences and expectations over future prices of complements and substitutes or future income.

Denote by $\kappa_t \equiv \bar{\alpha}_t$ and $\eta_i \equiv \bar{\alpha}_m - \eta_i^*$. Observe that κ_t captures the time fixed effect while η_i , which includes both $\bar{\alpha}_m$ and η_i^* , captures the firm fixed effect. Then, proceeding as in Section 3 (see, in particular the proof of Proposition 1), adding the subscript t for time and using Equations (23) and (24), the econometric model equivalent to the best-response quantity in Equation (13) is given by:

$$q_{it} = \varphi \sum_{j=1}^n a_{ij,t} q_{jt} - \rho \sum_{j=1}^n b_{ij} q_{jt} + \mathbf{x}_{it}^\top \boldsymbol{\beta} + \eta_i + \kappa_t + \varepsilon_{it}. \quad (25)$$

Observe that the econometric specification in Equation (25) has a similar specification as the product competition and technology spillover production function estimation in Bloom et al. [2013] where the estimation of φ will give the intensity of the *technology (or knowledge) spillover effect* of R&D while the estimation of ρ will give the intensity of the *product rivalry effect*. However, differently to these authors, we explicitly take into account the technology spillovers stemming from R&D collaborations by using a network approach.

In vector-matrix form, we can write Equation (25) as

$$\mathbf{q}_t = \varphi \mathbf{A}_t \mathbf{q}_t - \rho \mathbf{B} \mathbf{q}_t + \mathbf{X}_t \boldsymbol{\beta} + \boldsymbol{\eta} + \kappa_t \mathbf{u}_n + \boldsymbol{\varepsilon}_t, \quad (26)$$

where $\mathbf{q}_t = (q_{1t}, \dots, q_{nt})^\top$, $\mathbf{A}_t = [a_{ij,t}]$, $\mathbf{B} = [b_{ij}]$, $\mathbf{X}_t = (\mathbf{x}_{1t}, \dots, \mathbf{x}_{nt})^\top$, $\boldsymbol{\eta} = (\eta_1, \dots, \eta_n)^\top$, $\boldsymbol{\varepsilon}_t = (\varepsilon_{1t}, \dots, \varepsilon_{nt})^\top$, and \mathbf{u}_n is an n -dimensional vector of ones.

For the T periods, Equation (26) can be written as

$$\mathbf{q} = \varphi \text{diag}\{\mathbf{A}_t\} \mathbf{q} - \rho (\mathbf{I}_T \otimes \mathbf{B}) \mathbf{q} + \mathbf{X} \boldsymbol{\beta} + \mathbf{u}_T \otimes \boldsymbol{\eta} + \boldsymbol{\kappa} \otimes \mathbf{u}_n + \boldsymbol{\varepsilon}, \quad (27)$$

where $\mathbf{q} = (\mathbf{q}_1^\top, \dots, \mathbf{q}_T^\top)^\top$, $\mathbf{X} = (\mathbf{X}_1^\top, \dots, \mathbf{X}_T^\top)^\top$, $\boldsymbol{\kappa} = (\kappa_1, \dots, \kappa_T)^\top$, and $\boldsymbol{\varepsilon} = (\boldsymbol{\varepsilon}_1^\top, \dots, \boldsymbol{\varepsilon}_T^\top)^\top$. All vectors are of dimension $(nT \times 1)$, where T is the number of years available in the data.

In terms of data, our main variables will be measured as follows. The output q_{it} is the value of sales of firm i at time t and comes from the Compustat data. The network data comes from the Cati database and $a_{ij,t} = 1$ if there is an R&D collaboration between firms i and j in the

last s years before time t , where s is the duration of an alliance.²⁶ The exogenous variables captured by \mathbf{x}_{it} are the firm's number of employees and capital. Finally, we measure b_{ij} as in the theoretical model so that $b_{ij} = 1$ if firms i and j are the same industry (measured by the industry SIC codes at the 4-digit level) and zero otherwise.

8.2. Identification and IV Estimation

We adopt here a structural approach in the sense that we estimate exactly the first-order condition of the firm's maximization in terms of output and R&D effort, which lead to Equation (26). Interestingly, the best-response quantity in Equation (26) corresponds to a high-order Spatial Auto-Regressive (SAR) model with two spatial lags $\mathbf{A}_t \mathbf{q}_t$ and $\mathbf{B} \mathbf{q}_t$ [Lee and Liu, 2010]. As in the SAR model, the spatial lags $\mathbf{A}_t \mathbf{q}_t$ and $\mathbf{B} \mathbf{q}_t$ are endogenous variables and need to be instrumented by $\mathbf{A}_t \mathbf{X}_t$ and $\mathbf{B} \mathbf{X}_t$.

To be more specific, let us consider Equation (25). The output of firm i at time t , q_{it} , is a function of the total output of all firms that have an R&D collaboration with firm i at time t , i.e. $\bar{q}_{a,it} = \sum_{j=1}^n a_{ij,t} q_{jt}$, and the total output of all firms that operate in the same market as firm i , i.e. $\bar{q}_{b,it} = \sum_{j=1}^n b_{ij} q_{jt}$. Due the feedback effect, q_{jt} also depends on q_{it} and, thus, $\bar{q}_{a,it}$ and $\bar{q}_{b,it}$ are endogenous. We instrument $\bar{q}_{a,it}$ by the total number of employees and total capital of all firms that have an R&D collaboration with firm i , i.e. $\sum_{j=1}^n a_{ij,t} \mathbf{x}_{it}$, and instrument $\bar{q}_{b,it}$ by the total number of employees and total capital of all firms that operate in the same industry as firm i , i.e. $\sum_{j=1}^n b_{ij} \mathbf{x}_{it}$. In other words, we estimate Equation (25) using a two stage least squares (2SLS) approach where, in the first stage we regress $\bar{q}_{a,it}$ and $\bar{q}_{b,it}$ on $\sum_{j=1}^n a_{ij,t} \mathbf{x}_{it}$ and $\sum_{j=1}^n b_{ij} \mathbf{x}_{it}$, respectively, to obtain $\hat{\bar{q}}_{a,it}$ and $\hat{\bar{q}}_{b,it}$. In the second stage of the estimation, we replace the spatial lags in Equation (25) by $\hat{\bar{q}}_{a,it}$ and $\hat{\bar{q}}_{b,it}$ and estimate

$$q_{it} = \phi \hat{\bar{q}}_{a,it} - \rho \hat{\bar{q}}_{b,it} + \mathbf{x}_{it}^\top \boldsymbol{\beta} + \eta_i + \kappa_t + \epsilon_{it}. \quad (28)$$

Obviously, the above identification strategy based on IVs is valid only if \mathbf{X}_t and \mathbf{A}_t are exogenous. To control for the potential endogeneity of \mathbf{X}_t , we consider IVs based on time-lagged employment and capital, i.e. $\mathbf{A}_t \mathbf{X}_{t-1}$ and $\mathbf{B} \mathbf{X}_{t-1}$, for $\mathbf{A}_t \mathbf{q}_t$ and $\mathbf{B} \mathbf{q}_t$. However, this could not be enough. Indeed, the potential endogeneity of \mathbf{A}_t is a little more complicated to deal with. \mathbf{A}_t is endogenous if there exists an *unobservable factor* that affects both q_{it} and $a_{ij,t}$. If the unobservable factor is time-invariant, then it is captured by the firm fixed effect. If the unobservable factor is time-specific, then it is captured by the time fixed effect. Therefore, the fixed effects in the panel data model is helpful to attenuate the potential endogeneity of \mathbf{A}_t . As a robustness check, we also consider IVs based on the predicted adjacency matrix, i.e. $\hat{\mathbf{A}}_t \mathbf{X}_t$ following Kelejian and Piras [2012]. To be more specific, let us consider the estimation of Equation (25) using the predicted adjacency matrix by a three stage least squares (3SLS) approach. In the first stage of the estimation, we obtain the predicted links $\hat{a}_{ij,t}$ from

²⁶For the benchmark estimation results reported in Table 1, we set $s = 5$. We report estimation results with different lengths of alliance duration in Table 3 and the results are robust.

the regression of $a_{ij,t}$ on whether firms i and j collaborated before time $(t - s)$ where s is the duration of an alliance, whether i and j are in the same industry (measured by the first 2 digits of their SIC codes), whether i and j are both U.S. firms.²⁷ In the second stage, we regress $\bar{q}_{a,it}$ on $\sum_{j=1}^n \hat{a}_{ij,t} \mathbf{x}_{jt}$ to obtain $\tilde{q}_{a,it}$, and regress $\bar{q}_{b,it}$ on $\sum_{j=1}^n b_{ij} \mathbf{x}_{it}$ to obtain $\hat{q}_{b,it}$. In the third stage, we replace the spatial lags in Equation (25) by $\tilde{q}_{a,it}$ and $\hat{q}_{b,it}$ respectively and estimate

$$q_{it} = \varphi \tilde{q}_{a,it} - \rho \hat{q}_{b,it} + \mathbf{x}_{it}^\top \boldsymbol{\beta} + \eta_i + \kappa_t + \epsilon_{it}. \quad (29)$$

Let us now give a formal definition for the estimator. In Equation (27), η and κ capture respectively the firm and time fixed effects. We allow for η and κ to depend on $\text{diag}\{\mathbf{A}_t\}$, \mathbf{B} and \mathbf{X} by treating them as vectors of unknown parameters. To avoid the incidental problem, we transform Equation (27) using a within projector $\mathbf{J} = \mathbf{J}_T \otimes \mathbf{J}_n$ where $\mathbf{J}_T = \mathbf{I}_T - \frac{1}{T} \mathbf{u}_T \mathbf{u}_T^\top$ and $\mathbf{J}_n = \mathbf{I}_n - \frac{1}{n} \mathbf{u}_n \mathbf{u}_n^\top$. The transformed Equation (27) is

$$\mathbf{J}\mathbf{q} = \varphi \mathbf{J} \text{diag}\{\mathbf{A}_t\} \mathbf{q} - \rho \mathbf{J}(\mathbf{I}_T \otimes \mathbf{B}) \mathbf{q} + \mathbf{J}\mathbf{X}\boldsymbol{\beta} + \mathbf{J}\boldsymbol{\epsilon}. \quad (30)$$

where the firm and time fixed effects η and κ have been washed out.

As stated above, to estimate Equation (30), we consider the IV matrix with the actual adjacency matrix \mathbf{A}_t , i.e. $\mathbf{Q}_1 = \mathbf{J}[\text{diag}\{\mathbf{A}_t\}\mathbf{X}, (\mathbf{I}_T \otimes \mathbf{B})\mathbf{X}, \mathbf{X}]$, and the IV matrix with the predicted adjacency matrix $\hat{\mathbf{A}}_t = [\hat{a}_{ij,t}]$, i.e. $\mathbf{Q}_2 = \mathbf{J}[\text{diag}\{\hat{\mathbf{A}}_t\}\mathbf{X}, (\mathbf{I}_T \otimes \mathbf{B})\mathbf{X}, \mathbf{X}]$.

Let $\mathbf{P}_1 = \mathbf{Q}_1(\mathbf{Q}_1^\top \mathbf{Q}_1)^{-1} \mathbf{Q}_1^\top$, $\mathbf{P}_2 = \mathbf{Q}_2(\mathbf{Q}_2^\top \mathbf{Q}_2)^{-1} \mathbf{Q}_2^\top$ and $\mathbf{Z} = [\text{diag}\{\mathbf{A}_t\}\mathbf{q}, (\mathbf{I}_T \otimes \mathbf{B})\mathbf{q}, \mathbf{X}]$. The 2SLS estimator with IVs based on the actual adjacency matrix is given by $(\mathbf{Z}^\top \mathbf{P}_1 \mathbf{Z})^{-1} \mathbf{Z}^\top \mathbf{P}_1 \mathbf{q}$. The 3SLS estimator with IVs based on the predicted adjacency matrix is given by $(\mathbf{Z}^\top \mathbf{P}_2 \mathbf{Z})^{-1} \mathbf{Z}^\top \mathbf{P}_2 \mathbf{q}$. With the estimates of $\varphi, \rho, \boldsymbol{\beta}$, we can recover η and κ by the least squares dummy variable method.

9. Empirical Results

9.1. Results from Estimating our Model

The parameter estimates of Equation (26) are reported in Table 1, which reports three different models. Models A and B are the 2SLS estimation of (26) with time fixed effects only and time and firm fixed effects, respectively. Model C is the 3SLS estimation of (26) where we estimate the adjacency matrix (network formation) in the first stage. In all these models, we obtain the expected signs, that is the *technology (or knowledge) spillover effect* (estimate of φ) has always a *positive* impact on own output while the *product rivalry effect* (estimate of $-\rho$) has always *negative* impact on own output. Indeed, the more a given firm collaborate with other firms in R&D, the higher is her output production. This indicates that R&D by allied firms in the network

²⁷ A year-by-year linear regression is carried out. The estimated coefficients of the regressors are all statistically significant with expected signs. The estimation results of this first stage are omitted to save space and are available upon request.

Table 1: Parameter estimates (with standard errors in parenthesis) from a panel regression with time dummies of Equation (26). Model A does not include firm fixed effects (f.e.), while Model B introduces also firm fixed effects. Model C uses the predicted instead of the actual adjacency matrix.

	Model A		Model B		Model C	
time f.e.	yes		yes		yes	
firm f.e.	no		yes		yes	
φ	0.0382***	(0.0059)	0.0092***	(0.0025)	0.0236***	(0.0045)
ρ	0.0037***	(0.0004)	0.0035***	(0.0006)	0.0027***	(0.0006)
β_1	0.0615***	(0.0060)	0.0419***	(0.0077)	0.0400***	(0.0073)
β_2	0.8530***	(0.0520)	1.1316***	(0.0370)	1.0970***	(0.0386)
<hr/>						
# obs.	29184					
R^2	= 0.9447					

*** Statistically significant at 1% level.

** Statistically significant at 5% level.

* Statistically significant at 10% level.

is associated with higher product value and indicate that there are strategic complementarities between own and allied firms. However, conditional on technology spillovers, the more firms compete in the same market, the lower is the production of the good by the given firm. As in Bloom et al. [2013], this table shows that the magnitude of the first effect (technology spillover) is much higher than that of the second effect (product rivalry). Keeping all the other firms' output levels constant, suppose firm j is both a collaboration partner of firm i and operates in the same market as firm i . Then we find that the net effect of firm j increasing its output by one unit is captured by the difference of the two effects. As the technology spillover effect is much higher than the rivalry effect, we find that the latter dominates the former so that the net returns to R&D collaborations are strictly positive. Furthermore, this table also shows that capital and labor have a positive and significant impact on own output.

9.2. Robustness Checks

9.2.1. Missing Data

The actual number of observations used in the estimation is much less than the 13,040 companies in MERIT-CATI database due to missing data in the dependent variables (q_{it} , e_{it}) and controls \mathbf{x}_{it} . The presence of missing data not only introduces some technical difficulty as the panel is unbalanced,²⁸ but may also lead to more severe consequences. Suppose $a_{ij,t} = 1$ and the observation on q_{jt} is missing. Then, the missing observation introduces a measurement error to

²⁸For notational simplicity, we present the estimation procedure for a balanced panel. For an unbalanced panel due to missing data, the projector introduced by Wansbeek and Kapteyn [1989] can be easily extended to the current model to eliminate the individual and time fixed effects.

Table 2: Parameter estimates (with standard errors in parenthesis) from a panel regression with time dummies of Equation (26). Model A does not include firm fixed effects (f.e.), while Model B introduces also firm fixed effects. Model C uses the predicted instead of the actual adjacency matrix. Firms for which one of the neighbors has missing data are dropped from the sample.

	Model A		Model B		Model C	
time f.e.	yes		yes		yes	
firm f.e.	no		yes		yes	
φ	0.0382***	(0.0059)	0.0035	(0.0043)	0.0432**	(0.0188)
ρ	0.0037***	(0.0004)	0.0046***	(0.0006)	0.0037***	(0.0007)
β_1	0.0615***	(0.0060)	0.0555**	(0.0072)	0.0559***	(0.0067)
β_2	0.8530***	(0.0520)	1.1107***	(0.0546)	1.0678***	(0.056)

*** Statistically significant at 1% level.

** Statistically significant at 5% level.

* Statistically significant at 10% level.

the spatial lag $\sum_{j=1}^n a_{ij,t} q_{jt}$ in Equation (25) and the above estimators may not be consistent.²⁹ Note that, this is a different sampling issue from the one studied by [Chandrasekhar and Lewis \[2011\]](#) and [Liu \[2013\]](#), where the dependent variable and controls can be observed and the observations on network links might be missing. This missing data issue is more in line with the one in [Wang and Lee \[2013\]](#). However, the method in [Wang and Lee \[2013\]](#) cannot be applied here as they consider a random-effect panel data model rather than a fixed-effect model and they assume that there is no missing data in control variables.

As a robustness check, we estimate our model using the subsample of firms whose collaboration partners have no missing outputs. For those firms, the collaboration effect is correctly specified. The estimation results are reported in Table 2 and remain largely unchanged with respect to those reported in Table 1.

9.2.2. Time Span of Alliances

We here analyze the impact of considering different time spans (other than 5 years as in the previous section) for the duration of an alliance. The estimation results from Table 1 in Section 8.2 for alliance durations ranging from 3 to 7 years are shown in Table 3. We find that the estimates are robust over the different durations considered.

9.2.3. Intra- versus Interindustry Collaborations

So far, we have assumed that network effects or knowledge spillovers were the same whether they were intra- or inter-industry collaborations. In the real-world, the knowledge spillovers

²⁹The missing observation of an individual firm output is less a concern for the product rivalry effect because we directly use the industry-level total output from the data to get $\sum_{j=1}^n b_{ij} q_{jt}$.

Table 3: Parameter estimates (with standard errors in parenthesis) from a panel regression with time dummies of Equation (26) including firm fixed effects assuming different durations of an alliance ranging from 3 to 7 years.

	3 years		4 years		5 years		6 years		7 years	
φ	0.0122***	(0.0037)	0.0110***	(0.0033)	0.0092***	(0.0025)	0.0095***	(0.0027)	0.0095***	(0.0023)
ρ	0.0034***	(0.0006)	0.0035***	(0.0006)	0.0035***	(0.0006)	0.0034***	(0.0006)	0.0034***	(0.0006)
β_1	0.0429***	(0.0074)	0.0426***	(0.0075)	0.0419***	(0.0077)	0.0420***	(0.0076)	0.0418***	(0.0077)
β_2	1.1295***	(0.0370)	1.1290***	(0.0373)	1.1316***	(0.0370)	1.1255***	(0.0381)	1.1213***	(0.0379)
# obs.	29200		29116		29026		28934		28837	

*** Statistically significant at 1% level.

** Statistically significant at 5% level.

* Statistically significant at 10% level.

between two firms in the same industry (say Volvo and Honda in the car manufacturing sector) may be different than between two firms from different industries (for example, between Volvo and Toshiba in the car manufacturing and ICT sectors, respectively). The rationale is that the involved firms might differ in the similarity of their areas of technological competences and knowledge domains depending on whether the collaborating firms operate in the same or in different industries [cf. [Nooteboom et al., 2006](#); [Powell and Grodal, 2006](#)].³⁰

In this section, we extend our empirical model (25) by allowing for intra-industry technology spillovers to differ from inter-industry spillovers. The generalized model is given by:³¹

$$q_{it} = \varphi_1 \sum_{j=1}^n a_{ij,t}^{(1)} q_{jt} + \varphi_2 \sum_{j=1}^n a_{ij,t}^{(2)} q_{jt} - \rho \sum_{j=1}^n b_{ij} q_{jt} + \mathbf{x}_{it}^\top \boldsymbol{\beta} + \eta_i + \kappa_t + \epsilon_{it}, \quad (31)$$

where $a_{ij,t}^{(1)} = a_{ij,t} b_{ij}$, $a_{ij,t}^{(2)} = a_{ij,t} (1 - b_{ij})$, and the coefficients φ_1 and φ_2 capture the intra-industry and the inter-industry technology spillover effect, respectively. In vector-matrix form, we have:

$$\mathbf{q}_t = \varphi_1 \mathbf{A}_t^{(1)} \mathbf{q}_t + \varphi_2 \mathbf{A}_t^{(2)} \mathbf{q}_t - \rho \mathbf{B} \mathbf{q}_t + \mathbf{X}_t \boldsymbol{\beta} + \boldsymbol{\eta} + \kappa_t \mathbf{u}_n + \boldsymbol{\epsilon}_t, \quad (32)$$

The parameter estimates from a fixed-effect panel regression with time dummies of Equation (31) are given in Table 4. We observe that the signs and significance of the coefficients stay the same as before. Interestingly, the effects of R&D spillovers of own industry on own output is much higher than that of R&D spillovers from other industries. This highlights the importance of technology spillovers from firms in the same industry driven by similarities in technology [cf. [Cohen and Levinthal, 1990](#); [Nooteboom et al., 2006](#)].

10. Policy Results

We now go back to our main estimation results (provided in Table 1) and analyze the different policies highlighted in Section 5 (key-player policy) and Section 6 (subsidy policy).

10.1. Determining the Key Firms

Now that we have credible estimates of the main parameters of the model, i.e. φ , ρ , β_1 and β_2 (given in Table 1), using the results of Section 5, and especially Proposition 5, we can calculate the intercentrality of each firm in our database. The corresponding formula is given in part (ii) of Proposition 5. This will determine the key players or key firms in our dataset. We can therefore rank the firms according to their intercentrality measures. This means that the firm that will be ranked number 1 is such that, if it exits from the market, then it will generate the

³⁰This specification also allows for testing the possibility that allied firms which operate in the same market might form a collusive agreement and thus affect each other's quantity levels differently than firms operating in different markets [cf. [Duso et al., 2012](#); [Goeree and Helland, 2012](#)].

³¹The theoretical foundation of equation (31) can be found in Appendix D.

Table 4: Parameter estimates (with standard errors in parenthesis) from a fixed effects panel regression with time dummies of Equation (31). Model D does not include firm fixed effects (f.e.), while Model E introduces also firm fixed effects.

	Model D		Model E	
time f.e.	yes		yes	
firm f.e.	no		yes	
φ_1	0.0625***	(0.0096)	0.0306***	(0.0110)
φ_2	0.0258***	(0.0035)	0.0053***	(0.0019)
ρ	0.0044***	(0.0004)	0.0038***	(0.0006)
β_1	0.0558***	(0.0044)	0.0451***	(0.0064)
β_2	0.8924***	(0.0434)	1.1219***	(0.0394)

*** Statistically significant at 1% level.

** Statistically significant at 5% level.

* Statistically significant at 10% level.

highest loss in total welfare in the economy. The firm ranked number 2 will be the one that, if removed, will generate the second highest loss in total welfare, etc..

A ranking of the first 25 firms with the highest impact on welfare upon exit in the year 1990 can be found in Table 5 while the corresponding ranking in the year 2005 is shown in Table 6. In these two tables, we also calculate the market share of each firm in the primary 4-digit sector in which it operates, its degree d (i.e. the number of R&D collaborations), its eigenvector centrality v_{PF} , its betweenness and closeness centralities (see Wasserman and Faust [1994] and Jackson [2008] for a list and definitions of these and other centrality measures), the relative output or Bonacich centrality of the firm, the key player according to Ballester et al. [2006, 2010] (i.e. the firm which once removed generates the highest decrease in total activity) and finally the key player defined in the present paper (i.e. the firm which once removed generates the highest decrease in total welfare).

It should be clear that key firms are not always those with the highest centralities. If we look, for example, at Table 5, then one can see that the key firm is *General Motors* but it is not the one that has the highest number of R&D collaborations (degree), nor the highest eigenvector, betweenness or closeness centrality. More importantly, *General Motors* is not the firm that has the highest market share in its sector since it detains "only" 12.14 % of market share while, for example, *Hitachi*, *Altria* or *Pepsico* have a much higher share (up to more than 50 %). This means that it is not straightforward to determine which firm should be "targeted" in the network by only observing its market share, size or even its position in the network. Interestingly, our intercentrality and that of Ballester et al. [2006, 2010] give roughly the same rankings of firms. If *General Motors* would be removed from the market, then total welfare will be reduced by 23.85 %, while total output (sales) will decrease by 6.44 %. If *Sony* (which has 32 % of market share of its market) or *Procter and Gamble* (which has nearly 59 % of market share of its market)

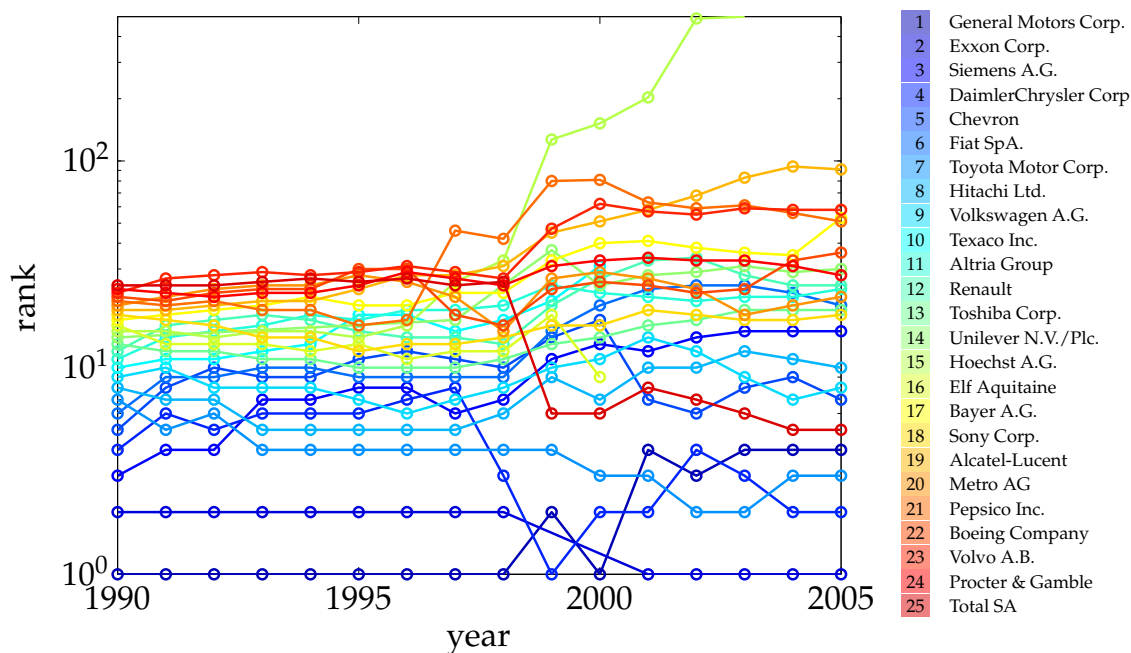


Figure 6: Change in ranking of the 25 key firms (Table 5) from the year 1990 to the year 2005.

were removed from the economy, then less than 1 % decrease in output or welfare would follow.

If we now compare the key player ranking between 1990 and 2005 (15 years after), then, from Tables 5 and 6, we find that key firms change over time. For example, *General Motors*, which was the key firm in 1990 is ranked number 4 in 2005 and its removal will reduce welfare by 6.53 % and total output by 2.29 % while these numbers were 23.85 and 6.44 % in 1990. More generally, it can be seen that the decline in welfare and total output due to the removal of the highest ranked firms is generally much lower in 2005. Apart from the fact that some key firms in 1990 are not anymore present in 2005 (for example, *Texaco*, *Unilever*, *Elf Aquitaine*), most key firms are still "key" in 2005. Figure 6 captures this idea by showing the change in the ranking of the 25 highest ranked firms from 1990 to 2005. The ranking of firms can be quite stable for some, while it is rather volatile for others. For example *Daimler Chrysler* was among the four highest ranked firms in 1990 and moved up into the ranking to second place in 2005. In contrast, *Hoechst A.G.*, which was among the 15 highest ranked firms in 1990 slipped down to rank 499 in 2003. The left panel of Figure 7 shows the (ordered) percentage decrease in welfare due to the removal of a firm over the years 1990 to 2005. The exit of most firms has only a minor impact on welfare, while the highest ranked ones can considerably affect total welfare.

10.2. R&D Subsidies

As an alternative policy to the key player analysis in the previous section, we now would like to study empirically the subsidy policy both for the homogenous subsidy, s^* , (see Proposition

Table 5: Key player ranking for the year 1990 for the first 25 firms.

Firm	Share [%] ^a	d	v_{PF}	Betweenness ^b	Closeness ^c	$q_i / \ \mathbf{q}\ _1$ [%] ^d	$\frac{\ \mathbf{q}(G)\ _1 - \ \mathbf{q}(G^{-i})\ _1}{\ \mathbf{q}(G)\ _1}$ [%] ^e	$\frac{W(G) - W(G^{-i})}{W(G)}$ [%]	Rank
General Motors Corp.	12.1445	83	0.0545	0.0436	451.4219	5.8191	6.4430	23.8516	1
Exxon Corp.	10.1151	23	0.0146	0.0023	352.7285	5.5412	5.5290	21.0288	2
Siemens A.G.	20.1008	170	0.1877	0.0911	518.0625	2.6049	3.1586	5.0410	3
DaimlerChrysler Corp	5.2310	0	0.0195	0.0017	330.0020	2.6246	2.5719	4.5619	4
Chevron	3.7009	25	0.0141	0.0079	351.7266	2.3556	2.3937	4.0250	5
Fiat SpA.	4.7173	32	0.0408	0.0168	396.7344	2.2813	2.3462	3.8197	6
Toyota Motor Corp.	6.2806	46	0.0549	0.0153	407.9688	2.2261	2.3579	3.5419	7
Hitachi Ltd.	37.6873	111	0.1289	0.0359	478.9062	2.0132	2.1847	2.8829	8
Volkswagen A.G.	4.1641	26	0.0096	0.0047	281.2852	2.0177	2.0340	2.8101	9
Texaco Inc.	3.9206	34	0.0158	0.0028	349.6562	1.9002	1.9484	2.6897	10
Altria Group	57.0787	0	0.0000	0.0000	0.0000	1.5113	1.5113	1.5204	11
Renault	2.9712	13	0.0042	0.0020	270.2812	1.4930	1.4771	1.5196	12
Toshiba Corp.	10.4548	103	0.1312	0.0313	460.5176	1.3201	1.4640	1.3301	13
Unilever N.V./Plc.	8.2910	16	0.0068	0.0035	323.2695	1.3860	1.3812	1.2771	14
Hoechst A.G.	13.8715	29	0.0115	0.0127	348.9766	1.3491	1.3683	1.2714	15
Elf Aquitaine	3.1007	13	0.0025	0.0049	259.8105	1.3895	1.3572	1.2493	16
Bayer A.G.	12.8762	13	0.0016	0.0056	251.6250	1.2504	1.2431	1.0596	17
Sony Corp.	32.0711	57	0.0883	0.0110	404.7207	1.1597	1.2587	0.9718	18
Alcatel-Lucent	31.0329	0	0.0000	0.0000	0.0000	1.1935	1.1529	0.9469	19
Metro AG	11.3765	0	0.0000	0.0000	0.0000	1.0385	1.0385	0.7180	20
Pepsico Inc.	52.5069	3	0.0000	0.0000	0.0000	1.0074	1.0038	0.6752	21
Boeing Company	37.1888	5	0.0086	0.0001	278.9453	0.9991	0.9915	0.6696	22
Volvo A.B.	1.3887	31	0.0045	0.0106	278.3184	0.9203	0.9282	0.6598	23
Procter & Gamble	58.8860	5	0.0002	0.0013	168.6270	0.9879	1.0049	0.6504	24
Total SA	2.2696	0	0.0000	0.0000	0.0000	0.9891	0.9582	0.6209	25

^a Market share in the primary 4-digit sector in which the firm is operating.

^b The normalized betweenness centrality is the fraction of all shortest paths in the network that contain a given node, divided by $(n - 1)(n - 2)$, the maximum number of such paths.

^c The closeness centrality of node i is computed as $\sum_{j=1}^n 2^{-d_G(i,j)}$, where $d_G(i, j)$ is the length of the shortest path between i and j in the network G [Dangalchev, 2006].

^d The relative output of a firm i is computed as $q_i / \|\mathbf{q}\|_1 = b_{\mu,i} / \|\mathbf{b}_{\mu}\|_1$.

^e The decrease in output due to the removal of firm i is computed as $\frac{\|\mathbf{q}(G)\|_1 - \|\mathbf{q}(G^{-i})\|_1}{\|\mathbf{q}(G)\|_1} = \frac{b_{\mathbf{u},i}(G)b_{\mu,i}(G)}{m_{ii}(G)} / \|\mathbf{b}_{\mu}(G)\|_1$.

Table 6: Key player ranking for the year 2005 for the first 25 firms.

Firm	Share [%] ^a	d	v_{PF}	Betweenness ^b	Closeness ^c	$q_i / \ \mathbf{q}\ _1$ [%] ^d	$\frac{\ \mathbf{q}(G)\ _1 - \ \mathbf{q}(G^{-i})\ _1}{\ \mathbf{q}(G)\ _1}$ [%] ^e	$\frac{W(G) - W(G^{-i})}{W(G)}$ [%]	Rank
Exxon Corp.	7.8647	3	0.0000	0.0000	0.0000	3.7352	3.6706	16.9843	1
DaimlerChrysler Corp	7.5743	25	0.0086	0.0166	124.7754	2.8079	2.8860	10.0255	2
Toyota Motor Corp.	7.7760	11	0.0049	0.0010	103.9712	2.6658	2.6190	9.0050	3
General Motors Corp.	7.7341	25	0.0065	0.0086	119.6819	2.2636	2.2857	6.5354	4
Total SA	3.6544	0	0.0000	0.0000	0.0000	2.2086	2.1704	5.9033	5
Mitsubishi Corp	87.2569	14	0.1259	0.0004	168.5938	1.9756	2.0920	4.9633	6
Chevron	4.4312	6	0.0001	0.0000	44.0676	1.9967	1.9622	4.8175	7
Volkswagen A.G.	4.8178	11	0.0046	0.0051	104.1240	1.7621	1.7150	3.9439	8
Mitsui Group	30.0437	3	0.0008	0.0000	53.0688	1.6387	1.6423	3.2730	9
Hitachi Ltd.	27.8692	54	0.1718	0.0282	200.1504	1.2792	1.4240	2.1865	10
Itochu Corp.	21.1047	2	0.0000	0.0007	25.0889	1.3323	1.3348	2.1566	11
RWE AG	3.5459	0	0.0000	0.0000	0.0000	1.2686	1.2255	1.9533	12
Sumitomo Corp	90.5320	4	0.0000	0.0000	1.5000	1.2327	1.2327	1.8592	13
Marubeni Corp.	17.5319	0	0.0000	0.0000	0.0000	1.1387	1.1307	1.5721	14
Siemens A.G.	11.0608	41	0.0255	0.0059	140.9321	1.0710	1.0942	1.4144	15
UBS AG	66.4551	0	0.0000	0.0000	0.0000	0.9069	0.9069	1.0063	16
NTT DoCoMo	4.3962	18	0.1035	0.0086	176.1514	0.8159	0.8464	0.8839	17
Sony Corp.	32.1340	44	0.2352	0.0171	212.3281	0.7692	0.8554	0.8666	18
Toshiba Corp.	9.9939	52	0.2512	0.0215	214.1133	0.7181	0.8249	0.7764	19
Fiat SpA.	2.3538	18	0.0051	0.0044	97.6677	0.7957	0.7599	0.7727	20
Intel Corp.	9.8341	89	0.2462	0.0385	221.3911	0.7445	0.7162	0.7686	21
Metro AG	17.6754	2	0.0171	0.0000	112.4143	0.7796	0.7925	0.7596	22
Endesa	1.5322	0	0.0000	0.0000	0.0000	0.7918	0.7649	0.7558	23
Altria Group	40.0416	0	0.0000	0.0000	0.0000	0.7390	0.7364	0.6664	24
Renault	2.0905	16	0.0029	0.0013	91.4758	0.7400	0.6998	0.6293	25

^a Market share in the primary 4-digit sector in which the firm is operating.

^b The normalized betweenness centrality is the fraction of all shortest paths in the network that contain a given node, divided by $(n-1)(n-2)$, the maximum number of such paths.

^c The closeness centrality of node i is computed as $\sum_{j=1}^n 2^{-d_G(i,j)}$, where $d_G(i,j)$ is the length of the shortest path between i and j in the network G [Dangalchev, 2006].

^d The relative output of a firm i is computed as $q_i / \|\mathbf{q}\|_1 = b_{\mu,i} / \|\mathbf{b}_\mu\|_1$.

^e The decrease in output due to the removal of firm i is computed as $\frac{\|\mathbf{q}(G)\|_1 - \|\mathbf{q}(G^{-i})\|_1}{\|\mathbf{q}(G)\|_1} = \frac{b_{\mathbf{u},i}(G)b_{\mu,i}(G)}{m_{ii}(G)} / \|\mathbf{b}_\mu(G)\|_1$.

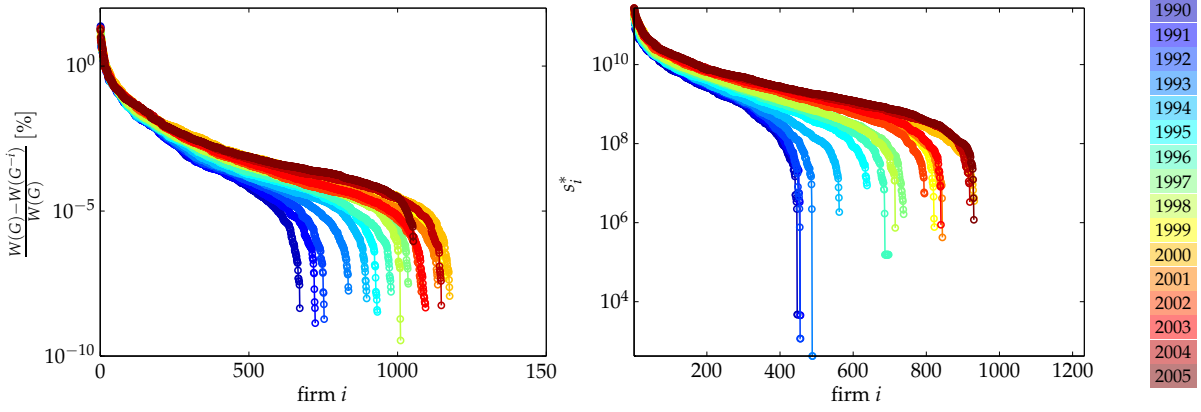


Figure 7: (Left panel) The ordered percentage decrease in welfare due to the removal of firm i over the years 1990 to 2005. (Right panel) The ordered targeted subsidy level of firm i over the years 1990 to 2005.

6) and for the targeted subsidy (see Proposition 7), where we denote by $\|\mathbf{s}^*\|_1 = \sum_{i=1}^n s_i^*$ the total amount of subsidies. In Figure 8, in the top panel, we calculate the optimal homogenous subsidy times R&D effort, $s^* \|\mathbf{e}\|_1$, over time (top left panel) and the percentage increase in welfare due to the homogenous subsidy over time (top right panel). Interestingly, the total subsidized effort increases over time by nearly fourfold between 1990 and 2005. In terms of welfare, the highest increase (almost 6 %) is in 1990, 2000 and 2005, while the increase in welfare in 1995 is smaller (around 4.5 %). The bottom panel of Figure 8 does the same exercise for the targeted subsidy policy. The results are quite similar. However, the targeted subsidy program has a much higher impact on total welfare since it can improve it by up to 80 % while the homogeneous subsidies can improve total welfare by up to 6 %. Moreover, the optimal subsidy levels show a strong variation over time. Both, the homogeneous and the aggregate targeted subsidy, seem to follow a cyclical trend that resembles the one we have observed for the number of firms participating in R&D collaborations in a given year in Figure 3. This cyclical trend is also reminiscent of the R&D expenditures observed in the empirical literature on business cycles [cf. Barlevy, 2007; Galí, 1999]

We can compare the optimal subsidy level predicted from our model with the R&D tax subsidies actually implemented in the United States and selected other countries between 1979 to 1997 [see Bloom et al., 2002; Impullitti, 2010]. While these time series typically show an increase of R&D subsidies over time, they do not seem to incorporate the cyclicity that we obtain for the optimal subsidy levels. Our analysis thus suggests that policy makers should adjust R&D subsidies to these cycles.

Let us now provide a similar ranking for the key player policy by ranking firms in terms of targeted subsidies. In other words, if the planner wants to maximize total welfare, which firm should have the highest subsidy and how much. The ranking of the first 25 firms by their optimal subsidy levels in 1990 can be found in Table 7 while the one for 2005 is shown in Table 8. As for the key player policy, we see that the ranking of firms in terms of subsidy does not

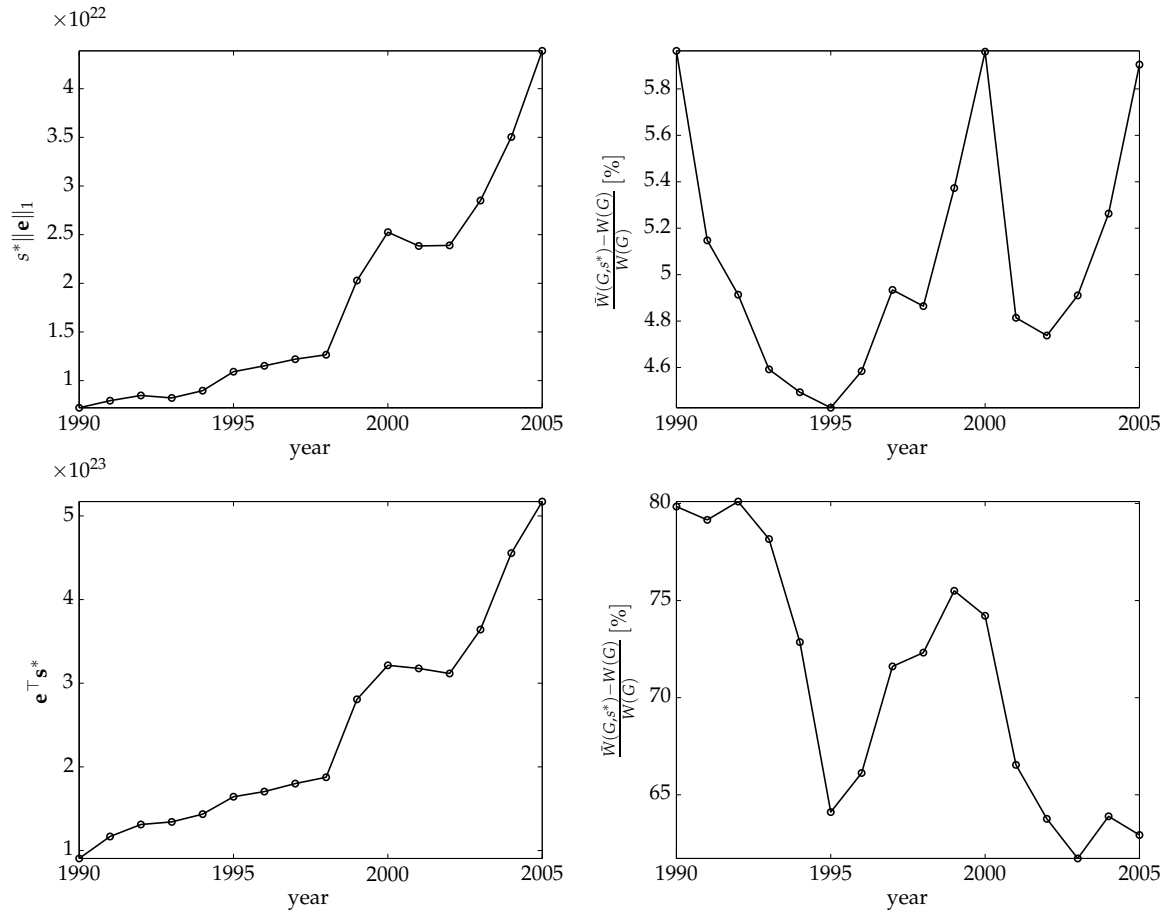


Figure 8: (Top left panel) The optimal subsidy level s^* over time. (Top right panel) The %age increase in welfare due to the subsidy s^* over time. (Bottom left panel) The total subsidy level $\|s^*\|_1$ when the subsidies are targeted towards specific firms. (Bottom right panel) The percentage increase in welfare due to the targeted subsidies s^* over time.

correspond to other rankings in terms of network centrality or market share. The ranking is similar to the one for the key firms. In particular, the top three firms in the key player ranking in 1990 (*General Motors Corp.*, *Exxon Corp.* and *Siemens A.G.*) are also the top three firms for the subsidy ranking in the same year. There is also volatility in the ranking since many firms that are ranked in the top 25 in 1990 are not anymore there in 2005 (for example, *Texaco Inc.*, *Fiat*, *Motorola*, etc.). Figure 9 shows the change in the ranking of the 25 highest subsidized firms (Table 7) from 1990 to 2005.

Observe that our subsidy rankings typically favor larger firms as they tend to be better connected in the R&D network than small firms. This adds to the discussion of whether large or small firms are contributing more to the innovativeness of an economy [cf. [Economist, 2011](#); [Mandel, 2011](#)], by adding another dimension along which larger firms can have an advantage over small ones in creating R&D spillover effects that contribute to the ever all productivity of the economy. While studies such as [Spencer and Brander \[1983\]](#) and [Acemoglu et al. \[2012\]](#) find that R&D often should be taxed rather than subsidized, we find in line with e.g. [Hinloopen \[2001\]](#) that R&D subsidies can have a significantly positive effect on welfare. As argued by [Hinloopen \[2001\]](#) the reason why our results differ from [Spencer and Brander \[1983\]](#) is that we take into account consumer surplus when deriving the optimal R&D subsidy. Moreover, in contrast to [Acemoglu et al. \[2012\]](#), we do not focus on entry and exit but incorporate the network of R&D collaborating firms. This allows us to take into account the R&D spillover effects of incumbent firms, which are typically ignored in studies of the innovative activity of incumbent firms versus entrants. We therefore see our analysis as complementary to [Acemoglu et al. \[2012\]](#), and we show that R&D subsidies can trigger considerable welfare gains when technology spillovers through R&D alliances are incorporated.

Finally, if we compare the key player ranking and the subsidy ranking, we see that many firms appear in both rankings (such as *General Motors*, *Exxon*, *Sony*, etc.) but many firms do not (such as *Motorola*, *Texas Instruments*, *Sun Microsystems*, etc.). We believe that the key player policy is more efficient than the subsidy policy. First, it captures the fragility of the system. Second it allows the planner to help or bail out the key firms whose removal or disappearance would be extremely costly in terms of total welfare and total activity for the economy.

11. Conclusion

In this paper, we have developed a model in which firms jointly form R&D collaborations (networks) to lower their production costs while at the same time competing on the product market. We have highlighted the positive role of the network in terms of technology spillovers and the negative role of product rivalry in terms of market competition. We have also determined the importance of the key firms and targeted subsidies on the total welfare of the economy.

Using a panel of R&D alliance networks and annual reports, we have then tested our theoretical results and first showed that the magnitude of the technology spillover effect is much

Table 7: Subsidies ranking for the year 1990 for the first 25 firms.

Firm	Share [%] ^a	d	v_{PF}	Betweenness ^b	Closeness ^c	$q_i / \ \mathbf{q}\ _1$ [%] ^d	$\frac{\ \mathbf{q}(G)\ _1 - \ \mathbf{q}(G^{-i})\ _1}{\ \mathbf{q}(G)\ _1}$ [%] ^e	s* [10 ¹²]	Rank
General Motors Corp.	12.1445	83	0.0545	0.0436	451.4219	5.8163	6.4400	0.1787	1
Exxon Corp.	10.1151	23	0.0146	0.0023	352.7285	5.6300	5.6176	0.1410	2
Siemens A.G.	20.1008	170	0.1877	0.0911	518.0625	2.5355	3.0746	0.1069	3
Fiat SpA.	4.7173	32	0.0408	0.0168	396.7344	2.3043	2.3700	0.0798	4
Toyota Motor Corp.	6.2806	46	0.0549	0.0153	407.9688	2.1970	2.3271	0.0789	5
Chevron	3.7009	25	0.0141	0.0079	351.7266	2.3915	2.4302	0.0769	6
Texaco Inc.	3.9206	34	0.0158	0.0028	349.6562	1.9093	1.9577	0.0695	7
Hitachi Ltd.	37.6873	111	0.1289	0.0359	478.9062	1.9889	2.1583	0.0691	8
DaimlerChrysler Corp	5.2310	0	0.0195	0.0017	330.0020	2.7359	2.6809	0.0613	9
Toshiba Corp.	10.4548	103	0.1312	0.0313	460.5176	1.2887	1.4292	0.0607	10
Volkswagen A.G.	4.1641	26	0.0096	0.0047	281.2852	2.0391	2.0556	0.0568	11
Intel Corp.	12.2966	78	0.1404	0.0222	458.6562	0.0325	0.0370	0.0534	12
Motorola Inc.	18.5193	76	0.1340	0.0172	424.8301	0.5729	0.6572	0.0488	13
McDonnell Douglas Corp.	21.8941	64	0.0338	0.0125	343.3789	0.6786	0.7643	0.0449	14
Sony Corp.	32.0711	57	0.0883	0.0110	404.7207	1.1516	1.2498	0.0436	15
Electronic Data Systems Corp.	6.8935	25	0.0711	0.0045	381.2832	0.4109	0.4305	0.0428	16
Sun Microsystems	11.0880	89	0.1664	0.0222	434.1582	0.1435	0.1708	0.0427	17
Texas Instruments Inc.	20.5932	76	0.1217	0.0159	415.5879	0.3100	0.3467	0.0422	18
TRW Inc	7.0559	52	0.0515	0.0111	364.2559	0.4293	0.4627	0.0412	19
Volvo A.B.	1.3887	31	0.0045	0.0106	278.3184	0.9245	0.9324	0.0409	20
Renault	2.9712	13	0.0042	0.0020	270.2812	1.5079	1.4918	0.0406	21
National Semiconductor Corp.	5.3366	50	0.1048	0.0045	422.4453	0.1409	0.1474	0.0404	22
Hoechst A.G.	13.8715	29	0.0115	0.0127	348.9766	1.3179	1.3366	0.0374	23
Honeywell Inc.	63.9769	61	0.1004	0.0117	416.0898	0.2321	0.2567	0.0343	24
Xerox Corp.	84.2264	34	0.0817	0.0045	385.7695	0.5864	0.6359	0.0326	25

^a Market share in the primary 4-digit sector in which the firm is operating.

^b The normalized betweenness centrality is the fraction of all shortest paths in the network that contain a given node, divided by $(n-1)(n-2)$, the maximum number of such paths.

^c The closeness centrality of node i is computed as $\sum_{j=1}^n 2^{-d_G(i,j)}$, where $d_G(i,j)$ is the length of the shortest path between i and j in the network G [Dangalchev, 2006].

^d The relative output of a firm i is computed as $q_i / \|\mathbf{q}\|_1 = b_{\mu,i} / \|\mathbf{b}_\mu\|_1$.

^e The decrease in output due to the removal of firm i is computed as $\frac{\|\mathbf{q}(G)\|_1 - \|\mathbf{q}(G^{-i})\|_1}{\|\mathbf{q}(G)\|_1} = \frac{b_{\mathbf{u},i}(G)b_{\mu,i}(G)}{m_{ii}(G)} / \|\mathbf{b}_\mu(G)\|_1$.

Table 8: Subsidiaries ranking for the year 2005 for the first 25 firms.

Firm	Share [%] ^a	d	v_{PF}	Betweenness ^b	Closeness ^c	$q_i / \ \mathbf{q}\ _1$ [%] ^d	$\frac{\ \mathbf{q}(G)\ _1 - \ \mathbf{q}(G^{-i})\ _1}{\ \mathbf{q}(G)\ _1}$ [%] ^e	s* [10 ¹²]	Rank
Exxon Corp.	7.8647	3	0.0000	0.0000	0.0000	3.7512	3.6863	0.2663	1
DaimlerChrysler Corp	7.5743	25	0.0086	0.0166	124.7754	2.8408	2.9198	0.2553	2
Toyota Motor Corp.	7.7760	11	0.0049	0.0010	103.9712	2.6595	2.6128	0.2319	3
General Motors Corp.	7.7341	25	0.0065	0.0086	119.6819	2.2439	2.2658	0.2037	4
Mitsubishi Corp	87.2569	14	0.1259	0.0004	168.5938	1.9663	2.0821	0.1853	5
Volkswagen A.G.	4.8178	11	0.0046	0.0051	104.1240	1.7669	1.7196	0.1584	6
Total SA	3.6544	0	0.0000	0.0000	0.0000	2.2221	2.1836	0.1559	7
Hitachi Ltd.	27.8692	54	0.1718	0.0282	200.1504	1.2674	1.4109	0.1528	8
Chevron	4.4312	6	0.0001	0.0000	44.0676	2.0051	1.9704	0.1403	9
Toshiba Corp.	9.9939	52	0.2512	0.0215	214.1133	0.7051	0.8101	0.1325	10
Sony Corp.	32.1340	44	0.2352	0.0171	212.3281	0.7640	0.8496	0.1285	11
Mitsui Group	30.0437	3	0.0008	0.0000	53.0688	1.6301	1.6337	0.1173	12
Fujitsu Ltd.	17.3622	44	0.1993	0.0159	204.4375	0.5170	0.5511	0.1155	13
Intel Corp.	9.8341	89	0.2462	0.0385	221.3911	0.7351	0.7071	0.1091	14
NTT DoCoMo	4.3962	18	0.1035	0.0086	176.1514	0.8191	0.8497	0.0989	15
Itochu Corp.	21.1047	2	0.0000	0.0007	25.0889	1.3392	1.3417	0.0951	16
RWE AG	3.5459	0	0.0000	0.0000	0.0000	1.2759	1.2325	0.0901	17
Sumitomo Corp	90.5320	4	0.0000	0.0000	1.5000	1.2274	1.2274	0.0880	18
Microsoft Corp.	21.5980	90	0.1986	0.0856	245.1406	0.3090	0.3098	0.0879	19
Siemens A.G.	11.0608	41	0.0255	0.0059	140.9321	1.0430	1.0656	0.0816	20
Marubeni Corp.	17.5319	0	0.0000	0.0000	0.0000	1.1449	1.1368	0.0806	21
Sharp Corp.	8.5948	23	0.1325	0.0056	160.2207	0.3494	0.3530	0.0784	22
Mitsubishi Electric Corp	5.6782	22	0.1218	0.0054	189.0078	0.4137	0.4363	0.0702	23
Continental A.G.	4.3929	10	0.0046	0.0001	99.3442	0.2956	0.2906	0.0656	24
UBS AG	66.4551	0	0.0000	0.0000	0.0000	0.9111	0.9111	0.0653	25

^a Market share in the primary 4-digit sector in which the firm is operating.

^b The normalized betweenness centrality is the fraction of all shortest paths in the network that contain a given node, divided by $(n-1)(n-2)$, the maximum number of such paths.

^c The closeness centrality of node i is computed as $\sum_{j=1}^n 2^{-d_G(i,j)}$, where $d_G(i,j)$ is the length of the shortest path between i and j in the network G [Dangalchev, 2006].

^d The relative output of a firm i is computed as $q_i / \|\mathbf{q}\|_1 = b_{\mu,i} / \|\mathbf{b}_\mu\|_1$.

^e The decrease in output due to the removal of firm i is computed as $\frac{\|\mathbf{q}(G)\|_1 - \|\mathbf{q}(G^{-i})\|_1}{\|\mathbf{q}(G)\|_1} = \frac{b_{\mathbf{u},i}(G)b_{\mu,i}(G)}{m_{ii}(G)} / \|\mathbf{b}_\mu(G)\|_1$.

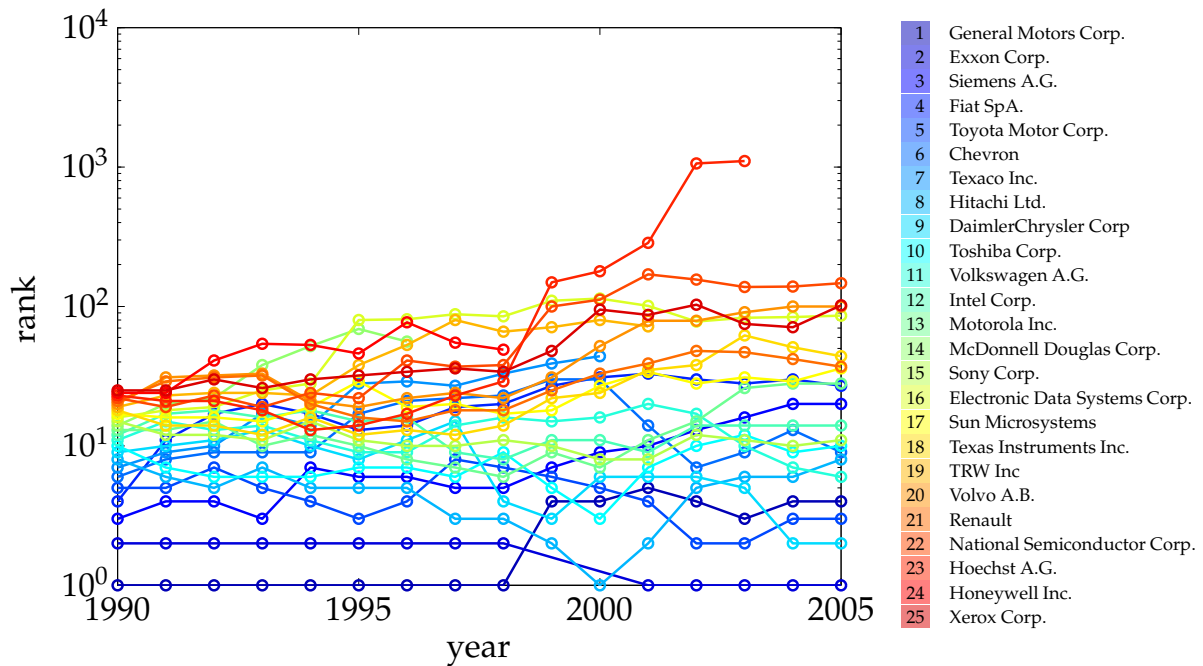


Figure 9: Change in the ranking of the 25 highest subsidized firms (Table 7) from 1990 to 2005.

higher than that of the product rivalry effect, indicating that the latter dominates the former so that the net returns to R&D collaborations are strictly positive. We have also identified the key firms whose default would reduce social welfare and aggregate industry output the most. Finally, we have drawn some policy conclusions about optimal R&D subsidies from the results obtained over different sectors, as well as their temporal variation.

We believe that the methodology developed in this paper offers a fruitful way to analyze the existence of R&D spillovers and their policy implications in terms of firms' subsidies. We also believe that putting forward the role of the network in terms of R&D collaborations is key to understand the different aspects of these markets.

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Appendix

A. Definitions and Characterizations

A.1. Network Definitions

A *network (graph)* G is the pair $(\mathcal{N}, \mathcal{E})$ consisting of a set of *nodes (vertices)* $\mathcal{N} = \{1, \dots, n\}$ and a set of edges (*links*) $\mathcal{E} \subset \mathcal{N} \times \mathcal{N}$ between them. A link (i, j) is *incident* with nodes i and j . The *neighborhood* of a node $i \in \mathcal{N}$ is the set $\mathcal{N}_i = \{j \in \mathcal{N} : (i, j) \in \mathcal{E}\}$. The *degree* d_i of a node $i \in \mathcal{N}$ gives the number of links incident to node i . Clearly, $d_i = |\mathcal{N}_i|$. Let $\mathcal{N}_i^{(2)} = \bigcup_{j \in \mathcal{N}_i} \mathcal{N}_j \setminus (\mathcal{N}_i \cup \{i\})$ denote the second-order neighbors of node i . Similarly, the k -th order neighborhood of node i is defined recursively from $\mathcal{N}_i^{(0)} = \{i\}$, $\mathcal{N}_i^{(1)} = \mathcal{N}_i$ and $\mathcal{N}_i^{(k)} = \bigcup_{j \in \mathcal{N}_i^{(k-1)}} \mathcal{N}_j \setminus \left(\bigcup_{l=0}^{k-1} \mathcal{N}_i^{(l)} \right)$. A *walk* in G of length k from i to j is a sequence $\langle i_0, i_1, \dots, i_k \rangle$ of nodes such that $i_0 = i$, $i_k = j$, $i_p \neq i_{p+1}$, and i_p and i_{p+1} are (directly) linked, that is $i_p i_{p+1} \in \mathcal{E}$, for all $0 \leq p \leq k-1$. Nodes i and j are said to be *indirectly linked* in G if there exists a walk from i to j in G containing nodes other than i and j . A pair of nodes i and j is *connected* if they are either directly or indirectly linked. A node $i \in \mathcal{N}$ is *isolated* in G if $\mathcal{N}_i = \emptyset$. The network G is said to be *empty* (denoted by \bar{K}_n) when all its nodes are isolated.

A *subgraph*, G' , of G is the graph of subsets of the nodes, $\mathcal{N}(G') \subseteq \mathcal{N}(G)$, and links, $\mathcal{E}(G') \subseteq \mathcal{E}(G)$. A graph G is *connected*, if there is a path connecting every pair of nodes. Otherwise G is disconnected. The *components* of a graph G are the maximally connected subgraphs. A component is said to be *minimally connected* if the removal of any link makes the component disconnected.

A *dominating set* for a graph $G = (\mathcal{N}, \mathcal{E})$ is a subset \mathcal{S} of \mathcal{N} such that every node not in \mathcal{S} is connected to at least one member of \mathcal{S} by a link. An *independent set* is a set of nodes in a graph in which no two nodes are adjacent. For example the central node in a star $K_{1,n-1}$ forms a dominating set while the peripheral nodes form an independent set.

Let $G = (\mathcal{N}, \mathcal{E})$ be a graph whose distinct positive degrees are $d_{(1)} < d_{(2)} < \dots < d_{(k)}$, and let $d_0 = 0$ (even if no agent with degree 0 exists in G). Further, define $\mathcal{D}_i = \{v \in \mathcal{N} : d_v = d_{(i)}\}$ for $i = 0, \dots, k$. Then the set-valued vector $\mathcal{D} = (\mathcal{D}_0, \mathcal{D}_1, \dots, \mathcal{D}_k)$ is called the *degree partition* of G . Consider a *nested split graph* $G = (\mathcal{N}, \mathcal{E})$ and let $\mathcal{D} = (\mathcal{D}_0, \mathcal{D}_1, \dots, \mathcal{D}_k)$ be its degree partition. Then the nodes \mathcal{N} can be partitioned in independent sets \mathcal{D}_i , $i = 1, \dots, \left\lfloor \frac{k}{2} \right\rfloor$ and a dominating set $\bigcup_{i=\left\lfloor \frac{k}{2} \right\rfloor+1}^k \mathcal{D}_i$ in the graph $G' = (\mathcal{N} \setminus \mathcal{D}_0, \mathcal{E})$. Moreover, the neighborhoods of the nodes are nested. In particular, for each node $v \in \mathcal{D}_i$, $\mathcal{N}_v = \bigcup_{j=1}^i \mathcal{D}_{k+1-j}$ if $i = 1, \dots, \left\lfloor \frac{k}{2} \right\rfloor$ if $i = 1, \dots, k$, while $\mathcal{N}_v = \bigcup_{j=1}^i \mathcal{D}_{k+1-j} \setminus \{v\}$ if $i = \left\lfloor \frac{k}{2} \right\rfloor + 1, \dots, k$.

In a *complete graph* K_n , every node is adjacent to every other node. The graph in which no pair of nodes is adjacent is the empty graph \bar{K}_n . A *clique* $K_{n'}$, $n' \leq n$, is a complete subgraph of the network G . A graph is *k-regular* if every node i has the same number of links $d_i = k$ for all $i \in \mathcal{N}$. The complete graph K_n is $(n-1)$ -regular. The cycle C_n is 2-regular. In a *bipartite graph* there exists a partition of the nodes in two disjoint sets V_1 and V_2 such that each link

connects a node in V_1 to a node in V_2 . V_1 and V_2 are independent sets with cardinalities n_1 and n_2 , respectively. In a complete bipartite graph K_{n_1, n_2} each node in V_1 is connected to each other node in V_2 . The *star* $K_{1, n-1}$ is a complete bipartite graph in which $n_1 = 1$ and $n_2 = n - 1$.

The *complement* of a graph G is a graph \bar{G} with the same nodes as G such that any two nodes of \bar{G} are adjacent if and only if they are not adjacent in G . For example the complement of the complete graph K_n is the empty graph \bar{K}_n .

Let \mathbf{A} be the symmetric $n \times n$ *adjacency matrix* of the network G . The element $a_{ij} \in \{0, 1\}$ indicates if there exists a link between nodes i and j such that $a_{ij} = 1$ if $(i, j) \in \mathcal{E}$ and $a_{ij} = 0$ if $(i, j) \notin \mathcal{E}$. The k -th power of the adjacency matrix is related to walks of length k in the graph. In particular, $(\mathbf{A}^k)_{ij}$ gives the number of walks of length k from node i to node j . The *eigenvalues* of the adjacency matrix \mathbf{A} are the numbers $\lambda_1, \lambda_2, \dots, \lambda_n$ such that $\mathbf{A}\mathbf{v}_i = \lambda_i\mathbf{v}_i$ has a nonzero solution vector \mathbf{v}_i , which is an *eigenvector* associated with λ_i for $i = 1, \dots, n$. Since the adjacency matrix \mathbf{A} of an undirected graph G is real and symmetric, the eigenvalues of \mathbf{A} are real, $\lambda_i \in \mathbb{R}$ for all $i = 1, \dots, n$. Moreover, if \mathbf{v}_i and \mathbf{v}_j are eigenvectors for different eigenvalues, $\lambda_i \neq \lambda_j$, then \mathbf{v}_i and \mathbf{v}_j are orthogonal, i.e. $\mathbf{v}_i^\top \mathbf{v}_j = 0$ if $i \neq j$. In particular, \mathbb{R}^n has an orthonormal basis consisting of eigenvectors of \mathbf{A} . Since \mathbf{A} is a real symmetric matrix, there exists an orthogonal matrix \mathbf{S} such that $\mathbf{S}^\top \mathbf{S} = \mathbf{S}\mathbf{S}^\top = \mathbf{I}$ (that is $\mathbf{S}^\top = \mathbf{S}^{-1}$) and $\mathbf{S}^\top \mathbf{A} \mathbf{S} = \mathbf{D}$, where \mathbf{D} is the diagonal matrix of eigenvalues of \mathbf{A} and the columns of \mathbf{S} are the corresponding eigenvectors. The *Perron-Frobenius eigenvalue* $\lambda_{\text{PF}}(G)$ is the *largest real eigenvalue* of \mathbf{A} associated with G , i.e. all eigenvalues λ_i of \mathbf{A} satisfy $|\lambda_i| \leq \lambda_{\text{PF}}(G)$ for $i = 1, \dots, n$ and there exists an associated nonnegative eigenvector $\mathbf{v}_{\text{PF}} \geq 0$ such that $\mathbf{A}\mathbf{v}_{\text{PF}} = \lambda_{\text{PF}}(G)\mathbf{v}_{\text{PF}}$. For a connected graph G the adjacency matrix \mathbf{A} has a unique largest real eigenvalue $\lambda_{\text{PF}}(G)$ and a positive associated eigenvector $\mathbf{v}_{\text{PF}} > 0$. There exists a relation between the number of walks in a graph and its eigenvalues. The number of closed walks of length k from a node i in G to herself is given by $(\mathbf{A}^k)_{ii}$ and the total number of closed walks of length k in G is $\text{tr}(\mathbf{A}^k) = \sum_{i=1}^n (\mathbf{A}^k)_{ii} = \sum_{i=1}^n \lambda_i^k$. We further have that $\text{tr}(\mathbf{A}) = 0$, $\text{tr}(\mathbf{A}^2)$ gives twice the number of links in G and $\text{tr}(\mathbf{A}^3)$ gives six times the number of triangles in G .

A.2. Walk Generating Functions

Denote by $\mathbf{u} = (1, \dots, 1)^\top$ the n -dimensional vector of ones and define $\mathbf{M}(G, \phi) = (\mathbf{I}_n - \phi\mathbf{A})^{-1}$. Then, the quantity $N_G(\phi) = \mathbf{u}^\top \mathbf{M}(G, \phi) \mathbf{u}$ is the *walk generating function* of the graph G [cf. [Cvetkovic et al., 1995](#)]. Let us show this result. Let N_k denote the number of walks of length k in G . Then we can write N_k as follows

$$N_k = \sum_{i=1}^n \sum_{j=1}^n a_{ij}^{[k]} = \mathbf{u}^\top \mathbf{A}^k \mathbf{u},$$

where $a_{ij}^{[k]}$ is the ij -th element of \mathbf{A}^k . The walk generating function is then defined as

$$N_G(\phi) \equiv \sum_{k=0}^{\infty} N_k \phi^k = \mathbf{u}^\top \left(\sum_{k=0}^{\infty} \phi^k \mathbf{A}^k \right) \mathbf{u} = \mathbf{u}^\top (\mathbf{I}_n - \phi\mathbf{A})^{-1} \mathbf{u} = \mathbf{u}^\top \mathbf{M}(G, \phi) \mathbf{u}.$$

For a k -regular graph G_k , the walk generating function is equal to

$$N_{G_k}(\phi) = \frac{n}{1 - k\phi}.$$

It holds that $N_G(0) = n$, and one can show that $N_G(\phi) \geq 0$. We further have that

$$\mathbf{M}(G, \phi) = (\mathbf{I}_n - \phi \mathbf{A})^{-1} = \sum_{k=0}^{\infty} \phi^k \mathbf{A}^k = \sum_{k=0}^{\infty} \phi^k \mathbf{S} \mathbf{\Lambda}^k \mathbf{S}^{\top},$$

where $\mathbf{\Lambda} \equiv \text{diag}(\lambda_1, \dots, \lambda_n)$ is the diagonal matrix containing the eigenvalues of the real, symmetric matrix \mathbf{A} , and \mathbf{S} is an orthogonal matrix with columns given by the orthogonal eigenvectors of \mathbf{A} (with $\mathbf{S}^{\top} = \mathbf{S}^{-1}$), and we have used the fact that $\mathbf{A} = \mathbf{S} \mathbf{\Lambda} \mathbf{S}^{\top}$ [Horn and Johnson, 1990]. The eigenvectors \mathbf{v}_i have the property that $\mathbf{A} \mathbf{v}_i = \lambda_i \mathbf{v}_i$ and are normalized such that $\mathbf{v}_i^{\top} \mathbf{v}_i = 1$. Note that $\mathbf{A} = \mathbf{S} \mathbf{\Lambda} \mathbf{S}^{\top}$ is equivalent to $\mathbf{A} = \sum_{i=1}^n \lambda_i \mathbf{v}_i \mathbf{v}_i^{\top}$. It then follows that

$$\mathbf{u}^{\top} \mathbf{M}(G, \phi) \mathbf{u} = \mathbf{u}^{\top} \mathbf{S} \sum_{k=0}^{\infty} \phi^k \mathbf{\Lambda}^k \mathbf{S}^{\top} \mathbf{u},$$

where

$$\mathbf{S}^{\top} \mathbf{u} = \left(\mathbf{u}^{\top} \mathbf{v}_1, \dots, \mathbf{u}^{\top} \mathbf{v}_n \right)^{\top},$$

and

$$\mathbf{\Lambda}^k = \begin{pmatrix} \lambda_1^k & 0 & \dots & 0 \\ 0 & \lambda_2^k & \dots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & \dots & & \lambda_n^k \end{pmatrix} = \lambda_1^k \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & \left(\frac{\lambda_2}{\lambda_1}\right)^k & \dots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & \dots & & \left(\frac{\lambda_n}{\lambda_1}\right)^k \end{pmatrix}.$$

We then can write

$$\mathbf{u}^{\top} \mathbf{M}(G, \phi) \mathbf{u} = \sum_{k=0}^{\infty} \phi^k \lambda_1^k \left(\mathbf{u}^{\top} \mathbf{v}_1, \dots, \mathbf{u}^{\top} \mathbf{v}_n \right) \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & \left(\frac{\lambda_2}{\lambda_1}\right)^k & \dots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & \dots & & \left(\frac{\lambda_n}{\lambda_1}\right)^k \end{pmatrix} \left(\mathbf{u}^{\top} \mathbf{v}_1, \dots, \mathbf{u}^{\top} \mathbf{v}_n \right)^{\top},$$

which gives

$$\begin{aligned} \mathbf{u}^{\top} \mathbf{M}(G, \phi) \mathbf{u} &= \sum_{k=0}^{\infty} \phi^k \lambda_1^k \left((\mathbf{u}^{\top} \mathbf{v}_1)^2 + \left(\frac{\lambda_2}{\lambda_1}\right)^k (\mathbf{u}^{\top} \mathbf{v}_2)^2 + \dots + \left(\frac{\lambda_n}{\lambda_1}\right)^k (\mathbf{u}^{\top} \mathbf{v}_n)^2 \right) \\ &= \sum_{i=1}^n (\mathbf{u}^{\top} \mathbf{v}_i)^2 \sum_{k=0}^{\infty} \phi^k \lambda_i^k \\ &= \sum_{i=1}^n \frac{(\mathbf{u}^{\top} \mathbf{v}_i)^2}{1 - \phi \lambda_i}. \end{aligned}$$

The above computation also shows that

$$N_k = \mathbf{u}^\top \mathbf{A}^k \mathbf{u} = \sum_{i=1}^n (\mathbf{u}^\top \mathbf{v}_i)^2 \lambda_i^k.$$

Hence, we can write the walk generating function as follows

$$N_G(\phi) = \mathbf{u}^\top \mathbf{M}(G, \phi) \mathbf{u} = \sum_{k=0}^{\infty} N_k \phi^k = \sum_{i=1}^n \frac{(\mathbf{v}_i^\top \mathbf{u})^2}{1 - \lambda_i \phi}.$$

If λ_1 is much larger than λ_j for all $j \geq 2$, then we can approximate

$$N_G(\phi) \approx (\mathbf{u}^\top \mathbf{v}_1)^2 \sum_{k=0}^{\infty} \phi^k \lambda_1^k = \frac{(\mathbf{u}^\top \mathbf{v}_1)^2}{1 - \phi \lambda_1}.$$

Cvetkovic et al. [1995, p. 45] has found an alternative expression for the walk generating function given by

$$N_G(\phi) = \frac{1}{\phi} \left((-1)^n \frac{c_{\mathbf{A}^c} \left(-\frac{1}{\phi} - 1 \right)}{c_{\mathbf{A}} \left(\frac{1}{\phi} \right)} - 1 \right),$$

where $c_{\mathbf{A}}(\phi) \equiv \det(\mathbf{A} - \phi \mathbf{I}_n)$ is the characteristic polynomial of the matrix \mathbf{A} , whose roots are the eigenvalues of \mathbf{A} . It can be written as $c_{\mathbf{A}}(\phi) = \phi^n - a_1 \phi^{n-1} + \dots + (-1)^n a_n$, where $a_1 = \text{tr}(\mathbf{A})$ and $a_n = \det(\mathbf{A})$. Further, $\mathbf{A}^c = \mathbf{u} \mathbf{u}^\top - \mathbf{I}_n - \mathbf{A}$ is the complement of \mathbf{A} , and $\mathbf{u} \mathbf{u}^\top$ is an $n \times n$ matrix of ones. This is a convenient expression for the walk generating function, as there exist fast algorithms to compute the characteristic polynomial [Nakos and Williams, 2000; Samuelson, 1942].

A.3. Nested Split Graphs

Let us define *nested split graphs* [Cvetkovic and Rowlinson, 1990; Mahadev and Peled, 1995], which include many common networks such as the star network. Moreover, as their name already indicates, they have a *nested neighborhood structure*. This means that the set of neighbors of each agent is contained in the set of neighbors of each higher degree agent. Nested split graphs have particular topological properties and an associated adjacency matrix with a well defined structure.

In order to characterize nested split graphs, it will be necessary to consider the degree partition of a graph, which is defined as follows:

Definition 1 (Mahadev and Peled [1995]). Let $G = (\mathcal{N}, \mathcal{E})$ be a graph whose distinct positive degrees are $d_{(1)} < d_{(2)} < \dots < d_{(k)}$, and let $d_0 = 0$ (even if no agent with degree 0 exists in G). Further, define $\mathcal{D}_i = \{v \in \mathcal{N} : d_v = d_{(i)}\}$ for $i = 0, \dots, k$. Then the set-valued vector $\mathcal{D} = (\mathcal{D}_0, \mathcal{D}_1, \dots, \mathcal{D}_k)$ is called the *degree partition* of G .

With the definition of a degree partition, we can now give a more formal definition of a

nested split graph.³²

Definition 2 (Mahadev and Peled [1995]). Consider a nested split graph $G = (\mathcal{N}, \mathcal{E})$ and let $\mathcal{D} = (\mathcal{D}_0, \mathcal{D}_1, \dots, \mathcal{D}_k)$ be its degree partition. Then the nodes \mathcal{N} can be partitioned in independent sets \mathcal{D}_i , $i = 1, \dots, \lfloor \frac{k}{2} \rfloor$ and a dominating set $\bigcup_{i=\lfloor \frac{k}{2} \rfloor + 1}^k \mathcal{D}_i$ in the graph $G' = (\mathcal{N} \setminus \mathcal{D}_0, \mathcal{E})$. Moreover, the neighborhoods of the nodes are nested. In particular, for each node $v \in \mathcal{D}_i$, $i = 1, \dots, k$,

$$\mathcal{N}_v = \begin{cases} \bigcup_{j=1}^i \mathcal{D}_{k+1-j} & \text{if } i = 1, \dots, \lfloor \frac{k}{2} \rfloor, \\ \bigcup_{j=1}^i \mathcal{D}_{k+1-j} \setminus \{v\} & \text{if } i = \lfloor \frac{k}{2} \rfloor + 1, \dots, k. \end{cases} \quad (33)$$

In the following, we will call the sets \mathcal{D}_i , $i = \lfloor \frac{k}{2} \rfloor + 1, \dots, k$, *dominating subsets*, since the set \mathcal{D}_i induces a dominating set in the graph obtained by removing the nodes in the set $\bigcup_{j=0}^{k-i} \mathcal{D}_j$ from G .

A nested split graph has an associated adjacency matrix which is called *stepwise matrix* and it is defined as follows:

Definition 3 (Brualdi and Hoffman [1985]). A stepwise matrix \mathbf{A} is a symmetric, binary $(n \times n)$ -matrix with elements a_{ij} satisfying the condition: if $i < j$ and $a_{ij} = 1$ then $a_{hk} = 1$ whenever $h < k \leq j$ and $h \leq i$.

If a nested split graph is connected we call it a connected nested split graph. From the stepwise property of the adjacency matrix, it follows that a connected nested split graph contains at least one spanning star, that is, there is at least one agent that is connected to all other agents (see e.g. König et al. [2014] for further properties).

A.4. Bonacich Centrality

We introduce a network measure capturing the centrality of a firm in the network due to Bonacich [1987]. Let \mathbf{A} be the symmetric $n \times n$ adjacency matrix of the network G and λ_{PF} its largest real eigenvalue. The matrix $\mathbf{M}(G, \phi) = (\mathbf{I} - \phi \mathbf{A})^{-1}$ exists and is non-negative if and only if $\phi < 1/\lambda_{\text{PF}}$.³³ Then

$$\mathbf{M}(G, \phi) = \sum_{k=0}^{\infty} \phi^k \mathbf{A}^k. \quad (34)$$

The Bonacich centrality vector is given by

$$\mathbf{b}_u(G, \phi) = \mathbf{M}(G, \phi) \cdot \mathbf{u}, \quad (35)$$

³²Let x be a real valued number $x \in \mathbb{R}$. Then, $\lceil x \rceil$ denotes the smallest integer larger or equal than x (the ceiling of x). Similarly, $\lfloor x \rfloor$ denotes the largest integer smaller or equal than x (the floor of x).

³³The proof can be found e.g. in Debreu and Herstein [1953].

where $\mathbf{u} = (1, \dots, 1)^\top$. We can write the Bonacich centrality vector as

$$\mathbf{b}_u(G, \phi) = \sum_{k=0}^{\infty} \phi^k \mathbf{A}^k \cdot \mathbf{u} = (\mathbf{I} - \phi \mathbf{A})^{-1} \cdot \mathbf{u}.$$

For the components $b_{u,i}(G, \phi)$, $i = 1, \dots, n$, we get

$$b_{u,i}(G, \phi) = \sum_{k=0}^{\infty} \phi^k (\mathbf{A}^k \cdot \mathbf{u})_i = \sum_{k=0}^{\infty} \phi^k \sum_{j=1}^n (\mathbf{A}^k)_{ij}. \quad (36)$$

Because $\sum_{j=1}^n (\mathbf{A}^k)_{ij}$ counts the number of all walks of length k in G starting from i , $b_{u,i}(G, \phi)$ is the number of all walks in G starting from i , where the walks of length k are weighted by their geometrically decaying factor ϕ^k .

Observe that we can also define the *weighted* Bonacich centrality exactly as above but when \mathbf{u} is not anymore the $(n \times 1)$ vector of 1 but any $(n \times 1)$ vector.

The Bonacich matrix of Equation (34) is also a measure of structural similarity of the firms in the network, called *regular equivalence*. Blondel et al. [2004]; Leicht et al. [2006] define a similarity score b_{ij} , which is high if nodes i and j have neighbors that themselves have high similarity, given by $b_{ij} = \phi \sum_{k=1}^n a_{ik} b_{kj} + \delta_{ij}$. In matrix-vector notation this reads $\mathbf{M} = \phi \mathbf{A} \mathbf{M} + \mathbf{I}$. Rearranging yields $\mathbf{M} = (\mathbf{I} - \phi \mathbf{A})^{-1} = \sum_{k=0}^{\infty} \phi^k \mathbf{A}^k$, assuming that $\phi < 1/\lambda_{\text{PF}}$. We hence obtain that the similarity matrix \mathbf{M} is equivalent to the Bonacich matrix from Equation (34). The average similarity of firm i is $\frac{1}{n} \sum_{j=1}^n b_{ij} = \frac{1}{n} b_{u,i}(G, \phi)$, where $b_{u,i}(G, \phi)$ is the Bonacich centrality of i . It follows that the Bonacich centrality of i is proportional to the average regular equivalence of i . Firms with a high Bonacich centrality are then the ones which also have a high average structural similarity with the other firms in the R&D network.

Since equilibrium profits are closely related to the Bonacich centralities of the firms in the network, it is worth introducing a connection between the Bonacich centrality of a node and its coreness in the network. Coreness is defined as follows: Given a network G , the induced subgraph $G_k \subseteq G$ is the k -core of G if it is the largest subgraph such that the degree of all nodes in G_k is at least k . Note that the cores of a graph are nested such that $G_{k+1} \subseteq G_k$. Cores can be used as a measure of centrality in the network G . Note that k -cores can be obtained by a simple pruning algorithm: at each step, we remove all nodes with degree less than k . We repeat this procedure until there exist no such nodes or all nodes are removed. We define the coreness of each node as follows: The coreness of node i , cor_i , is k if and only if $i \in G_k$ and $i \notin G_{k+1}$. We have that $\text{cor}_i \leq d_i$. However, there is no other relation between the degree and coreness of nodes in a graph. We then have the following result due to Manshadi and Johari [2010], which relates the Nash equilibrium to the k -cores of the graph: If $\text{cor}_i = k$ then $b_i(G, \phi) \geq \frac{1}{1-\phi^k}$, where the inequality is tight when i belongs to a disconnected clique of size $k+1$. The coreness of networks of firms has also been studied empirically in Kitsak et al. [2010] and Rosenkopf and Schilling [2007]. In particular, Kitsak et al. [2010] find that the coreness of a firm correlates with its market value. We can easily explain this from our model because we know that firms in higher cores tend to have higher Bonacich centrality, and

therefore higher sales and profits (cf. Proposition 1).

B. Bertrand Competition

In the case of price setting firms we obtain from the profit function in Equation (3) the FOC with respect to price p_i for firm i

$$\frac{\partial \pi_i}{\partial p_i} = (p_i - c_i) \frac{\partial q_i}{\partial p_i} - q_i = 0.$$

When $i \in \mathcal{M}_m$, then observe that from the inverse demand in Equation (1) we find that

$$q_i = \frac{\alpha_m(1 - \rho_m) - (1 - (n_m - 2)\rho_m)p_i + \rho_m \sum_{\substack{j \in \mathcal{M}_m \\ j \neq i}} p_j}{(1 - \rho)(1 + (n_m - 1)\rho_m)},$$

where $n_m \equiv |\mathcal{M}_m|$. It then follows that

$$\frac{\partial q_i}{\partial p_i} = -\frac{1 - (n_m - 2)\rho_m}{(1 - \rho_m)(1 + (n_m - 1)\rho_m)}.$$

Inserting into the FOC with respect to p_i gives

$$q_i = -\frac{1 - (n_m - 2)\rho_m}{(1 - \rho_m)(1 + (n_m - 1)\rho_m)}(p_i - c_i).$$

Inserting Equations (1) and (2) yields

$$\begin{aligned} q_i &= \frac{(1 - (n_m - 2)\rho_m)(\alpha_m - \bar{c}_i)}{\rho_m(4 - (2 - \rho_m)n_m - \rho_m)} - \frac{1 - (n_m - 2)\rho_m}{4 - (2 - \rho_m)n_m - \rho_m} \sum_{\substack{j \in \mathcal{M}_m \\ j \neq i}} q_j \\ &+ \frac{(1 - (n_m - 2)\rho_m)}{\rho_m(4 - (2 - \rho_m)n_m - \rho_m)} e_i + \frac{(1 - (n_m - 2)\rho_m)\varphi}{\rho_m(4 - (2 - \rho_m)n_m - \rho_m)} \sum_{j=1}^n a_{ij} e_j. \end{aligned}$$

The FOC with respect to R&D effort is the same as in the case of perfect competition, so that we get $e_i = q_i$. Inserting equilibrium effort and rearranging terms gives

$$\begin{aligned} q_i &= \frac{(1 - (n_m - 2)\rho_m)(\alpha_m - \bar{c}_i)}{\rho_m(4 - (2 - \rho_m)n_m - \rho_m) - 1(1 - (n_m - 2)\rho_m)} \\ &- \frac{\rho_m(1 - (n_m - 2)\rho_m)}{\rho_m(4 - (2 - \rho_m)n_m - \rho_m) - 1(1 - (n_m - 2)\rho_m)} \sum_{\substack{j \in \mathcal{M}_m \\ j \neq i}} q_j \\ &+ \frac{\varphi(1 - (n_m - 2)\rho_m)}{\rho_m(4 - (2 - \rho_m)n_m - \rho_m) - 1(1 - (n_m - 2)\rho_m)} \sum_{j=1}^n a_{ij} q_j. \end{aligned}$$

If we denote by

$$\begin{aligned}\mu_i &\equiv \frac{(1 - (n_m - 2)\rho_m)(\alpha_m - \bar{c}_i)}{\rho_m(4 - (2 - \rho_m)n_m - \rho_m) - 1(1 - (n_m - 2)\rho_m)}, \\ \rho &\equiv \frac{\rho_m(1 - (n_m - 2)\rho_m)}{\rho_m(4 - (2 - \rho_m)n_m - \rho_m) - 1(1 - (n_m - 2)\rho_m)}, \\ \lambda &\equiv \frac{\varphi(1 - (n_m - 2)\rho_m)}{\rho_m(4 - (2 - \rho_m)n_m - \rho_m) - 1(1 - (n_m - 2)\rho_m)}.\end{aligned}$$

Then we can write equilibrium quantities as follows

$$q_i = \mu_i - \rho \sum_{j=1}^n b_{ij}q_j + \lambda \sum_{j=1}^n a_{ij}q_j. \quad (37)$$

Observe that the reduced form Equation (37) is identical to the Cournot case in Equation (39).

C. Additional Results on Welfare

Here, we analyze welfare issues for a particular class of networks, namely the ones with a large spectral gap, such that λ_1 is much larger than λ_j for all $j \geq 2$.³⁴ These networks not only allow for a more explicit computation of welfare, but they are also representative for many real-world networks with a fat-tailed degree distribution,³⁵ as we observe it in our data (see Figure 5).

Proposition 8. *Consider substitutable goods and assume that $\mu_i = \mu$ for all $i = 1, \dots, n$, and let ϕ and μ be defined as in Proposition 1. Then in the limit of ϕ approaching the inverse of the largest eigenvalue λ_{PF} from below welfare can be written as*

$$\lim_{\phi \uparrow 1/\lambda_{PF}} W(G) = \frac{2 - \rho}{2} \frac{\mu^2}{\rho^2} \left(\frac{\rho}{2 - \rho} + \frac{1}{\|\mathbf{v}_1\|_1^2} \right).$$

Further, denote by $\mathcal{G}(n)$ the class of graphs with n nodes and the class of graphs with n nodes and m links by $\mathcal{H}(n, m) \subset \mathcal{G}(n)$. Consider the class $\mathcal{S}(n, m) \subset \mathcal{H}(n, m)$ of graphs with a large spectral gap, such that $\lambda_1 = \lambda_{PF}$ is much larger than λ_j for all $j \geq 2$. Then the welfare maximizing graph $G^* = \operatorname{argmax}_{G \in \mathcal{S}(n, m)} W(G)$ in this class is the one that minimizes the ℓ^1 -norm $\|\mathbf{v}_1\|_1$ of the principal eigenvector \mathbf{v}_1 associated with the largest eigenvalue λ_1 .

Proposition 8 implies that the social planner's problem reduces to finding the principal eigenvector of \mathbf{A} . For this problem there exist efficient algorithms, e.g. by using the power iteration method [Mises and Pollaczek-Geiringer, 1929].

³⁴The spectral gap is defined as $\lambda_1 - \lambda_2$. It is maximal in the complete graph K_n where it is equal to n . In the star $K_{1, n-1}$ we get $\lambda_1 - \lambda_2 = \sqrt{n-1}$. In a k -regular graph we obtain $\lambda_1 - \lambda_2 = \mu_{n-1}$, where μ_{n-1} is the second smallest eigenvalue of the Laplacian $\mathbf{Q} = \operatorname{diag}(\mathbf{d}) - \mathbf{A}$ and \mathbf{d} is the vector of degrees in G .

³⁵Mihail and Papadimitriou [2002] have shown that networks with a power-law degree distribution also have a power-law eigenvalue distribution. See also Anderson et al. [2010]; Dorogovtsev et al. [2003].

Note that the norm $\|\mathbf{v}_1\|_1$ is the projection of the principal eigenvector \mathbf{v}_1 onto the all ones vector \mathbf{u} ,

$$\|\mathbf{v}_1\|_1 = \|\mathbf{v}_1\|_2 \|\mathbf{u}\|_2 \cos(\alpha_1) = \sqrt{n} \cos(\alpha_1),$$

where α_1 is the angle between the vector \mathbf{v}_1 and \mathbf{u} . α_1 is called the principal graph angle [Cvetkovic et al., 1997, Chap. 4.5]. Welfare can then be written in terms of the graph angle α_1 as follows

$$\lim_{\phi \uparrow 1/\lambda_{\text{PF}}} W(G) = \frac{2-\rho}{2} \frac{\mu^2}{\rho^2} \left(\frac{\rho}{2-\rho} + \frac{1}{n \cos(\alpha_1)^2} \right).$$

Consider the spectral decomposition of the matrix \mathbf{A} given by $\mathbf{A} = \sum_{i=1}^n \lambda_i \mathbf{v}_i \mathbf{v}_i^\top$, then the principal graph angle satisfies $\cos(\alpha_1)^2 = \frac{1}{n} \|\mathbf{v}_1 \mathbf{v}_1^\top\|_1$. Moreover, its value is maximal for the regular graph, where it is one. We thus have that $\|\mathbf{v}_1\|_1^2 \leq n$, and we obtain a lower bound for welfare given by

$$\lim_{\phi \uparrow 1/\lambda_{\text{PF}}} W(G) \geq \frac{2-\rho}{2} \frac{\mu^2}{\rho^2} \left(\frac{\rho}{2-\rho} + \frac{1}{n} \right),$$

which is the welfare function in the regular graph. For the star $G = K_{1,n-1}$ the principal eigenvector is given by $\mathbf{v}_1 = \frac{1}{\sqrt{2(n-1)}}(\sqrt{n-1}, 1, \dots, 1)^\top$ where the corresponding largest eigenvalue is $\lambda_1 = \sqrt{n-1}$. In this case $(\mathbf{v}_1^\top \mathbf{u})^2 = \frac{1}{2}(2\sqrt{n-1} + n)$, and we obtain a lower bound on welfare in the efficient graph given by

$$\lim_{\phi \uparrow 1/\lambda_{\text{PF}}} W(K_{1,n-1}) = \frac{2-\rho}{2} \frac{\mu^2}{\rho^2} \left(\frac{\rho}{2-\rho} + \frac{2}{2\sqrt{n-1} + n} \right).$$

This is larger than the value we have obtained for the regular graph.³⁶ Note that the star has a higher degree variance than the regular graph. This indicates that the result of Proposition 4 does not hold for large values of the spillover parameter ϕ . Moreover, the star is dissortative while the complete graph is not.

The quantity $\|\mathbf{v}_1\|_1^2 = (\sum_{i=1}^n v_{1i})^2$ has been called *mixedness* of G by Rucker et al. [2002], since it relates to the variance of the principal eigenvector components as follows³⁷

$$\sigma_{\mathbf{v}_1}^2 = \frac{1}{n-1} \left(\sum_{i=1}^n v_{1i}^2 - \frac{1}{n} \left(\sum_{i=1}^n v_{1i} \right)^2 \right) = \frac{n - \|\mathbf{v}_1\|_1^2}{n(n-1)}.$$

The variance $\sigma_{\mathbf{v}_1}^2$ is decreasing in $\|\mathbf{v}_1\|_1$, and it is minimal for the regular graph where $v_{1i} = 1/\sqrt{n}$ for all $i = 1, \dots, n$, that is to say they are maximally mixed. Welfare can then be written as

$$\lim_{\phi \uparrow 1/\lambda_{\text{PF}}} W(G) = \frac{2-\rho}{2} \frac{\mu^2}{\rho^2} \left(\frac{\rho}{2-\rho} + \frac{1}{n(1 - (n-1)\sigma_{\mathbf{v}_1}^2)} \right).$$

³⁶Observe that $W(K_{1,n-1}) = \frac{2}{n+2\sqrt{n-1}} > W(K_n) = \frac{1}{n}$ and $\lim_{n \rightarrow \infty} W(K_{1,n-1})/W(K_n) = \frac{2n}{n+2\sqrt{n-1}} = 2$.

³⁷An alternative way to write the norm is $\|\mathbf{v}_1\|_1^2 = n - \sum_{j=1}^n \sum_{l=1}^{j-1} (v_{kj} - v_{kl})^2$ [Van Mieghem, 2011, p.40], which shows that $\|\mathbf{v}_1\|_1^2$ is maximal for an eigenvector \mathbf{v}_1 with minimal difference between its components.

This suggests that the welfare maximizing graph (among the graphs with a large spectral gap) is eigenvector heterogeneous, or minimally mixed. [Rucker et al. \[2002\]](#) have shown by means of numerical computations for all networks of size $n \leq 10$ that graphs called *k-kites* minimize the mixedness.

A graph with a principal eigenvalue λ_1 contains the more walks, the larger is $\|\mathbf{v}_1\|_1^2$. Moreover, the reciprocal $1/\|\mathbf{v}_1\|_1^2$ measures the share of self returning walks among all walks. It follows that, a small value of $\|\mathbf{v}_1\|_1^2$ implies a large share of self returning walks, or a small probability that a randomly chosen walk ends at a vertex other than its origin. In terms of our model, where the network governs the way knowledge spillovers and diffusion are directed between firms, we thus find that the welfare maximizing graph has a large share of self returning walks, that is, knowledge originating in a firm passes through others before returning to its originator. This indicates that maximizing the cross-fertilization of knowledge and *knowledge recombination* between firms is welfare enhancing [cf. [Weitzman, 1998](#)].

D. Intra- versus Interindustry Collaborations: Theory

We extend our model by allowing for intra-industry technology spillovers to differ from inter-industry spillovers. The profit of firm $i \in \mathcal{N}$ is still given by $\pi_i = (p_i - c_i)q_i - \frac{1}{2}e_i^2$, where the inverse demand is $p_i = \bar{\alpha}_i - q_i - \rho \sum_{j=1}^n b_{ij}q_j$. The main change is in the marginal cost of production, which is now equal to

$$c_i = \bar{c}_i - e_i - \varphi_1 \sum_{j=1}^n a_{ij}^{(1)} e_j - \varphi_2 \sum_{j=1}^n a_{ij}^{(2)} e_j,$$

where we have introduced two matrices $\mathbf{A}^{(1)}$ and $\mathbf{A}^{(2)}$ with elements $a_{ij}^{(1)}$ and $a_{ij}^{(2)}$, respectively, indicating a collaboration within the same industry (with the superscript (1)) or across different industries (with the superscript (2)). Note that we can write $\mathbf{A}^{(1)} = \mathbf{A} \circ \mathbf{B}$ and $\mathbf{A}^{(2)} = \mathbf{A} \circ (\mathbf{U} - \mathbf{B})$, with the matrix \mathbf{B} having elements $b_{ij} \in \{0, 1\}$ indicating whether firms i and j operate in the same market or not, \mathbf{U} being a matrix of all ones, and \circ denotes the Hadamard elementwise matrix product.³⁸ Inserting this marginal cost of production into the profit function gives

$$\pi_i = (\bar{\alpha}_i - \bar{c}_i)q_i - q_i^2 - \rho q_i \sum_{j=1}^n b_{ij}q_j + q_i e_i + \varphi_1 q_i \sum_{j=1}^n a_{ij}^{(1)} e_j + \varphi_2 q_i \sum_{j=1}^n a_{ij}^{(2)} e_j - \frac{1}{2}e_i^2.$$

As above, from the first-order condition with respect to R&D effort, we obtain $e_i = q_i$. Inserting this optimal effort into the first-order condition with respect to output, we obtain

$$q_i = \bar{\alpha}_i - \bar{c}_i - \rho \sum_{j=1}^n b_{ij}q_j + \varphi_1 \sum_{j=1}^n a_{ij}^{(1)} q_j + \varphi_2 \sum_{j=1}^n a_{ij}^{(2)} q_j.$$

³⁸Let \mathbf{A} and \mathbf{B} be $m \times n$ matrices. The Hadamard product of \mathbf{A} and \mathbf{B} is defined by $[\mathbf{A} \circ \mathbf{B}]_{ij} = [\mathbf{A}]_{ij}[\mathbf{B}]_{ij}$ for all $1 \leq i \leq m, 1 \leq j \leq n$, i.e. the Hadamard product is simply an element-wise multiplication.

Denoting by $\mu_i \equiv \bar{\alpha}_i - \bar{c}_i$, we can write this as

$$q_i = \mu_i - \rho \sum_{j=1}^n b_{ij} q_j + \varphi_1 \sum_{j=1}^n a_{ij}^{(1)} q_j + \varphi_2 \sum_{j=1}^n a_{ij}^{(2)} q_j. \quad (38)$$

If the matrix $\mathbf{I}_n + \rho \mathbf{B} - \varphi_1 \mathbf{A}^{(1)} - \varphi_2 \mathbf{A}^{(2)}$ is invertible, this gives us the equilibrium quantities

$$\mathbf{q} = (\mathbf{I}_n + \rho \mathbf{B} - \varphi_1 \mathbf{A}^{(1)} - \varphi_2 \mathbf{A}^{(2)})^{-1} \boldsymbol{\mu}.$$

Let us now write the econometric equivalent of Equation (38). Proceeding as in Section 8.1, using Equations (23) and (24) and introducing time t , we get

$$\mu_{it} = \mathbf{x}_{it}^\top \boldsymbol{\beta} + \eta_i + \kappa_t + \epsilon_{it}.$$

Plugging this value of μ_{it} into Equation (38), we obtain

$$q_{it} = \varphi_1 \sum_{j=1}^n a_{ij,t}^{(1)} q_{jt} + \varphi_2 \sum_{j=1}^n a_{ij,t}^{(2)} q_{jt} - \rho \sum_{j=1}^n b_{ij} q_{jt} + \mathbf{x}_{it}^\top \boldsymbol{\beta} + \eta_i + \kappa_t + \epsilon_{it},$$

where $a_{ij,t}^{(1)} = a_{ij,t} b_{ij}$ and $a_{ij,t}^{(2)} = a_{ij,t} (1 - b_{ij})$. This is Equation (31) in Section 9.2.3.

E. Proofs

Before we proceed with the proof of Proposition 1 we state the following lemma which will be needed in the proof.

Lemma 1. *Let \mathbf{A} and \mathbf{B} be two symmetric, real matrices and assume that the inverse \mathbf{A}^{-1} exists and is non-negative and also that \mathbf{B} is non-negative. Provided that $\lambda_{\max}(\mathbf{A}^{-1}\mathbf{B}) < 1$ we have that*

(i) *the following series expansion exists*

$$(\mathbf{A} + \mathbf{B})^{-1} = \sum_{k=0}^{\infty} (-1)^k (\mathbf{A}^{-1}\mathbf{B})^k \mathbf{A}^{-1},$$

(ii) *for any $\mathbf{x} \in \mathbf{R}_+^n$ we have that $\mathbf{A}^{-1}\mathbf{B}\mathbf{x} < \mathbf{x}$, and*

(iii) *if also $\mathbf{A}^{-1}\mathbf{x} > \mathbf{0}$ then $(\mathbf{A} + \mathbf{B})^{-1}\mathbf{x} > \mathbf{0}$.*

Proof of Lemma 1. We first prove part (i) of the lemma. Notice that

$$\begin{aligned} (\mathbf{A} + \mathbf{B})^{-1} &= (\mathbf{A}(\mathbf{I}_n + \mathbf{A}^{-1}\mathbf{B}))^{-1} \\ &= (\mathbf{I}_n + \mathbf{A}^{-1}\mathbf{B})^{-1} \mathbf{A}^{-1} \\ &= \sum_{k=0}^{\infty} (-1)^k (\mathbf{A}^{-1}\mathbf{B})^k \mathbf{A}^{-1}, \end{aligned}$$

where the Neumann series expansion for $(\mathbf{I}_n + \mathbf{A}^{-1}\mathbf{B})^{-1}$ can be applied if $\lambda_{\max}(\mathbf{A}^{-1}\mathbf{B}) < 1$.

For the second part (ii), observe that $\lambda_{\max}(\mathbf{A}^{-1}\mathbf{B}) < 1$ is equivalent to $\mathbf{A}^{-1}\mathbf{B}\mathbf{x} < \mathbf{x}$ for any $\mathbf{x} \in \mathbf{R}_+^n$. To see this consider an orthonormal basis of \mathbf{R}^n spanned by the eigenvectors of $\mathbf{A}^{-1}\mathbf{B}$. Then we can write $\mathbf{x} = \sum_{i=1}^n c_i \mathbf{v}_i$ with suitable coefficients $c_i = \mathbf{x}^\top \mathbf{v}_i / (\mathbf{v}_i^\top \mathbf{v}_i)$ and $\mathbf{A}^{-1}\mathbf{B}\mathbf{v}_i = \lambda_i \mathbf{v}_i$. It then follows that

$$\mathbf{A}^{-1}\mathbf{B}\mathbf{x} = \sum_{i=1}^n c_i \lambda_i \mathbf{v}_i \leq \lambda_{\max}(\mathbf{A}^{-1}\mathbf{B}) \sum_{i=1}^n c_i \mathbf{v}_i = \lambda_{\max}(\mathbf{A}^{-1}\mathbf{B})\mathbf{x}.$$

Hence, if $\lambda_{\max}(\mathbf{A}^{-1}\mathbf{B}) < 1$ it must hold that $\mathbf{A}^{-1}\mathbf{B}\mathbf{x} < \mathbf{x}$.

For part (iii) of the proof note that we can write the series expansion of the inverse as follows

$$(\mathbf{A} + \mathbf{B})^{-1}\mathbf{x} = \sum_{k=0}^{\infty} (-1)^k (\mathbf{A}^{-1}\mathbf{B})^k \mathbf{A}^{-1}\mathbf{x} = \mathbf{A}^{-1}\mathbf{x} - \mathbf{A}^{-1}\mathbf{B}\mathbf{A}^{-1}\mathbf{x} + \mathbf{A}^{-1}\mathbf{B}\mathbf{A}^{-1}\mathbf{B}\mathbf{A}^{-1}\mathbf{x} - \dots$$

By assumption we have that $\mathbf{A}^{-1}\mathbf{x} \geq \mathbf{0}$. Then denote by $\tilde{\mathbf{x}} = \mathbf{A}^{-1}\mathbf{x} \geq \mathbf{0}$. Then the first two terms in the series can be written as

$$(\mathbf{I}_n - \mathbf{A}^{-1}\mathbf{B})\mathbf{A}^{-1}\mathbf{x} = (\mathbf{I}_n - \mathbf{A}^{-1}\mathbf{B})\tilde{\mathbf{x}} > \mathbf{0}$$

where the inequality follows from part (ii) of the lemma. Next, consider the third and fourth terms in the series expansion

$$(\mathbf{A}^{-1}\mathbf{B}\mathbf{A}^{-1}\mathbf{B} - \mathbf{A}^{-1}\mathbf{B}\mathbf{A}^{-1}\mathbf{B}\mathbf{A}^{-1}\mathbf{B})\tilde{\mathbf{x}} = \mathbf{A}^{-1}\mathbf{B}\mathbf{A}^{-1}\mathbf{B}(\mathbf{I}_n - \mathbf{A}^{-1}\mathbf{B})\tilde{\mathbf{x}} \geq \mathbf{0},$$

where the inequality follows again from the fact that $(\mathbf{I}_n - \mathbf{A}^{-1}\mathbf{B})\tilde{\mathbf{x}} > \mathbf{0}$ from part (ii) of the lemma and the assumption that \mathbf{A}^{-1} and \mathbf{B} are non-negative matrices. We can then iterate by induction to show the desired claim. \square

Proof of Proposition 1. Let us start with the most general case, i.e. case (i). The profit of firm $i \in \mathcal{N}$ is given by

$$\pi_i = (\bar{\alpha}_i - \bar{c}_i)q_i - q_i^2 - \rho \sum_{j \in \mathcal{M}_m, j \neq i} q_i q_j + q_i e_i + \varphi q_i \sum_{j=1}^n a_{ij} e_j - \frac{1}{2} e_i^2,$$

where $b_{ij} \in \{0, 1\}$ is the ij -th element of the $n \times n$ matrix \mathbf{B} defined by

$$\mathbf{B} \equiv \sum_{m=1}^M (\mathbf{u}_m \mathbf{u}_m^\top - \mathbf{D}_m) = \begin{pmatrix} 0 & 1 & \dots & 1 & 0 & \dots & \dots & 0 & \dots \\ 1 & 0 & \dots & \vdots & \vdots & & & & \vdots \\ \vdots & \vdots & \ddots & 1 & \vdots & & & & \vdots \\ 1 & \dots & 1 & 0 & 0 & \dots & \dots & 0 & \dots \\ 0 & \dots & \dots & 0 & 0 & 1 & \dots & 1 & \vdots \\ \vdots & & & \vdots & 1 & 0 & \dots & \vdots & \vdots \\ \vdots & & & \vdots & \vdots & \vdots & \ddots & 1 & \vdots \\ 0 & \dots & \dots & 0 & 1 & \dots & 1 & 0 & \vdots \\ \vdots & & & \vdots & \vdots & & & & \ddots \end{pmatrix}_{n \times n}$$

and \mathbf{u}_m is a $n \times 1$ zero-one vector with elements $u_{mi} = 1$ if $i \in \mathcal{M}_m$ and $u_{mi} = 0$ otherwise for all $i = 1, \dots, n$. Moreover, $\mathbf{D}_m = \text{diag}(\mathbf{u}_m)$ is the diagonal matrix with diagonal entries given by \mathbf{u}_m . The FOC of profits with respect to R&D effort e_i of firm i is given by

$$\frac{\partial \pi_i}{\partial e_i} = q_i - e_i = 0,$$

so that we obtain

$$e_i = q_i.$$

The FOC with respect to quantity is given by

$$\frac{\partial \pi_i}{\partial q_i} = \bar{\alpha}_i - \bar{c}_i - 2q_i - \rho \sum_{j=1}^n b_{ij} q_j + e_i + \varphi \sum_{j=1}^n a_{ij} e_j.$$

Inserting equilibrium effort and rearranging terms gives

$$q_i = (\bar{\alpha}_i - \bar{c}_i) - \rho \sum_{j=1}^n b_{ij} q_j + \varphi \sum_{j=1}^n a_{ij} q_j.$$

In the following we denote by $\mu_i \equiv \bar{\alpha}_i - \bar{c}_i$, so that we obtain for equilibrium quantity

$$q_i = \mu_i - \rho \sum_{j=1}^n b_{ij} q_j + \varphi \sum_{j=1}^n a_{ij} q_j. \quad (39)$$

In matrix-vector notation it can be written as

$$\mathbf{q} = \boldsymbol{\mu} - \rho \mathbf{B} \mathbf{q} + \varphi \mathbf{A} \mathbf{q}$$

or, equivalently,

$$(\mathbf{I}_n + \rho \mathbf{B} - \varphi \mathbf{A}) \mathbf{q} = \boldsymbol{\mu}.$$

The matrix $\mathbf{I}_n + \rho \mathbf{B} - \varphi \mathbf{A}$ is invertible if its determinant is not zero. This also guarantees the uniqueness and existence of the equilibrium. Following [Lee and Liu \[2010\]](#), the determinant of $\mathbf{I}_n - \sum_{j=1}^p \lambda_j \mathbf{W}_j$ is strictly positive if $\sum_{j=1}^p |\lambda_j| < 1 / \max_{j=1, \dots, p} \|\mathbf{W}_j\|$, where $\|\mathbf{W}_j\|$ is any

matrix norm, including the spectral norm (which is the largest eigenvalue of \mathbf{W}_j). We have that the largest eigenvalue of the matrix \mathbf{B} is equal to the size of the largest market $|\mathcal{M}_m|$ minus one (as this is a block-diagonal matrix with all elements being one in each block and zero diagonal), and the largest eigenvalue of \mathbf{A} is the Perron-Frobenius eigenvalue $\lambda_{\text{PF}}(\mathbf{A})$. A sufficient condition for invertibility is then given by

$$\rho + \varphi < \left(\max \left\{ \lambda_{\text{PF}}(\mathbf{A}), \max_{m=1, \dots, M} \{(|\mathcal{M}_m| - 1)\} \right\} \right)^{-1},$$

which can also be written as

$$1 + \varphi/\rho < \left(\max \left\{ \lambda_{\text{PF}}(\mathbf{A}), \max_{m=1, \dots, M} \{(|\mathcal{M}_m| - 1)\rho_m\} \right\} \right)^{-1}.$$

When the inverse of $\mathbf{I}_n + \rho\mathbf{B} - \varphi\mathbf{A}$ exists, we can write equilibrium quantities as

$$\mathbf{q} = (\mathbf{I}_n + \rho\mathbf{B} - \varphi\mathbf{A})^{-1}\boldsymbol{\mu}.$$

We have shown that there exists a unique equilibrium given by $\mathbf{q} = (\mathbf{I}_n + \rho\mathbf{B} - \varphi\mathbf{A})^{-1}\boldsymbol{\mu}$, but we have not yet shown that it is interior, i.e. $q_i > 0, \forall i \in \mathcal{N}$. We will deal with corner solutions below. Profits in equilibrium can be written as

$$\pi_i = (\bar{\alpha}_i - \bar{c}_i)q_i - \rho q_i \sum_{j=1}^n b_{ij}q_j + \varphi q_i \sum_{j=1}^n a_{ij}q_j - \frac{1}{2}q_i^2.$$

From Equation (39) it follows that

$$\begin{aligned} \rho q_i \sum_{j=1}^n b_{ij}q_j - \varphi q_i \sum_{j=1}^n a_{ij}q_j &= \rho q_i \sum_{j=1}^n b_{ij}q_j - \varphi q_i \sum_{j=1}^n a_{ij}q_j \\ &= q_i((\rho\mathbf{B} - \varphi\mathbf{A})\mathbf{q})_i \\ &= q_i((\mathbf{I}_n + \rho\mathbf{B} - \varphi\mathbf{A})\mathbf{q} - \mathbf{q})_i \\ &= q_i((\bar{\alpha}_i - \bar{c}_i) - q_i), \end{aligned} \tag{40}$$

so that we can write equilibrium profits as

$$\begin{aligned} \pi_i &= (\bar{\alpha}_i - \bar{c}_i)q_i - q_i((\bar{\alpha}_i - \bar{c}_i) - q_i) - \frac{1}{2}q_i^2 \\ &= \frac{1}{2}q_i^2. \end{aligned}$$

Let us now deal with case (ii) in the proposition, i.e. we assume that all firms operate in the same market so that $M = 1$. The first-order condition for a firm i is given by Equation (39),

which, when $M = 1$, can be written as:

$$q_i = \mu_i - \rho \sum_{j \neq i} q_j + \varphi \sum_{j=1}^n a_{ij} q_j$$

Let us have the following notation: $\bar{q}_{-i} \equiv \sum_{j \neq i} q_j$, which is the total output of all firms but excluding firm i . The equation above is equivalent to:

$$q_i = \mu_i - \rho \bar{q}_{-i} + \varphi \sum_{j=1}^n a_{ij} q_j$$

We can now define $\bar{q} \equiv \sum_{j \neq i} q_j + q_i$, which corresponds to the total output of all firms (including i). The equation above is now equivalent to

$$\begin{aligned} q_i &= \mu_i - \rho \bar{q} + \rho q_i + \varphi \sum_{j=1}^n a_{ij} q_j \\ \Leftrightarrow q_i &= \frac{1}{(1-\rho)} \mu_i - \frac{\rho}{(1-\rho)} \bar{q} + \frac{\varphi}{(1-\rho)} \sum_{j=1}^n a_{ij} q_j \end{aligned} \quad (41)$$

Observe that even if firms are local monopolies (i.e. $\rho = 0$) this solution is still well-defined. Observe also that $1 - \rho > 0$ if and only if $\rho < 1$, which we assume throughout.

In matrix form, Equation (41) can be written as:

$$\left[\mathbf{I} - \frac{\varphi}{(1-\rho)} \mathbf{A} \right] \mathbf{q} = \frac{1}{1-\rho} \boldsymbol{\mu} - \frac{\rho \bar{q}}{1-\rho} \mathbf{u}$$

where $\boldsymbol{\mu} = (\mu_1, \dots, \mu_n)^\top$, and $\mathbf{u} = (1, \dots, 1)^\top$. Denote $\phi = \varphi / (1 - \rho)$. If $\phi \lambda_{\text{PF}}(\mathbf{A}) < 1$, this is equivalent to

$$\mathbf{q} = \left(\frac{1}{1-\rho} \right) (\mathbf{I} - \phi \mathbf{A})^{-1} \boldsymbol{\mu} - \frac{\rho \bar{q}}{1-\rho} (\mathbf{I} - \phi \mathbf{A})^{-1} \mathbf{u}$$

This equation is equivalent to:

$$\mathbf{q} = \left(\frac{1}{1-\rho} \right) [\mathbf{b}_\mu(G, \phi) - \rho \bar{q} \mathbf{b}_u(G, \phi)] \quad (42)$$

where $\mathbf{b}_u(G, \varphi / (1 - \rho)) = (\mathbf{I} - \phi \mathbf{A})^{-1} \mathbf{u}$ is the *unweighted* vector of Bonacich centralities and $\mathbf{b}_\mu(G, \varphi / (1 - \rho)) = (\mathbf{I} - \phi \mathbf{A})^{-1} \boldsymbol{\mu}$ is the *weighted* vector of Bonacich centralities where the weights are the μ_i for $i = 1, \dots, n$.³⁹

We need now to calculate \bar{q} . Multiplying Equation (42) to the left by \mathbf{u}^\top , we obtain:

$$(1 - \rho) \bar{q} = \|\mathbf{b}_\mu(G, \phi)\|_1 - \rho \bar{q} \|\mathbf{b}_u(G, \phi)\|_1$$

³⁹ A definition and further discussion of the Bonacich centrality is given in Appendix A.4.

where

$$\|\mathbf{b}_\mu(G, \phi)\|_1 = \mathbf{u}^\top \mathbf{b}_\mu(G, \phi) = \sum_{i=1}^n b_{\mu,i}(G, \phi) = \sum_{i=1}^n \sum_{j=1}^n \sum_{p=0}^{+\infty} \phi^p a_{ij}^{[p]} \mu_j$$

is the sum of the weighted Bonacich centralities and

$$\|\mathbf{b}_u(G, \phi)\|_1 = \mathbf{u}^\top \mathbf{b}_u(G, \phi) = \sum_{i=1}^n b_{u,i}(G, \phi) = \sum_{i=1}^n \sum_{j=1}^n \sum_{p=0}^{+\infty} \phi^p a_{ij}^{[p]}$$

is the sum of the unweighted Bonacich centralities. Solving this equation, we get:

$$\bar{q} = \frac{\|\mathbf{b}_\mu(G, \phi)\|_1}{(1 - \rho) + \rho \|\mathbf{b}_u(G, \phi)\|_1}$$

Plugging this value of \bar{q} into Equation (42), we finally obtain:

$$\mathbf{q} = \left(\frac{1}{1 - \rho} \right) \left[\mathbf{b}_\mu(G, \phi) - \frac{\rho \|\mathbf{b}_\mu(G, \phi)\|_1}{1 - \rho + \rho \|\mathbf{b}_u(G, \phi)\|_1} \mathbf{b}_u(G, \phi) \right] \quad (43)$$

This corresponds to Equation (9) in the proposition. For each firm i , we thus have

$$q_i = \left(\frac{1}{1 - \rho} \right) \left[b_{\mu,i}(G, \phi) - \frac{\rho \|\mathbf{b}_\mu(G, \phi)\|_1}{1 - \rho + \rho \|\mathbf{b}_u(G, \phi)\|_1} b_{u,i}(G, \phi) \right] \quad (44)$$

Next, we consider corner solutions and provide conditions which guarantee that the equilibrium is always interior. For that, we would like to show that $q_i > 0$, $\forall i = 1, \dots, n$. Using Equation (44), this is equivalent to

$$b_{\mu,i}(G, \phi) > \frac{\rho \|\mathbf{b}_\mu(G, \phi)\|_1}{1 - \rho + \rho \|\mathbf{b}_u(G, \phi)\|_1} b_{u,i}(G, \phi), \quad \forall i = 1, \dots, n. \quad (45)$$

Denote by $\underline{\mu} = \max_i \{\mu_i \mid i \in N\}$ and $\bar{\mu} = \max_i \{\mu_i \mid i \in N\}$, with $\underline{\mu} < \bar{\mu}$. Then, $\forall i = 1, \dots, n$, we have

$$\begin{aligned} \|\mathbf{b}_u(G, \phi)\|_1 &= \sum_{i=1}^n \sum_{j=1}^n \sum_{p=0}^{\infty} \phi^p a_{ij}^{[p]} \mu_j \\ &\leq \bar{\mu} \sum_{i=1}^n \sum_{j=1}^n \sum_{p=0}^{\infty} \phi^p a_{ij}^{[p]} = \bar{\mu} \|\mathbf{b}_u(G, \phi)\|_1 \end{aligned}$$

and

$$b_{\mu,i}(G, \phi) = \sum_{j=1}^n \sum_{p=0}^{\infty} \phi^p a_{ij}^{[p]} \mu_j \geq \underline{\mu} b_{u,i}(G, \phi) = \sum_{j=1}^n \sum_{p=0}^{\infty} \phi^p a_{ij}^{[p]} \underline{\mu}$$

Thus, a sufficient condition for Equation (45) to hold is:

$$\underline{\mu} b_{u,i}(G, \phi) > \frac{\rho \bar{\mu} \|\mathbf{b}_u(G, \phi)\|_1}{1 - \rho + \rho \|\mathbf{b}_u(G, \phi)\|_1} b_{u,i}(G, \phi)$$

or equivalently

$$\underline{\mu} > \frac{\rho \bar{\mu} \|\mathbf{b}_u(G, \phi)\|_1}{1 - \rho + \rho \|\mathbf{b}_u(G, \phi)\|_1}$$

or

$$1 - \rho > \rho \|\mathbf{b}_u(G, \phi)\|_1 \left(\frac{\bar{\mu}}{\underline{\mu}} - 1 \right) \quad (46)$$

Observe that, by definition,

$$\|\mathbf{b}_u(G, \phi)\|_1 = \sum_{i=1}^n \sum_{j=1}^n \sum_{p=0}^{\infty} \phi^p a_{ij}^{[p]} = \sum_{p=0}^{\infty} \phi^p \mathbf{u}^\top \mathbf{A}^p \mathbf{u} \quad (47)$$

We know that $\lambda_{\text{PF}}(\mathbf{A}^p) = \lambda_{\text{PF}}(\mathbf{A})^p$, for all $p \geq 0$.⁴⁰ Also, $\mathbf{u}^\top \mathbf{A}^p \mathbf{u}/n$ is the average connectivity in the matrix \mathbf{A}^p of paths of length p in the original network \mathbf{A} , which is smaller than that its spectral radius $\lambda_{\text{PF}}(\mathbf{A})^p$ [Cvetkovic et al., 1995], i.e. $\mathbf{u}^\top \mathbf{A}^p \mathbf{u}/n \leq \lambda_{\text{PF}}(\mathbf{A})^p$. Therefore, Equation (47) leads to the following inequality

$$\|\mathbf{b}_u(G, \phi)\|_1 = \sum_{p=0}^{\infty} \phi^p \mathbf{u}^\top \mathbf{A}^p \mathbf{u} \leq n \sum_{p=0}^{\infty} \phi^p \lambda_{\text{PF}}(\mathbf{A})^p = \frac{n}{1 - \phi \lambda_{\text{PF}}(\mathbf{A})}.$$

A sufficient condition for Equation (46) to hold is thus

$$\phi \lambda_{\text{PF}}(\mathbf{A}) + \frac{n\rho}{1 - \rho} \left(\frac{\bar{\mu}}{\underline{\mu}} - 1 \right) < 1.$$

Clearly, this interior equilibrium is unique. This is the condition given in the proposition for case (ii).

Let us now go back to case (i) in the proposition and show that we have an interior equilibrium with all firms producing at positive quantity levels, that is $\mathbf{q} = (\mathbf{I}_n + \rho \mathbf{B} - \phi \mathbf{A})^{-1} \boldsymbol{\mu} > \mathbf{0}$. To do this we would like to apply Lemma 1. Let $\mathbf{I}_n - \phi \mathbf{A}$ be the matrix \mathbf{A} in the lemma and $\rho \mathbf{B}$ the corresponding matrix \mathbf{B} . We have that both are real and symmetric, and that \mathbf{B} is a non-negative matrix. Further, provided that $\phi < 1/\lambda_{\text{PF}}(\mathbf{A})$, the inverse \mathbf{A}^{-1} exists and is non-negative. Next, we need to show that $\lambda_{\text{PF}}(\mathbf{A}^{-1} \mathbf{B}) < 1$, but this is equivalent to

$$\lambda_{\text{PF}}((\mathbf{I}_n - \phi \mathbf{A})^{-1} \rho \mathbf{B}) < 1.$$

⁴⁰Observe that $\lambda_{\text{PF}}(\mathbf{A}^p) = \lambda_{\text{PF}}(\mathbf{A})^p$ is true for both a *symmetric* and an *asymmetric* adjacency matrix \mathbf{A} as long as \mathbf{A} has non-negative entries $a_{ij} \geq 0$. This follows from the Perron-Frobenius theorem.

Note that

$$\begin{aligned}\lambda_{\text{PF}}((\mathbf{I}_n - \varphi \mathbf{A})^{-1} \rho \mathbf{B}) &= \rho \lambda_{\text{PF}}((\mathbf{I}_n - \varphi \mathbf{A})^{-1} \mathbf{B}) \\ &\leq \rho \lambda_{\text{PF}}((\mathbf{I}_n - \varphi \mathbf{A})^{-1}) \lambda_{\text{PF}}(\mathbf{B}) \\ &= \frac{\rho \lambda_{\text{PF}}(\mathbf{B})}{1 - \varphi \lambda_{\text{PF}}(\mathbf{A})},\end{aligned}$$

so that a sufficient condition is given by

$$\frac{\rho \lambda_{\text{PF}}(\mathbf{B})}{1 - \varphi \lambda_{\text{PF}}(\mathbf{A})} < 1,$$

which is implied by

$$\rho \lambda_{\text{PF}}(\mathbf{B}) = \rho \max_{m=1, \dots, M} \{(|\mathcal{M}_m| - 1)\} < 1 - \varphi \lambda_{\text{PF}}(\mathbf{A}).$$

The lemma then implies that $(\mathbf{A} + \mathbf{B})^{-1} \mathbf{x} > \mathbf{0}$ for any vector $\mathbf{x} > \mathbf{0}$, and in particular for the vector $\boldsymbol{\mu}$, which is positive by assumption.

Consider now case (iii) where not only $M = 1$ but also $\mu_i = \mu$ for all $i = 1, \dots, n$. If $\varphi \lambda_{\text{PF}}(\mathbf{A}) < 1$, the equilibrium condition in Equation (43) can be further simplified to

$$\mathbf{q} = \frac{\mu}{1 - \rho + \rho \|\mathbf{b}_{\mathbf{u}}(G, \varphi)\|_1} \mathbf{b}_{\mathbf{u}}(G, \varphi). \quad (48)$$

It should be clear that the output is now always strictly positive.

Let us now consider case (iv) where markets are independent and goods are non-substitutable (i.e., $\rho = 0$). If $\varphi < \lambda_{\text{PF}}(\mathbf{A})^{-1}$, the equilibrium quantity further simplifies to $\mathbf{q} = \mu \mathbf{b}_{\mathbf{u}}(G, \varphi)$, which is always strictly positive. Equilibrium profit follows from Equation (11). \square

Proof of Proposition 2. We first give a proof of part (ii) of the proposition. Assuming that $\mu_i = \mu$ for all $i = 1, \dots, n$, at the Nash equilibrium, we have that $\mathbf{q} = \mu \mathbf{M}(G, \varphi) \mathbf{u}$, where we have denoted by $\mathbf{M}(G, \varphi) \equiv (\mathbf{I}_n - \varphi \mathbf{A})^{-1}$.⁴¹ We then obtain

$$W(G) = \mathbf{q}^\top \mathbf{q} = \mu^2 \mathbf{u}^\top \mathbf{M}(G, \varphi)^2 \mathbf{u}.$$

Observe that the quantity $\mathbf{u}^\top \mathbf{M}(G, \varphi) \mathbf{u}$ is the *walk generating function* $N_G(\varphi)$ of G that we de-

⁴¹Note that there exists a relationship between the matrix $\mathbf{M}(G, \varphi)$ with elements $m_{ij}(G, \varphi)$ and the length of the shortest path ℓ_{ij} between nodes i and j in the network G , which have been used e.g. in [Bala and Goyal \[2000\]](#); [Jackson and Wolinsky \[1996\]](#). Namely

$$\ell_{ij} = \lim_{\varphi \rightarrow 0} \frac{\partial \ln m_{ij}(G, \varphi)}{\partial \ln \varphi} = \lim_{\varphi \rightarrow 0} \frac{\varphi}{m_{ij}(G, \varphi)} \frac{\partial m_{ij}(G, \varphi)}{\partial \varphi}.$$

See also [Newman \[2010, Chap. 6\]](#). This means that the length of the shortest path between i and j is given by the relative %age change in the weighted number of walks between nodes i and j in G with respect to a relative %age change in φ in the limit of $\varphi \rightarrow 0$.

defined in detail in Appendix A.2. Using the results of Appendix A.2, we obtain:

$$\begin{aligned}
\mathbf{u}^\top \mathbf{M}(G, \varphi)^2 \mathbf{u} &= \mathbf{u}^\top \left(\sum_{k=0}^{\infty} \varphi^k \mathbf{A}^k \right)^2 \mathbf{u} \\
&= \mathbf{u}^\top \left(\sum_{k=0}^{\infty} \sum_{l=0}^k \varphi^l \mathbf{A}^l \varphi^{k-l} \mathbf{A}^{k-l} \right) \mathbf{u} \\
&= \sum_{k=0}^{\infty} (k+1) \varphi^k \mathbf{u}^\top \mathbf{A}^k \mathbf{u} \\
&= N_G(\varphi) + \sum_{k=0}^{\infty} k \varphi^k \mathbf{u}^\top \mathbf{A}^k \mathbf{u}.
\end{aligned}$$

Alternatively, we can write

$$\sum_{k=0}^{\infty} (k+1) \varphi^k \mathbf{u}^\top \mathbf{A}^k \mathbf{u} = \sum_{k=0}^{\infty} (k+1) N_k \varphi^k = \frac{d}{d\varphi} (\varphi N_G(\varphi)),$$

so that

$$\mathbf{u}^\top \mathbf{M}(G, \varphi)^2 \mathbf{u} = \frac{d}{d\varphi} (\varphi N_G(\varphi)) = N_G(\varphi) + \varphi \frac{d}{d\varphi} N_G(\varphi).$$

Using Rayleigh's inequality, one can show that [Van Mieghem, 2011, p. 51]

$$\frac{d}{d\varphi} (\varphi N_G(\varphi)) \geq \frac{1}{\lambda_1} \frac{d}{d\varphi} (N_G(\varphi)).$$

From this we can obtain a lower bound on welfare given by

$$W(G) \geq \mu^2 \frac{1}{\lambda_1} \frac{d}{d\varphi} (N_G(\varphi)).$$

Further, using the fact that

$$\begin{aligned}
\mathbf{u}^\top \mathbf{A}^k \mathbf{u} &= \sum_{i=1}^n (\mathbf{u}^\top \mathbf{v}_i)^2 \lambda_i^k, \\
N_G(\varphi) &= \sum_{i=1}^n \frac{(\mathbf{v}_i^\top \mathbf{u})^2}{1 - \lambda_i \varphi},
\end{aligned}$$

we can write

$$\begin{aligned}
\mathbf{u}^\top \mathbf{M}(G, \varphi)^2 \mathbf{u} &= \sum_{i=1}^n \frac{(\mathbf{v}_i^\top \mathbf{u})^2}{1 - \lambda_i \varphi} + \sum_{i=1}^n (\mathbf{u}^\top \mathbf{v}_i)^2 \sum_{k=0}^{\infty} k \varphi^k \lambda_i^k \\
&= \sum_{i=1}^n \frac{(\mathbf{v}_i^\top \mathbf{u})^2}{1 - \lambda_i \varphi} + \sum_{i=1}^n \frac{(\mathbf{u}^\top \mathbf{v}_i)^2 \varphi \lambda_i}{(1 - \varphi \lambda_i)^2} \\
&= \sum_{i=1}^n \frac{(\mathbf{u}^\top \mathbf{v}_i)^2}{1 - \varphi \lambda_i} \left(1 + \frac{\varphi \lambda_i}{1 - \varphi \lambda_i} \right) \\
&= \sum_{i=1}^n \frac{(\mathbf{u}^\top \mathbf{v}_i)^2}{(1 - \varphi \lambda_i)^2}.
\end{aligned}$$

From the above it follows that welfare can also be written as

$$W(G) = \mu^2 \frac{d}{d\varphi} (\varphi N_G(\varphi)) = \mu^2 \sum_{i=1}^n \frac{(\mathbf{u}^\top \mathbf{v}_i)^2}{(1 - \varphi \lambda_i)^2}.$$

This expression shows that gross welfare is highest in the graph where λ_1 approaches $1/\varphi$. Since, in the k -regular graph G_k it holds that $N_G(\varphi) = \frac{n}{1-k\varphi}$ and $\frac{d}{d\varphi}(\varphi N_G(\varphi)) = N_G(\varphi) + \varphi \frac{d}{d\varphi} N_G(\varphi) = \frac{n}{1-k\varphi} + \frac{nk\varphi}{(1-k\varphi)^2} = \frac{n}{1-k\varphi} \left(1 + \frac{k\varphi}{1-k\varphi} \right) = \frac{n}{(1-k\varphi)^2}$, which gives us a lower bound on welfare in the efficient graph $\frac{n}{(1-\frac{2m}{n}\varphi)^2} \leq W(G^*)$, where we have used the fact that the number of links in a k -regular graph is given by $m = \frac{nk}{2}$.

In order to derive an upper bound, observe that

$$\mathbf{u}^\top \mathbf{M}(G, \varphi)^2 \mathbf{u} = \sum_{i=1}^n \frac{(\mathbf{u}^\top \mathbf{v}_i)^2}{(1 - \varphi \lambda_i)^2},$$

and we can write welfare as follows

$$\begin{aligned}
W(G) &= \mu^2 \sum_{i=1}^n \frac{(\mathbf{u}^\top \mathbf{v}_i)^2}{(1 - \varphi \lambda_i)^2} \\
&\leq \mu^2 \frac{\sum_{i=1}^n (\mathbf{u}^\top \mathbf{v}_i)^2}{(1 - \varphi \lambda_1)^2} \\
&\leq \mu^2 \frac{n}{(1 - \varphi \lambda_1)^2},
\end{aligned}$$

where we have used the fact that $N_G(0) = \sum_{i=1}^n (\mathbf{u}^\top \mathbf{v}_i)^2 = n$ so that $(\mathbf{u}^\top \mathbf{v}_1)^2 < n$. Moreover, the largest eigenvalue in a graph G with m links and n nodes is bounded from above by $\lambda_1 \leq \sqrt{\frac{2m(n-1)}{n}} \leq n-1$.⁴² This gives us an upper bound on welfare according to

$$W(G^*) \leq \mu^2 \frac{n}{\left(1 - \varphi \sqrt{2m(n-1)/n} \right)^2},$$

⁴²If we assume that G is connected then we can also use the bound $\lambda_1 \leq \sqrt{2m - n + 1} \leq n - 1$.

which completes part (ii) of the proposition. Part (iii) follows immediately, if the number of links m can be chosen freely, because the largest eigenvalue λ_1 is upper bounded by the largest eigenvalue of the complete graph K_n , which is the $(n-1)$ -regular graph. In this case, upper and lower bounds coincide, and the efficient graph is therefore complete, that is $K_n = \operatorname{argmax}_{G \in \mathcal{G}(n)} W(G)$.

Finally, a similar calculation as in part (ii) shows that

$$\boldsymbol{\mu}^\top \mathbf{M} \boldsymbol{\mu} = \sum_{i=1}^n \frac{(\boldsymbol{\mu}^\top \mathbf{v}_i)^2}{1 - \phi \lambda_i},$$

and similarly

$$\boldsymbol{\mu}^\top \mathbf{M}^2 \boldsymbol{\mu} = \sum_{i=1}^n \frac{(\boldsymbol{\mu}^\top \mathbf{v}_i)^2}{(1 - \phi \lambda_i)^2},$$

so that welfare can be written as

$$W(G) = \boldsymbol{\mu}^2 \boldsymbol{\mu}^\top \mathbf{M}^2 \boldsymbol{\mu} = \boldsymbol{\mu}^2 \sum_{i=1}^n \frac{(\boldsymbol{\mu}^\top \mathbf{v}_i)^2}{(1 - \phi \lambda_i)^2},$$

which completes part (i) of the proposition. \square

Proof of Proposition 3. In the case of imperfectly substitutable goods, welfare can be written as

$$W(G) = \frac{2}{2} \mathbf{q}^\top \mathbf{q} + \frac{\rho}{2} \mathbf{q}^\top \mathbf{B} \mathbf{q}.$$

Further, denoting by $\mathbf{M} = (\mathbf{I}_n + \rho \mathbf{B} - \phi \mathbf{A})^{-1}$ we can write equilibrium output as $\mathbf{q} = \mathbf{M} \boldsymbol{\mu}$, and welfare can be written as

$$W(G) = \boldsymbol{\mu}^\top \mathbf{M}^2 \boldsymbol{\mu} + \frac{\rho}{2} \boldsymbol{\mu}^\top \mathbf{M} \mathbf{B} \mathbf{M} \boldsymbol{\mu}.$$

Observe that $\mathbf{M} = (\mathbf{I}_n - \phi \mathbf{C})^{-1}$, where we have denoted by $\mathbf{C} = \mathbf{A} - \frac{\rho}{\phi} \mathbf{B}$, so that we can write $\mathbf{M} = \sum_{k=0}^{\infty} \phi^k \mathbf{C}^k$. Let $\{v_i\}_{i=1}^n$ be the eigenvalues of \mathbf{C} and \mathbf{v}_i the associated eigenvectors. Further, let $\Lambda = \operatorname{diag}\{v_1, \dots, v_n\}$ and \mathbf{S} the matrix whose columns are the eigenvectors \mathbf{v}_i . Then we have that $\mathbf{C} = \mathbf{S} \Lambda \mathbf{S}^\top$, and we can write $\mathbf{M} = \sum_{k=0}^{\infty} \phi^k \mathbf{S} \Lambda^k \mathbf{S}^\top$. From this one can show that

$$\boldsymbol{\mu}^\top \mathbf{M} \boldsymbol{\mu} = \sum_{i=1}^n \frac{(\boldsymbol{\mu}^\top \mathbf{v}_i)^2}{1 - \phi v_i},$$

and similarly

$$\boldsymbol{\mu}^\top \mathbf{M}^2 \boldsymbol{\mu} = \sum_{i=1}^n \frac{(\boldsymbol{\mu}^\top \mathbf{v}_i)^2}{(1 - \phi v_i)^2}.$$

Moreover, we have that

$$\begin{aligned}
\boldsymbol{\mu}^\top \mathbf{M} \mathbf{B} \mathbf{M} \boldsymbol{\mu} &= \boldsymbol{\mu}^\top \mathbf{M} \sum_{m=1}^M \left(\mathbf{u}_m \mathbf{u}_m^\top - \mathbf{D}_m \right) \mathbf{M} \boldsymbol{\mu} \\
&= \sum_{m=1}^M (\boldsymbol{\mu}^\top \mathbf{M} \mathbf{u}_m) (\mathbf{u}_m^\top \mathbf{M} \boldsymbol{\mu}) - \boldsymbol{\mu}^\top \mathbf{M} \boldsymbol{\mu} \\
&= \sum_{m=1}^M \left(\sum_{i=1}^n \frac{(\boldsymbol{\mu}^\top \mathbf{v}_i) (\mathbf{u}_m^\top \mathbf{v}_i)}{1 - \varphi v_i} \right)^2 - \sum_{i=1}^n \frac{(\boldsymbol{\mu}^\top \mathbf{v}_i)^2}{(1 - \varphi v_i)^2} \\
&= \left(\sum_{i=1}^n \frac{(\boldsymbol{\mu}^\top \mathbf{v}_i) (\mathbf{v}_i^\top \mathbf{B} \mathbf{v}_i)}{1 - \varphi v_i} \right)^2 - \sum_{i=1}^n \frac{(\boldsymbol{\mu}^\top \mathbf{v}_i)^2}{(1 - \varphi v_i)^2}.
\end{aligned}$$

It then follows that welfare can be written as

$$W(G) = \frac{2-\rho}{2} \sum_{i=1}^n \frac{\boldsymbol{\mu}^\top \mathbf{v}_i}{1 - \varphi v_i} \left(\frac{\boldsymbol{\mu}^\top \mathbf{v}_i}{1 - \varphi v_i} \left(1 + \frac{\rho}{2-\rho} \mathbf{v}_i^\top \mathbf{B} \mathbf{v}_i \right) + \frac{\rho}{2-\rho} \sum_{j \neq i}^n \frac{(\boldsymbol{\mu}^\top \mathbf{v}_i) (\mathbf{v}_i^\top \mathbf{B} \mathbf{v}_j)}{1 - \varphi v_i} \right).$$

□

Proof of Proposition 4. Let us start with part (i) of the proposition. Assuming that $\mu_i = \mu$ for all $i = 1, \dots, n$, we have that

$$\mathbf{q} = \frac{\mu}{1 + \rho(\mathbf{u}^\top \mathbf{M}(G, \phi) \mathbf{u} - 1)} \mathbf{M}(G, \phi) \mathbf{u},$$

with $\mathbf{M}(G, \phi) \equiv (\mathbf{I}_n - \phi \mathbf{A})^{-1}$, and we can write

$$W(G) = \frac{2-\rho}{2} \frac{\mu^2}{(1 + \rho(\mathbf{u}^\top \mathbf{M}(G, \phi) \mathbf{u} - 1))^2} \left(\mathbf{u}^\top \mathbf{M}(G, \phi)^2 \mathbf{u} + \frac{\rho}{2-\rho} (\mathbf{u}^\top \mathbf{M}(G, \phi) \mathbf{u})^2 \right).$$

Using the fact that $\mathbf{u}^\top \mathbf{M}(G, \phi) \mathbf{u} = N_G(\phi)$ and $\mathbf{u}^\top \mathbf{M}(G, \phi)^2 \mathbf{u} = \frac{d}{d\phi} (\phi N_G(\phi))$, we then can write welfare in terms of the walk generating function $N_G(\phi)$ as

$$W(G) = \frac{2-\rho}{2} \frac{\mu^2}{(1 + \rho(N_G(\phi) - 1))^2} \left(\frac{d}{d\phi} (\phi N_G(\phi)) + \frac{\rho}{2-\rho} N_G(\phi)^2 \right).$$

Next, observe that

$$N_G(\phi) = N_0 + N_1 \phi + N_2 \phi^2 + O(\phi^3),$$

and consequently

$$\frac{d}{d\phi} (\phi N_G(\phi)) = N_0 + 2N_1 \phi + 3N_2 \phi^2 + O(\phi^3).$$

Inserting into welfare gives

$$\begin{aligned}
W(G) &= \frac{\mu^2(-\rho + N_0\rho + 2)}{2N_0(1 - \rho + N_0\rho)^2} - \frac{N_1\mu^2\rho(-\rho + N_0\rho + 2)}{N_0(1 - \rho + N_0\rho)^3}\phi \\
&\quad + \frac{1}{2}\mu^2(-\rho + 2) \left(\frac{-N_1^2 + N_0N_2}{N_0^3(1 - \rho + N_0\rho)^2} + \left(\frac{3N_1^2\rho^2}{(1 - \rho + N_0\rho)^4} - \frac{2N_2\rho}{(1 - \rho + N_0\rho)^3} \right) \left(\frac{1}{N_0} + \frac{\rho}{-\rho + 2} \right) \right) \phi^2 \\
&\quad + O(\phi)^3.
\end{aligned}$$

Using the fact that

$$\begin{aligned}
N_0 &= n, \\
N_1 &= 2m = n\bar{d}, \\
N_2 &= \mathbf{d}^\top \mathbf{d} = n(\bar{d}^2 + \sigma_d^2),
\end{aligned}$$

we get

$$\begin{aligned}
W(G) &= \frac{\mu^2(-\rho + n\rho + 2)}{2n(1 - \rho + n\rho)^2} - \frac{2(m\mu^2\rho(-\rho + n\rho + 2))}{n(1 - \rho + n\rho)^3}\phi \\
&\quad + \frac{1}{2}\mu^2(-\rho + 2) \left(\frac{-4m^2 + 2mn + n^2\sigma^2}{n^3(1 - \rho + n\rho)^2} + \left(\frac{12m^2\rho^2}{(1 - \rho + n\rho)^4} \right. \right. \\
&\quad \left. \left. - \frac{4m\rho}{(1 - \rho + n\rho)^3} - \frac{2n\rho\sigma^2}{(1 - \rho + n\rho)^3} \right) \left(\frac{1}{n} + \frac{\rho}{-\rho + 2} \right) \right) \phi^2 \\
&\quad + O(\phi)^3.
\end{aligned}$$

Taking the derivative with respect to σ_d^2 yields

$$\frac{\partial W(G)}{\partial \sigma_d^2} = \frac{\mu^2\phi^2((-1 + (1 + n - 2n^2)\rho)\rho + 2 - (1 + n)\rho^2)}{2n(1 + (-1 + n)\rho)^3} + O(\phi)^3,$$

and in the limit of large n we obtain

$$\lim_{n \rightarrow \infty} n^2 \frac{\partial W(G)}{\partial \sigma_d^2} = -\frac{\mu^2\rho\phi^2}{\rho^2} + O(\phi)^3,$$

which is negative, indicating that welfare is decreasing in the degree variance σ_d^2 for large n up to the second order of ϕ .

Let us now deal with part (ii) of the proposition. Up to the third order in ϕ we have that

$$N_G(\phi) = N_0 + N_1\phi + N_2\phi^2 + N_3\phi^3 + O(\phi^4),$$

and consequently

$$\frac{d}{d\phi} (\phi N_G(\phi)) = N_0 + 2N_1\phi + 3N_2\phi^2 + 4N_3\phi^3 + O(\phi^4).$$

Inserting into welfare gives and using the fact that

$$\begin{aligned} N_0 &= n, \\ N_1 &= 2m = n\bar{d}, \\ N_2 &= \mathbf{d}^\top \mathbf{d} = n(\bar{d}^2 + \sigma_d^2), \end{aligned}$$

we get

$$\begin{aligned} W(G) &= \frac{\mu^2(-\rho + n\rho + 2)}{2n(1 - \rho + n\rho)^2} - \frac{2(m\mu^2\rho(-\rho + n\rho + 2))}{n(1 - \rho + n\rho)^3}\phi \\ &\quad + \frac{1}{2}\mu^2(-\rho + 2) \left(\frac{-4m^2 + 2mn + n^2\sigma^2}{n^3(1 - \rho + n\rho)^2} + \left(\frac{12m^2\rho^2}{(1 - \rho + n\rho)^4} \right. \right. \\ &\quad \left. \left. - \frac{4m\rho}{(1 - \rho + n\rho)^3} - \frac{2n\rho\sigma^2}{(1 - \rho + n\rho)^3} \right) \left(\frac{1}{n} + \frac{\rho}{-\rho + 2} \right) \right) \phi^2 \\ &\quad + \frac{1}{2}\mu^2(-\rho + 2) \left(-\frac{4m\rho(-4m^2 + 2mn + n^2\sigma^2)}{n^3(1 - \rho + n\rho)^3} + \frac{2(8m^3 - 8m^2n + n^2N_3 - 4mn^2\sigma^2)}{n^4(1 - \rho + n\rho)^2} \right. \\ &\quad \left. + \left(-\frac{32m^3\rho^3}{(1 - \rho + n\rho)^5} + \frac{24m^2\rho^2}{(1 - \rho + n\rho)^4} - \frac{2N_3\rho}{(1 - \rho + n\rho)^3} + \frac{12mn\rho^2\sigma^2}{(1 - \rho + n\rho)^4} \right) \left(\frac{1}{n} + \frac{\rho}{-\rho + 2} \right) \right) \phi^3 \\ &\quad + O(\phi)^4. \end{aligned}$$

Taking the derivative with respect to N_3 yields

$$\frac{\partial W(G)}{\partial N_3} = -\frac{\mu^2\phi^3((1 + (-1 + n^2)\rho)\rho + (-1 + \rho)2)}{n^2(1 + (-1 + n)\rho)^3} + O(\phi)^4,$$

and in the limit of large n we obtain

$$\lim_{n \rightarrow \infty} n^3 \frac{\partial W(G)}{\partial N_3} = -\frac{\mu^2\rho\phi^3}{\rho^2} + O(\phi)^4.$$

It follows that welfare in the limit of large n is decreasing in N_3 . We have that [Van Mieghem, 2011, p. 183]

$$\begin{aligned} N_3 &= \sum_{i=1}^n d_i^3 - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n a_{ij}(d_i - d_j)^2 \\ &= \frac{N_2^2}{N_1} + \rho_d(G) \underbrace{\left(\sum_{i=1}^n d_i^3 - \frac{N_2^2}{N_1} \right)}_{\geq 0}, \end{aligned}$$

where $\rho_d(G)$ is the degree assortativity coefficient of G [Newman, 2003]. Since welfare is decreasing in N_3 , and N_3 is increasing in the assortativity $\rho_d(G)$, we have that welfare in the limit of large n is decreasing in $\rho_d(G)$.

We now deal with part (iii) of the proposition. We first provide a lower bound on welfare

in the efficient graph G^* by considering the complete graph K_n . Welfare can be written as

$$W(G) = \frac{2-\rho}{2} \frac{\mu^2}{\rho^2} \frac{\mathbf{u}^\top \mathbf{M}^2 \mathbf{u} + \frac{\rho}{2-\rho} (\mathbf{u}^\top \mathbf{M} \mathbf{u})^2}{\left(\frac{1-\rho}{\rho} + \mathbf{u}^\top \mathbf{M} \mathbf{u} \right)^2}.$$

For the complete graph K_n we have that

$$\begin{aligned} \mathbf{u}^\top \mathbf{M} \mathbf{u} &= \frac{n}{1 - (n-1)\phi}, \\ \mathbf{u}^\top \mathbf{M}^2 \mathbf{u} &= \frac{n}{(1 - (n-1)\phi)^2}, \end{aligned}$$

so that we obtain for welfare in the complete graph

$$W(K_n) = \frac{\mu^2}{2} \frac{n((n-1)\rho + 2)}{(\rho((n-1)\phi + n - 1) - k\phi + 1)^2}.$$

Using the fact that $\phi = \frac{\varphi}{1-\rho}$ this can be written as

$$W(K_n) = \frac{\mu^2}{2} \frac{n((n-1)\rho + 2)}{((n-1)(\rho - \varphi) + 1)^2}.$$

This gives us the lower bound on welfare in part (iii) of the proposition. To obtain an upper bound, note that welfare can be written as

$$W(G) = \frac{2-\rho}{2} \frac{\mu^2}{\rho^2} \frac{\frac{\mathbf{u}^\top \mathbf{M}^2 \mathbf{u}}{(\mathbf{u}^\top \mathbf{M} \mathbf{u})^2} + \frac{\rho}{2-\rho}}{\frac{\left(\frac{1-\rho}{\rho} + \mathbf{u}^\top \mathbf{M} \mathbf{u} \right)^2}{(\mathbf{u}^\top \mathbf{M} \mathbf{u})^2}}.$$

Next, observe that

$$\frac{\left(\frac{1-\rho}{\rho} + \mathbf{u}^\top \mathbf{M} \mathbf{u} \right)^2}{(\mathbf{u}^\top \mathbf{M} \mathbf{u})^2} = 1 + \frac{2(1-\rho)}{\rho} \frac{1}{\mathbf{u}^\top \mathbf{M} \mathbf{u}} + \frac{1-\rho}{\rho} \frac{1}{(\mathbf{u}^\top \mathbf{M} \mathbf{u})^2} \geq 1,$$

if $\rho \leq 1$. This implies that

$$W(G) \leq \frac{2-\rho}{2} \frac{\mu^2}{\rho^2} \left(\frac{\mathbf{u}^\top \mathbf{M}^2 \mathbf{u}}{(\mathbf{u}^\top \mathbf{M} \mathbf{u})^2} + \frac{\rho}{2-\rho} \right).$$

Moreover, we have that⁴³

$$\begin{aligned}
\frac{\mathbf{u}^\top \mathbf{M}^2 \mathbf{u}}{(\mathbf{u}^\top \mathbf{M} \mathbf{u})^2} &= \frac{\frac{d}{d\phi} (\phi N_G(\phi))}{N_G(\phi)^2} \\
&= \frac{\sum_{i=1}^n \frac{(\mathbf{u}^\top \mathbf{v}_i)^2}{(1-\phi\lambda_i)^2}}{\left(\sum_{i=1}^n \frac{(\mathbf{u}^\top \mathbf{v}_i)^2}{1-\phi\lambda_i}\right)^2} \\
&\leq \frac{\frac{1}{1-\phi\lambda_1} \sum_{i=1}^n \frac{(\mathbf{u}^\top \mathbf{v}_i)^2}{1-\phi\lambda_i}}{\left(\sum_{i=1}^n \frac{(\mathbf{u}^\top \mathbf{v}_i)^2}{1-\phi\lambda_i}\right)^2} \\
&= \frac{1}{(1-\phi\lambda_1)N_G(\phi)} \\
&\leq \frac{1}{n(1-\phi\lambda_1)},
\end{aligned}$$

where we have used the fact that $N_G(\phi) \geq N_G(0) = N_0 = n$. Hence, we obtain an upper bound on welfare in the efficient graph G^* for large n given by

$$W(G^*) \leq \frac{2-\rho}{2} \frac{\mu^2}{\rho^2} \left(\frac{1}{n(1-\phi\lambda_1)} + \frac{\rho}{2-\rho} \right).$$

Using the upper bound $\lambda_1 \leq \max\{\sqrt{2m(n-1)/n}, \Delta\}$, where $\Delta \equiv \max_{i=1,\dots,n} d_i$, we get

$$W(G^*) \leq \frac{2-\rho}{2} \frac{\mu^2}{\rho^2} \left(\frac{\rho}{2-\rho} + \frac{1}{n(1-\phi(\max\{\sqrt{2m(n-1)/n}, \Delta\}))} \right).$$

This allows us to state an upper and lower bound (from the explicit solution for welfare in the complete graph K_n) for the efficient graph $G^* = \operatorname{argmax}_{G \in \mathcal{H}(n,m)} W(G)$.

In the following let us denote by \overline{W} the upper bound on welfare in part (iii) of the proposition. Then, for part (iv) of the proposition, note that in the limit of large n the upper bound \overline{W} converges to

$$\lim_{n \rightarrow \infty} \overline{W} = \frac{\rho\mu^2}{2\rho^2},$$

⁴³Let $\mathbf{x} \equiv \mathbf{M}\mathbf{u}$, then we can write

$$\frac{\mathbf{u}^\top \mathbf{M}^2 \mathbf{u}}{(\mathbf{u}^\top \mathbf{M} \mathbf{u})^2} = \frac{\|\mathbf{x}\|_2^2}{\|\mathbf{x}\|_1^2} = \frac{\sum_{i=1}^n x_i^2}{(\sum_{i=1}^n |x_i|)^2} = \pi(\mathbf{x})^{-1},$$

which is the inverse of the *participation ratio* $\pi(\mathbf{x})$. The participation ratio $\pi(\mathbf{x})$ measures the number of elements of \mathbf{x} which are dominant. We have that $1 \leq \pi(\mathbf{x}) \leq n$, where a value of $\pi(\mathbf{x}) = n$ corresponds to a fully homogenous case, while $\pi(\mathbf{x}) = 1$ corresponds to a fully concentrated case (note that, if all x_i are identical then $\pi(\mathbf{x}) = n$, while if one x_i is much larger than all others we have $\pi(\mathbf{x}) = 1$). Moreover, $\pi(\mathbf{x})$ is scale invariant, that is, $\pi(\phi\mathbf{x}) = \pi(\mathbf{x})$ for any $\phi \in \mathbb{R}_+$.

while for the complete graph we get

$$\lim_{n \rightarrow \infty} W(K_n) = \frac{\mu^2}{2} \frac{\rho}{(\varphi - \rho)^2}.$$

Hence, we have that

$$\lim_{n \rightarrow \infty} \frac{W(K_n)}{\bar{W}} = \frac{\rho^2}{(\varphi - \rho)^2}.$$

Hence, we get

$$\lim_{\varphi \rightarrow 0} \lim_{n \rightarrow \infty} \frac{W(K_n)}{\bar{W}} = 1,$$

which proves part (iv) of the proposition. \square

Proof of Proposition 5. (i) In the case of independent markets ($\rho = 0$), the welfare can be written as

$$W(G) = \mathbf{q}^\top \mathbf{q} = \boldsymbol{\mu}^\top \mathbf{M}(G, \phi)^2 \boldsymbol{\mu},$$

where $\mathbf{M}(G, \phi) = (\mathbf{I}_n - \phi \mathbf{A})^{-1}$. Using the fact that (see the proof of Proposition 2):

$$\boldsymbol{\mu}^\top \mathbf{M}(G, \phi)^2 \boldsymbol{\mu} = \frac{d}{d\phi} (\phi N_G(\phi)) = \boldsymbol{\mu}^\top \frac{d}{d\phi} (\phi \mathbf{M}(G, \phi)) \boldsymbol{\mu},$$

welfare can be written as

$$W(G) = \boldsymbol{\mu}^\top \frac{d}{d\phi} (\phi \mathbf{M}(G, \phi)) \boldsymbol{\mu},$$

we can write the change in welfare due to the exit of firm i as follows

$$\begin{aligned} W(G) - W(G^{-i}, \phi) &= \left(\boldsymbol{\mu}^\top \mathbf{M}(G, \phi)^2 \boldsymbol{\mu} - \boldsymbol{\mu}^\top \mathbf{M}(G^{-i}, \phi)^2 \boldsymbol{\mu} \right) \\ &= \left(\frac{d}{d\phi} \phi \left(\boldsymbol{\mu}^\top \mathbf{M}(G, \phi) \boldsymbol{\mu} - \boldsymbol{\mu}^\top \mathbf{M}(G^{-i}, \phi) \boldsymbol{\mu} \right) \right). \end{aligned}$$

Denoting by

$$\Delta_i(G, \phi) \equiv \boldsymbol{\mu}^\top \mathbf{M}(G, \phi) \boldsymbol{\mu} - \boldsymbol{\mu}^\top \mathbf{M}(G^{-i}, \phi) \boldsymbol{\mu},$$

we can write the change in welfare as follows

$$W(G) - W(G^{-i}, \phi) = \left(\frac{d}{d\phi} \phi (\Delta_i(G, \phi)) \right).$$

We next turn to the analysis of the quantity $\Delta_i(G, \phi)$. We first make the following observation (see Lemma 1 in [Ballester et al. \[2006\]](#))

$$m_{jk}(G^{-i}, \phi) = m_{jk}(G, \phi) - \frac{m_{ij}(G, \phi)m_{ik}(G, \phi)}{m_{ii}(G, \phi)}.$$

We then can write

$$\begin{aligned}
\boldsymbol{\mu}^\top \mathbf{M}(G^{-i}, \phi) \boldsymbol{\mu} &= \sum_{j,k} \mu_j m_{jk}(G^{-i}, \phi) \mu_k \\
&= \boldsymbol{\mu}^\top \mathbf{M}(G, \phi) \boldsymbol{\mu} - \frac{\sum_{j,k} \mu_j m_{ij}(G, \phi) m_{ik}(G, \phi) \mu_k}{m_{ii}(G, \phi)} \\
&= \boldsymbol{\mu}^\top \mathbf{M}(G, \phi) \boldsymbol{\mu} - \frac{b_{\boldsymbol{\mu},i}(G, \phi)^2}{m_{ii}(G, \phi)},
\end{aligned}$$

and we obtain

$$\Delta_i(G, \phi) = \frac{b_{\boldsymbol{\mu},i}(G, \phi)^2}{m_{ii}(G, \phi)}.$$

We then define the centrality measure

$$c_i \equiv \frac{1}{2} \frac{d}{d\phi} (\phi \Delta_i(G, \phi)) = \frac{1}{2} \frac{d}{d\phi} \left(\frac{\phi b_{\boldsymbol{\mu},i}(G, \phi)^2}{m_{ii}(G, \phi)} \right). \quad (49)$$

The centrality c_i corresponds to the welfare loss incurred from to the removal of firm i . Observe that

$$m_{ii}(G, \phi) = N_G(\phi, i) \equiv \sum_{k=0}^{\infty} a_{ii}^{[k]} \phi^k,$$

is the generating function of the number of closed walks that start and terminate at node i . It can be written as [Van Mieghem, 2011]

$$N_G(\phi, i) = \sum_{k=1}^n \frac{(\mathbf{v}_k \mathbf{v}_k^\top)_{ii}}{1 - \lambda_k \phi} = - \frac{c_{\mathbf{A}^{-i}} \left(\frac{1}{\phi} \right)}{\phi c_{\mathbf{A}} \left(\frac{1}{\phi} \right)},$$

where $c_{\mathbf{A}}(\phi) \equiv \det(\mathbf{A} - \phi \mathbf{I}_n)$ is the characteristic polynomial of the matrix \mathbf{A} , and \mathbf{A}^{-i} is the matrix obtained from \mathbf{A} by removing the i -th column and row. We can then write the centrality index as follows.

$$c_i = \frac{1}{2} \frac{d}{d\phi} \left(\frac{\phi b_{\boldsymbol{\mu},i}(G, \phi)^2}{N_G(\phi, i)} \right). \quad (50)$$

This shows that the centrality index $\mathbf{c}(G, \phi)$ is determined by the Bonacich centrality

$b_i(G, \phi)$ of firm i and the walk generating function $N_G(\phi, i)$. Further note that⁴⁴

$$\begin{aligned}
\frac{d}{d\phi} \left(\frac{\phi b_{\mu,i}(G, \phi)^2}{N_G(\phi, i)} \right) &= \frac{b_{\mu,i}(G, \phi)^2}{N_G(\phi, i)} + \frac{\phi b_{\mu,i}(G, \phi)}{N_G(\phi, i)} [2(\mathbf{M}(G, \phi) \mathbf{A} \mathbf{b}_{\mu}(G, \phi))_i \\
&\quad - \frac{b_{\mu,i}(G, \phi)}{N_G(\phi, i)} (\mathbf{M}(G, \phi) \mathbf{A} \mathbf{M}(G, \phi))_{ii}] \\
&= \frac{b_{\mu,i}(G, \phi)}{N_G(\phi, i)} \left[2(\mathbf{M}(G, \phi) \mathbf{b}_{\mu}(G, \phi))_i - \frac{b_{\mu,i}(G, \phi)}{N_G(\phi, i)} (\mathbf{M}(G, \phi)^2)_{ii} \right] \\
&= \boldsymbol{\mu}^\top \mathbf{M}(G, \phi) \boldsymbol{\mu} - \boldsymbol{\mu}^\top \mathbf{M}(G^{-i}, \phi) \boldsymbol{\mu} \\
&= \Delta_i(G, \phi).
\end{aligned} \tag{51}$$

We then can write the centrality as follows

$$c_i = \frac{b_{\mu,i}(G, \phi)}{N_G(\phi, i)} \left[(\mathbf{M}(G, \phi) \mathbf{b}_{\mu}(G, \phi))_i - \frac{1}{2} \frac{b_{\mu,i}(G, \phi)}{N_G(\phi, i)} (\mathbf{M}(G, \phi)^2)_{ii} \right].$$

(ii) Welfare for $\rho > 0$ is given by

$$W(G) = \frac{1}{2} \sum_{i=1}^n q_i^2 + \frac{\rho}{2} \sum_{i=1}^n \sum_{j=1}^n b_{ij} q_i q_j + \sum_{i=1}^n \pi_i.$$

Using the fact that $\pi_i = \frac{1}{2} q_i^2$, we obtain for welfare

$$W(G) = \sum_{i=1}^n q_i^2 + \frac{\rho}{2} \sum_{i=1}^n \sum_{j=1}^n b_{ij} q_i q_j.$$

In vector-matrix notation this can be written as

$$W(G) = \mathbf{q}^\top(G) \mathbf{q}(G) + \frac{\rho}{2} \mathbf{q}^\top(G) \mathbf{B} \mathbf{q}(G).$$

We denote by G^{-i} the network obtained from G by removing firm i . Applying Lemma 1 in [Ballester et al. \[2006\]](#) to the weighted symmetric matrix $\mathbf{M}(G, \rho, \varphi)$, we get

$$m_{jk}(G^{-i}, \rho, \varphi) = m_{jk}(G, \rho, \varphi) - \frac{m_{ij}(G, \rho, \varphi) m_{ik}(G, \rho, \varphi)}{m_{ii}(G, \rho, \varphi)}$$

For equilibrium output we have that $\mathbf{q} = \mathbf{b}_{\mu} = \mathbf{M} \boldsymbol{\mu}$, so that we obtain for the output of

⁴⁴We have used the fact that $\frac{d\mathbf{M}(G, \phi)}{d\phi} = \mathbf{M}(G, \phi) \mathbf{A} \mathbf{M}(G, \phi)$, which follows from $\frac{d\mathbf{X}^{-1}}{d\phi} = -\mathbf{X}^{-1} \frac{d\mathbf{X}}{d\phi} \mathbf{X}^{-1}$ for any invertible matrix \mathbf{X} .

firm j after the removal of firm i

$$\begin{aligned}
q_j(G^{-i}) &= \sum_{l=1}^{n-1} m_{jl}(G^{-i}) \mu_l^{-i}(G) \\
&= \sum_{l=1}^{n-1} \left(m_{jl}(G) - \frac{m_{ij}(G)m_{il}(G)}{m_{ii}(G)} \right) \mu_l^{-i}(G) \\
&= \sum_{l=1}^n m_{jl}(G) \mu_l - \frac{m_{ij}(G)}{m_{ii}(G)} \sum_{l=1}^n m_{il}(G) \mu_l \\
&= (\mathbf{M}(G)\boldsymbol{\mu})_j - \frac{m_{ij}(G)b_{\boldsymbol{\mu},i}(G)}{m_{ii}(G)}.
\end{aligned}$$

Moreover, we have that

$$\sum_{j=1}^{n-1} q_j(G^{-i}) = \mathbf{u}^\top \mathbf{M}(G)\boldsymbol{\mu}(G) - \frac{b_{\mathbf{u},i}(G)b_{\boldsymbol{\mu},i}(G)}{m_{ii}(G)}$$

We then have that

$$\begin{aligned}
\mathbf{q}(G^{-i})^\top \mathbf{B}^{-i} \mathbf{q}(G^{-i}) &= \sum_{j,k=1}^n q_j(G^{-i}) b_{jk}^{-i} q_k(G^{-i}) \\
&= \sum_{j,k \neq i}^n b_{jk} \left(q_j(G) - \frac{m_{ij}(G)q_i(G)}{m_{ii}(G)} \right) \left(q_k(G) - \frac{m_{ik}(G)q_i(G)}{m_{ii}(G)} \right) \\
&= \sum_{j,k \neq i}^n b_{jk} q_j(G) q_k(G) - \frac{b_{\boldsymbol{\mu},i}(G)}{m_{ii}(G)} \sum_{j,k \neq i}^n b_{jk} (q_j(G)m_{ik}(G) + q_k(G)m_{ij}(G)) \\
&\quad + \frac{b_{\boldsymbol{\mu},i}(G)^2}{m_{ii}(G)^2} \sum_{j,k \neq i}^n b_{jk} m_{ij}(G) m_{ik}(G).
\end{aligned}$$

This can be simplified to

$$\mathbf{q}(G^{-i})^\top \mathbf{B}^{-i} \mathbf{q}(G^{-i}) = \mathbf{q}(G)^\top \mathbf{B} \mathbf{q}(G) - \frac{q_i(G)}{m_{ii}(G)} \left(2(\mathbf{M}(G)\mathbf{B}\mathbf{q}(G))_i - \frac{q_i(G)}{m_{ii}(G)} (\mathbf{M}(G)\mathbf{B}\mathbf{M}(G))_{ii} \right)$$

In the special case of $\mathbf{B} = \mathbf{I}_n$ this is

$$\mathbf{q}(G^{-i})^\top \mathbf{q}(G^{-i}) = \mathbf{q}(G)^\top \mathbf{q}(G) - \frac{q_i(G)}{m_{ii}(G)} \left(2(\mathbf{M}(G)\mathbf{q}(G))_i - \frac{q_i(G)}{m_{ii}(G)} (\mathbf{M}(G)^2)_{ii} \right).$$

We then obtain

$$\begin{aligned}
W(G) - W(G^{-i}) &= (\mathbf{q}^\top(G)\mathbf{q}(G) - \mathbf{q}^\top(G^{-i})\mathbf{q}(G^{-i})) + \frac{\rho}{2} (\mathbf{q}^\top(G)\mathbf{B}\mathbf{q}(G) - \mathbf{q}^\top(G^{-i})\mathbf{B}\mathbf{q}(G^{-i})) \\
&= \frac{q_i(G)}{m_{ii}(G)} \left((\mathbf{M}(G)(2\mathbf{I}_n + \rho\mathbf{B})\mathbf{q}(G))_i - \frac{1}{2} \frac{q_i(G)}{m_{ii}(G)} (\mathbf{M}(G)(2\mathbf{I}_n + \rho\mathbf{B})\mathbf{M}(G))_{ii} \right) \\
&= \frac{b_{\boldsymbol{\mu},i}(G)}{m_{ii}(G)} \left((\mathbf{M}(G)(2\mathbf{I}_n + \rho\mathbf{B})\mathbf{b}_{\boldsymbol{\mu}}(G))_i - \frac{1}{2} \frac{b_{\boldsymbol{\mu},i}(G)}{m_{ii}(G)} (\mathbf{M}(G)(2\mathbf{I}_n + \rho\mathbf{B})\mathbf{M}(G))_{ii} \right).
\end{aligned}$$

□

Proof of Proposition 6. (i) The FOC of profits in Equation (17) with respect to effort is

$$\frac{\partial \pi_i}{\partial e_i} = q_i - e_i + s = 0,$$

so that equilibrium effort is

$$e_i = q_i + s.$$

The FOC with respect to output is given by

$$\frac{\partial \pi_i}{\partial q_i} = (\bar{\alpha} - \bar{c}_i) - 2q_i - \rho \sum_{j \neq i} b_{ij} q_j + e_i + \varphi \sum_{j=1}^n a_{ij} e_j = 0.$$

Inserting equilibrium efforts, rearranging terms and introducing the reduced form variables of Equation (??) gives

$$q_i = \mu_i - \rho \sum_{j \neq i} b_{ij} q_j + \varphi \sum_{j=1}^n a_{ij} q_j + s + \varphi d_i s.$$

where $d_i = \sum_{j=1}^n a_{ij}$ is the degree (or total number of links) of firm i . In vector-matrix notation this is

$$(\mathbf{I}_n + \rho \mathbf{B} - \varphi \mathbf{A}) \mathbf{q} = \boldsymbol{\mu} + s \mathbf{u} + \varphi s \mathbf{A} \mathbf{u}.$$

We then can write equilibrium quantities as follows

$$\mathbf{q} = \bar{\mathbf{q}} + s \mathbf{r},$$

where we have denoted by

$$\begin{aligned} \bar{\mathbf{q}} &\equiv (\mathbf{I}_n + \rho \mathbf{B} - \varphi \mathbf{A})^{-1} \boldsymbol{\mu} = \mathbf{M} \boldsymbol{\mu} \\ \mathbf{r} &\equiv \varphi (\mathbf{I}_n + \rho \mathbf{B} - \varphi \mathbf{A})^{-1} \left(\frac{1}{\varphi} \mathbf{I}_n + \mathbf{A} \right) \mathbf{u} = \mathbf{M} \mathbf{u} + \varphi \mathbf{M} \mathbf{d}, \end{aligned}$$

where $\mathbf{M} = (\mathbf{I}_n + \rho \mathbf{B} - \varphi \mathbf{A})^{-1}$. The vector $\bar{\mathbf{q}}$ gives equilibrium quantities in the absence of the subsidy and is derived in Section 3. The vector \mathbf{r} has elements r_i for $i = 1, \dots, n$. Furthermore, equilibrium profits are given by

$$\pi_i = \frac{1}{2} q_i^2 + \frac{1}{2} s^2,$$

(ii) Net social welfare is given by

$$\bar{W}(G, s) = W(G, s) - s \sum_{i=1}^n e_i = \sum_{i=1}^n (q_i^2 + \pi_i - s e_i) = \sum_{i=1}^n q_i^2 - s \sum_{i=1}^n q_i - \frac{n}{2} s^2.$$

Using the fact that $q_i = \bar{q}_i + sr_i$, where

$$\begin{aligned}\bar{\mathbf{q}} &= (\mathbf{I}_n - \varphi \mathbf{A})^{-1} \boldsymbol{\mu} = \mathbf{M} \boldsymbol{\mu} \\ \mathbf{r} &= \varphi (\mathbf{I}_n - \varphi \mathbf{A})^{-1} \left(\frac{1}{\varphi} \mathbf{I}_n + \mathbf{A} \right) \mathbf{u} = \boldsymbol{\mu} + \varphi \mathbf{d},\end{aligned}$$

we can write net welfare as follows

$$\bar{W}(G, s) = \sum_{i=1}^n (\bar{q}_i + r_i s)^2 - \sum_{i=1}^n (\bar{q}_i + r_i s) - \frac{n}{2} s^2.$$

The FOC of net welfare $\bar{W}(G, s)$ is given by

$$\frac{\partial \bar{W}(G, s)}{\partial s} = 2 \sum_{i=1}^n \bar{q}_i (2r_i - 1) + s \sum_{i=1}^n (2r_i^2 - 2r_i - 1) = 0,$$

from which we obtain the optimal subsidy level

$$s^* = \frac{\sum_{i=1}^n \bar{q}_i (1 - 2r_i)}{\sum_{i=1}^n (r_i (2r_i - 2) - 1)},$$

where the equilibrium quantities are given by Equation (18). For the second-order derivative we obtain

$$\frac{\partial^2 \bar{W}(G, s)}{\partial s^2} = - \sum_{i=1}^n (-2r_i^2 + 2r_i + 1),$$

and we have an interior solution if the condition $\sum_{i=1}^n (-2r_i^2 + 2r_i + 1) \geq 0$ is satisfied.

(iii) Net welfare can be written as

$$\begin{aligned}\bar{W}(G, s) &= \frac{1}{2} \sum_{i=1}^n q_i^2 + \frac{\rho}{2} \sum_{i=1}^n \sum_{j \neq i}^n b_{ij} q_i q_j + \sum_{i=1}^n \pi_i - s \sum_{i=1}^n e_i \\ &= \sum_{i=1}^n q_i^2 + \frac{n}{2} s^2 + \frac{\rho}{2} \sum_{i=1}^n \sum_{j \neq i}^n b_{ij} q_i q_j - \sum_{i=1}^n (q_i + s) s.\end{aligned}$$

Using the fact that $q_i = \bar{q}_i + sr_i$, where

$$\begin{aligned}\bar{\mathbf{q}} &\equiv (\mathbf{I}_n + \rho \mathbf{B} - \varphi \mathbf{A})^{-1} \boldsymbol{\mu} \\ \mathbf{r} &\equiv \varphi (\mathbf{I}_n + \rho \mathbf{B} - \varphi \mathbf{A})^{-1} \left(\frac{1}{\varphi} \mathbf{I}_n + \mathbf{A} \right) \mathbf{u},\end{aligned}$$

we can write net welfare as follows

$$\bar{W}(G, s) = \sum_{i=1}^n (\bar{q}_i + r_i s)^2 - ns^2 + \frac{\rho}{2} \sum_{i=1}^n \sum_{j \neq i}^n b_{ij} (\bar{q}_i + sr_i) (\bar{q}_j + sr_j) - \sum_{i=1}^n (\bar{q}_i s + r_i s^2).$$

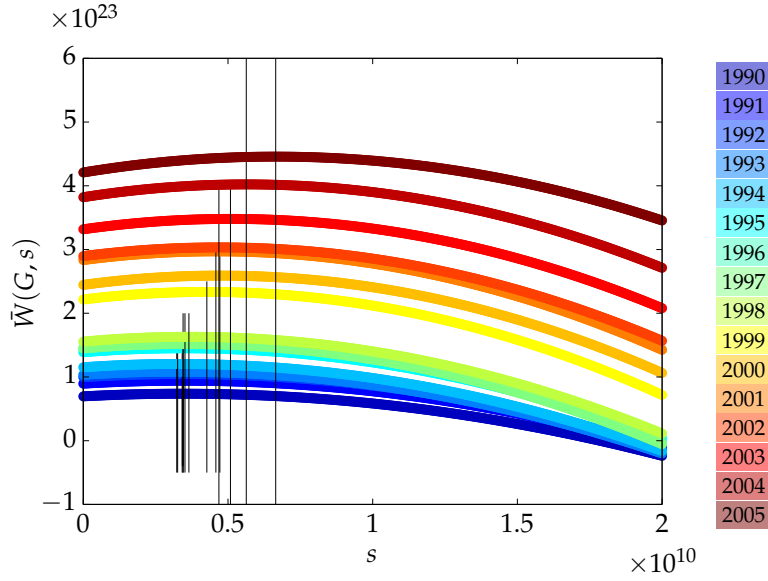


Figure E.1: The concave welfare function $\bar{W}(G, s)$ for different years and different subsidy levels s . The location of the maximum s^* for each year is indicated with a vertical line.

The FOC of net welfare $\bar{W}(G, s)$ is given by

$$\frac{\partial \bar{W}(G, s)}{\partial s} = \sum_{i=1}^n \left(2\bar{q}_i r_i - \bar{q}_i + \frac{\rho}{2} b_{ij} (\bar{q}_i r_j + \bar{q}_j r_i) \right) + s \sum_{i=1}^n \left(2r_i^2 - 2r_i - 1 + \rho \sum_{j=1}^n b_{ij} r_i r_j \right) = 0,$$

from which we obtain the optimal subsidy level

$$s^* = \frac{\sum_{i=1}^n \left(\bar{q}_i (2r_i + 1) + \frac{\rho}{2} \sum_{j=1}^n b_{ij} (\bar{q}_i r_j + \bar{q}_j r_i) \right)}{\sum_{i=1}^n \left(1 + r_i (2 - 2r_i - \rho \sum_{j=1}^n b_{ij} r_j) \right)},$$

where the equilibrium quantities are given by Equation (18). The second-order derivative is given by

$$\frac{\partial^2 \bar{W}(G, s)}{\partial s^2} = - \sum_{i=1}^n \left(-2r_i^2 + 2r_i + 1 - \rho \sum_{j=1}^n b_{ij} r_i r_j \right).$$

Hence, the solution is interior if $\sum_{i=1}^n \left(-2r_i^2 + 2r_i + 1 - \rho \sum_{j=1}^n b_{ij} r_i r_j \right) \geq 0$.

The concave welfare function $\bar{W}(G, s)$ for different years and different subsidy levels s is shown in Figure E.1. The location of the maximum s^* for each year is indicated with a vertical line.

□

Proof of Proposition 7. (i) The FOC of profits from Equation (20) with respect to effort is

$$\frac{\partial \pi_i}{\partial e_i} = q_i - e_i + s_i = 0,$$

so that equilibrium effort is

$$e_i = q_i + s_i.$$

The FOC with respect to output is given by

$$\frac{\partial \pi_i}{\partial q_i} = (\bar{a} - \bar{c}_i) - 2q_i - \rho \sum_{j \neq i} b_{ij} q_j + e_i + \varphi \sum_{j=1}^n a_{ij} e_j = 0.$$

Inserting equilibrium efforts together with the reduced form variables of Equation (??) and rearranging terms gives

$$q_i = \mu_i - \rho \sum_{j \neq i} b_{ij} q_j + \varphi \sum_{j=1}^n a_{ij} q_j + s_i + \varphi \sum_{j=1}^n a_{ij} s_j.$$

In vector-matrix notation this is

$$(\mathbf{I}_n + \rho \mathbf{B} - \varphi \mathbf{A}) \mathbf{q} = \boldsymbol{\mu} + \mathbf{s} + \varphi \mathbf{A} \mathbf{s}.$$

We then can write equilibrium quantities as follows

$$\mathbf{q} = \bar{\mathbf{q}} + \mathbf{R} \mathbf{s},$$

where we have denoted by

$$\begin{aligned} \bar{\mathbf{q}} &\equiv (\mathbf{I}_n + \rho \mathbf{B} - \varphi \mathbf{A})^{-1} \boldsymbol{\mu} = \mathbf{M} \boldsymbol{\mu} \\ \mathbf{R} &\equiv \varphi (\mathbf{I}_n + \rho \mathbf{B} - \varphi \mathbf{A})^{-1} \left(\frac{1}{\varphi} \mathbf{I}_n + \mathbf{A} \right) = \mathbf{M} + \varphi \mathbf{M} \mathbf{A}, \end{aligned}$$

with $\mathbf{M} = (\mathbf{I}_n + \rho \mathbf{B} - \varphi \mathbf{A})^{-1}$. The matrix \mathbf{R} has elements r_{ij} for $1 \leq i, j \leq n$. Furthermore, one can show that equilibrium profits are given by

$$\pi_i = \frac{1}{2} q_i^2 + \frac{1}{2} s_i^2.$$

(ii) Net welfare can be written as follows

$$\begin{aligned} \overline{W}(G, \mathbf{s}) &= \sum_{i=1}^n \left(\frac{q_i^2}{2} + \pi_i - s_i e_i \right) \\ &= \sum_{i=1}^n q_i^2 - \sum_{i=1}^n q_i s_i - \frac{1}{2} \sum_{i=1}^n s_i^2. \end{aligned}$$

Using the fact that $q_i = \bar{q}_i + r_{ij} s_j$, with

$$\begin{aligned} \bar{\mathbf{q}} &= (\mathbf{I}_n - \varphi \mathbf{A})^{-1} \boldsymbol{\mu} = \mathbf{M} \boldsymbol{\mu} \\ \mathbf{R} &= \varphi (\mathbf{I}_n - \varphi \mathbf{A})^{-1} \left(\frac{1}{\varphi} \mathbf{I}_n + \mathbf{A} \right) = \boldsymbol{\mu} + \varphi \mathbf{d}, \end{aligned}$$

where \mathbf{R} is symmetric, i.e. $r_{ij} = r_{ji}$, we can write net welfare as follows

$$\bar{W}(G, \mathbf{s}) = \sum_{i=1}^n \bar{q}_i^2 - \sum_{i=1}^n \bar{q}_i s_i - \frac{1}{2} \sum_{i=1}^n s_i^2 + \sum_{i=1}^n \left(\sum_{j=1}^n r_{ij} s_j \right) \left(2\bar{q}_i + \sum_{j=1}^n r_{ij} s_j - s_i \right).$$

The FOC for net welfare $\bar{W}(G, \mathbf{s})$ yields the following system of linear equations

$$\begin{aligned} \frac{\partial \bar{W}(G, \mathbf{s})}{\partial s_i} &= -\bar{q}_i - s_i + \sum_{k=1}^n r_{ki} \left(2\bar{q}_k + \sum_{j=1}^n r_{kj} s_j - s_k \right) \\ &+ \sum_{k=1}^n \left(\sum_{j=1}^n r_{kj} s_j \right) \left(\frac{1}{2} r_{ki} - \delta_{ki} \right) = 0. \end{aligned}$$

In vector-matrix notation this can be written as

$$(\mathbf{I}_n + 2\mathbf{R} - 2\mathbf{R}^2)\mathbf{s} = (2\mathbf{R} - \mathbf{I}_n)\bar{\mathbf{q}}.$$

When the conditions for invertibility are satisfied, it then follows that the optimal subsidy levels can be written as

$$\mathbf{s}^* = (\mathbf{I}_n + 2\mathbf{R} - 2\mathbf{R}^2)^{-1} (2\mathbf{R} - \mathbf{I}_n) \bar{\mathbf{q}},$$

with $\bar{\mathbf{q}} = (\mathbf{I}_n - \varphi \mathbf{A})^{-1} \boldsymbol{\mu} = \mathbf{b}_\mu$. The second-order derivative is given by

$$\frac{\partial^2 \bar{W}(G, \mathbf{s})}{\partial s_i \partial s_j} = -\delta_{ij} - 2r_{ij} + 2 \sum_{k=1}^n r_{ki} r_{kj}.$$

In vector-matrix notation this can be written as

$$\frac{\partial^2 \bar{W}(G, \mathbf{s})}{\partial \mathbf{s} \partial \mathbf{s}^\top} = -\mathbf{I}_n + 2\mathbf{R} - 2\mathbf{R}^2.$$

Hence, we obtain a global maximum for the concave quadratic optimization problem if the matrix $\mathbf{I}_n + 2\mathbf{R} - 2\mathbf{R}^2 = \mathbf{I}_n - 2\mathbf{R}^2 + 2\mathbf{R}$ is positive definite, which means that it is also invertible and its inverse is also positive definite.

- (iii) In the case of interdependent markets, when goods are substitutable, net welfare can be written as

$$\begin{aligned} \bar{W}(G, \mathbf{s}) &= \frac{1}{2} \left(\sum_{i=1}^n q_i^2 + \rho \sum_{i=1}^n \sum_{j \neq i}^n b_{ij} q_i q_j \right) + \sum_{i=1}^n \pi_i - \sum_{i=1}^n s_i e_i \\ &= \sum_{i=1}^n q_i^2 - \sum_{i=1}^n q_i s_i - 2 \sum_{i=1}^n s_i^2 + \frac{\rho}{2} \sum_{i=1}^n \sum_{j \neq i}^n b_{ij} q_i q_j. \end{aligned}$$

Using the fact that $q_i = \bar{q}_i + r_{ij}s_j$, with

$$\bar{\mathbf{q}} \equiv (\mathbf{I}_n + \rho\mathbf{B} - \varphi\mathbf{A})^{-1}\boldsymbol{\mu}$$

$$\mathbf{R} \equiv \varphi(\mathbf{I}_n + \rho\mathbf{B} - \varphi\mathbf{A})^{-1} \left(\frac{1}{\varphi}\mathbf{I}_n + \mathbf{A} \right),$$

where \mathbf{R} is in general not symmetric, unless $\mathbf{AB} = \mathbf{BA}$,⁴⁵ we can write net welfare as follows

$$\begin{aligned} \bar{W}(G, \mathbf{s}) &= \sum_{i=1}^n \left(\bar{q}_i + \sum_{j=1}^n r_{ij}s_j \right)^2 - \sum_{i=1}^n \left(\bar{q}_i + \sum_{j=1}^n r_{ij}s_j \right) s_i - \frac{1}{2} \sum_{i=1}^n s_i^2 \\ &\quad + \frac{\rho}{2} \sum_{i=1}^n \sum_{j=1}^n b_{ij} \left(\bar{q}_i + \sum_{k=1}^n r_{ik}s_k \right) \left(\bar{q}_j + \sum_{l=1}^n r_{jl}s_l \right). \end{aligned}$$

The FOC is given by

$$\begin{aligned} \frac{\partial \bar{W}(G, \mathbf{s})}{\partial s_i} &= -\bar{q}_i + 2 \sum_{k=1}^n r_{ki}\bar{q}_k - s_i - 2 \sum_{k=1}^n r_{ki}s_k + 2 \sum_{k=1}^n \sum_{j=1}^n r_{ki}r_{kj}s_j \\ &\quad + \frac{\rho}{2} \sum_{l=1}^n \sum_{j=1}^n b_{li}\bar{q}_l r_{ji} + \frac{\rho}{2} \sum_{l=1}^n \sum_{j=1}^n b_{lj}\bar{q}_j r_{li} + \frac{\rho}{2} \sum_{l=1}^n \sum_{j=1}^n b_{lj} \left(r_{li} \sum_{k=1}^n r_{jk}s_k + r_{ji} \sum_{k=1}^n r_{lk}s_k \right) = 0. \end{aligned}$$

In vector-matrix notation this can be written as follows

$$\frac{\partial \bar{W}(G, \mathbf{s})}{\partial \mathbf{s}} = -\bar{\mathbf{q}} + \bar{\mathbf{q}}^\top (2\mathbf{R} + \rho\mathbf{BR}) - \mathbf{s} - 2\mathbf{R}^\top \left(\mathbf{I}_n - \frac{1}{2}(2\mathbf{I}_n + \rho\mathbf{B})\mathbf{R} \right) \mathbf{s}$$

When the matrix $\mathbf{I}_n - 2\mathbf{R}^\top \left(\frac{1}{2}(2\mathbf{I}_n + \rho\mathbf{B})\mathbf{R} - \mathbf{I}_n \right)$ is invertible, the optimal subsidy levels can then be written as

$$\mathbf{s}^* = \left(\mathbf{I}_n - 2\mathbf{R}^\top \left(\frac{1}{2}(2\mathbf{I}_n + \rho\mathbf{B})\mathbf{R} - \mathbf{I}_n \right) \right)^{-1} \left(\mathbf{R}^\top (2\mathbf{I}_n + \rho\mathbf{B}) - \mathbf{I}_n \right) \bar{\mathbf{q}},$$

where the equilibrium quantities in the absence of the subsidy are given by

$$\bar{\mathbf{q}} = (\mathbf{I}_n + \rho\mathbf{B} - \varphi\mathbf{A})^{-1}\boldsymbol{\mu}.$$

The second-order derivative is given by

$$\frac{\partial^2 \bar{W}(G, \mathbf{s})}{\partial \mathbf{s} \partial \mathbf{s}^\top} = -\mathbf{I}_n + 2\mathbf{R}^\top \left(\mathbf{I}_n - \frac{1}{2}(2\mathbf{I}_n + \rho\mathbf{B})\mathbf{R} \right).$$

⁴⁵While the inverse of a symmetric matrix is symmetric, the product of symmetric matrices is not necessarily symmetric.

Hence, we obtain a global maximum for the concave quadratic optimization problem if the matrix $\mathbf{I}_n + 2\mathbf{R}^\top (\mathbf{I}_n - \frac{1}{2}(2\mathbf{I}_n + \rho\mathbf{B})\mathbf{R})$ is positive definite. Note that if this matrix is positive definite then it is also invertible and its inverse is also positive definite. \square

Proof of Proposition 8. In terms of the walk generating function welfare can be written as

$$\begin{aligned} W(G) &= \frac{2-\rho}{2} \frac{\mu^2}{\rho^2} \frac{N_G(\phi)^2}{\left(\frac{1-\rho}{\rho} + N_G(\phi)\right)^2} \left(\frac{\rho}{2-\rho} + \frac{\frac{d}{d\phi}(\phi N_G(\phi))}{N_G(\phi)^2} \right) \\ &= \frac{2-\rho}{2} \frac{\mu^2}{\rho^2} \frac{(1-\phi\lambda_1)^2 N_G(\phi)^2}{\left(\frac{1-\rho}{\rho}(1-\phi\lambda_1) + (1-\phi\lambda_1)N_G(\phi)\right)^2} \left(\frac{\rho}{2-\rho} + \frac{(1-\phi\lambda_1)^2 \frac{d}{d\phi}(\phi N_G(\phi))}{(1-\phi\lambda_1)^2 N_G(\phi)^2} \right). \end{aligned}$$

Then the following limits for the walk generating function hold

$$\begin{aligned} \lim_{\phi \uparrow 1/\lambda_1} (1-\phi\lambda_1)N_G(\phi) &= \lim_{\phi \uparrow 1/\lambda_1} (1-\phi\lambda_1) \sum_{i=1}^n \frac{(\mathbf{u}^\top \mathbf{v}_i)^2}{1-\phi\lambda_i} = (\mathbf{u}^\top \mathbf{v}_1)^2 \\ \lim_{\phi \uparrow 1/\lambda_1} (1-\phi\lambda_1)^2 N_G(\phi)^2 &= \lim_{\phi \uparrow 1/\lambda_1} (1-\phi\lambda_1)^2 \left(\sum_{i=1}^n \frac{(\mathbf{u}^\top \mathbf{v}_i)^4}{(1-\phi\lambda_i)^2} + \sum_{i=1}^n \sum_{j \neq i}^n \frac{(\mathbf{u}^\top \mathbf{v}_i)^2 (\mathbf{u}^\top \mathbf{v}_j)^2}{(1-\phi\lambda_i)(1-\phi\lambda_j)} \right) = (\mathbf{u}^\top \mathbf{v}_1)^4 \\ \lim_{\phi \uparrow 1/\lambda_1} (1-\phi\lambda_1)^2 \frac{d}{d\phi}(\phi N_G(\phi)) &= \lim_{\phi \uparrow 1/\lambda_1} (1-\phi\lambda_1)^2 \sum_{i=1}^n \frac{(\mathbf{u}^\top \mathbf{v}_i)^2}{(1-\phi\lambda_i)^2} = (\mathbf{u}^\top \mathbf{v}_1)^2. \end{aligned}$$

In the limit of $\phi \uparrow \lambda_1$ we then get for welfare

$$\begin{aligned} \lim_{\phi \uparrow 1/\lambda_1} W(G) &= \frac{2-\rho}{2} \frac{\mu^2}{\rho^2} \frac{(\mathbf{u}^\top \mathbf{v}_1)^4}{(\mathbf{u}^\top \mathbf{v}_1)^4} \left(\frac{\rho}{2-\rho} + \frac{(\mathbf{u}^\top \mathbf{v}_1)^2}{(\mathbf{u}^\top \mathbf{v}_1)^4} \right) \\ &= \frac{2-\rho}{2} \frac{\mu^2}{\rho^2} \left(\frac{\rho}{2-\rho} + \frac{1}{(\mathbf{u}^\top \mathbf{v}_1)^2} \right). \end{aligned}$$

This expression is increasing with decreasing values of $(\mathbf{u}^\top \mathbf{v}_1)^2 = \|\mathbf{v}_1\|_1^2$. We thus find that the welfare maximizing graph G^* is the one that minimizes the ℓ^1 -norm $\|\mathbf{v}_1\|_1$ of the principal eigenvector \mathbf{v}_1 associated with the largest eigenvalue λ_1 . \square